Update On 3D Orientation Reconstruction

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Forward Model

$$g_i = \int_{\mathbb{S}^2} d\hat{\mathbf{r}} \ h_i(\hat{\mathbf{r}}) f_i(\hat{\mathbf{r}})$$

- $g_i \rightarrow \text{intensity measurement}$
- ▶ h_i → point response function
- $f_i \rightarrow$ orientation distribution function

Fourier Transforms

Fourier Transform
$$\to F(\nu) = \int_{\mathbb{R}} dx \ f(x) e^{-2\pi i x \nu}$$

Spherical Fourier Transform $\to F_l^m = \int_{\mathbb{S}^2} d\hat{\mathbf{r}} \ f(\hat{\mathbf{r}}) \overline{Y_l^m(\hat{\mathbf{r}})}$

Forward Model

$$g_i = \int_{\mathbb{S}^2} d\hat{\mathbf{r}} \ h_i(\hat{\mathbf{r}}) f_i(\hat{\mathbf{r}})$$

Simplifies to:

$$g_i = \mathbf{H}^T \mathbf{F}$$

- ightharpoonup H ightharpoonup is a vector of the Fourier coefficients of the point response function
- ightharpoonup is a vector of the Fourier coefficients of the orientation distribution function

Multiple measurements:

$$\mathbf{g} = \Psi \mathbf{F}$$

No Prior Reconstruction

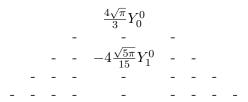
$$\mathbf{F} = \Psi^{+}\mathbf{g}$$

If Ψ is full column rank then we can recover \mathbf{F} —the spherical harmonic coefficients passed by the system.

F is a representation of the true object projected onto the spherical harmonic components passed by the system.

Isotropic Excitation - Single Pixel z View

$$h(\theta, \phi) = \sin^2 \theta =$$



Isotropic Excitation - Single Pixel x View

$$h(\theta, \phi) = 1 - \sin^2 \theta \cos^2 \phi =$$

$$-\frac{4\sqrt{\pi}}{3}Y_0^0$$

$$-\frac{\sqrt{30\pi}}{15}Y_1^{-2} - +2\frac{\sqrt{5\pi}}{15}Y_1^0 - -\frac{\sqrt{30\pi}}{15}Y_1^2$$

Isotropic Excitation - Single Pixel y View

$$h(\theta, \phi) = 1 - \sin^2 \theta \sin^2 \phi =$$

Isotropic Excitation - Single Pixel (Θ, Φ) View

$$h(\theta,\phi) = 1 - (\sin\Theta\cos\Phi\sin\theta\cos\phi + \sin\Theta\sin\Phi\sin\theta\sin\phi + \cos\Theta\cos\theta)^2 =$$

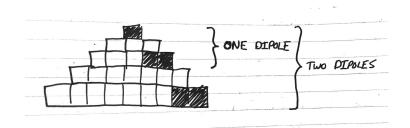
- ▶ Need >=4 single pixel measurements to satisfy full rank condition.
- ▶ Choose orientations so that the spherical harmonic coefficients are measured as independently as possible. I expect a tetrahedron pattern is optimal, but I haven't shown this.

diSPIM - polarized illuminatation from z - detect from x - $\phi_{\rm p}$ parameter

diSPIM - polarized illuminatation from x - detect from z - $\phi_{\mathbf{p}}$ parameter

$$\begin{split} h(\theta,\phi) &= \left(\sin\theta\sin\phi\sin\phi_{\rm p} - \cos\theta\cos\phi_{\rm p}\right)^2 \cdot 2(A+B\sin^2\theta) = \\ &\quad H_0^0 Y_0^0 \\ &\quad + \overline{H_2^2} Y_2^{-2} + \overline{H_2^1} Y_2^{-1} + H_2^0 Y_2^0 + H_2^2 Y_2^1 + H_2^2 Y_2^2 \\ &\quad + \overline{H_4^2} Y_4^{-2} + \overline{H_4^1} Y_4^{-1} + H_4^0 Y_4^0 + H_4^1 Y_4^1 + H_4^2 Y_4^2 - - - \\ &\quad H_0^0 &= \frac{4\sqrt{\pi}}{15} (5A + 2B\sin^2\phi_{\rm p}) \\ &\quad H_2^0 &= \frac{4\sqrt{5\pi}}{105} (-21A\sin^2\phi_{\rm p} + 14A - 10B\sin^2\phi_{\rm p} + 2B) \\ &\quad H_2^1 &= \frac{-2\sqrt{30\pi}i}{105} (7A + 4B)\sin(2\phi_{\rm p}) \\ &\quad H_2^2 &= \frac{-2\sqrt{30\pi}}{105} (7A + 6B)\sin^2\phi_{\rm p} \\ &\quad H_4^0 &= \frac{16\sqrt{\pi}B}{105} (3\sin^2\phi_{\rm p} - 2) \\ &\quad H_4^1 &= \frac{8\sqrt{5\pi}iB}{105}\sin(2\phi_{\rm p}) \\ &\quad H_2^2 &= \frac{4\sqrt{10\pi}B}{105}\sin^2\phi_{\rm p} \end{split}$$

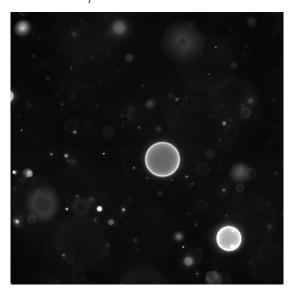
Single Molecule Prior Reconstruction



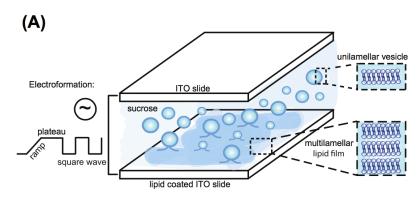
M. Vetterli, P. Marziliano and T. Blu, "Sampling signals with finite rate of innovation," in IEEE Transactions on Signal Processing, vol. 50, no. 6, pp. 1417-1428, Jun 2002.

S. Deslauriers-Gauthier and P. Marziliano, "Sampling signals with a finite rate of innovation on the sphere," in IEEE Transactions on Signal Processing, vol. 61, no. 18, pp. 4552-4561, Sept.15, 2013.

Giant Unilam
allar Vesicles (GUV) FOV $\approx 150 \times 150 \ \mu \mathrm{m}$

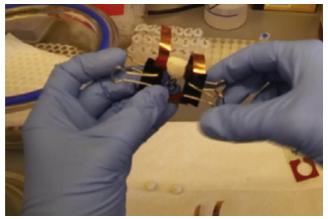


GUV Protocol



Schmid, 2015

GUV Chamber



Schmid, 2015