

ECE 1390/2390

# Image Processing and Computer Vision – Fall 2021

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*Generative Classification*

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*Classification: Generative models*




*Supervised* classification  $f(\mathbf{x}) \rightarrow \text{label}$

Given a collection of labeled examples, come up with a function that will predict the labels of new examples.

Training examples

"four"				
"nine"				

Novel input

 ?

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Supervised classification

How good is the function we come up with to do the classification? (What does "good" mean?)

Depends on: *Need to measure quality of function*

- What mistakes does it make
- Cost associated with the mistakes

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## Supervised classification

Since we know the desired labels of training data, we want to *minimize the expected misclassification*

Supervised classification

### Two general strategies

- Use the training data to build representative probability model; separately model class-conditional densities and priors (*Generative*) Bayesian Classifier
- Directly construct a good decision boundary, model the posterior (*Discriminative*) SVM, neural nets, logistic regression, etc.

## Supervised classification: Generative

Given labeled training examples, predict labels for new examples

- Notation:  $(4 \rightarrow 9)$  - object is a '4' but you call it a '9' (Mistake)
- We'll assume the cost of  $X \rightarrow X$  is zero. Correct: no penalty  
 $4 \rightarrow 4$  : No mistake

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## Supervised classification: Generative

Consider the two-class (binary) decision problem:

- $L(4 \rightarrow 9)$ : Loss of classifying a 4 as a 9
- $L(9 \rightarrow 4)$ : Loss of classifying a 9 as a 4

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Supervised classification: Generative

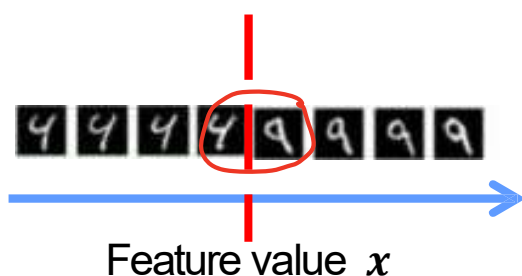
**Risk** of a classifier strategy **S** is expected loss:

$$R(S) = \Pr(4 \rightarrow 9 \mid \text{using } S)L(4 \rightarrow 9) \\ + \Pr(9 \rightarrow 4 \mid \text{using } S)L(9 \rightarrow 4)$$

We want to choose a classifier so as to minimize this total risk

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Supervised classification: minimal risk



At best decision boundary,  
either choice of label yields  
same expected loss. 50/50

If we choose class “four” at boundary, expected loss is:

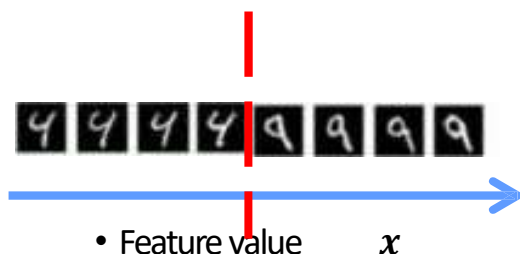
$$= P(\text{class is } 9 \mid \mathbf{x}) L(9 \rightarrow 4) + P(\text{class is } 4 \mid \mathbf{x}) L(4 \rightarrow 4) \\ = P(\text{class is } 9 \mid \mathbf{x}) L(9 \rightarrow 4)$$

If we choose class “nine” at boundary, expected loss is:

$$= P(\text{class is } 4 \mid \mathbf{x}) L(4 \rightarrow 9)$$

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## Supervised classification: minimal risk

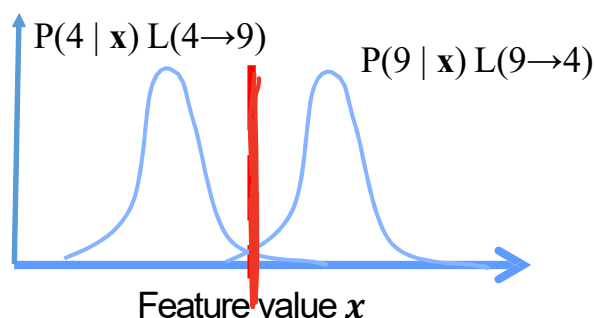


- At best decision boundary, either choice of label yields same expected loss.

- So, best decision boundary is at point  $x$  where:
  - $P(\text{class is } 9 | \mathbf{x}) L(9 \rightarrow 4) = P(\text{class is } 4 | \mathbf{x}) L(4 \rightarrow 9)$
- To classify a new point, choose class with lowest expected loss; i.e., choose “four” if:  $P(4 | \mathbf{x}) L(4 \rightarrow 9) > P(9 | \mathbf{x}) L(9 \rightarrow 4)$

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## Supervised classification: minimal risk *x is feature*



- At best decision boundary, either choice of label yields same expected loss.

So, best decision boundary is at point  $x$  where:

$$P(\text{class is } 9 | \mathbf{x}) L(9 \rightarrow 4) = P(\text{class is } 4 | \mathbf{x}) L(4 \rightarrow 9)$$

*How to evaluate these probabilities?*

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*How risky the decision is*

## Example: learning skincolors

$$P(\text{face}|\text{hue}) \stackrel{\text{face}}{>} \stackrel{\text{not face}}{<} P(\text{not face}|\text{hue})$$

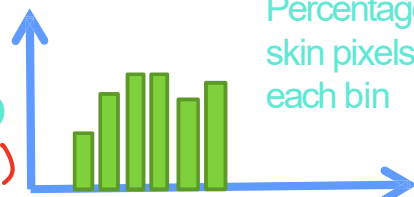


$$P(x|\text{skin})$$

$$P(\text{hue}|\text{face})$$

Distribution of colors  
that belong  
to faces

Percentage of  
skin pixels in  
each bin

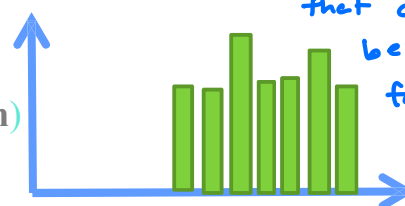


$$P(x|\text{not skin})$$

$$P(\text{hue}|\text{not face})$$

Feature  $x = \text{Hue}$

Same for colors  
that don't  
belong to  
faces



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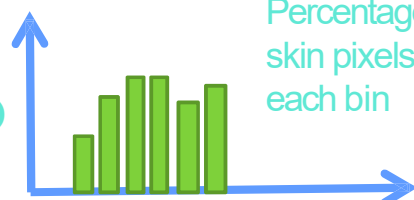
## Example: learning skincolors



Now we get a new image,  
and want to label each pixel  
as skin or non-skin.

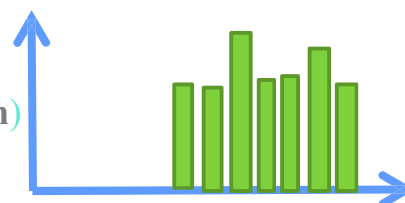
$$P(x|\text{skin})$$

Percentage of  
skin pixels in  
each bin



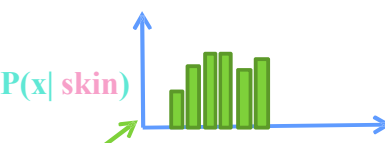
Feature  $x = \text{Hue}$

$$P(x|\text{not skin})$$



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## Bayes rule



$$\begin{array}{c}
 \text{posterior} \\
 \hline
 P(\text{skin} \mid x) = \frac{
 \begin{array}{c}
 \text{likelihood} \quad \text{prior} \\
 \hline
 \begin{array}{c}
 \text{hue} \quad \text{face} \\
 P(x \mid \text{skin}) P(\text{skin})
 \end{array}
 \end{array}
 }{
 \begin{array}{c}
 P(x) \quad \text{hue}
 \end{array}
 }
 \end{array}$$

$$P(\text{skin} \mid x) \propto P(x \mid \text{skin}) P(\text{skin})$$

*Where does the prior come from?*

## Bayes rule in(ab)use

Likelihood ratio test (assuming cost of errors is the same):

If  $P(\text{skin} \mid x) > P(\sim \text{skin} \mid x)$  classify  $x$  as skin

...SO ... *Get from distributions (two slides previous)*

If  $P(x \mid \text{skin}) P(\text{skin}) > P(x \mid \sim \text{skin}) P(\sim \text{skin})$   
 classify  $x$  as skin (**Bayes rule**)

*(if the costs are different just re-weight)*



Bayesrule in(ab)use

Count number of  
pixels that are  
a face

...but I don't really know prior  $P(\text{skin})$ ...

...but I can assume it some constant  $\Omega$ ...

...so with some training data I can **estimate**  $\Omega$  ...

...and with the same training data I can **measure likelihood densities** of **both**  $P(x|\text{skin})$  and  $P(x|\sim\text{skin})$ ...

So...I can more or less come up with a rule...

Steve Seitz

Example: classifying skinpixels

Now for every pixel in a new image, we can estimate probability that it is generated by skin:

If  $p(\text{skin} | x) > \theta$  classify as skin; otherwise not



Brighter pixels are  
higher probability  
of being skin

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## Example: classifying skin pixels



**Figure 6:** A video image and its flesh probability image



**Figure 7:** Orientation of the flesh probability distribution marked on the source video image

Gary Bradski, 1998

## More general generative models

For a given <sup>(feature)</sup> measurement  $\mathbf{x}$  and set of classes  $c_i$  choose  $c^*$  by:

$$c^* = \arg \max_c p(c | \mathbf{x}) = \arg \max_c p(c) p(\mathbf{x} | c)$$

More than 2 classes

$$P(\text{chair} | \text{feature}) = 0.7$$

$$P(\text{person} | \text{feature}) = 0.02$$

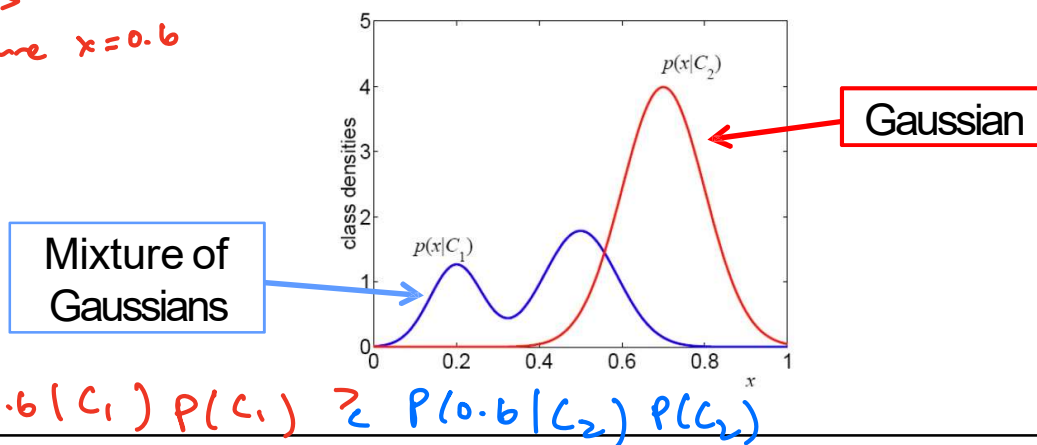
$$P(\text{whiteboard} | \text{feature}) = 0.28$$

## Continuous generativemodels

- If  $\mathbf{x}$  is continuous, need *likelihood* density model of  $p(\mathbf{x}|c)$
- Typically parametric – Gaussian or mixture of Gaussians

Image

Measure  $x=0.6$



## Continuous generativemodels

- Why not just some histogram or some KNN (Parzen window) method?
  - You might...
  - But you would need lots and lots of data everywhere you might get a point
  - The whole point of modeling with a parameterized model is not to need lots of data.

Don't need tons of data

Summary of generative models:

- + Firm probabilistic grounding
- + Allows inclusion of prior knowledge
- + *Parametric modeling of likelihood permits using small number of examples*
- + *New classes do not perturb previous models*
- + Others:
  - Can take advantage of unlabelled data
  - Can be used to generate samples

Summary of generative models:  $P(c_1), P(c_2), \text{etc.}$   
 $L(c_1 \rightarrow c_2) ??$

- And just where did you get those priors?
- Why are you modeling those obviously non-C points?
- The example hard cases aren't special
- If you have lots of data, doesn't help

Next...

- A really cool way of building a generative model for face recognition (not detection)