# **Newton's Method**

MATLAB Implementation

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### 1 Download and Installation

## 1.1 Download from MATLAB File Exchange

The newtons\_method function is available for download on MATLAB® File Exchange at https://www.mathworks.com/matlabcentral/fileexchange/85735-newton-s-method-newtons method.

#### 1.2 Download from GitHub

The newtons\_method function is available for download on GitHub at https://github.com/tamaskis/newtons\_method-MATLAB.

#### 1.3 Files Included With Download

There are **five** files included in the downloaded zip file:

- 1. EXAMPLE.M example for using the newtons\_method function
- 2. LICENSE license for the newtons method function
- 3. Newton's Method MATLAB Implementation.pdf this PDF
- 4. newtons method.m MATLAB function implementing Newton's method
- 5. README.md markdown file for GitHub documentation

# 1.4 Accessing the newtons\_method Function in a MATLAB Script

There are **four** options for accessing the newtons\_method function in a MATLAB script:

- 1. Copy the newtons method function to the *end* of your MATLAB script.
- 2. Place the newtons method.m file in the same folder as the MATLAB script.
- 3. Place the newtons\_method.m file into whatever folder you want, and then use the addpath (folderName) command where the folderName parameter is a string that stores the filepath of the folder that newtons\_-method.m is in *relative to* the folder that your script is in.
- 4. Make a toolbox by first opening newtons\_method.m, then going to the HOME tab in MATLAB, and finally selecting Package Toolbox in the drop-down menu under Add-Ons. Once you package the newtons\_method function as a toolbox, you can use it in any script.

<sup>1</sup> https://www.mathworks.com/help/matlab/ref/addpath.html

# 2 newtons method

Calculates the root of a differentiable, univariate function using Newton's method.

#### **Syntax**

```
root = newtons_method(f,df,x0)
root = newtons_method(f,df,x0,TOL)
root = newtons_method(f,df,x0,[],imax)
root = newtons_method(f,df,x0,TOL,imax)
```

#### **Description**

root = newtons\_method(f,df,x0) returns the root of a differentiable function f(x) specified by the function handle f, where df is the derivative of f(x) (i.e. f'(x)) and x0 is an initial guess of the root. The default tolerance and maximum number of iterations are TOL = 1e-12 and imax = 1e6, respectively.

root = newtons\_method(f,df,x0) returns the root of a differentiable function f(x) specified by the function handle f, where df is the derivative of f(x) (i.e. f'(x)), x0 is an initial guess of the root, and TOL is the tolerance. The default maximum number of iterations is imax = 1e6.

root = newtons\_method(f,df,x0,[],imax) returns the root of a differential function f(x) specified by the function handle f, where df is the derivative of f(x) (i.e. f'(x)), x0 is an initial guess of the root, and imax is the maximum number of iterations. The default tolerance is TOL = 1e-12.

root = newtons\_method(f,df,x0,TOL,imax) returns the root of a differentiable function f(x) specified by the function handle f, where df is the derivative of f(x) (i.e. f'(x)), x0 is an initial guess of the root, TOL is the tolerance, and imax is the maximum number of iterations.

#### **Example**

Example 2.1

Find the root(s) of  $f(x) = x^2 - 1$ .

#### **■** SOLUTION

To apply Newton's method to find the root(s) of f(x), we first need to find f'(x).

$$f'(x) = \frac{d}{dx} \left( x^2 - 1 \right) = 2x$$

Defining f(x) and f'(x) in MATLAB,

```
% f(x) and its derivative f = \theta(x) x^2-1; df = \theta(x) 2*x;
```

We know  $f(x)=x^2-1$  has roots at  $x=\pm 1$ , but let's pretend we don't know this, and solve this problem using a more general approach. Since f(x) is a quadratic function, we know that it will have either 0 roots (in the case where f(x) does not cross the x-axis) or 2 roots. Let's assume the latter case (otherwise it would be pointless to try and find roots of f(x)). Therefore, we use Newton's method twice, with two different guesses. Let's pick -10 and 10 as our initial guesses.

1

### 3 Newton's Method

**Newton's method** is a technique used to find the root (based on an initial guess<sup>2</sup>  $x_0$ ) of a *differentiable*, univariate function f(x). The equation of the tangent line to the curve y = f(x) at  $x = x_0$  is

$$y = f'(x_0)(x - x_0) + f(x_0)$$

where  $f'(x_0)$  is the derivative of f(x) evaluated at  $x_0$ . The x-intercept of this tangent line,  $x = x_1$ , can be solved by setting y = 0.

$$0 = f'(x_0)(x_1 - x_0) + f(x_0)$$

$$\therefore x_1 = x_0 - \frac{f(x_0)}{f'(x_0)}$$

 $x_1$  is an updated estimate of the root of f(x). To keep refining our estimate, we can keep iterating through this procedure using Eq. (1).

$$x_{i+1} = x_i - \frac{f(x_i)}{f'(x_i)}$$
 (1)

So how do we actually use Eq. (1)? Given an initial guess  $x_0$ , we can keep coming up with new estimates of the root. But how do we know when to stop? To resolve this issue, we define the **error**<sup>3</sup> as

$$\boxed{\varepsilon = |x_{i+1} - x_i|} \tag{2}$$

Once  $\varepsilon$  is small enough, we say that the estimate of the root has **converged** to the true root, within some **tolerance** (which we denote as TOL). Therefore, if we predetermine that, at most, we can *tolerate* an error of TOL, then we will keep iterating Eq. (1) until  $\varepsilon$  < TOL. In some cases, the error may never decrease below TOL, or take too long to decrease to below TOL. Therefore, we also define the **maximum number of iterations** ( $i_{max}$ ) so that the algorithm does not keep iterating forever, or for too long of a time.

The algorithm itself is shown below in Algorithm 1 [1, 2].

Often, a function f(x) will have multiple roots. Therefore, Newton's method typically finds the root closest to the initial guess  $x_0$ . However, this is not always the case; the algorithm depends heavily on the derivative of f(x), which, depending on its form, may cause it to converge on a root further from  $x_0$ .

<sup>&</sup>lt;sup>3</sup> Note that  $\varepsilon$  is an *approximate* error. The motivation behind using this definition of  $\varepsilon$  is that as i gets large (i.e.  $i \to \infty$ ),  $x_{i+1} - x_i$  approaches  $x_{i+1} - x^*$  (assuming this sequence is convergent), where  $x^*$  is the true root (and therefore  $x_{i+1} - x^*$  represents the exact error).

#### Algorithm 1: Newton's method.

1 Given: f(x), f'(x),  $x_0$ , TOL,  $i_{max}$ 

// initializes the error so the loop will be entered

$$2 \text{ err} = (2)(\text{TOL})$$

3 Preallocate an  $i_{\rm max} \times 1$  vector  ${\bf x}$ , where  ${\bf x}$  is the vector storing the root estimate at each iteration.

// inputs initial guess for root into  $\mathbf x$  vector

4 
$$x_1 = x_0$$

// Newton's method

$$i = 1$$

6 while  $\varepsilon > \mathrm{TOL}$  and  $i < i_{\mathrm{max}}$  do

7 
$$x_{i+1} = x_i - \frac{f(x_i)}{f'(x_i)}$$

// increments loop index

$$i = i + 1$$

10 end

// returns root

- 11 root =  $x_i$
- 12 return root

REFERENCES 9

# References

- [1] James Hateley. Nonlinear Equations. MATH 3620 Course Reader (Vanderbilt University). 2019.
- [2] Newton's method. https://en.wikipedia.org/wiki/Newton%27s\_method. (accessed: June 10, 2020).