Continuous to Discrete Transfer Function Transformation Using the Euler Methods

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1 EULER CONTINUOUS TO DISCRETE TRANSFORMA-TIONS

Consider a continuous transfer function H(s) that we wish to transform to a discrete transfer function H(z) using a sampling period of T and some approximation method (i.e. some approximate transformation). Both the **forward Euler** and **backward Euler** are transformations based on evaluating H(s) at some value of s representing an approximate transformation between s and s [1].

1.1 Forward Euler

$$s \leftarrow \frac{z-1}{T}$$
 $\therefore H(z) = H(s)|_{s=\frac{z-1}{T}}$

1.2 Backward Euler

$$s \leftarrow \frac{z-1}{Tz}$$
 $\therefore H(z) = H(s)|_{s=\frac{z-1}{Tz}}$

2 REFERENCES FOR CODE

Syms to TF Conversion (syms2tf.m) [4]:

• Conversion of a symbolic function object to a transfer function object.

SYM2TF: a matlab function which converts symbolic math rationals to transfer function object [3]:

• Conversion of a symbolic function object to a transfer function object.

How can I convert a transfer function object from the Control System Toolbox into a symbolic object for use with the Symbolic Math Toolbox? [2]:

• Conversion of a transfer function object to a symbolic function object.

4 REFERENCES

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[1] Gene F. Franklin, J. David Powell, and Michael Workman. *Digital Control of Dynamic Systems*. 3rd. Half Mooon Bay, CA: Ellis-Kagle Press, 1998.

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