

Midterm 2
MAC2302, ODE

Instructor: Tamasan
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Student Name:

50 minutes. Write each solution on a separate sheet, order them, and place this on top for stapling. Closed book. NO calculator. Work without justification gets no credit. All problems are equally weighted.

1. Consider the non-homogeneous fourth order linear differential equation

$$y^{(4)} + 8y'' + 16y = 9\sin(t) + 4.$$

- Find a fundamental set of solutions of the corresponding homogeneous equation. You may use $(a^2 + b^2)^2 = a^4 + 2a^2b^2 + b^4$.
- Find a particular solution y_p as the sum $u + v$, where u solves $u^{(4)} + 8u'' + 16u = 4$ and v solves $v^{(4)} + 8v'' + 16v = 9\sin(t)$.
- Write down the general solution of the non-homogeneous equation (four arbitrary constants should show).
- How many solutions satisfy $y(0) = y'(0) = 0$? Justify.
- How many solutions satisfy $y(0) = y'(0) = 0$ and are also bounded? Justify.

2. Find the general solution of the equation

$$(1-x)y''(x) + xy'(x) - y(x) = 4(1-x)^2e^{-x}, \quad x < 1,$$

by answering the following:

- Check that e^x and x solve the corresponding homogeneous equation.
- Seek a particular solution for the non-homogeneous equation in the form $y_p(x) = c_1(x)e^x + c_2(x)x$, for some unknown functions c_1, c_2 with $c_1'(x)e^x + c_2'(x)x = 0$:
 - Plug y_p into the equation, to find a second equation for c_1', c_2' ;
 - Solve the linear system for c_1' and c_2' ;
 - Integrate to find c_1 and c_2 , and then y_p .
- Write the general solution of the non-homogeneous equation.
- Can you use the method of the unknown coefficients in this problem? Justify.

3. A large spring is stretched 2ft by a hanging object weighing w pounds (this is a force!). The object is attached to a dashpot mechanism with damping constant $\frac{1}{8}lb \cdot sec/ft$ and is acted on by an external force of $\cos(4t)$ lb. Let $x(t)$ be the displacement at time t of the center of mass measured from the dynamic equilibrium and use the gravitation $g = 32ft/sec^2$.

- Draw two side by side pictures showing the ~~string~~ ^{spring} with the weight: at the dynamic equilibrium (on the left), respectively at some displacement x from the dynamic equilibrium (on the right). Show the acting forces.
- What is the mass (measured in $lb \cdot sec^2/ft$) of the object in terms of its weight w ?
- What is the elastic constant k (measured in lb/ft) in terms of w ?
- Write down the differential equation for $x(t)$ governing the motion of the system. Your answer should depend on w .
- Determine the steady state response (which does not die out exponentially in time) of the system.
- Show that the amplitude of the steady state response is independent of w .

$$1. \quad y^{(4)} + 8y'' + 16y = 9 \sin(2t) + 4$$

a) char. eqn: $r^4 + 8r^2 + 16 = 0 \Rightarrow (r^2 + 4)^2 = 0 \Rightarrow r^2 + 4 = 0 \Rightarrow r = \pm 2i$ (mult. 2)
 $\Rightarrow \{ \cos(2t), \sin(2t), t \cos(2t), t \sin(2t) \}$ is a fund. set

b) $u = A \Rightarrow 16A = 4$
 $u' = 0 \Rightarrow A = \frac{1}{4}$
 $u'' = 0$
 $u''' = 0$
 $u^{(4)} = 0$

$$\begin{aligned} v &= A \cos t + B \sin t \\ v' &= -A \sin t + B \cos t \\ v'' &= -A \cos t - B \sin t \\ v''' &= A \sin t - B \cos t \\ v^{(4)} &= A \cos t + B \sin t \end{aligned}$$

Note that A is not involved. or plug in to see $A=0$.

$$\Rightarrow 16B - 8B + B = 9$$

$$\Rightarrow B = 1$$

$$\Rightarrow y_p = \frac{1}{4} + \sin t$$

c) general solution:

$$y = C_1 \cos(2t) + C_2 \sin(2t) + C_3 t \cos(2t) + C_4 t \sin(2t) + \frac{1}{4} + \sin t$$

d) There are infinitely many solutions with $y(0) = y'(0) = 0$. To see why, plug in initial conditions to get $C_1 = -\frac{1}{4}$, $2C_2 + C_3 + 1 = 0$, so there are two degrees of freedom.

e) There is exactly one bounded solution with $y(0) = y'(0) = 0$. Since $C_3 t \cos(2t) + C_4 t \sin(2t)$ is unbounded if $C_3 \neq 0$ or $C_4 \neq 0$, the boundedness condition forces $C_3 = C_4 = 0$. Thus, the only solution has $C_1 = -\frac{1}{4}$, $C_2 = -\frac{1}{2}$, $C_3 = 0$, $C_4 = 0$.

If you're not fully convinced $C_3 t \cos(2t) + C_4 t \sin(2t)$ is unbounded, put it in the form $R \cos(\omega t + \delta)$. Then, the amplitude is $R = \sqrt{(C_3 t)^2 + (C_4 t)^2} = t \sqrt{C_3^2 + C_4^2}$, which grows to infinity as $t \rightarrow \infty$ unless $C_3 = C_4 = 0$.

$$2. (1-x)y'' + xy' - y = 4(1-x)^2 e^{-x}, \quad x < 1$$

$$a) y = e^x = y' = y'' \Rightarrow \begin{cases} (1-x)e^x + xe^x - e^x = 0 \Rightarrow 0=0 \quad \checkmark \\ y=x \\ y'=1 \Rightarrow x \cdot 1 - x = 0 \Rightarrow 0=0 \quad \checkmark \\ y''=0 \end{cases}$$

$$b) (i) \quad \begin{array}{l|l} -1 & y_p = c_1 e^x + c_2 x \\ x & y_p' = c_1 e^x + c_2 + \overbrace{c_1' e^x + c_2' x}^{\text{set } = 0} \\ 1-x & y_p'' = c_1' e^x + c_1 e^x + c_2' \end{array}$$

$$\Rightarrow c_1' e^x + c_2' x = 0$$

$$c_1' e^x (\cancel{1-x}) + c_2' (\cancel{1-x}) = 4(1-x)^2 e^{-x} \quad \begin{array}{l} \text{cancels one} \Rightarrow \\ c_1' e^x + c_2' x = 0 \\ c_1' e^x + c_2' = 4(1-x)e^{-x} \end{array}$$

$$(ii) \text{ Using Cramer's rule: } D = \begin{vmatrix} e^x & x \\ e^x & 1 \end{vmatrix} = e^x - x e^x = (1-x)e^x$$

$$\text{Then, } c_1' = \frac{\begin{vmatrix} 0 & x \\ 4(1-x)e^{-x} & 1 \end{vmatrix}}{D} = \frac{-4x(1-x)e^{-x}}{(1-x)e^x} = \frac{-4x}{e^{2x}} = c_1'$$

$$c_2' = \frac{\begin{vmatrix} e^x & 0 \\ e^x & 4(1-x)e^{-x} \end{vmatrix}}{D} = \frac{4(1-x)}{(1-x)e^x} = \frac{4}{e^x} = c_2'$$

$$(iii) \quad c_2 = \int 4e^{-x} dx = \boxed{-4e^{-x} + A} \quad \leftarrow \text{arbitrary constant}$$

$$c_1 = -4 \int x e^{-2x} dx = -4 \left(-\frac{x}{2} e^{-2x} + \int \frac{1}{2} e^{-2x} dx \right) = \frac{x}{2} e^{-2x} - \frac{1}{4} e^{-2x}$$

By parts

$$u=x \\ du=dx$$

$$v=-\frac{1}{2}e^{-2x} \\ dv=e^{-2x}dx$$

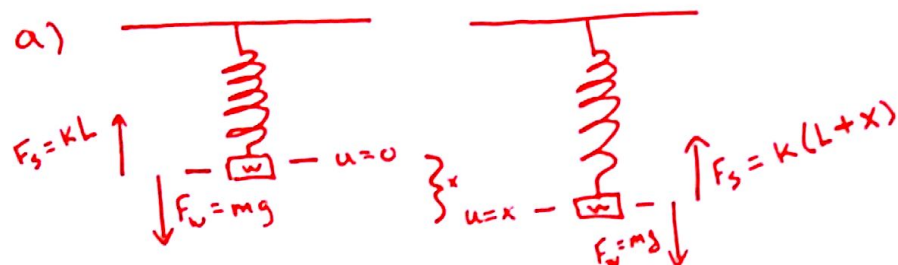
$$\Rightarrow c_1 = 2x e^{-2x} + e^{-2x} + B = \boxed{(2x+1)e^{-2x} + B}$$

c) general sol'n:

$$y = [(2x+1)e^{-2x} + B]e^x + [-4e^{-x} + A]x = \boxed{(1-2x)e^{-x} + B e^x + A x}$$

d) Yes. Because $g(t) = 4(1-x)e^{-x}$ is a product of an exponential and a polynomial.

3. a)



Dashpot force depends on velocity (not pictured) and acts in the opposite direction.

b) $mg = w \Rightarrow m = \frac{w}{32}$

c) $mg = kL \Rightarrow w = kL \Rightarrow k = \frac{w}{L}$

d) $mu'' + \gamma u' + ku = F \Rightarrow$

$$\frac{w}{32} u'' + \frac{1}{8} u' + \frac{w}{2} u = \cos(4t)$$

e) Steady State = particular use $wu'' + 4u' + 16u = 32 \cos(4t)$

$$16w \mid y_p = A \cos(4t) + B \sin(4t)$$

$$4 \mid y_p' = -4A \sin(4t) + 4B \cos(4t)$$

$$w \mid y_p'' = -16A \cos(4t) - 16B \sin(4t)$$

$$\Rightarrow 16wA + 16B - 16Aw = 32 \Rightarrow 16B = 32 \Rightarrow B = 2$$

$$16wB - 16A - 16Bw = 0 \Rightarrow -16A = 0 \Rightarrow A = 0$$

So, $y_p = 2 \sin(4t)$

f) Amplitude (which is $R = \sqrt{A^2 + B^2}$) is 2,

which is independent of w , since it is a constant.