Bisection Method

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2 Section 1 Bisection Method

1 BISECTION METHOD

The **bisection method** can be used to find the root of a univariate function f(x), with no restrictions on the differentiability of f. The basic idea behind the bisection is starting off with some interval [a, b] containing a root, iteratively "shrinking" this interval until it is below some tolerance threshold, and then taking the root to be the midpoint of this interval. The general procedure is as follows:

- 1. Make an initial guess for the interval [a, b] containing the root.
- 2. Assume the root, c, is the midpoint of this interval: c = (a + b)/2.
- 3. Evaluate f(a) and f(c).
 - (a) If f(a) < 0 and f(c) > 0 (i.e. they have different sign), we know the true root is contained in the interval [a, c]. Therefore, we update our interval so that a remains the same, but b is updated to be c.
 - (b) If f(a) and f(c) have the same sign (either both negative or both positive), we know the true root must be contained in the interval [c, b]. Therefore, we update our interval so that b remains the same, but a is updated to be c.
- 4. Repeating steps 2 and 3, the interval [a, b] will keep shrinking. Once the difference (b a) is small enough, we say that the estimate of the root has **converged** to the true root, within some **tolerance** (which we denote as TOL). Therefore, if we predetermine that, at most, the root must be restricted to an interval of length TOL, we will keep repeating steps 2 and 3 until (b a) < TOL.

In some cases, the difference (b-a) may never decrease below TOL, or take too long to decrease to below TOL. Therefore, we also define the **maximum number of iterations** (i_{max}) so that the algorithm does not keep iterating forever, or for too long of a time [1, 2].

There are two basic algorithms for implementing the bisection method. The first implementation, shown in Algorithm 1 below, does *not* store the result of each iteration. On the other hand, the second implementation, shown in Algorithm 2, *does* store the result of each iteration. bisection method implements both of these algorithms.

Since Algorithm 2 first needs to preallocate a potentially huge array to store all of the intermediate solutions, Algorithm 1 is significantly faster. Even if $i_{\rm max}$ (determines size of the preallocated array) is set to be a small number (for example, 10), Algorithm 1 is still faster. The reason we still consider and implement Algorithm 2 is so that convergence studies may be performed.

Algorithm 1:

Bisection method (fast implementation).

Given:

- f(x) function
- a lower bound for initial guess of interval with root
- b upper bound for initial guess of interval with root
- TOL tolerance
- $i_{
 m max}$ maximum number of iterations

Procedure:

1. Initial guess for root.

$$c = \frac{a+b}{2}$$

2. Initialize x_{new} so its scope will not be limited to within the while loop.

$$x_{\text{new}} = 0$$

3. Initialize the loop index.

$$i = 1$$

4. Find the root using the bisection method.

while
$$((b-a) > TOL)$$
 and $(i < i_{max})$

(a) Update interval.

$$\begin{aligned} & \textbf{if} \ f(c) = 0 \\ & \middle| \quad \textbf{Stop} \\ & \textbf{else} \ \textbf{if} \ \text{sgn} \left[f(c) \right] = \text{sgn} \left[f(a) \right] \\ & \middle| \quad a = c \\ & \textbf{else} \\ & \middle| \quad b = c \\ & \textbf{end} \end{aligned}$$

(b) Update root estimate.

$$c=\frac{a+b}{2}$$

(c) Increment loop index.

$$i=i+1$$

end

Return:

• root = c - converged root

Algorithm 2:

Bisection method (storing intermediate root estimates).

Given:

- f(x) function
- a lower bound for initial guess of interval with root
- b upper bound for initial guess of interval with root
- TOL tolerance
- $i_{
 m max}$ maximum number of iterations

Procedure:

- 1. Preallocate $\mathbf{x} \in \mathbb{R}^{i_{\max}}$ to store the estimates of the root at each iteration.
- 2. Store the initial guess for the root in the first element of x.

$$x_1 = \frac{a+b}{2}$$

3. Initialize the loop index.

$$i = 1$$

4. Find the root using the bisection method.

while
$$((b-a) > TOL)$$
 and $(i < i_{max})$

(a) Update interval.

$$\begin{aligned} & \textbf{if} \ f(x_i) = 0 \\ & & | \quad \textbf{Stop} \\ & \textbf{else} \ \textbf{if} \ \text{sgn} \left[f(x_i) \right] = \text{sgn} \left[f(a) \right] \\ & | \quad a = x_i \\ & \textbf{else} \\ & | \quad b = x_i \\ & \textbf{end} \end{aligned}$$

(b) Update root estimate.

$$x_{i+1} = \frac{a+b}{2}$$

(c) Increment loop index.

$$i = i + 1$$

end

Return:

ullet vector where the first element is the initial guess for the root, the subsequent elements are the intermediate root estimates, and the final element is the converged root

REFERENCES 5

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[2] James Hateley. Nonlinear Equations. MATH 3620 Course Reader (Vanderbilt University). 2019.