Planner classification

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pip install tensorflow


import tensorflow as tf
from tensorflow.keras import datasets, layers, models
import matplotlib.pyplot as plt

# Load and preprocess
(train_images, train_labels), (test_images, test_labels) = datasets.cifar10.load_data()

# Normalize pixel values to be between 0 and 1
train_images, test_images = train_images / 255.0, test_images / 255.0

# Define the class names
class_names = ['airplane', 'automobile', 'bird', 'cat', 'deer',
               'dog', 'frog', 'horse', 'ship', 'truck']

# Build the CNN model
model = models.Sequential([
    layers.Conv2D(32, (3, 3), activation='relu', input_shape=(32, 32, 3)),
    layers.MaxPooling2D((2, 2)),

    layers.Conv2D(64, (3, 3), activation='relu'),
    layers.MaxPooling2D((2, 2)),

    layers.Conv2D(64, (3, 3), activation='relu'),
    layers.MaxPooling2D((2, 2)),

    layers.Flatten(),
    layers.Dense(64, activation='relu'),
    layers.Dense(10, activation='softmax')
])
```

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# Compile the model
model.compile(optimizer='adam',
              loss='sparse_categorical_crossentropy',
              metrics=['accuracy'])

# Train the model
history = model.fit(train_images, train_labels, epochs=10,
                    validation_data=(test_images, test_labels))

# Evaluate the model
test_loss, test_acc = model.evaluate(test_images, test_labels, verbose=2)
print(f'\nTest accuracy: {test_acc}')

# Plot accuracy and loss over epochs
plt.figure(figsize=(10, 4))

plt.subplot(1, 2, 1)
plt.plot(history.history['accuracy'], label='accuracy')
plt.plot(history.history['val_accuracy'], label = 'val_accuracy')
plt.xlabel('Epoch')
plt.ylabel('Accuracy')
plt.ylim([0, 1])
plt.legend(loc='lower right')

plt.subplot(1, 2, 2)
plt.plot(history.history['loss'], label='loss')
plt.plot(history.history['val_loss'], label = 'val_loss')
plt.xlabel('Epoch')
plt.ylabel('Loss')
plt.legend(loc='upper right')

plt.show()
```

Findings from Research paper

The paper concludes that careful consideration of activation functions and weight initialization is crucial for successfully training deep feedforward neural networks. By addressing the vanishing and exploding gradient problems, these techniques have enabled the development of more powerful and deeper neural networks.