### ECE 2521: Analysis of Stochastic Processes

#### Lecture 1

Department of Electrical and Computer Engineering University of Pittsburgh September, 1<sup>st</sup> 2021

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### Instructor

- Instructor: Azime Can-Cimino (azime.cancimino@pitt.edu)
  - Lectures on Wednesday: 6:00-8:30 PM, G37 Benedum Hall (except first two weeks online via Zoom)
  - Office Hours: Friday 10:00-11:00 AM Via Zoom (link on Syllabus)

**Textbook**: Probability, Statistics and Random Processes for Electrical Engineering by Alberto Leon-Garcia (3rd Edition)

### Grading

Midterm Exam: 50%

• Final Exam: 50%

• Homework: 5-7 assignments. No submission!

• Exams: are mandatory! If you cannot make it, please let me know at least a week prior to the scheduled exam.

## **Application Areas**

- Engineering
  - Communication
  - Radar systems
  - Signal processing
  - Control systems
  - Decision and resource allocation
  - Reliability
- Economics and finance
- Meteorology
- Natural sciences: physics, statistical mechanics
- Statistics (collection and organization of data so that useful inference can be drawn from them)



### Mathematical Models

- **Deterministic Models**: set of mathematical equations specifies the exact outcome
- **Probability Models**: outcome varies in unpredictable fashion (random) when repeated under the same conditions
  - Define the random experiment
  - Specify the set of all possible outcomes
  - Specify the probability assignment from which the probabilities of all events of interest can be computed

### **Probability**

- What is a probability?
  - Number between 0 and 1 inclusive that reflects the likelihood of occurring of a physical event
- Relative Frequency approach
  - Repeat experiment n times under identical conditions
  - Compute the relative frequency of the outcome k = 0, 1, 2, ...

$$f_k(n) = \frac{N_k(n)}{n}$$

- Estimate the probability of the outcome k:  $p_k = \lim_{n \to \infty} f_k(n)$
- Axiomatic approach
  - Unified mathematical theory of probability that is not tied to any particular application
  - Allows the interpretation of the probability as relative frequency
  - Set of axioms for the probability assignment to satisfy



# Review of Set Theory

- **Set**: Collection of distinct objects.
- **Universal set**: Set containing all elements in all sets under consideration in a particular problem, denoted by *S*.
- **Null set**: Set that has no elements (empty), denoted by  $\phi$ .
- Examples:
  - Define a set by listing all of its elements:  $A = \{1, 4, 9, 16, 25\}$
  - Define a set by showing a rule to generate all elements of the set:  $B = \{x^2 | x = 1, 2, 3, 4, 5\}$
  - Some sets can have infinite dimensions:
    - C={all positive integers}
    - D={all even positive integers}
    - $E = \{x^2 | x = 1, 2, 3, ...\}$

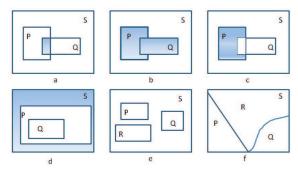


# Set Operations and Properties

- Set Theoretic Operations:
  - Union:  $\xi \in A \cup B$  iff  $\xi \in A$  or  $\xi \in B$ .
  - Intersection:  $\xi \in A \cap B$  iff  $\xi \in A$  and  $\xi \in B$ .
  - Complement:  $\xi \in A^c \Leftrightarrow (iff) \xi \notin A$ .
  - Difference:  $\xi \in A B \Leftrightarrow \xi \in A$  and  $\xi \notin B$   $(A B = A \cap B^c)$ .
  - Set equality: Any two sets A and B are equal to each other, A = B, if and only if (iff)  $B \subset A$  and  $A \subset B$ .
- Mutually Exclusive: Two or more sets,  $A_1$ ,  $A_2$ ,  $A_3$ , ... are mutually exclusive (disjoint) if they have no common elements:  $A_i \cap A_i = \phi$ , for all  $i \neq j$
- Collectively Exhaustive: A collection of sets  $A_1, \ldots, A_n$  is collectively exhaustive iff:  $\bigcup A_i = A_1 \cup A_2 \cup \cdots \cup A_n = S$
- Partition: A collection of mutually exclusive and collectively exhaustive sets form a partition of the sample space, S.

### Venn Diagram

• Illustrates the relationship among sets



- (a)  $P \cap Q$ . (b)  $P \cup Q$ . (c)  $P \cap Q^c$ . (d)  $Q \subset P$ . Complement of P.
  - (e) Sets P, Q, and R are disjoint. (f) Sets P, Q, and R form a partition of the sample space S.

# Elementary Set Relations

(1) Commutativity:

$$A \cup B = B \cup A$$
$$A \cap B = B \cap A$$

(2) Associativity:

$$A \cup (B \cup C) = (A \cup B) \cup C = (A \cup C) \cup B$$
$$A \cap (B \cap C) = (A \cap B) \cap C = (A \cap C) \cap B$$

(3) Distributivity:

$$A \cup (B \cap C) = (A \cup B) \cap (A \cup C)$$
$$A \cap (B \cup C) = (A \cap B) \cup (A \cap C)$$

$$(4) (A^c)^c = A,$$

(5) 
$$A \cap A^c = \phi$$

# Elementary Set Relations

- (6) De Morgan's Laws  $(A \cup B)^c = A^c \cap B^c$   $(A \cap B)^c = A^c \cup B^c$
- (7)  $A \cap S = A$
- (8) Using Commutativity and Associativity we can define
  - (i)  $\bigcap_{i=1}^{N} A_i = A_1 \cap A_2 \cap A_3 \dots \cap A_N$
  - (ii)  $\bigcup_{i=1}^{N} A_i = A_1 \bigcup A_2 \bigcup A_3 \ldots \bigcup A_N$
- (9) Countably Infinite Set Operations
  - (i)  $\xi \in \bigcap_{i=1}^{\infty} A_i \triangleq \{\xi \in S | \xi \in A_i \text{ for all } i\}$
  - (ii)  $\xi \in \bigcup_{i=1}^{\infty} A_i \triangleq \{\xi \in S | \xi \in A_i \text{ for at least one } i\}$



### Fields and $\sigma$ -Fields of Sets

- ullet A set of subsets  $\mathcal F$  of a universal set S is a **field** if
  - (1)  $S \in \mathcal{F}$
  - (2) if  $A \in \mathcal{F} \to A^c \in \mathcal{F}$  ( $\mathcal{F}$  is closed under complement)
  - (3) if  $A, B \in \mathcal{F} \to A \cup B \in \mathcal{F}$  ( $\mathcal{F}$  is closed under *finite* unions)
    - Example: If  $S = \{0, 1\}$ , then  $\mathcal{F} = \{S, \{1\}, \{0\}, \phi\}$  is a field. **Proposition 1**: If  $A, B \in \mathcal{F}$  then  $A \cap B \in \mathcal{F}$ . **Proposition 2**: If  $A_i \in \mathcal{F}$  for i = 1, ..., N, then  $\bigcup_{i=1}^{N} A_i \in \mathcal{F}$ .
- A set of subsets of S is a  $\sigma$ -field  $\mathcal{F}$  if
  - (1)  $S \in \mathcal{F}$
  - (2) if  $A \in \mathcal{F} \to A^c \in \mathcal{F}$  ( $\mathcal{F}$  is closed under complement)
  - (3) if  $A_i \in \mathcal{F}$  for  $\forall i \to \bigcup_{i=1}^{\infty} A_i \in \mathcal{F}$  ( $\mathcal{F}$  is closed under *countable* unions)

**Proposition**: If  $A_i \in \mathcal{F}$  for i = 1, ..., N, then  $\bigcap_{i=1}^{\infty} A_i \in \mathcal{F}$ . (Hint: countable generalization of De Morgan's Law)

# Probability Model

- **Experiment**: Some process that results in an outcome that is not fully predictable.
  - Examples: (a) Flipping a coin. (b) Measuring the temperature in the park a week from now. (c) Signal received at the output of a noisy communication channel.
- Outcome: Any possible observation of the experiment.
- **Sample Space** (*S*): Set of all the finest grain, mutually exclusive, collectively exhaustive outcomes of the experiment.
- Event: An event is a set of outcomes of an experiment.
- **Event Space**: An event space is a collectively exhaustive, mutually exclusive set of events.
- **Probability Measure**: Assigns a number P(A) to every event A satisfying a set of axioms.

# Axioms of Probability

- Let  $\mathcal{F}$  be a  $\sigma$ -field of a sample space S (specified for a random experiment). A function  $P: \mathcal{F} \to [0,1]$  is a **probability measure** if
  - **1 Axiom I**: P(S) = 1
  - **2 Axiom II**:  $P(E) \ge 0$  for every event  $E \in \mathcal{F}$
  - **3** Axiom III: If  $E_i \in \mathcal{F}$  for i = 1, 2, 3, ... are disjoint (mutually exclusive) then  $P\left(\bigcup_{i=1}^{\infty} E_i\right) = \sum_{i=1}^{\infty} P(E_i)$ .

• The triple  $(S, \mathcal{F}, P)$  defines a **probability space** 

## Observations on Probability Measure

- Sample space could be continuous (S uncountable), or discrete (S finite or countable)
- When S is uncountable, for example if  $S=\mathbb{R}$  or  $S=\mathbb{R}^2$ ,  $\sigma$ -field (i.e. set of events of interest) is defined by countable unions, intersections, and complements of intervals in  $\mathbb{R}$  or rectangles in  $\mathbb{R}^2$
- For discrete models the probability measure is specified by the probabilities of every single event
- For continuous models the probabilities are determined by sub-intervals or lengths (1D), or areas (2D), or volumes (3D)



Probability Model Axioms and Properties of Probability Conditional Probability Multiplication Rule (Sequential Tree) Bayes' Rule Independence

### Examples

• Example 1

```
Experiment Select a ball from an urn containing balls numbered 1 to 50 Sample space S = \frac{1}{2}
```

Probability Assume outcomes are equally likely

Event "An even ball is selected"

Determine P(A) =

• Example 2

Experiment Toss a coin three times and note the sequence of H and T Sample space S=

Probability Assume fair coin: H and T are equally likely

Event "The three tosees give the same outcome"

Determine P(A) =

#### • Example 1

```
Experiment Select a ball from an urn containing balls numbered 1 to 50 Sample space S = \{1, 2, \ldots, 50\}
Probability Assume outcomes are equally likely
Event "An even ball is selected": A = \{2, 4, \ldots, 48, 50\}
Determine P(A) = 0.5
```

#### Example 2

```
Experiment Toss a coin three times and note the sequence of H and T Sample space S = \{HTT, THT, TTH, HHT, HTH, THH, HHH, TTT\}
Probability Assume fair coin: H and T are equally likely
Event "The three tosees give the same outcome": A = \{HHH, TTT\}
Determine P(A) = \frac{2}{8} = 0.25
```

#### Example 3

Experiment Alice takes the bus to work each morning and her travel time T varies from 20 to 40 mins.

Sample space S =

Probability Assume all travel times in the interval are equally likely:

$$P(S) = P(20 \le T \le 40) = 1$$

- Determine (a) Alice's travel time is more than 30 mins.
  - (b) Alice's travel time is exactly 22.01 mins.

#### • Example 3

Experiment Alice takes the bus to work each morning and her travel time T varies from 20 to 40 mins.

Sample space  $S = \{T | 20 \le T \le 40 \text{ mins}\}$ 

Probability Assume all travel times in the interval are equally likely:

$$P(S) = P(20 \le T \le 40) = 1$$

Determine

(a) Alice's travel time is more than 30 mins. P(T > 30) = 1/2

(b) Alice's travel time is exactly 22.01 mins.

$$P(T = 22.01) = 0$$

# Properties of Probability

- For every probabilistic model and events A, B and C:
  - Corollary 1:  $P(A^c) = 1 P(A)$ .
  - Corollary 2:  $P(A) \le 1$ .
  - **Corollary 3**:  $P(\phi) = 0$
  - Corollary 4:

$$P(A \cup B \cup C) = P(A) + P(A^c \cap B) + P(A^c \cap B^c \cap C)$$

- Corollary 5:  $P(A \cup B) = P(A) + P(B) P(A \cap B)$
- Corollary 6:  $P(A \cup B) \le P(A) + P(B)$
- Corollary 7: If  $A \subset B$ ,  $P(A) \leq P(B)$



# Conditional Probability

• Given a probability space  $(S, \mathcal{F}, P)$  and two events  $A, B \in \mathcal{F}$ , where P(B) > 0, the conditional probability is defined as

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

- If we define  $\mathcal{F}_B \triangleq \{Q \in \mathcal{F} | Q \subseteq B\}$ , then  $(B, \mathcal{F}_B, P(\cdot | B))$  is the new probability space
- Allows us to reason about the likelihood of an event based on partial knowledge (a priori information)
- It forms the basis for inference theory: observe the effect and reason about the cause



# Conditional Probability

- All probabilities are concentrated on B because P(B|B) = 1
- If A and B are mutually exclusive, then

$$P(A|B) = \frac{P(A \cap B)}{P(B)} = \frac{P(\phi)}{P(B)} = 0$$

- If  $B \subset A$ , then  $P(A|B) = \frac{P(B)}{P(B)} = 1$
- If  $A \subset B$ , then  $P(A|B) = \frac{P(A)}{P(B)} \le 1$
- Nonnegativity:  $P(A|B) = \frac{P(A \cap B)}{P(B)} \ge 0$
- Additivity: For any two disjoint (mutually exclusive) events  $A_1$  and  $A_2$  we have that:  $P(A_1 \cup A_2|B) = P(A_1|B) + P(A_2|B)$ .



Experiment Test two integrated circuits from the same silicon wafer and observe whether a circuit is accepted (a) or rejected (r).

Sample space 
$$S = \{aa, ar, ra, rr\}$$

Probabilities 
$$P(rr) = 0.01$$
,  $P(ra) = 0.01$ ,  $P(ar) = 0.01$ ,  $P(aa) = 0.97$ .

Event A The second circuit is rejected 
$$A = \{rr, ar\}$$

Event B The first circuit is rejected, 
$$B = \{rr, ra\}$$

Determine P(A), P(B), and probability of second circuit to be rejected observing that the first one is rejected, P(A|B)

Solution 
$$P(A) = P(rr) + P(ar) = 0.02$$
  
 $P(B) = P(rr) + P(ra) = 0.02$   
 $P(A \cap B) = P(\text{both rejected}) = 0.01$   
 $P(A|B) = \frac{P(A \cap B)}{P(B)} = 0.01/0.02 = 0.5$ 

• The probability of rejecting the second circuit increases from 0.02 to 0.5 once we know that first circuit is rejected.

### Multiplication Rule

- Provides a means to compute the occurrence of multiple events in an experiment as a result of multiple subexperiments
- The output of each subexperiment may depend on the results of previous experiments
- If  $A_1, \ldots, A_n$  are events,

$$P(\bigcap_{i=1}^{n} A_i) = P(A_1 \cap A_2 \cap \cdots \cap A_n)$$

$$= P(A_1)P(A_2|A_1)P(A_3|A_1 \cap A_2) \cdots P(A_n|\bigcap_{i=1}^{n-1} A_i).$$

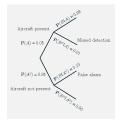
## Sequential Tree

- Sequential calculation of probabilities
- Construct a sequential description of the sample space.
- Record the corresponding conditional probabilities along branches of the tree.
- Obtain the probability of any one outcome using the multiplication rule.

If an aircraft is present, a radar correctly registers its presence with probability 0.99. If an aircraft is absent, the radar falsely registers a presence with probability 0.1. An aircraft is present with probability 0.05.

- (a) What is the probability of a false alarm (false detection of an aircraft's presence)?
- (b) What is the probability of a missed detection (an aircraft is present but does not register)?
- (c) What is the probability that an aircraft is present given a registration on the radar screen?





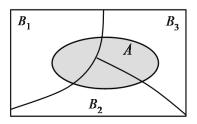
Let's define the following events:

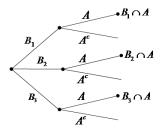
A: aircraft present, B: a registration on the radar screen  $P(\text{false alarm}) = P(A^c \cap B) = P(A^c)P(B|A^c) = (0.95)(0.1) = 0.095$   $P(\text{missed detection}) = P(A \cap B^c) = P(A)P(B^c|A) = 0.095$ 

$$P(\text{missed detection}) = P(A \cap B^c) = P(A)P(B^c|A) = (0.05)(0.01) = 0.0005$$

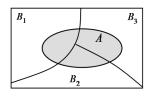
### Law of Total Probability

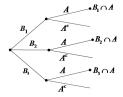
• The events  $B_1, \ldots, B_n$  form a partition of the sample space such that  $B = \{B_1, B_2, \ldots, B_n\}$  is an event space with  $B_i$ 's mutually exclusive  $(B_i \cap B_j = \phi \text{ for } i \neq j)$  and collectively exhaustive (B = S)





### Law of Total Probability





• The conditional probabilities for an event A, i.e.  $P(A|B_1)$ , ...,  $P(A|B_n)$ , are known, and the unconditional probability for event A using a divide and conquer approach can be calculated using:

$$P(A) = P(A \cap B_1) + \cdots + P(A \cap B_n)$$
  
=  $P(A|B_1)P(B_1) + \cdots + P(A|B_n)P(B_n).$ 

### Bayes' Rule

• Useful for problems where the prior probabilities  $P(B_i)$  and  $P(A|B_i)$  are given,  $B = \{B_1, \ldots, B_n\}$  is an event space, and we would like to compute  $P(B_i|A)$  when A is observed.

$$P(B_i|A) = \frac{P(B_i \cap A)}{P(A)} = \frac{P(A|B_i)P(B_i)}{P(A)}$$

From the total probability theorem (since B is an event space),

$$P(A) = \sum_{i=1}^{n} P(A|B_i)P(B_i)$$

Objective is inference rather than prediction



### **Example: Communication Channels**

A data communication system has 3 types of channels with varying quality of transmission.

The probability of receiving a bit in error is 0.01, 0.005 and 0.001 for channel types I, II and III respectively.

The three channel types are used to transfer bits in the ratio 20%, 30%, and 50% respectively.

Find the probability that a bit is received in error.

Let E denote the event that a bit is received in error. We are given, P(E|Type I) = 0.01 P(E|Type II) = 0.005 P(E|Type II) = 0.001, and also, P(Type I) = 0.2 P(Type II) = 0.3 P(Type III) = 0.5 Applying the total probability theorem, the unconditional probability for receiving an arbitrary bit in error is.

```
P(E) = P(E \cap \text{Type I}) + P(E \cap \text{Type II}) + P(E \cap \text{Type III})
= P(E|\text{Type I})P(\text{Type I}) + P(E|\text{Type II})P(\text{Type III}) + P(E|\text{Type III})P(\text{Type III})
= (0.01)(0.2) + (0.005)(0.3) + (0.001)(0.5)
= 0.004
```

### Independence of two events

• Two events A and B are independent if and only if

$$P(AB) = P(A)P(B)$$

• When events A and B have non-zero probabilities, the definition of independence is equivalent to:

$$P(A|B) = P(A)$$
  $P(B|A) = P(B)$ 

- When two events are independent, knowledge of any one of the events occurring does not alter our information (probability) of the other event.
- If events A and B are independent, their complements are also independent:  $P(A^cB^c) = P(A^c)P(B^c)$ .
- If events A and B are disjoint, they are neccessarily dependent. This is because:  $P(AB) = P(\phi) = 0 \neq P(A)P(B)$ .

# Independence of a collection of events

• The events  $A_1, \ldots, A_n$  are mutually independent if

$$P(\bigcap_{i\in I}A_i)=\prod_{i\in I}P(A_i)$$

for every subset I of  $\{1, 2, \dots, n\}$ 

Probability Model Axioms and Properties of Probability Conditional Probability Multiplication Rule (Sequential Tree) Bayes' Rule Independence

# Example

- Consider an experiment consisting of two independent fair coin tosses. We define the following events.
- A: First toss is a head
- B: Second toss is a head
- C: First and second tosses have different outcomes.
- Are events A, B and C mutually independent?