

Newton's Method

MATLAB Implementation

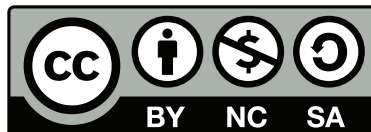
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1 Download and Installation

1.1 Download from GitHub

The `newtons_method` function is available for download on GitHub at https://github.com/tamaskis/newtons_method-MATLAB.

1.2 Files Included With Download

There are **five** files included in the downloaded zip file:

1. `EXAMPLE.M` – *example for using the `newtons_method` function*
2. `LICENSE` – *license for the `newtons_method` function*
3. `Newton's Method - MATLAB Implementation.pdf` – *this PDF*
4. `newtons_method.m` – *MATLAB function implementing Newton's method*
5. `README.md` – *markdown file for GitHub documentation*

1.3 Accessing the `newtons_method` Function in a MATLAB Script

There are **four** options for accessing the `newtons_method` function in a MATLAB script:

1. Copy the `newtons_method` function to the *end* of your MATLAB script.
2. Place the `newtons_method.m` file in the same folder as the MATLAB script.
3. Place the `newtons_method.m` file into whatever folder you want, and then use the `addpath(folderName)` command¹ where the `folderName` parameter is a string that stores the filepath of the folder that `newtons_method.m` is in *relative to* the folder that your script is in.
4. Make a toolbox by first opening `newtons_method.m`, then going to the **HOME** tab in MATLAB, and finally selecting **Package** **Toolbox** in the drop-down menu under **Add-Ons**. Once you package the `newtons_method` function as a toolbox, you can use it in any script.

¹ <https://www.mathworks.com/help/matlab/ref/addpath.html>

2 newtons_method MATLAB Function

Calculates the root of a differentiable, univariate function using Newton's method.

Syntax

```
root = newtons_method(f,df,x0)
root = newtons_method(f,df,x0,TOL)
root = newtons_method(f,df,x0,[],imax)
root = newtons_method(f,df,x0,TOL,imax)
```

Description

`root = newtons_method(f,df,x0)` returns the root of a differentiable function $f(x)$ specified by the function handle `f`, where `df` is the derivative of $f(x)$ (i.e. $f'(x)$) and `x0` is an initial guess of the root. The default tolerance and maximum number of iterations are `TOL = 1e-12` and `imax = 1e6`, respectively.

`root = newtons_method(f,df,x0)` returns the root of a differentiable function $f(x)$ specified by the function handle `f`, where `df` is the derivative of $f(x)$ (i.e. $f'(x)$), `x0` is an initial guess of the root, and `TOL` is the tolerance. The default maximum number of iterations is `imax = 1e6`.

`root = newtons_method(f,df,x0,[],imax)` returns the root of a differential function $f(x)$ specified by the function handle `f`, where `df` is the derivative of $f(x)$ (i.e. $f'(x)$), `x0` is an initial guess of the root, and `imax` is the maximum number of iterations. The default tolerance is `TOL = 1e-12`.

`root = newtons_method(f,df,x0,TOL,imax)` returns the root of a differentiable function $f(x)$ specified by the function handle `f`, where `df` is the derivative of $f(x)$ (i.e. $f'(x)$), `x0` is an initial guess of the root, `TOL` is the tolerance, and `imax` is the maximum number of iterations.

Examples

Consider the function

$$f(x) = x^2 - 1$$

To apply Newton's method to find the root(s) of $f(x)$, we first need to find $f'(x)$.

$$f'(x) = \frac{d}{dx} (x^2 - 1) = 2x$$

Next, we enter $f(x)$ and $f'(x)$ into MATLAB.

```
% f(x) and its derivative
f = @(x) x^2-1;
df = @(x) 2*x;
```

Since $f(x)$ is such a simple function, we can see, by inspection, that it will have two roots at $x = \pm 1$. Therefore, to find *both* roots using Newton's method, we first use `newtons_method` with an initial guess $x_0 = -10$, and then use `newtons_method` a second time but with an initial guess $x_0 = 10$.

```
% finds first root of f(x)=x^2-1 using Newton's method
root1 = newtons_method(f,df,-10)

% finds second root of f(x)=x^2-1 using Newton's method
root2 = newtons_method(f,df,10)
```

This yields the result

```
root1 =
```

```
-1
```

```
root2 =
```

```
1
```

3 Newton's Method

Newton's method is a technique used to find the root (based on an initial guess² x_0) of a *differentiable*, univariate function $f(x)$. The equation of the tangent line to the curve $y = f(x)$ at $x = x_0$ is

$$y = f'(x_0)(x - x_0) + f(x_0)$$

where $f'(x_0)$ is the derivative of $f(x)$ evaluated at x_0 . The x -intercept of this tangent line, $x = x_1$, can be solved by setting $y = 0$.

$$0 = f'(x_0)(x_1 - x_0) + f(x_0)$$

$$\therefore x_1 = x_0 - \frac{f(x_0)}{f'(x_0)}$$

x_1 is an updated estimate of the root of $f(x)$. To keep refining our estimate, we can keep iterating through this procedure using Eq. (1).

$$\boxed{x_{i+1} = x_i - \frac{f(x_i)}{f'(x_i)}} \quad (1)$$

So how do we actually use Eq. (1)? Given an initial guess x_0 , we can keep coming up with new estimates of the root. But how do we know when to stop? To resolve this issue, we define the **error**³ as

$$\boxed{\varepsilon = |x_{i+1} - x_i|} \quad (2)$$

Once ε is small enough, we say that the estimate of the root has **converged** to the true root, within some **tolerance** (which we denote as TOL). Therefore, if we predetermine that, at most, we can *tolerate* an error of TOL, then we will keep iterating Eq. (1) until $\varepsilon < \text{TOL}$. In some cases, the error may never decrease below TOL, or take too long to decrease to below TOL. Therefore, we also define the **maximum number of iterations** (i_{\max}) so that the algorithm does not keep iterating forever, or for too long of a time.

The algorithm itself is shown below in Algorithm 1 [1, 2].

² Often, a function $f(x)$ will have multiple roots. Therefore, Newton's method typically finds the root closest to the initial guess x_0 . However, this is not always the case; the algorithm depends heavily on the derivative of $f(x)$, which, depending on its form, may cause it to converge on a root further from x_0 .

³ Note that ε is an *approximate* error. The motivation behind using this definition of ε is that as i gets large (i.e. $i \rightarrow \infty$), $x_{i+1} - x_i$ approaches $x_{i+1} - x^*$ (assuming this sequence is convergent), where x^* is the true root (and therefore $x_{i+1} - x^*$ represents the *exact* error).

Algorithm 1: Newton's method.

```

1 Given:  $f(x)$ ,  $f'(x)$ ,  $x_0$ , TOL,  $i_{\max}$ 

   // initializes the error so the loop will be entered
2 err = (2)(TOL)

3 Preallocate an  $i_{\max} \times 1$  vector  $\mathbf{x}$ , where  $\mathbf{x}$  is the vector storing the root estimate at
   each iteration.

   // Newton's method
4  $i = 1$ 
5 while  $\varepsilon > \text{TOL}$  and  $i < i_{\max}$  do
    // updates estimate of root
6     $x_{i+1} = x_i - \frac{f(x_i)}{f'(x_i)}$ 

    // calculates error
7     $\varepsilon = |x_{i+1} - x_i|$ 

    // increments loop index
8     $i = i + 1$ 
9 end

   // returns root
10 root =  $x_i$ 
11 return root

```

References

- [1] James Hateley. *Nonlinear Equations*. MATH 3620 Course Reader (Vanderbilt University). 2019.
- [2] *Newton's method*. https://en.wikipedia.org/wiki/Newton%27s_method. (accessed: June 10, 2020).