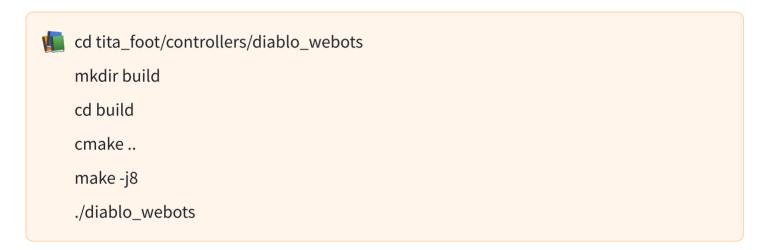
## narrow\_tita\_foot



- 1. 解压
- 2. cd tita\_foot
- 3. 打开两个终端
- 4. 一个终端打开webots,所需世界文件worlds/new\_world.wbt
- 5. 切到dev\_pure\_mpc或者dev\_wbc\_mpc分支
- 6. 另一个终端



- 7. 看到机器人开始摇头晃脑的踏步
- 8. 本代码所参考开源: https://github.com/DRCL-USC/Hector\_Simulation
- 9. Call me if you have any problem