

1. I spent about 45 minutes reading the supplemental document.

$$2. \begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} 2 & 3 \\ -1 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 \\ 2 \end{bmatrix} u$$

$$y = \begin{bmatrix} 2 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$(a) \quad O = \begin{bmatrix} C \\ CA \\ \vdots \\ CA^{n-1} \end{bmatrix}$$

$$CA = \begin{bmatrix} 2 & 0 \end{bmatrix} \begin{bmatrix} 2 & 3 \\ -1 & 4 \end{bmatrix} = \begin{bmatrix} 4 & 6 \end{bmatrix}$$

$$O = \begin{bmatrix} 2 & 0 \\ 4 & 6 \end{bmatrix}, \text{ which has full rank so the system is observable}$$

$$(b) \quad \omega_n = 5 \\ \zeta = 0.8$$

$$\begin{aligned} \text{Desirable char eq: } \lambda^2 + 2\zeta\omega_n\lambda + \omega_n^2 &= 0 \\ \lambda^2 + 2(0.8)(5)\lambda + (5)^2 &= 0 \\ \lambda^2 + 8\lambda + 25 &= 0 \end{aligned}$$

Get eigenvalues of $A - LC$

$$\begin{aligned} A - LC &= \begin{bmatrix} 2 & 3 \\ -1 & 4 \end{bmatrix} - \begin{bmatrix} L_1 \\ L_2 \end{bmatrix} \begin{bmatrix} 2 & 0 \end{bmatrix} \\ &= \begin{bmatrix} 2 & 3 \\ -1 & 4 \end{bmatrix} - \begin{bmatrix} 2L_1 & 0 \\ 2L_2 & 0 \end{bmatrix} \end{aligned}$$

$$= \begin{bmatrix} 2 - 2L_1 & 3 \\ -1 - 2L_2 & 4 \end{bmatrix}$$

$$\text{eig}(A-LC) = \det(\lambda I - [A-LC])$$

$$= \begin{bmatrix} \lambda - 2 + 2L_1 & -3 \\ 1 + 2L_2 & \lambda - 4 \end{bmatrix}$$

$$= (\lambda - 2 + 2L_1)(\lambda - 4) - (-3)(1 + 2L_2)$$

$$= \lambda^2 - 4\lambda - 2\lambda + 8 + 2L_1\lambda - 8L_1 - [-3 - 6L_2]$$

$$= \lambda^2 - 6\lambda + 2L_1\lambda + 8 - 8L_1 + 3 + 6L_2$$

$$= \lambda^2 + (2L_1 - 6)\lambda + (-8L_1 + 6L_2 + 11)$$

$$\lambda^2 + (2L_1 - 6)\lambda + (-8L_1 + 6L_2 + 11) = \lambda^2 + 8\lambda + 25$$

$$2L_1 - 6 = 8$$

$$L_1 = 14$$

$$-8L_1 + 6L_2 + 11 = 25$$

$$-8(14) + 6L_2 = 14$$

$$-112 + 6L_2 = 14$$

$$6L_2 = 126$$

$$L_2 = 21$$