$\mathrm{Ti}k\mathbf{Z}$ Diagrams

Tamas Kis

 $July\ 26,\ 2024$

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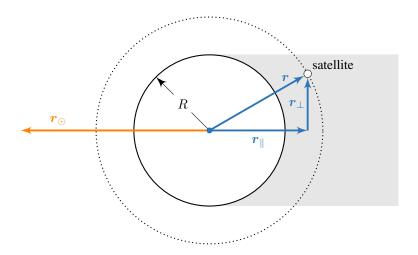
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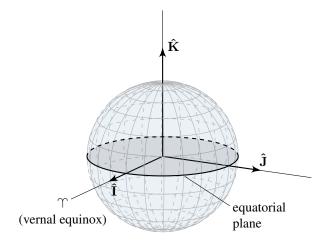
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1 aerospace

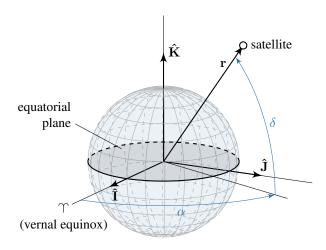
$1.1 \verb| cylindrical_eclipse_model|\\$



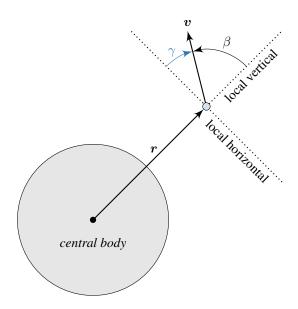
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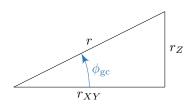
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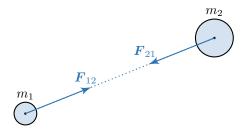
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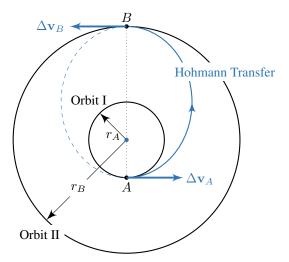
$1.5 \verb| geometry_of_the_geocentric_latitude|$



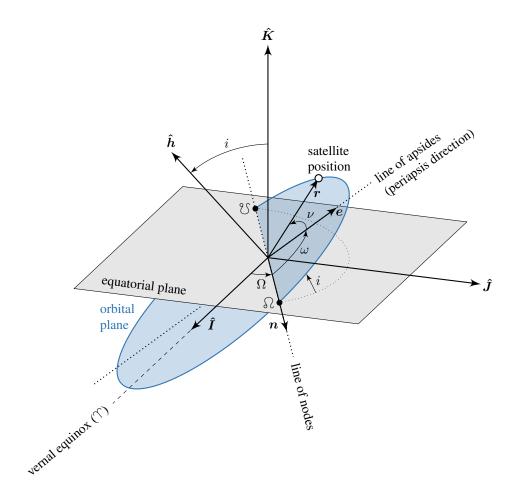
$1.6 \quad {\tt gravitational_interaction_between_two_bodies}$



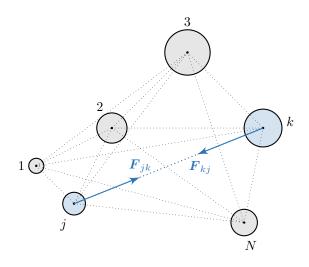
1.7 hohmann_transfer



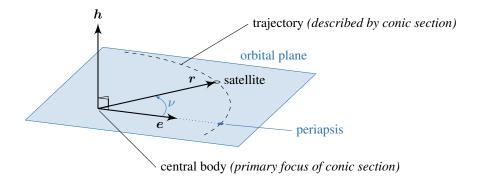
1.8 keplerian_orbital_elements



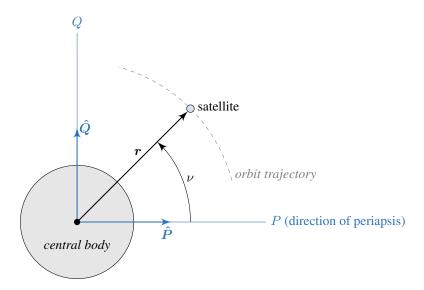
1.9 n_body_problem



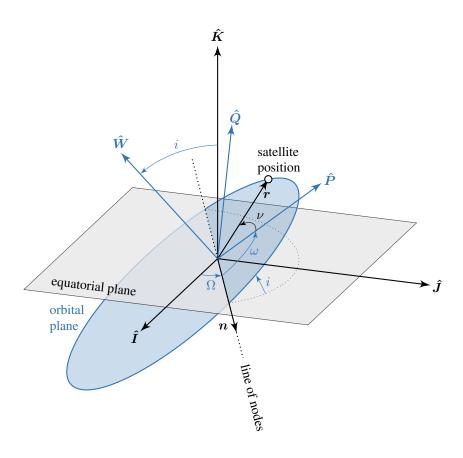
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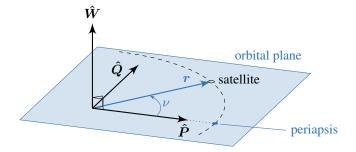
1.11 perifocal_frame



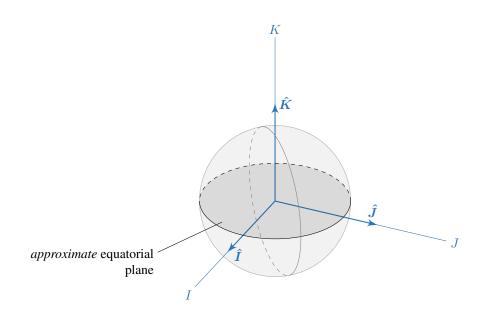
$1.12 \quad {\tt perifocal_frame_in_three_dimensions}$



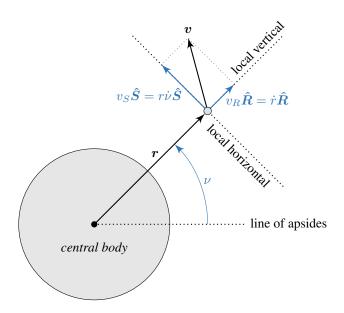
$1.13 \verb| perifocal_frame_on_the_orbital_plane|$



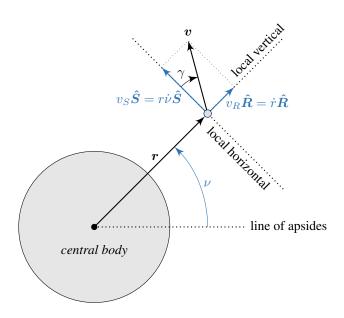
$1.14 \verb| planet_centered_inertial_pci_frame|$



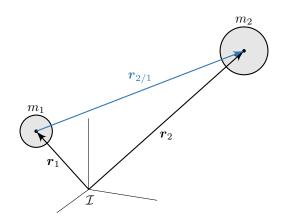
$1.15 \verb| radial_and_along_track_velocity_components|$



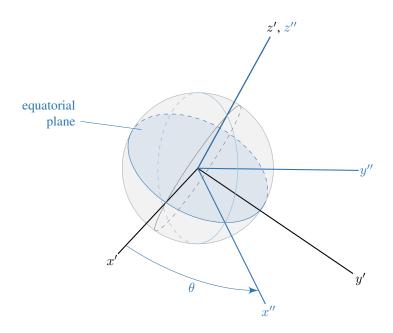
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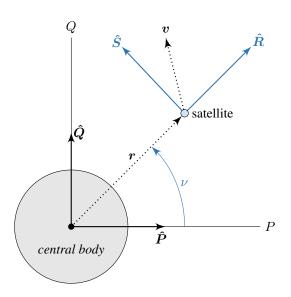
1.17 relative_position_of_bodies



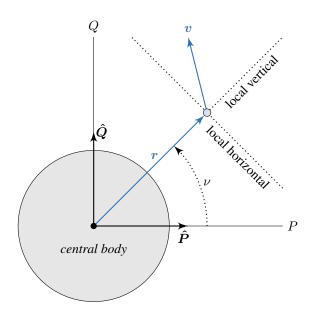
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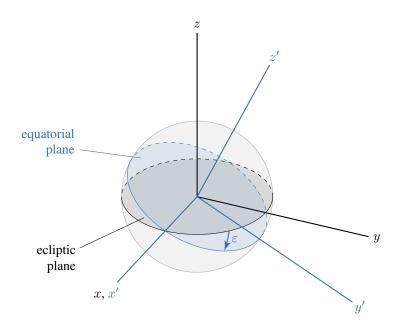
$1.19 \quad {\tt rsw_and_perifocal_frames}$



$1.20 \verb| satellite_position_and_velocity|$

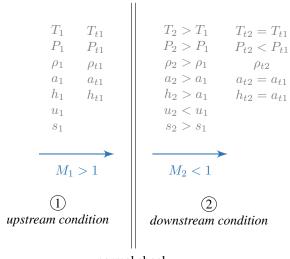


1.21 tilt_of_a_celestial_body



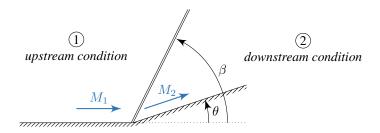
$2 \quad {\tt compressible_flow}$

$2.1 \verb| normal_shock|$



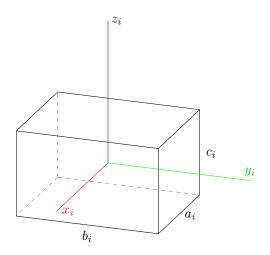
normal shock

2.2 oblique_shock

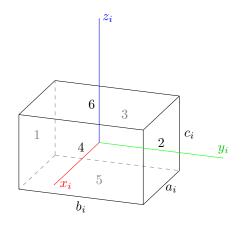


$3\ \ {\it geometric_and_inertial_modeling}$

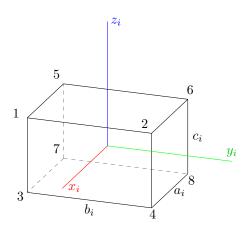
$3.1 \verb| body_axes_of_a_rectangular_prism|$



$3.2 \verb| rectangular_prism_face_numbering_convention|$

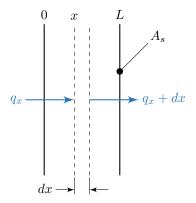


$3.3 \verb| rectangular_prism_vertex_numbering_convention|$



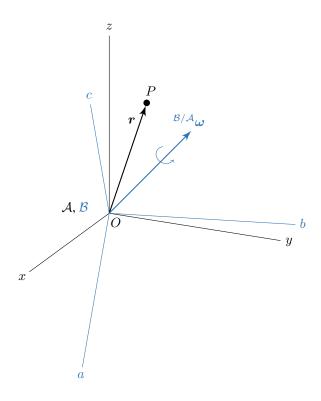
4 heat_transfer

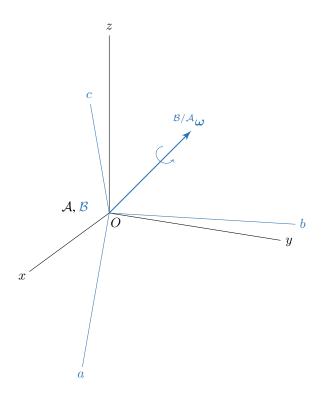
$4.1 \verb| heat_conduction_through_a_flat_plate|$



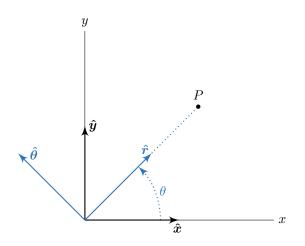
5 kinematics

5.1 absolute_kinematics

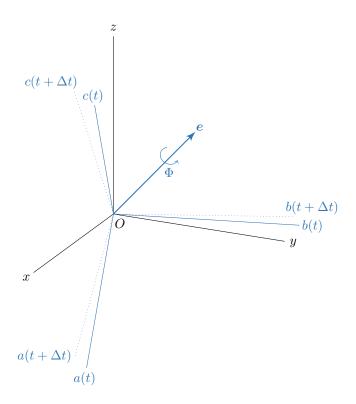




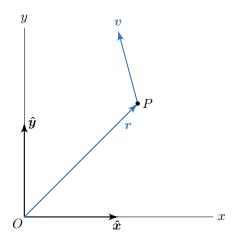
$5.3 \verb|| coordinate_frame_definitions_for_polar_coordinates|$



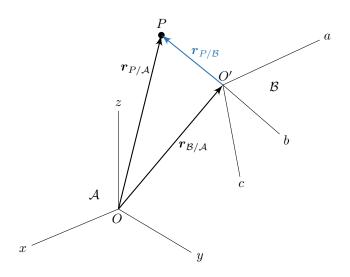
5.4 instantaneous_axis_of_rotation



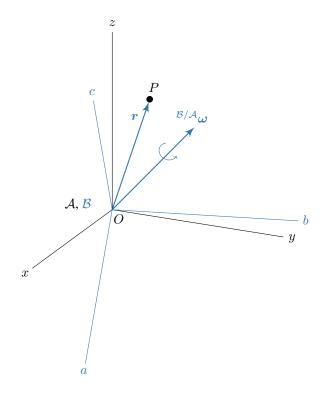
$5.5 \verb| instantaneous_plane_of_motion| \\$



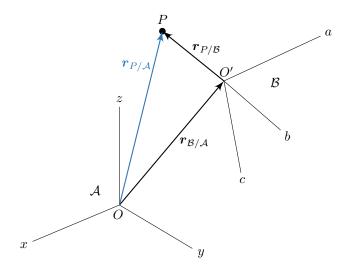
$5.6 \verb| kinematics_in_a_moving_frame|$



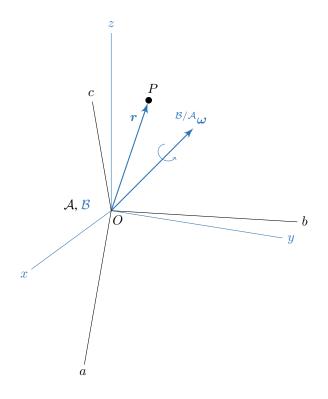
$5.7 \quad {\tt kinematics_in_a_rotating_frame}$

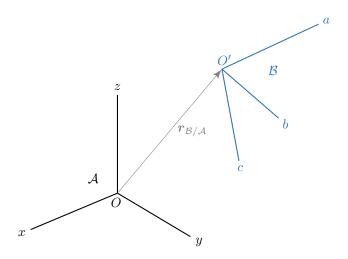


$5.8 \verb| kinematics_in_a_stationary_frame_1|$

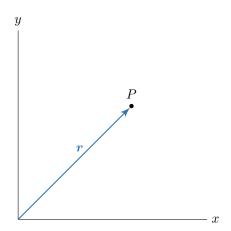


$5.9 \verb| kinematics_in_a_stationary_frame_2|$

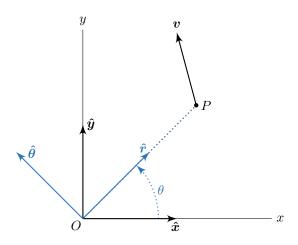




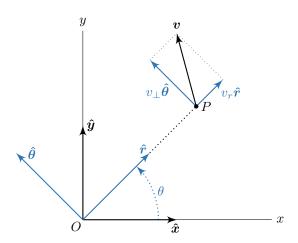
$5.11 \quad {\tt particle_in_the_xy_plane}$



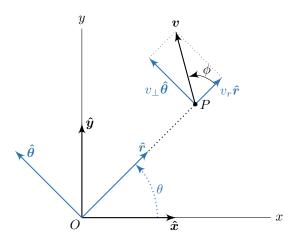
$5.12 \verb| polar_coordinates_of_the_instantaneous_motion|\\$



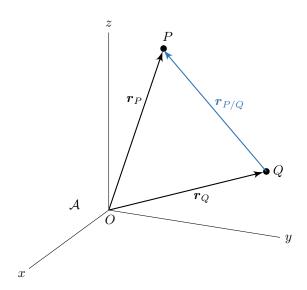
$5.13 \verb| radial_and_transverse_velocity_components|$

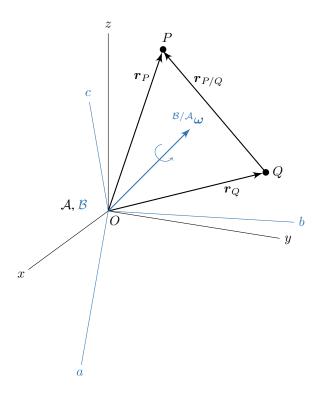


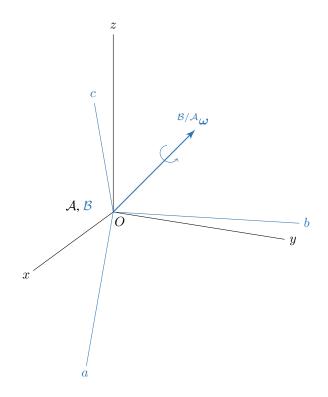
$5.14 \verb| radial_and_transverse_velocity_components_with_an_auxiliary_angle \\$



5.15 relative_kinematics

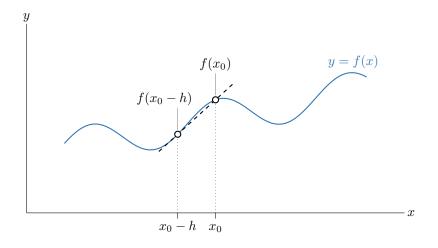




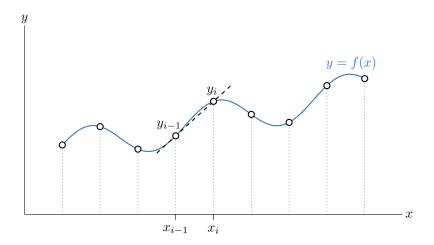


6 numerical_math

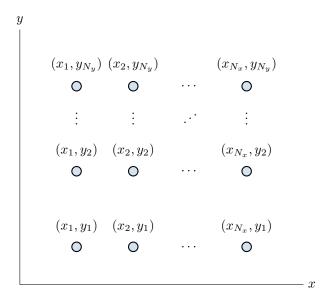
$6.1 \verb| backward_difference_approximation_v1|$



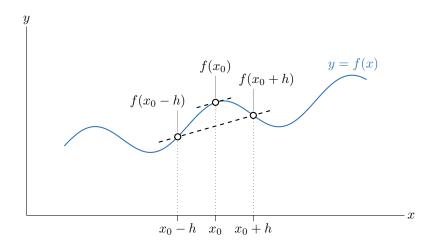
$6.2 \verb| backward_difference_approximation_v2|$



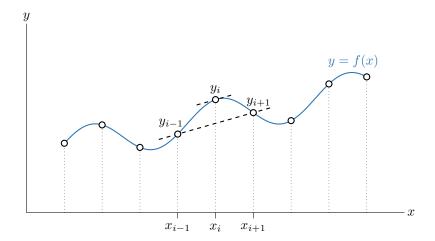
6.3 bivariate_grid



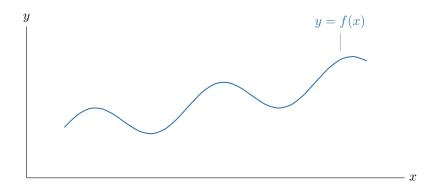
6.4 central_difference_approximation_v1



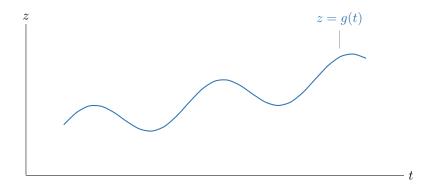
$6.5 \verb| central_difference_approximation_v2|$



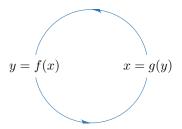
6.6 continuous_function



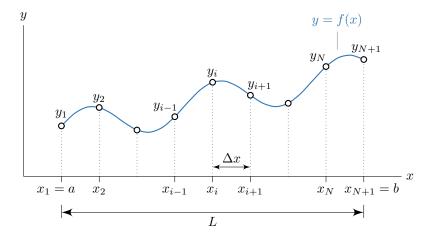
6.7 continuous_time_function



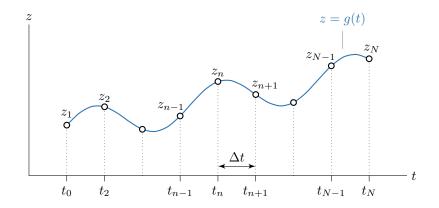
6.8 convergent_loop



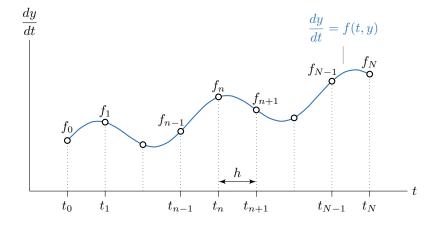
$6.9 \quad {\tt discretization_of_a_continuous_function}$



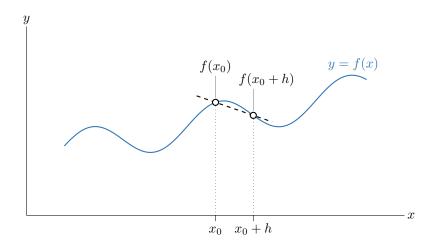
$6.10 \verb| discretization_of_a_continuous_time_function|$



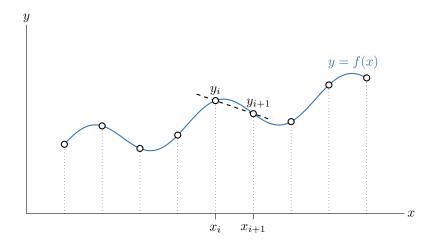
$6.11 \quad {\tt discretization_of_an_ODE_in_time}$



$6.12 \quad {\tt forward_difference_approximation_v1}$



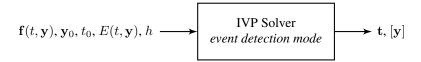
$6.13 \verb| forward_difference_approximation_v2|$



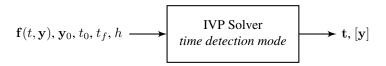
6.14 ivp_solver_block_diagram

$$\mathbf{f}(t, \mathbf{y}), \mathbf{y}_0, t_0, [termination condition], h \longrightarrow \text{IVP Solver}$$

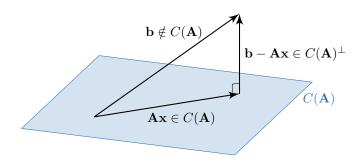
6.15 ivp_solver_block_diagram_event_detection_mode



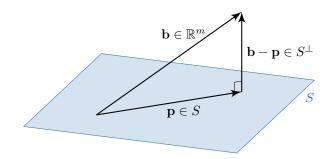
6.16 ivp_solver_block_diagram_time_detection_mode



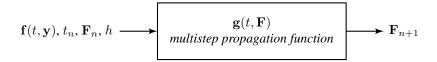
$6.17 \quad \texttt{least_squares_derivation_1}$



6.18 least_squares_derivation_2

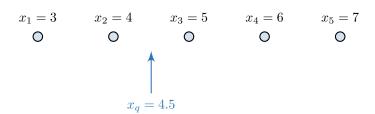


$6.19 \quad {\tt multistep_propagation_function}$

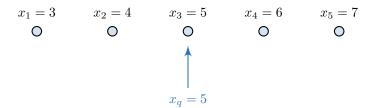


6.20 node_vector

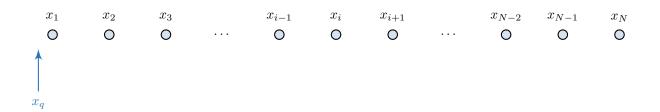
6.21 node_vector_example_v1



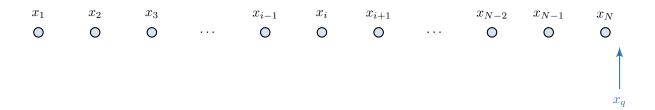
$6.20 \verb| node_vector_example_v2|$



6.23 node_vector_query_special_case_1

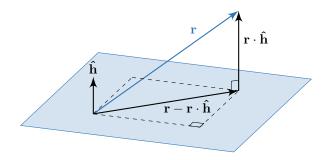


$6.24 \verb| node_vector_query_special_case_2|$

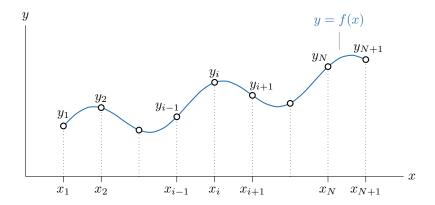


6.25 nonuniform_node_vector

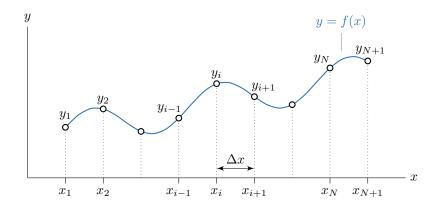
6.26 projection_onto_plane



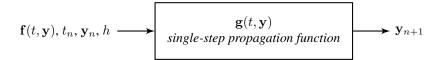
$6.27 \quad {\tt sampling_a_continuous_function_over_a_grid}$

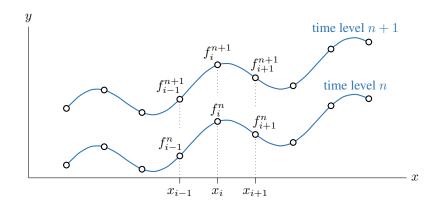


$6.28 \quad {\tt sampling_a_continuous_function_over_a_uniform_grid}$

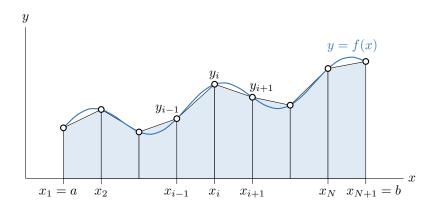


$6.29 \quad {\tt single_step_propagation_function}$





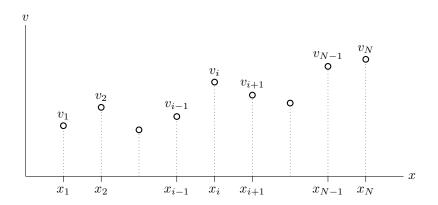
6.31 trapezoidal_rule



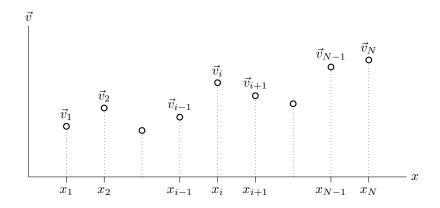
6.32 univariate_grid



6.33 univariate_scalar_valued_data

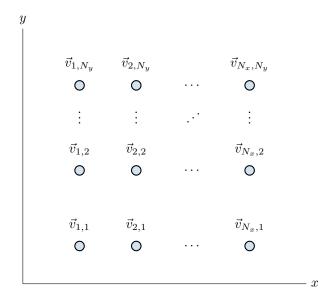


$6.34 \verb| univariate_vector_valued_data|$



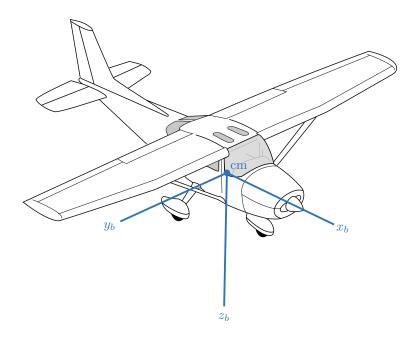
$6.35 \quad {\tt values_on_a_1D_grid}$

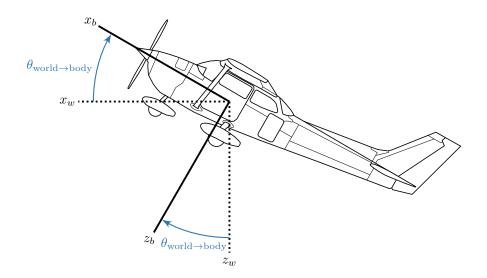




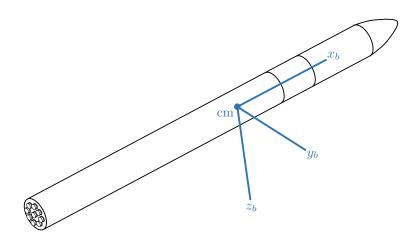
7 rotations_and_attitude

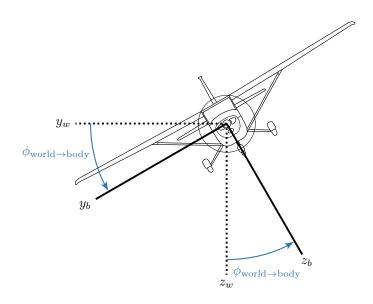
7.1 airplane_body_frame



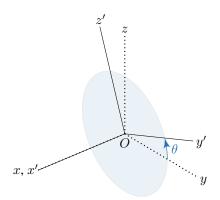


7.3 rocket_body_frame

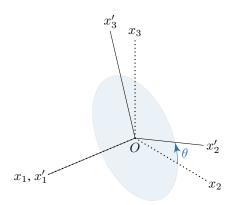




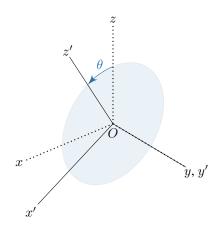
7.5 rotation_about_1st_axis_v1



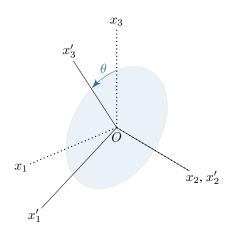
7.6 rotation_about_1st_axis_v2



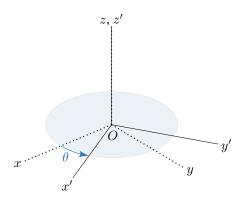
7.7 rotation_about_2nd_axis_v1

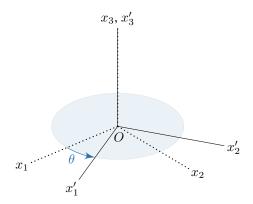


7.8 rotation_about_2nd_axis_v2

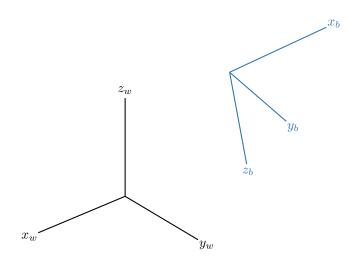


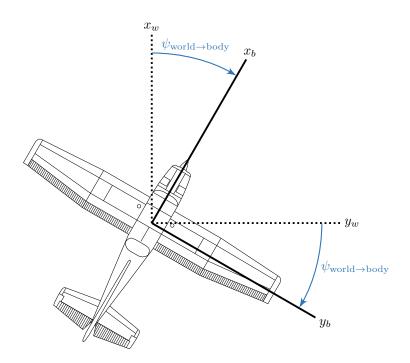
7.9 rotation_about_3rd_axis_v1





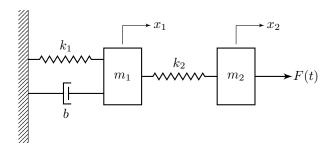
$7.11 \verb| world_and_body_frames|$



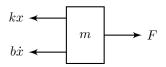


$8 \ \, \text{system_dynamics}$

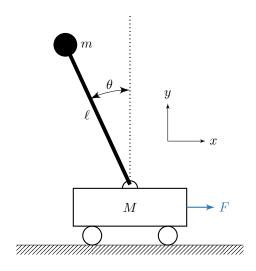
$8.1 \verb| coupled_mass_spring_damper_system|\\$



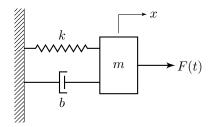
8.2 free_body_diagram_of_mass_spring_damper



8.3 inverted_pendulum_system

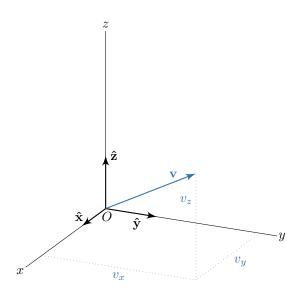


$8.4 \quad {\tt mass_spring_damper_system}$

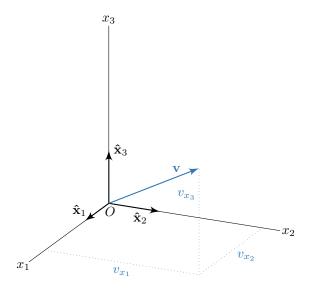


$9 \verb| vectors_and_coordinate_systems|$

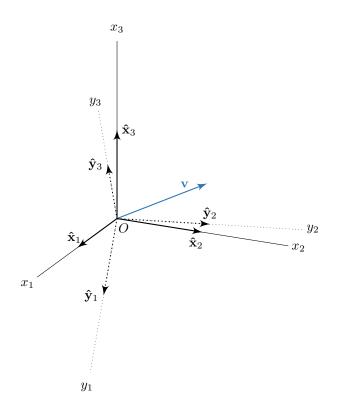
 $9.1 \verb| column_vector_in_a_coordinate_system_v1|$



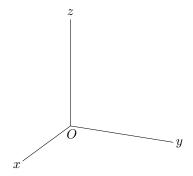
$9.2 \verb| column_vector_in_a_coordinate_system_v2|$



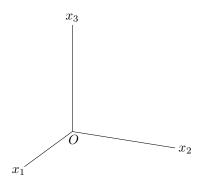
$9.3 \verb| column_vector_with_respect_to_two_coordinate_systems|$



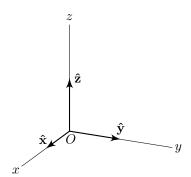
$9.4 \verb| coordinate_system_v1|$



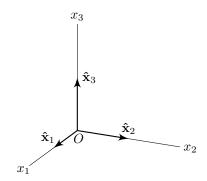
$9.5 \verb| coordinate_system_v2|$



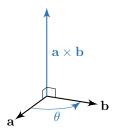
$9.6 \verb| coordinate_system_with_basis_vectors_v1|$



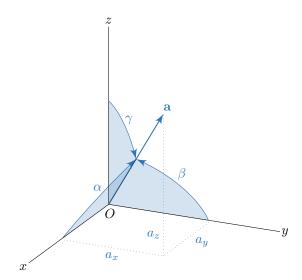
$9.7 \verb| coordinate_system_with_basis_vectors_v2|$



9.8 cross_product



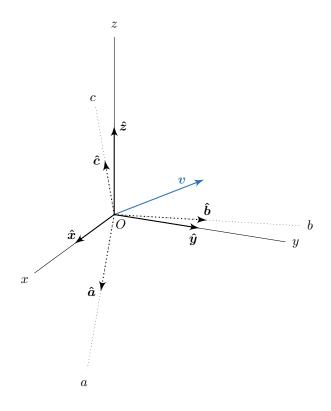
9.9 direction_angles



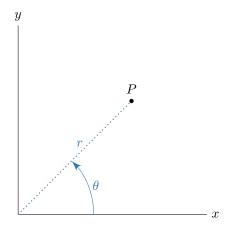
9.10 physical_vector



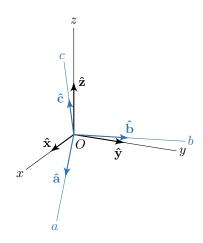
$9.11 \verb| physical_vector_with_respect_to_two_coordinate_frames|$



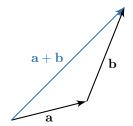
9.12 polar_coordinates



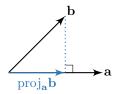
9.13 rotated_coordinate_systems



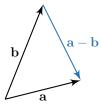
9.14 vector_addition



9.15 vector_projection



$9.16 \verb| vector_subtraction|$



$9.17 \verb| vectors_in_a_cartesian_coordinate_system|$

