

WEAK Supervision

INDEP CASE \rightarrow A simple "trick" for latent variables

Correlations \rightarrow INVERSE COVARIANCE \longleftrightarrow Graphs (Gaussians)

Graphical models

Nuggets: Method of Moments

USED IN Cross Survey, LS, Classical Stats (etc)

GIVEN: $x^{(1)} \dots x^{(n)} \in \mathbb{R}^d$

$\lambda_i: \mathbb{R}^d \rightarrow \{-1, 1\}$ "ACTIONS" for $i = 1 \dots n$

find $P(y^{(i)}) | \bar{x}, x^{(i)}$

<u>Given</u>	OBSERVE			Ground Truth (Unobserved)	
DATA	λ_1	λ_2	λ_3	<u>y</u>	
$x^{(1)}$	1	1	1	1	$y^{(1)}$
$x^{(2)}$	1	-1	1	-1	$y^{(2)}$
\vdots					
$x^{(n)}$	1	-1	-1	-1	$y^{(n)}$

IDEA: λ_i are noisy voters / functions (Inaccurate)

Model 0: No abstains, $\lambda_i(x) \in \{-1, 1\}$, independent experts

"Each labeler has a hidden accuracy, makes an error w/ $1-p_{\text{prob}}$ "

for each example $x^{(i)}$ and λ_j

$$\lambda_j(x^{(i)}) = y^{(i)} \Rightarrow \text{prob } p_j \text{ " } \lambda_j \text{ is right"}$$

$$\lambda_j(x^{(i)}) = -y^{(i)} \Rightarrow \text{prob } 1-p_j \text{ " } \lambda_j \text{ is wrong"}$$

WE NEED TO ESTIMATE p_j

$$P(\lambda_j(x) = 1 | y=1) = P(\lambda_j(x) = -1 | y=-1)$$

Goal Compute $P(y^{(i)} | \bar{\lambda}, x)$

for $m \geq 5$

Agree Disagree

$$\text{Def: } \mathbb{E}[\lambda_i \lambda_j] = p_j \cdot 1 + (1-p_j)(-1) = 2p_j - 1$$

$$\text{define } \alpha_j = 2p_j - 1$$

$$\begin{aligned} \mathbb{E}[\lambda_i \lambda_j] &= \begin{cases} 1 & \text{if } i=j \\ 0 \dots & \\ 1 & (p_i p_j + (1-p_i)(1-p_j)) \quad \text{Agree} \\ + -1 & ((1-p_i)p_j + p_i(1-p_j)) \quad \text{Disagree} \end{cases} \\ &= \alpha_i \cdot \alpha_j \end{aligned}$$

form a matrix $M \in \mathbb{R}^{m \times m}$ $M_{ij} = \mathbb{E}[\lambda_i \lambda_j]$

NB: WE CAN ESTIMATE \uparrow from DATA (unlike y)

CRAZY ALGORITHM

$$\text{OBSERVE } M_{ij} M_{jk} = \alpha_i \alpha_j^2 \alpha_k$$

$$\frac{M_{ij} M_{jk}}{M_{ik}} = \alpha_j^2 \quad \text{"compute triples"}$$

WE HAVE SOLVED upto sign BASED ON OBSERVED M_{ij}

$$\text{Sign}(M_{ij}) = \text{Sign}(a_i) \cdot \text{Sign}(a_j)$$

Once we know even A single Rademacher's sign

However $a_i, -a_i$ are solutions

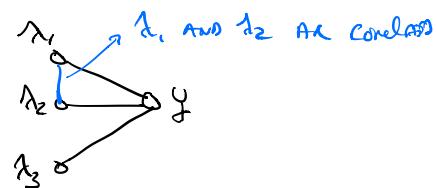
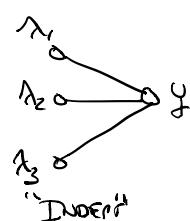
WEAKER Solution $\sum a_i > 0$, BREAKS Symmetry

THIS IS A SIMPLE Solution to an em like Problem. \square

WHAT if λ_i are CORRELATED?

In general, hopeless.

A graphical model



$$\mathbb{E}[\lambda_2 \lambda_3 | y] = \mathbb{E}[\lambda_2 | y] \mathbb{E}[\lambda_3 | y]$$

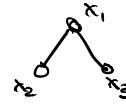
$$G = (V, E) \quad \text{nodes } V = \{\lambda_1, \dots, \lambda_m\}$$

edges $(i, j) \notin E \Rightarrow \lambda_i \perp \lambda_j$

Nugget Covariance Structure

$$x_1 \sim N(0, 1)$$

$$x_2 = x_1 + \epsilon_2 \quad \epsilon_2 \sim N(0, 1)$$



$$x_3 = x_1 + \epsilon_3 \quad \epsilon_3 \sim N(0, 1)$$

MEAN

$$\mathbb{E}[x_1] = 0 \quad \mathbb{E}[x_2] = \mathbb{E}[x_1] + \mathbb{E}[\epsilon_2] = 0 = \mathbb{E}[x_3]$$

Covariance

$$\mathbb{E}[x_1^2] = 1 \quad \mathbb{E}[x_2^2] = \mathbb{E}[(x_1 + \epsilon_2)^2] = \mathbb{E}[x_1^2] + \mathbb{E}[\epsilon_2^2] + 2\mathbb{E}[x_1 \epsilon_2] = 1 + 0 + 2 \cdot 0 = 1$$

$$\mathbb{E}[x_1 x_2] = \mathbb{E}[x_1^2] + \mathbb{E}[x_1 \epsilon_2] = 1 = \mathbb{E}[x_1 x_3]$$

$$\begin{aligned} \mathbb{E}[x_2 x_3] &= \mathbb{E}[(x_1 + \epsilon_2)(x_1 + \epsilon_3)] \\ &= \mathbb{E}[x_1^2] + \mathbb{E}[x_1 \epsilon_2] + \mathbb{E}[x_1 \epsilon_3] + \mathbb{E}[\epsilon_2 \epsilon_3] \\ &= 1 \end{aligned}$$

$$\Sigma = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{bmatrix} \quad \text{with DAG: } \begin{array}{c} x_1 \\ \swarrow \quad \searrow \\ x_2 \quad x_3 \end{array} \quad \text{No obvious!}$$

$$\Sigma^{-1} = \begin{bmatrix} 3 & -1 & -1 \\ -1 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix} \quad \text{with DAG: } \begin{array}{c} x_1 \\ \swarrow \quad \searrow \\ x_2 \quad x_3 \end{array} \quad \text{when no edge is present?}$$

The fact is Aesome, let's prove Gaussians!

(Wainwright & Loh 2014 about discrete cases

Ratliff 2018)

A probability distribution $p: \mathbb{R}^d \rightarrow [0, 1]$ factorizes

on \mathcal{G} if it graph $\mathcal{G} = (V, E)$ if

$$p(x) = C_0 \cdot \prod_{e=(i,j) \in E} p_e(x_i, x_j) \cdot \prod_{i \in V} p_i(x_i)$$

norm constant

Ex $p(x) = C \cdot \exp \left\{ -x^\top \Sigma^{-1} x \right\}$ Gaussians?
 Define $A = \Sigma^{-1}$ (covariance)

$$\log p(x) = \log C - \frac{x^\top A x}{\sum_{i,j} A_{ij} x_i x_j}$$

If p factors w.r.t. $\mathcal{G} = (V, E)$

$$\log p(x) = \log C_0 + \sum_{e=(i,j) \in E} \log p_e(x_i, x_j) + \sum_{i \in V} \log p_i(x_i)$$

Consider $(i, j) \notin E$ $\frac{\partial}{\partial x_i \partial x_j} \log p(x)$

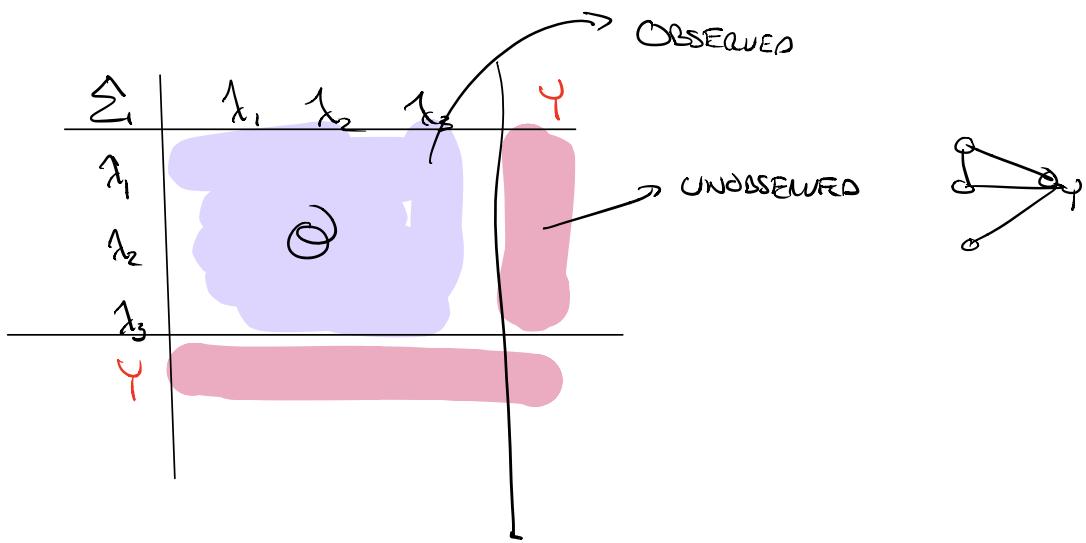
$$\frac{\partial}{\partial x_i \partial x_j} (*) = A_{ij} + A_{ji} = 2A_{ij} \quad (\text{covariance symmetric})$$

$$\frac{\partial}{\partial x_i \partial x_j} (**) = 0 = 2A_{ij}$$

i.e. $\sum_{i,j} = 0$ whenever $(i, j) \notin E$.

IT's NOT quite as clear for discrete r.v.

Back to our Problem



ASSUME WE KNOW graphical structure $G = (V, E)$
then from above $(i, j) \notin E \Rightarrow (\Sigma^{-1})_{ij} = 0$

IDEA: if there aren't too many edges, should be about
accuracy and correlation strength

$$\textcircled{1} \quad (\Sigma^{-1})_{ij} = (\Omega - u u^T)^{-1} \quad (\text{Block Inversion Lemma})$$

\downarrow Known entries \downarrow Do not concern? But I can measure
 $\Omega = \{1, 2, 3\}$

$$\textcircled{2} \quad (\Omega - u u^T)^{-1} = \Omega^{-1} + z z^T \quad z = \frac{\Omega^{-1} u}{\|u\|}$$

$$\left(\Sigma^{-1} \right)_{ij} = (\Omega^{-1})_{ij} + z_i z_j^T \quad \begin{matrix} \rightarrow \text{SOLVE for} \\ (i, j) \notin E \end{matrix}$$

$$= 0 \Rightarrow -\Omega^{-1}_{ij} = z_i z_j \quad \text{linear system}$$

$$\log(\Omega^{-1})^2 = \log z_i^2 + \log z_j^2$$

\Rightarrow LINEAR SYSTEM IN LOGS

∴ WE CAN RECOVER whenever this full rank!

- + This technique "Addy variables" (what we do w/ 4)
IS Powerful \Rightarrow Higher Rank Solves
- + LEARN Graph Structure "guess" (w/ SVD)

RECAP

- + "method of moments"
- + Nugget Graphs \leftrightarrow Probability (graphical models)
- + Application WEAK SUPERVISE