# Continuous to Discrete Transfer Function Transformation Using the Euler Methods

MATLAB Implementation

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# **Contents**

2d_euler																															
Syntax																															
Description																															
Examples .																															
Links																															
Continuous to 1	Discre	te T	Гrа	ns	for	m	ati	or	ıs	Us	sir	ıg	th	e :	Ει	ıle	r N	Μe	th	od	ls										
	<b>C</b> 1																														
References for	Coae																														

### c2d euler

Transforms a continuous transfer function to a discrete transfer function using the forward and backward Euler methods.

#### **Syntax**

```
Hz = c2d_euler(Hs,T,'forward')
Hz = c2d_euler(Hs,T,'backward')
```

#### **Description**

Hz = c2d\_euler(Hs,T,'forward') returns the discrete transfer function Hz obtained by applying the forward Euler (i.e. forward difference) transformation to a continuous transfer function Hs, where T is the sampling period.

Hz = c2d\_euler(Hs,T,'backward') returns the discrete transfer function Hz obtained by applying the backward Euler (i.e. backward difference) transformation to a continuous transfer function Hs, where T is the sampling period.

#### **Examples**

Example 1

Consider the following continuous transfer function:

$$H(s) = \frac{s+1}{0.1s+1}$$

Find the corresponding discrete transfer function H(z) using a sampling period of  $T=0.25\,\mathrm{s}$ . Use both the forward Euler and backward Euler transformations.

#### **■** SOLUTION

Defining H(s) as a transfer function object,

Applying the forward Euler transformation,

This results in

Hz\_forward =

```
Sample time: 0.25 seconds
Discrete-time transfer function.

Applying the backward Euler transformation,

Hz_backward = c2d_euler(Hs,T,'backward')

This results in

Hz_backward =

25 z - 20
------
7 z - 2

Sample time: 0.25 seconds
Discrete-time transfer function.
```

#### Links

#### MATLAB® Central's File Exchange:

 $\verb|https://www.mathworks.com/matlabcentral/file exchange/90267-euler-c2d-transformation-c2| d_euler|$ 

#### GitHub®:

https://github.com/tamaskis/c2d\_euler-MATLAB

# **Continuous to Discrete Transformations Using the Euler Methods**

Consider a continuous transfer function H(s) that we wish to transform to a discrete transfer function H(z) using a sampling period of T and some approximation method (i.e. some approximate transformation). Both the **forward Euler** and **backward Euler** are transformations based on evaluating H(s) at some value of s representing an *approximate* transformation between s and s [1].

Forward Euler: 
$$s \leftarrow \frac{z-1}{T}$$
  $\therefore H(z) = H(s)|_{s=\frac{z-1}{T}}$ 

# **References for Code**

#### Syms to TF Conversion (syms2tf.m) [4]:

• Conversion of a symbolic function object to a transfer function object.

#### SYM2TF: a matlab function which converts symbolic math rationals to transfer function object [3]:

• Conversion of a symbolic function object to a transfer function object.

How can I convert a transfer function object from the Control System Toolbox into a symbolic object for use with the Symbolic Math Toolbox? [2]:

• Conversion of a transfer function object to a symbolic function object.

## References

- [1] Gene F. Franklin, J. David Powell, and Michael Workman. *Digital Control of Dynamic Systems*. 3<sup>rd</sup>. Half Mooon Bay, CA: Ellis-Kagle Press, 1998.
- [2] How can I convert a transfer function object from the Control System Toolbox into a symbolic object for use with the Symbolic Math Toolbox? MATLAB Answers. https://www.mathworks.com/matlabcentral/answers/96275-how-can-i-convert-a-transfer-function-object-from-the-control-system-toolbox-into-a-symbolic-object. (accessed: April 10, 2021).
- [3] Ichiro Maruta. SYM2TF: a matlab function which converts symbolic math rationals to transfer function object. GitHub Gist. https://gist.github.com/maruta/1035254. (accessed: April 10, 2021).
- [4] Crystal Nassouri. Syms to TF Conversion. MATLAB Central File Exchange. https://www.mathworks.com/matlabcentral/fileexchange/27302-syms-to-tf-conversion. (accessed: April 10, 2021).