

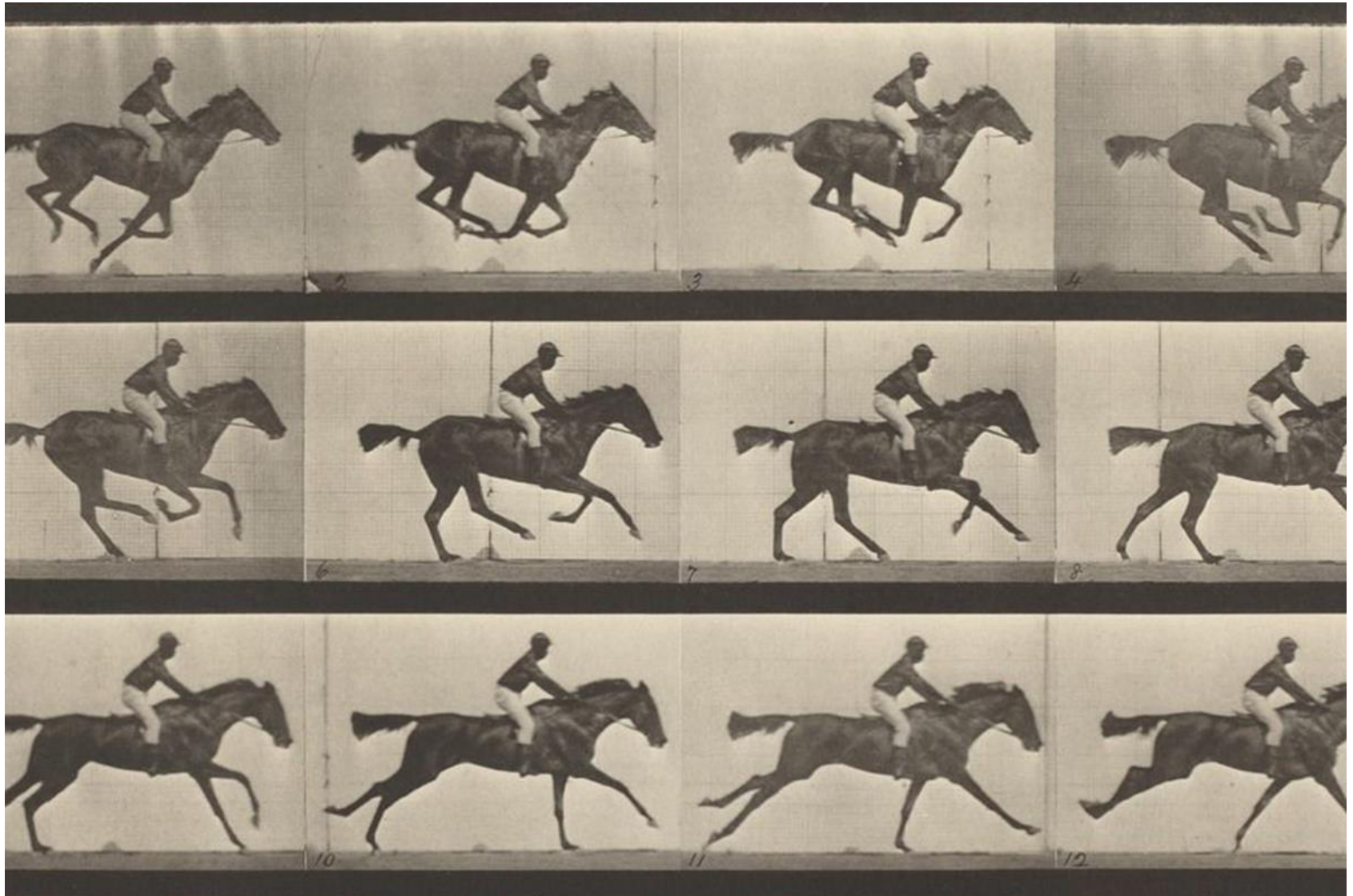
Event-based Robot Vision

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How do we capture visual information?



Master of Photography E. Muybridge ca. 1878. *"The Horse in Motion"*

How do we capture visual information?

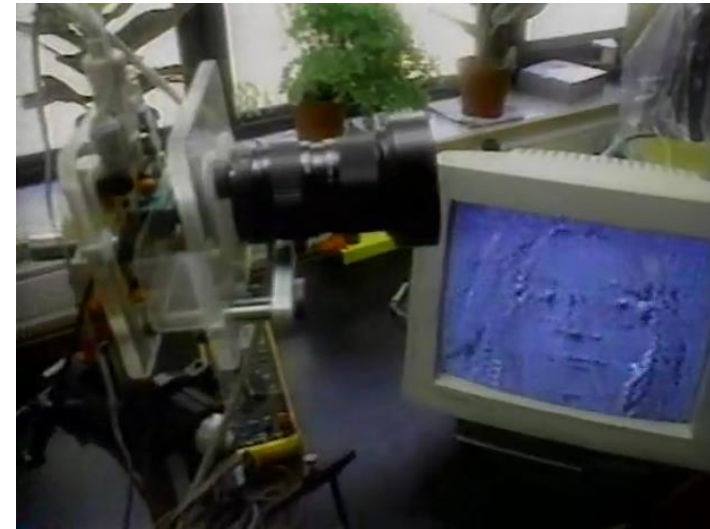
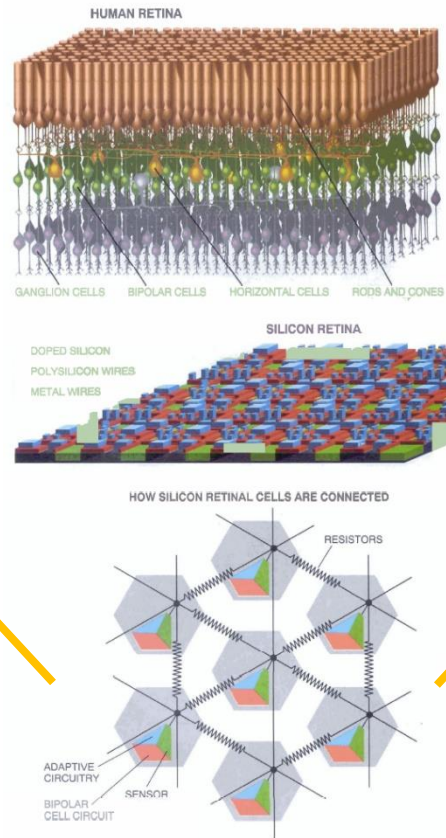


M. Mahowald & C. Mead (~1990)

- The spark of “Neuromorphic Engineering”
- Bringing **biology** into chip design on silicon (**engineering**)



Modeling Neural Structures in Silicon



Two types of cameras important to us (~2014)

Standard, frame-based camera

(outputs images
Here, frame rate= 6 Hz)

vs

Event-based camera
(outputs “events” or
“spikes”, represented
as red and green dots
in the video)

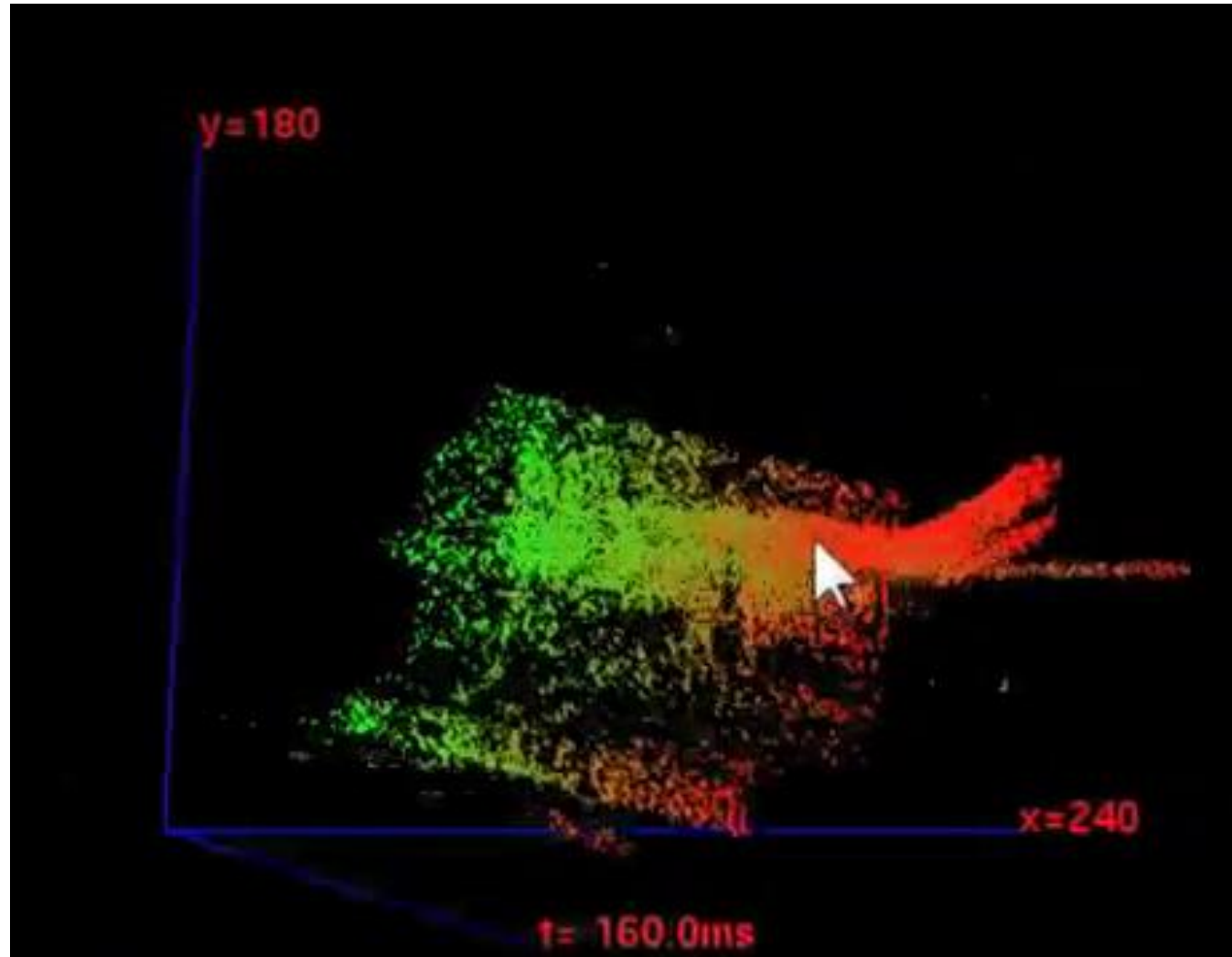


Space-time visualization of events

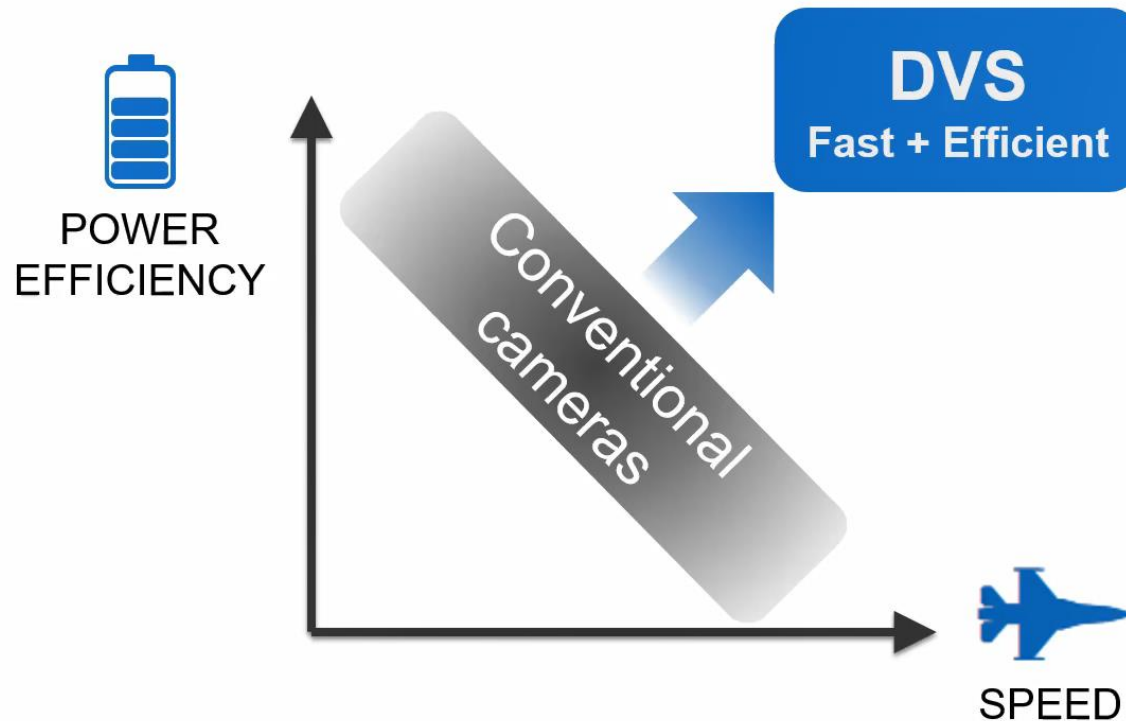
Space: sensor size is
240 x 180 pixels

Time: 160 ms

In the video, time is
colored: **red** means
new, **green** means old
(look at the trajectory
of the tennis ball).



Event camera. Efficiency - Latency trade off



The DVS beats the power vs speed trade-off providing high speed at low power.

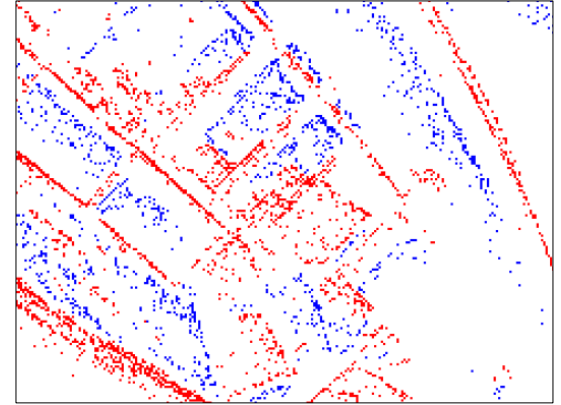
Comparison of two camera types

> 60 years of research!



Standard Camera

< 10 years research



Event Camera

Update rate	Low (synchronous)	High (asynchronous): 1 MHz
Dynamic Range	Low (60 dB)	High (140 dB)
Motion Blur	Yes	Almost none
Absolute intensity	Yes	No (but it can be reconstructed)
Mature?	Yes	Not yet

References

Reading:

- Mead & Mahowald. [*The Silicon Retina*](#), Scientific American 1991.
- If curious, read about early motion studies and devices:
[https://en.wikipedia.org/wiki/Eadweard_Muybridge#1872-1879: Stanford and horse gaits](https://en.wikipedia.org/wiki/Eadweard_Muybridge#1872-1879:_Stanford_and_horse_gaits)
[https://en.wikipedia.org/wiki/Eadweard_Muybridge#Later motion studies](https://en.wikipedia.org/wiki/Eadweard_Muybridge#Later_motion_studies)
- T. Delbruck, [*The Slow but Steady Rise of the Event Camera*](#), EE Times 2020.

Videos:

- Silicon Vision - Misha Mahowald <https://www.dailymotion.com/video/x28ktma>
- E. Muybridge BBC documentary <https://youtu.be/5Awo-P3t4Ho>