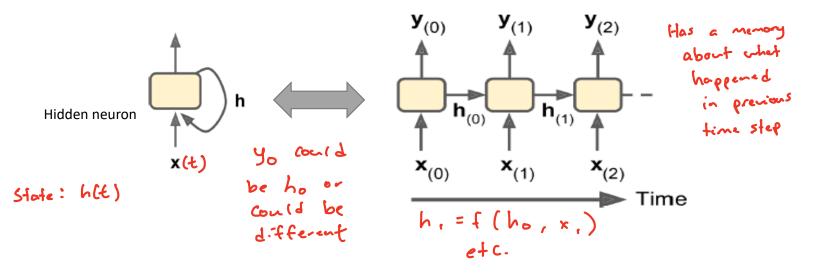


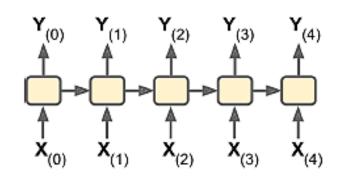
Recurrent Neural Networks

- RNN processes sequential data
- Has recurrent connection
 - Type of neural network that has an internal loop
 - Has memory of previous state to update next state
- State of hidden neuron at time step t, denoted h(t), is function of input at time step t and state at the previous time t-1: h(t) = f(h(t-1), x(t)) --- f is activation function e.g. tanh



Different Design Patterns (Architectures 1) Sequence to sequence network

- RNN can have sequence of input and produce sequence of output
 - Sequence to sequence network
- Applications:
 - Word-by-word translation
 - feed the RNN with prices over last N days, and it outputs the prices shifted by one day into the future (i.e., from N – 1 days ago to tomorrow)

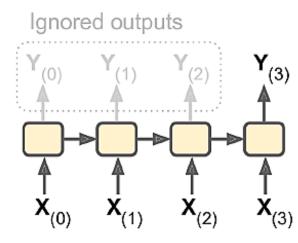


Different Design Patterns (Architectures 2)

Sequence to vector network

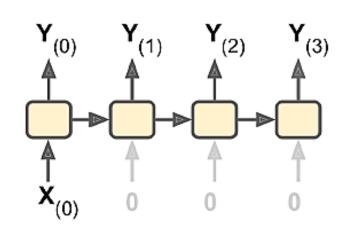
- RNN can have sequence at input & produce a single output (represemted as a vector)
 - Sequence to vector network

- Applications:
 - Review classification
 - Input is a sequence of words corresponding to a movie review
 - Output is a prediction of whether the review positive or negative
 - Identify topic of sentence
 - Predict next word



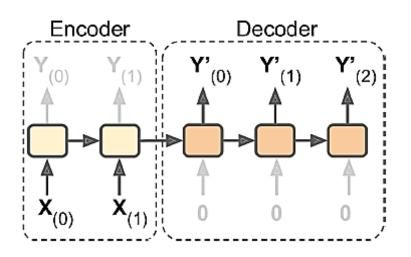
Different Design Patterns (Architectures 3) Vector to sequence network

- RNN can have a single input vector and produce an output sequence
 - Vector to sequence network
- For example, image captioning
 - Input image
 - Output a caption for that image
 - Caption is a sequence of words



Different Design Patterns (Architectures 4) Sequence to sequence of different length

- RNN can take input sequence, and produce output sequence of different length
- Example: translation a sentence from one language to another
 - Get whole sentence before translation
 - Works better than translating word by word using traditional sequence to sequence
- Composed on encoder then decoder:
 - Encoder: Input sequence to vector
 - Decoder: vector to sequence



Different Design Patterns (Architecture 5) Bidirectional RNN

- One hidden units propagates information forward in time
- Other hidden unit propagate information backward in time

 Has summary information of past and future

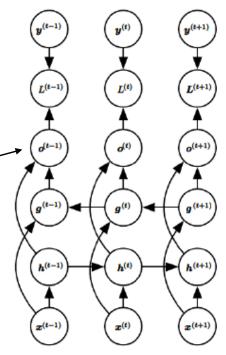
• Example: Natural language processing

 Speech recognition: understand after hearing future words

"she stop by yesterday"

if it only cares about what happened before would be corrected to stops

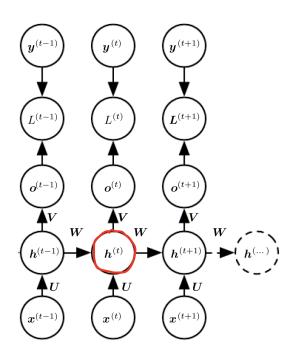
But - if feture information is propagated back, it could be corrected to stopped



Unfolding Basic RNN

$$egin{array}{lll} oldsymbol{a}^{(t)} &=& oldsymbol{b} + oldsymbol{W} oldsymbol{h}^{(t-1)} + oldsymbol{U} oldsymbol{x}^{(t)}, \ oldsymbol{h}^{(t)} &=& ext{tanh}(oldsymbol{a}^{(t)}), \ oldsymbol{o}^{(t)} &=& oldsymbol{c} + oldsymbol{V} oldsymbol{h}^{(t)}, \ oldsymbol{g}^{(t)} &=& ext{softmax}(oldsymbol{o}^{(t)}), \end{array}$$

 Parameters are shared across timesteps

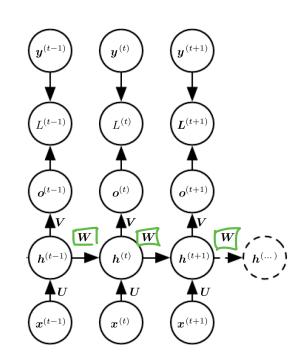


Unfolding Basic RNN

$$egin{array}{lll} m{a}^{(t)} & = & m{b} + m{W} m{h}^{(t-1)} + m{U} m{x}^{(t)}, \ m{h}^{(t)} & = & anh(m{a}^{(t)}), \ m{o}^{(t)} & = & m{c} + m{V} m{h}^{(t)}, \ m{\hat{y}}^{(t)} & = & ext{softmax}(m{o}^{(t)}), \end{array}$$

- Parameters are shared across timesteps applying some weights to
 - For simplicity consider no nonlinear activation and focus on the node states





Gradient will vanish or explode due to applying sample weight several times

$$\boldsymbol{h}^{(t)} = \boldsymbol{W}^{\top} \boldsymbol{h}^{(t-1)} \implies \boldsymbol{h}^{(t)} = \left(\boldsymbol{W}^{t}\right)^{\top} \boldsymbol{h}^{(0)}$$

$$\bullet \frac{\partial h^{(t)}}{\partial h^{(0)}} = \frac{\partial h^{(t)}}{\partial h^{(t-1)}} \frac{\partial h^{(t-1)}}{\partial h^{(t-2)}} \dots \frac{\partial h^{(1)}}{\partial h^{(0)}} = W^T W^T \dots W^T
\Rightarrow \text{vanish or explode}$$

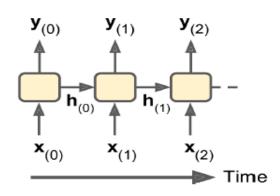
Slopes get very small (vanish) or very big (explode) if we consider a long sequence!!

Hard to Capture Long Term

- DependenciesGradient propagated over many steps will vanish or explode
 - This makes it harder to capture the longterm dependencies
- Computation has multiplication with weight multiple times
 - could vanish (small values) or gets very large (explodè).

$$\boldsymbol{h}^{(t)} = \boldsymbol{W}^{\top} \boldsymbol{h}^{(t-1)} \quad \Longrightarrow \quad \boldsymbol{h}^{(t)} = (\boldsymbol{W}^{t})^{\top} \boldsymbol{h}^{(0)}$$

- Implication: Not learning from long sequence
- Some solutions: normalize weights, clip large gradient, skip connections,...



Could we modify the processing in the neuron to solve this problems?

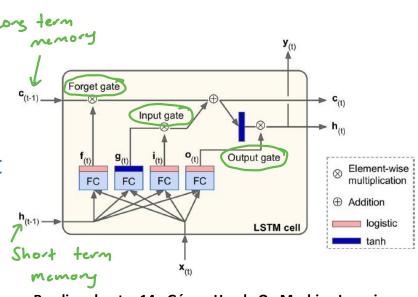
LSTM: Long Short-Term Memory Model

 Modified version of vanilla (i.e, basic) RNN

• Idea : not all information in a long sequence is important

 E.g. long review – only fews words can tell if the review is good or bad

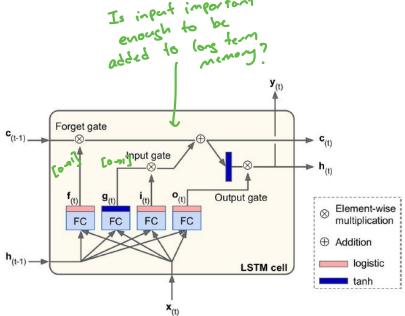
 LSTM tries to learn what information to keep in the memory and what to discard



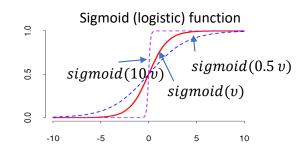
Reading chapter 14.: Géron, Hands-On Machine Learning with Scikit-Learn and TensorFlow

• Objective: learn when to include important input, when to consider • Objective: learn when to consider

- Objective: learn when to include important input, when to consider long term memory, and when to shut off the output.
- Has two states c and h
 - Short term state h
 - Long term state c
- Network learns what to store in the long-term state & what to discard
 - Forget gate control which part of the long-term state to be discarded
- Input gate controls the part of input that should be added to the longterm state
- Output of the state is controlled by the output gate



Reading chapter 14.: Géron, Hands-On Machine Learning with Scikit-Learn and TensorFlow



LSTM: Long Short-Term Memory Model

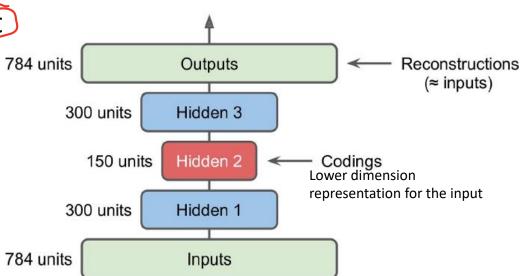
$$\begin{aligned} \mathbf{i}_{(t)} &= \sigma(\mathbf{W}_{xi}^T\mathbf{x}_{(t)} + \mathbf{W}_{hi}^T\mathbf{h}_{(t-1)} + \mathbf{b}_i) & \text{Input/update gate} \\ \mathbf{f}_{(t)} &= \sigma(\mathbf{W}_{xf}^T\mathbf{x}_{(t)} + \mathbf{W}_{hf}^T\mathbf{h}_{(t-1)} + \mathbf{b}_f) & \text{Forget gate} \\ \mathbf{o}_{(t)} &= \sigma(\mathbf{W}_{xo}^T\mathbf{x}_{(t)} + \mathbf{W}_{ho}^T\mathbf{h}_{(t-1)} + \mathbf{b}_o) & \text{Output gate} \\ \mathbf{g}_{(t)} &= \tanh(\mathbf{W}_{xg}^T\mathbf{x}_{(t)} + \mathbf{W}_{hg}^T\mathbf{h}_{(t-1)} + \mathbf{b}_g) & \text{State of cell} \\ \mathbf{c}_{(t)} &= \mathbf{f}_{(t)} \otimes \mathbf{c}_{(t-1)} + \mathbf{i}_{(t)} \otimes \mathbf{g}_{(t)} & \text{Long term state: how much to remember previous state, how much to include} \\ \mathbf{y}_{(t)} &= \mathbf{h}_{(t)} = \mathbf{o}_{(t)} \otimes \tanh(\mathbf{c}_{(t)}) & \text{How much to output from this state} \end{aligned}$$

- Keras implementation
 - https://www.tensorflow.org/guide/keras/rnn

```
# Add a LSTM layer with 128 internal units.
model.add(layers.LSTM(128))
```

Another Deep Learning Model - Autoencoders

- Final output = input
 - Unsupervised
- Applications:
 - denoising
 - dimensionality reduction



Stacked Autoencoder: has multiple hidden layers

Typically symmetrical with regards to the central hidden layer (the coding layer).

Ref: chapter 15, "Hands-On Machine Learning with Scikit-Learn and TensorFlow", by Géron

Resources

- Deep learning book
 - https://www.deeplearningbook.org/lecture_slides.html