Lecture 3: Expectations, moments, and distributions

STATS 101: Foundations of Statistics

Linh Tran

ThetaHat.AI@gmail.com

December 5, 2019

Announcements

- ► Review survey
- Question: How long did last homework take?
- ▶ Next assignment will be posted tonight
 - ▶ Due 12/11 @ 11:59pm
- Classes will be recorded going forward

Outline

Expectations, moments, and distributions

- ► Expected value
- Moments
- ► Moment generating functions
- Distributions

The *expected value* of rv X is defined as

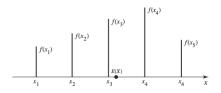
$$\mathbb{E}[X] = \begin{cases} \sum_{x} x f_X(x) & \text{if x is discrete} \\ \int x f_X(x) dx & \text{if x is continuous} \end{cases}$$
 (1)

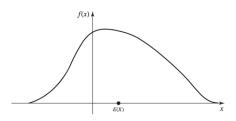
For functions g of X,

$$\mathbb{E}[g(X)] = \begin{cases} \sum_{x} g(x) f_X(x) & \text{if x is discrete} \\ \int g(x) f_X(x) dx & \text{if x is continuous} \end{cases}$$
 (2)

n.b. In general, $\mathbb{E}[g(X)] \neq g(\mathbb{E}[X])$

Examples:





Important: Expectations might not exist!

Example: Suppose $f_X(x) = \frac{1}{x^2}$, defined on $[1, \infty]$. Then

$$\mathbb{E}[X] = \int x f_X(x) dx = \int x \frac{1}{x^2} dx = \int \frac{1}{x} dx = \infty$$
 (3)

Important: Expectations might not exist!

Example: Suppose $f_X(x) = \frac{1}{x^2}$, defined on $[1, \infty]$. Then

$$\mathbb{E}[X] = \int x f_X(x) dx = \int x \frac{1}{x^2} dx = \int \frac{1}{x} dx = \infty$$
 (3)

Some properties of expectations:

- ▶ Linearity: $\mathbb{E}[ag(X) + bh(X)] = \mathbb{E}[ag(X)] + \mathbb{E}[bh(X)]$
- ▶ Order preserving: $g(X) \le h(X), \forall x \in \mathbb{R} \Rightarrow \mathbb{E}[g(X)] \le \mathbb{E}[h(X)]$

The *variance* of rv X is defined as

$$var(X) = \mathbb{E}[(X - \mu)^2] : \mu = \mathbb{E}[X]$$
 (4)

The *variance* of rv X is defined as

$$var(X) = \mathbb{E}[(X - \mu)^2] : \mu = \mathbb{E}[X]$$
 (4)

Some notes:

- ▶ If $\mathbb{E}[X]$ doesn't exist then var(X) doesn't exist.
- var(X) can be infinite.
- ▶ The standard deviation σ of X is $\sqrt{var(X)}$.

With some algebra, we see that

$$var(X) = \mathbb{E}[(X - \mu)^2]$$
 (5)

$$= \mathbb{E}[X^2 - 2X\mu + \mu^2] \tag{6}$$

$$= \mathbb{E}[X^2] - \mathbb{E}[2X\mu] + \mathbb{E}[\mu^2] \tag{7}$$

$$= \mathbb{E}[X^2] - \mu^2 \tag{8}$$

$$= \mathbb{E}[X^2] - \mathbb{E}[X]^2 \tag{9}$$

Some properties:

- ▶ If X is bounded, then var(X) exists and is finite.
- ▶ $var(X) = 0 \iff P(X = c) = 1$ for some constant c.
- ▶ $var(cX) = c^2 var(X)$ for some constant c.
- ▶ variance is linear, i.e. $var(X_1 + X_2) = var(X_1) + var(X_2)$.

The k^{th} moment of rv X is defined as

$$\mathbb{E}[X^k] = \mu_k : k \in \mathbb{N} \tag{10}$$

The k^{th} central/centered moment of rv X is defined as

$$\mathbb{E}[(X-\mu)^k] = \mu_k : k \in \mathbb{N}$$
 (11)

The k^{th} moment of rv X is defined as

$$\mathbb{E}[X^k] = \mu_k' : k \in \mathbb{N} \tag{10}$$

The k^{th} central/centered moment of rv X is defined as

$$\mathbb{E}[(X-\mu)^k] = \mu_k : k \in \mathbb{N}$$
 (11)

Notes:

- μ_k exists if and only if $\mathbb{E}[|X|^k] < \infty$.
- ▶ If μ_k exists, then for all j < k, μ_j also exists.
- Variance is μ₂.
- *Skewness* is μ_3/σ^2 .
- Kurtosis is μ_4/σ^4 .

Example: Suppose $X \sim N(0,1) \ni f_X(x) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{x^2}{2}\right)$.

$$\mu_1' = \mathbb{E}[X] = \int x f_X(x) dx = f_X(x)|_{-\infty}^{\infty} = 0$$
 (12)

n.b. For the normal distribution, $xf_X(x) = -\frac{\partial}{\partial x}f_X(x)$.

Example: Suppose $X \sim N(0,1) \ni f_X(x) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{x^2}{2}\right)$.

$$\mu_1' = \mathbb{E}[X] = \int x f_X(x) dx = f_X(x)|_{-\infty}^{\infty} = 0$$
 (12)

n.b. For the normal distribution, $xf_X(x) = -\frac{\partial}{\partial x}f_X(x)$.

$$\mu_2 = \mathbb{E}[(X - \mu)^2] = \mathbb{E}[(X - 0)^2] = \mathbb{E}[X^2] = \int x^2 f_X(x) dx$$
 (13)

using integration by parts, we get

$$\int x^2 f_X(x) dx = \underbrace{-x f_X(x)|_{-\infty}^{\infty}}_{=0} + \underbrace{\int_{-\infty}^{\infty} f_X(x) dx}_{=1} = 1$$
 (14)

Moment generating functions (mgf) are used to calculate the moments of a rv. The mgf of a rv X is a function $M_X: \mathbb{R} \Rightarrow \mathbb{R}_+$ such that

$$M_X(t) = \mathbb{E}[e^{tX}] : t \in \mathbb{R}$$
 (15)

Moment generating functions (mgf) are used to calculate the moments of a rv. The mgf of a rv X is a function $M_X: \mathbb{R} \Rightarrow \mathbb{R}_+$ such that

$$M_X(t) = \mathbb{E}[e^{tX}] : t \in \mathbb{R}$$
 (15)

Notes:

- ▶ The mgf is a function of t; X is integrated out by \mathbb{E} .
- ▶ The mgf only applies if the moments of the rv exists.
- ▶ If two rv X, Y have the same mgf (i.e. $M_X(t) = M_Y(t)$), then they have the same distribution.
- Even if a rv has moments, the mgf may yield infinity (e.g. log-normal distribution).

Taking the derivative of the mgf, we see that

$$\frac{\partial}{\partial t} M_X(t) = \frac{\partial}{\partial t} \int e^{tx} f_X(x) dx = \int x \cdot e^{tx} f_X(x) dx \qquad (16)$$

What happens when t = 0?

Taking the derivative of the mgf, we see that

$$\frac{\partial}{\partial t} M_X(t) = \frac{\partial}{\partial t} \int e^{tx} f_X(x) dx = \int x \cdot e^{tx} f_X(x) dx \qquad (16)$$

What happens when t = 0?

$$\int x \cdot e^{tx} f_X(x) dx = \int x f_X(x) dx = \mathbb{E}[X]$$
 (17)

Taking the derivative of the mgf, we see that

$$\frac{\partial}{\partial t} M_X(t) = \frac{\partial}{\partial t} \int e^{tx} f_X(x) dx = \int x \cdot e^{tx} f_X(x) dx \qquad (16)$$

What happens when t = 0?

$$\int x \cdot e^{tx} f_X(x) dx = \int x f_X(x) dx = \mathbb{E}[X]$$
 (17)

What happens when t = 0 for the k^{th} derivative?

Taking the derivative of the mgf, we see that

$$\frac{\partial}{\partial t} M_X(t) = \frac{\partial}{\partial t} \int e^{tx} f_X(x) dx = \int x \cdot e^{tx} f_X(x) dx \qquad (16)$$

What happens when t = 0?

$$\int x \cdot e^{tx} f_X(x) dx = \int x f_X(x) dx = \mathbb{E}[X]$$
 (17)

What happens when t = 0 for the k^{th} derivative?

$$\frac{\partial}{\partial t^k} M_X(t) = \int x^k \cdot e^{tx} f_X(x) dx \tag{18}$$

At t=0, we get $\frac{\partial}{\partial t^k} M_X(t)|_{t=0} = \mathbb{E}[X^k]$

Evaluating the k^{th} derivative at t = 0 gives us the k^{th} moment of X.

Example: The standard normal distribution

$$M_X(t) = \mathbb{E}[e^{tX}] = \int e^{tX} f_X(x) dx$$

$$= \int e^{tX} \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{x^2}{2}\right) dx$$

$$= \int \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{(x-t)^2}{2}\right) \exp\left(\frac{t^2}{2}\right) dx$$

$$= \exp\left(\frac{t^2}{2}\right) \int \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{(x-t)^2}{2}\right) dx$$

$$= \exp\left(\frac{t^2}{2}\right)$$

$$= \exp\left(\frac{t^2}{2}\right)$$
(23)

The mgf for affine transformations is straight forward, e.g. If Y = aX + b, then $M_Y(t) = e^{bt}M_X(at)$.

Example: Let $X = \mu + \sigma Z : Z \sim N(0,1)$. Then

$$M_X(t) = M_{\mu+\sigma Z}(t) = e^{\mu t} M_Z(\sigma t) = e^{\mu t} e^{\frac{1}{2}\sigma^2 t^2} = e^{\mu t + \frac{1}{2}\sigma^2 t^2}$$
 (24)

The mgf for affine transformations is straight forward, e.g. If Y = aX + b, then $M_Y(t) = e^{bt} M_X(at)$.

Example: Let $X = \mu + \sigma Z : Z \sim N(0,1)$. Then

$$M_X(t) = M_{\mu+\sigma Z}(t) = e^{\mu t} M_Z(\sigma t) = e^{\mu t} e^{\frac{1}{2}\sigma^2 t^2} = e^{\mu t + \frac{1}{2}\sigma^2 t^2}$$
 (24)

Another example:

Let $X_1, \ldots, X_n \stackrel{iid}{\sim} P_0$ and $Y = \sum_{i=1}^n X_i$. Then

$$M_{Y}(t) = \mathbb{E}[e^{tY}] = \mathbb{E}[e^{t(X_{1} + \dots + X_{n})}] = \mathbb{E}\left[\prod_{i=1}^{n} e^{tX_{i}}\right]$$
(25)
$$= \prod_{i=1}^{n} \mathbb{E}\left[e^{tX_{i}}\right] = \prod_{i=1}^{n} M_{Y}(t)$$
(26)

$$= \prod_{i=1}^{n} \mathbb{E}\left[e^{tX_{i}}\right] = \prod_{i=1}^{n} M_{X_{i}}(t)$$
 (26)

Distributions

Most useful distributions have names, e.g.

- Normal distribution
- Uniform distribution
- Bernoulli distribution
- Binomial distribution
- ▶ Poisson distribution
- Gamma distribution

Normal distribution

A rv X follows a *Normal distribution*, denoted as $X \sim N(\mu, \sigma^2)$ with mean μ and variance σ^2 , if X is continuous with pdf

$$f_X(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right) : x \in \mathbb{R}$$
 (27)

Note:

If $Z \sim N(0,1)$ then $X = \mu + \sigma Z \sim N(\mu, \sigma^2)$. It follows that

- $\mathbb{E}[X] = \mathbb{E}[\mu + \sigma Z] = \mu + \sigma \mathbb{E}[Z] = \mu.$
- $var(X) = var(\mu + \sigma Z) = \sigma^2 var(Z) = \sigma^2$.

Normal distribution

A rv X follows a *Normal distribution*, denoted as $X \sim N(\mu, \sigma^2)$ with mean μ and variance σ^2 , if X is continuous with pdf

$$f_X(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right) : x \in \mathbb{R}$$
 (27)

Note:

If $Z \sim N(0,1)$ then $X = \mu + \sigma Z \sim N(\mu, \sigma^2)$. It follows that

- $\mathbb{E}[X] = \mathbb{E}[\mu + \sigma Z] = \mu + \sigma \mathbb{E}[Z] = \mu.$
- $var(X) = var(\mu + \sigma Z) = \sigma^2 var(Z) = \sigma^2$.

Most well known distribution due to:

- 1. Good mathematical properties
- 2. Often (approximately) observed in the real world (e.g. heights, weights, etc.)
- 3. Central limit theorem

Central limit theorem

Let $X_1, \ldots, X_n \stackrel{iid}{\sim} P_0$, where $\mathbb{E}[X_i] = \mu$ and $var(X_i) = \sigma^2$. Then

$$\lim_{n \to \infty} P\left(\frac{n^{1/2}(\bar{X}_n - \mu)}{\sigma} \le x\right) = \Phi(x)$$
 (28)

where $\Phi(x)$ is the cdf for the standard normal distribution.

Central limit theorem

Let $X_1, \ldots, X_n \stackrel{iid}{\sim} P_0$, where $\mathbb{E}[X_i] = \mu$ and $var(X_i) = \sigma^2$. Then

$$\lim_{n\to\infty} P\left(\frac{n^{1/2}(\bar{X}_n-\mu)}{\sigma}\leq x\right) = \Phi(x) \tag{28}$$

where $\Phi(x)$ is the cdf for the standard normal distribution.

Example: The sample mean

$$\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i$$
 (29)

The 95% CI: $\bar{X}_n \pm z_{\alpha/2} \hat{se}_n$

Uniform distribution

A rv X follows a Uniform distribution U(a,b) if X is continuous with pdf

$$f_X(x) = \begin{cases} \frac{1}{b-a} & x \in [a, b] \\ 0 & \text{otherwise} \end{cases}$$
 (30)

Under U(a, b), all observations are "equally likely"

$$\mathbb{E}[X] = \frac{a+b}{2}$$
, $var(X) = \frac{(b-a)^2}{12}$, and $M_X(t) = \frac{e^{bt} - e^{at}}{(b-a)t}$.

Uniform distribution

A rv X follows a Uniform distribution U(a,b) if X is continuous with pdf

$$f_X(x) = \begin{cases} \frac{1}{b-a} & x \in [a, b] \\ 0 & \text{otherwise} \end{cases}$$
 (30)

Under U(a, b), all observations are "equally likely"

$$\mathbb{E}[X] = \frac{a+b}{2}$$
, $var(X) = \frac{(b-a)^2}{12}$, and $M_X(t) = \frac{e^{bt} - e^{at}}{(b-a)t}$.

Note: if $X \sim U(a,b)$, then $X = (b-a)\tilde{X} + a$: $\tilde{X} \sim U(0,1)$ and

$$f_{\tilde{X}}(x) = \begin{cases} 1 & x \in [0, 1] \\ 0 & \text{otherwise} \end{cases}$$
 (31)

Bernoulli distribution

A rv X follows a Bernoulli distribution Ber(p) if X is discrete with pmf

$$f_X(x) = \begin{cases} p & \text{if } x = 1\\ 1 - p & \text{if } x = 0\\ 0 & \text{otherwise} \end{cases}$$
 (32)

$$\mathbb{E}[X] = p$$
, $var(X) = p(1-p)$, and $M_X(t) = e^t p + (1-p)$.

Binomial distribution

A rv X follows a Binomial distribution Bin(n,p) if X is discrete with pmf

$$f_X(x) = \begin{cases} \binom{n}{x} p^x (1-p)^{n-x} & \text{if } x \in \{0, 1, ..., n\} \\ 0 & \text{otherwise} \end{cases}$$
(33)

$$\mathbb{E}[X] = np, \ var(X) = np(1-p), \ and \ M_X(t) = (e^t p + (1-p))^n.$$

If $X_1,...,X_n \stackrel{iid}{\sim} Ber(p)$, then $Y = X_1 + \cdots + X_n$ follows B(n,p).

Negative Binomial distribution

A rv X follows a Negative Binomial distribution NB(r,p) if X is discrete with pmf

$$f_X(x) = \begin{cases} \binom{r+x-1}{x} p^x (1-p)^r & \text{if } x \in \{0,1,...,n\} \\ 0 & \text{otherwise} \end{cases}$$
(34)

$$\mathbb{E}[X] = \frac{r(1-p)}{p}$$
, $var(X) = \frac{r(1-p)}{p^2}$, and $M_X(t) = \left(\frac{p}{1-qe^t}\right)^r$: $t < \log\left(\frac{1}{q}\right)$.

When r = 1, we refer to it as the *Geometric distribution*.

▶ It has a *memoryless* property.

Poisson distribution

A rv X follows a Poisson distribution $Pois(\lambda)$ if X is discrete with pmf

$$f_X(x) = \begin{cases} e^{-\lambda} \frac{\lambda^x}{x!} & x \in \mathbb{N} \\ 0 & \text{otherwise} \end{cases}$$
 (35)

$$\mathbb{E}[X] = \lambda$$
, $var(X) = \lambda$, and $M_X(t) = e^{\lambda(e^t - 1)}$.

Some notes:

- ▶ $Bin(n, p) \approx Pois(np)$ when n is large and np is small.
- "Poisson Processes" are typically used to model rates, e.g. mortality rates
 - 1. The number of events in each fixed time interval t has a Poisson distribution with mean λt .
 - 2. The number of events in each time interval is independent.

Gamma distribution

A rv X follows a Gamma distribution $\operatorname{Gamma}(\alpha,\beta)$ if X is continuous with pdf

$$f_X(x) = \begin{cases} \frac{1}{\Gamma(\alpha)\beta^{\alpha}} x^{\alpha - 1} e^{-\frac{x}{\beta}} & x > 0\\ 0 & \text{otherwise} \end{cases}$$
 (36)

where $\Gamma(x) = \int_0^\infty t^{\alpha-1} e^{-t} dt : \alpha > 0$.

$$\mathbb{E}[X] = \alpha \beta$$
, $var(X) = \alpha \beta^2$, and

$$M_X(t) = \left(1 - \frac{t}{\beta}\right)^{-\alpha} : t < \beta.$$

Gamma distribution

A rv X follows a Gamma distribution $\operatorname{Gamma}(\alpha,\beta)$ if X is continuous with pdf

$$f_X(x) = \begin{cases} \frac{1}{\Gamma(\alpha)\beta^{\alpha}} x^{\alpha - 1} e^{-\frac{x}{\beta}} & x > 0\\ 0 & \text{otherwise} \end{cases}$$
 (36)

where $\Gamma(x) = \int_0^\infty t^{\alpha-1} e^{-t} dt : \alpha > 0$.

$$\mathbb{E}[X] = \alpha \beta$$
, $var(X) = \alpha \beta^2$, and $M_X(t) = \left(1 - \frac{t}{\beta}\right)^{-\alpha} : t < \beta$.

Notes:

- $ightharpoonup rac{1}{\Gamma(\alpha)\beta^{\alpha}}$ is often referred to as the 'normalizing constant'.
- ▶ When $\alpha = 1$, we get the exponential distribution.

Beta distribution

A rv X follows a Beta distribution $Beta(\alpha, \beta)$ if X is continuous with pdf

$$f_X(x) = \begin{cases} \frac{\Gamma(\alpha+\beta)}{\Gamma(\alpha)\Gamma(\beta)} x^{\alpha-1} (1-x)^{\beta-1} & 0 < x < 1\\ 0 & \text{otherwise} \end{cases}$$
(37)

$$\mathbb{E}[X] = \frac{\alpha}{\alpha + \beta}, \ var(X) = \frac{\alpha\beta}{(\alpha + \beta)^2(\alpha + \beta + 1)}, \ \text{and}$$

$$M_X(t) = \frac{\Gamma(\alpha + \beta)}{\Gamma(\alpha)\Gamma(\beta)} \int_0^1 x^{\alpha + k - 1} (1 - x)^{\beta - 1} dx.$$

n.b. Very popular distribution in Bayesian statistics.

Multinomial distribution

Suppose rv $\mathbf{X} = (X_1, ..., X_k)$ represents counts of k different classes. Then it follows a Multinomial distribution $Multi(p_1, ..., p_k)$ if it has pdf

$$f_X(x) = \begin{cases} \binom{n}{x_1, \dots, x_k} p_1^{x_1} \cdots p_k^{x_k} & x_1 \ge 0, \dots, x_k \ge 0\\ 0 & \text{otherwise} \end{cases}$$
(38)

where $n = \sum_{i=1}^{k} X_i$.

$$\mathbb{E}[X_i] = np$$
, $var(X_i) = np_i(1 - p_i)$, and $Cov(X_i, X_j) = -np_ip_j$.

Dirac delta function

While not technically a pdf, often used for e.g. mixture of discrete distributions

The Dirac delta function is defined as $\delta: \mathbb{R} \to \mathbb{R} \cup \infty \ni$

$$\delta(x) = \begin{cases} +\infty & x = 0\\ 0 & \text{otherwise} \end{cases}$$
 (39)

and
$$\int_{-\infty}^{\infty} \delta(x) dx = 1$$

The sifting property:

$$\int f(x)\delta(x-a)dx = f(a) \tag{40}$$

Dirac delta function

Example: Let

$$Y = \begin{cases} 1 & \text{w.p. } \alpha \\ U(0,1) & \text{w.p. } 1 - \alpha \end{cases}$$
 (41)

Then
$$f_Y(y) = \alpha \delta(y-1) + (1-\alpha)\mathbb{I}(y \in [0,1])$$

Dirac delta function

Example: Let

$$Y = \begin{cases} 1 & \text{w.p. } \alpha \\ U(0,1) & \text{w.p. } 1 - \alpha \end{cases} \tag{41}$$

Then $f_Y(y) = \alpha \delta(y-1) + (1-\alpha)\mathbb{I}(y \in [0,1])$

$$\mathbb{E}[Y] = \int_{-\infty}^{\infty} y(\alpha\delta(y-1) + (1-\alpha)\mathbb{I}(y \in [0,1]))dy \quad (42)$$

$$= \alpha \int_{\infty}^{\infty} y(\delta(y-1)dy + (1-\alpha) \int_{0}^{1} ydy$$
 (43)

$$= \alpha + (1 - \alpha) \frac{y^2}{2} \Big|_0^1 \tag{44}$$

$$= \alpha + \frac{1-\alpha}{2} \tag{45}$$

$$= \frac{1+\alpha}{2} \tag{46}$$

References

- ▶ DeGroot & Schervish Chapters 4.1-4.5,5.1-5.9
- ► Grinstead & Snell Chapters 5,6