Tridiagonal Matrix Algorithm (Thomas Algorithm)

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1 TRIDIAGONAL MATRIX ALGORITHM (THOMAS AL-GORITHM)

A tridiagonal linear system is one of the form

We can define the x and d vectors as

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_{n-1} \\ x_n \end{bmatrix}, \quad \mathbf{d} = \begin{bmatrix} d_1 \\ d_2 \\ \vdots \\ d_{n-1} \\ d_n \end{bmatrix}$$

and the $n \times n$ triadiagonal matrix¹, A, as

$$\mathbf{A} = \begin{bmatrix} b_1 & c_1 \\ a_1 & b_2 & c_2 \\ & a_2 & \ddots & \ddots \\ & & \ddots & \ddots & c_{n-2} \\ & & & a_{n-2} & b_{n-1} & c_{n-1} \\ & & & & a_{n-1} & b_n \end{bmatrix}$$
 (1)

Now we can write the tridiagonal linear system as

$$\mathbf{A}\mathbf{x} = \mathbf{d} \tag{2}$$

where $\mathbf{A} \in \mathbb{R}^{n \times n}$ and $\mathbf{x}, \mathbf{d} \in \mathbb{R}^n$.

The **tridiagonal matrix algorithm** (also known as the **Thomas algorithm**) is an algorithm that can efficiently solve the tridiagonal linear system (given by Eq. (2)) for x. This algorithm uses three vectors, a, b, and c, which we define as [1]

$$\mathbf{a} = \begin{bmatrix} a_1 \\ \vdots \\ a_{n-1} \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix}, \quad \mathbf{c} = \begin{bmatrix} c_1 \\ \vdots \\ c_{n-1} \end{bmatrix}$$

$$\mathbf{A} = \begin{bmatrix} a_1 & b_1 \\ c_1 & a_2 & b_2 \\ & c_2 & \ddots & \ddots \\ & & \ddots & \ddots & \\ & & \ddots & \ddots & b_{n-2} \\ & & & c_{n-2} & a_{n-1} & b_{n-1} \\ & & & & c_{n-1} & a_n \end{bmatrix}$$

When dealing with the tridiagonal matrix algorithm, a convention similar to the one in Eq. (1) is used almost exclusively. However, the convention that most sources have has the a_i 's ranging from a_2 to a_n , which is inconvenient from a programming standpoint; therefore, I defined them here as ranging from a_1 to a_{n-1} . This convention is also reflected in Algorithm 1.

In many references, a tridiagonal matrix is defined with the convention

The tridiagonal matrix algorithm is shown below [1-3].

Algorithm 1: tridiagonal

Tridiagonal matrix algorithm (Thomas algorithm).

Given: A, d

- $\mathbf{A} \in \mathbb{R}^{n \times n}$
- $\mathbf{d} \in \mathbb{R}^n$
- Corresponds to the tridiagonal linear system Ax = d.

Procedure:

- 1. Determine n (where $\mathbf{A} \in \mathbb{R}^{n \times n}$).
- 2. Preallocate vectors of size $n \times 1$ to store **b** and **x**.
- 3. Preallocate vectors of size $(n-1) \times 1$ to store a and c.
- 4. Extract a from A.

$$\label{eq:constraints} \begin{cases} \text{for } i=2 \text{ to } n \\ \\ \\ \\ a_{i-1}=A_{i,i-1} \end{cases}$$
 end

5. Extract **b** from **A**.

for
$$i = 1$$
 to n

$$b_i = A_{i,i}$$

6. Extract c from A.

for
$$i = 2$$
 to n

$$c_{i-1} = A_{i-1,i}$$
end

7. Forward elimination.

$$\begin{cases} \text{for } i = 1 \text{ to } n \\ w = a_{i-1}/b_{i-1} \\ b_i = b_i - wc_{i-1} \\ d_i = d_i - wd_{i-1} \end{cases}$$

8. Backward substitution.

for
$$i=n-1$$
 to 1 by -1
$$\begin{vmatrix} x_i=\left(d_i-c_ix_{i+1}\right)/b_i \\ \text{end} \end{vmatrix}$$

Return: x

• $x \in \mathbb{R}^n$, solution of linear system $\mathbf{A}\mathbf{x} = \mathbf{d}$

REFERENCES

- [1] James Hateley. *Linear Systems of Equations and Direct Solvers*. MATH 3620 Course Reader (Vanderbilt University). 2019.
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- [3] Tridiagonal matrix algorithm TDMA (Thomas algorithm). CFD Online. https://www.cfd-online.com/Wiki/Tridiagonal_matrix_algorithm_-_TDMA_(Thomas_algorithm) (accessed: January 9, 2021).