

Computing a Delaunay triangulation

Lecture 10

Antoine Vigneron

`antoine.vigneron@jouy.inra.fr`

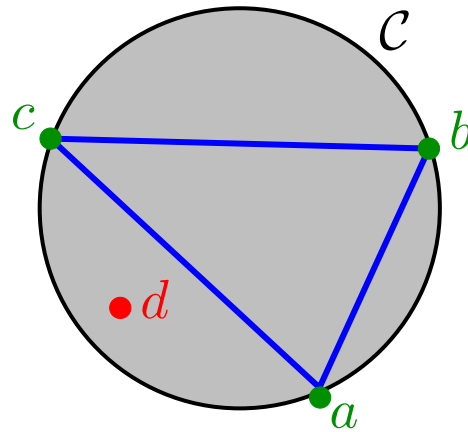
INRA

Outline

- RIC of the Delaunay triangulation
- optimal $O(n \log n)$ time randomized algorithm
- application: computing a Voronoi diagram
- references
 - D. Mount Lecture 18
 - textbook chapter 9
 - H. Edelsbrunner's book: Geometry and topology of mesh generation, chapter 1
 - demo (J. Snoeyink) at:
<http://www.cs.ubc.ca/spider/snoeyink/demos/crust/home.html>

Incircle test

Definition



$$\text{inCircle}(a, b, c, d) < 0$$

- assume triangle abc is counterclockwise
- let \mathcal{C} be the circumcircle of abc
- we want to design a test $\text{inCircle}(\cdot)$ such that
 - $\text{inCircle}(a, b, c, d) = 0$ if $d \in \mathcal{C}$
 - $\text{inCircle}(a, b, c, d) > 0$ if d is outside \mathcal{C}
 - $\text{inCircle}(a, b, c, d) < 0$ if d is inside \mathcal{C}

Expression

- we use the following expression:

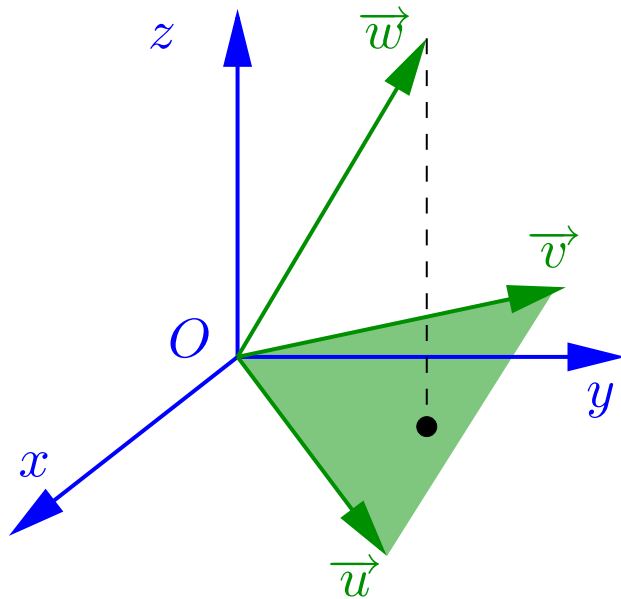
$$\text{inCircle}(a, b, c, d) = \det \begin{pmatrix} 1 & a_x & a_y & a_x^2 + a_y^2 \\ 1 & b_x & b_y & b_x^2 + b_y^2 \\ 1 & c_x & c_y & c_x^2 + c_y^2 \\ 1 & d_x & d_y & d_x^2 + d_y^2 \end{pmatrix}$$

- why does it work?
 - next ten slides: proof with geometric interpretation
 - D. Mount's notes 18: different proof, through algebra
 - be careful: we reversed the sign of $\text{inCircle}(\cdot)$ with respect to D. Mount's notes, in order to simplify the following proof.

Orientation of vectors in \mathbb{R}^3

- the orientation of $(\vec{u}, \vec{v}, \vec{w})$ is given by the sign of

$$\det \begin{pmatrix} u_x & u_y & u_z \\ v_x & v_y & v_z \\ w_x & w_y & w_z \end{pmatrix}$$



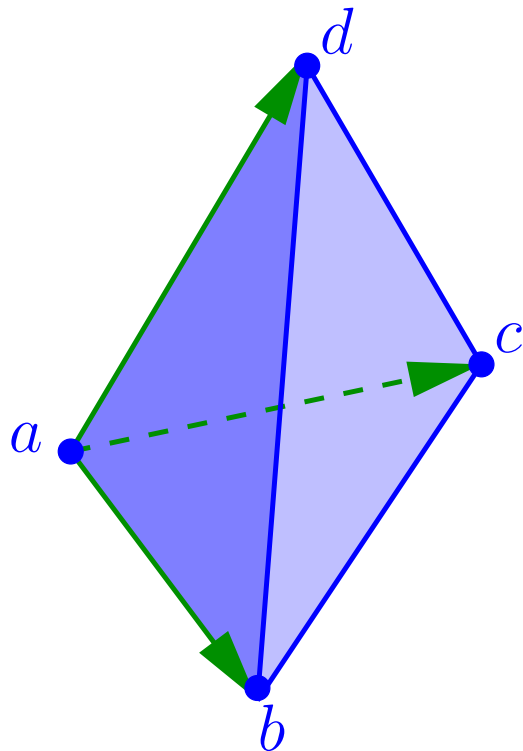
Orientation $(\vec{u}, \vec{v}, \vec{w}) > 0$

Orientation $(\vec{v}, \vec{u}, \vec{w}) < 0$

\Leftarrow right thumb rule

Orientation of a tetrahedron

- orientation of tetrahedron $abcd$ = orientation of $(\vec{ab}, \vec{ac}, \vec{ad})$



$$\text{Orientation}(abcd) = \text{Orientation}(\vec{ab}, \vec{ac}, \vec{ad}) > 0$$

\Leftarrow right thumb rule

Orientation of a tetrahedron

- Orientation $(abcd)$

$$= \det \begin{pmatrix} b_x - a_x & b_y - a_y & b_z - a_z \\ c_x - a_x & c_y - a_y & c_z - a_z \\ d_x - a_x & d_y - a_y & d_z - a_z \end{pmatrix}$$

$$= \det \begin{pmatrix} 1 & a_x & a_y & a_z \\ 0 & b_x - a_x & b_y - a_y & b_z - a_z \\ 0 & c_x - a_x & c_y - a_y & c_z - a_z \\ 0 & d_x - a_x & d_y - a_y & d_z - a_z \end{pmatrix}$$

- why?
- Develop with respect to first column

Orientation of a tetrahedron

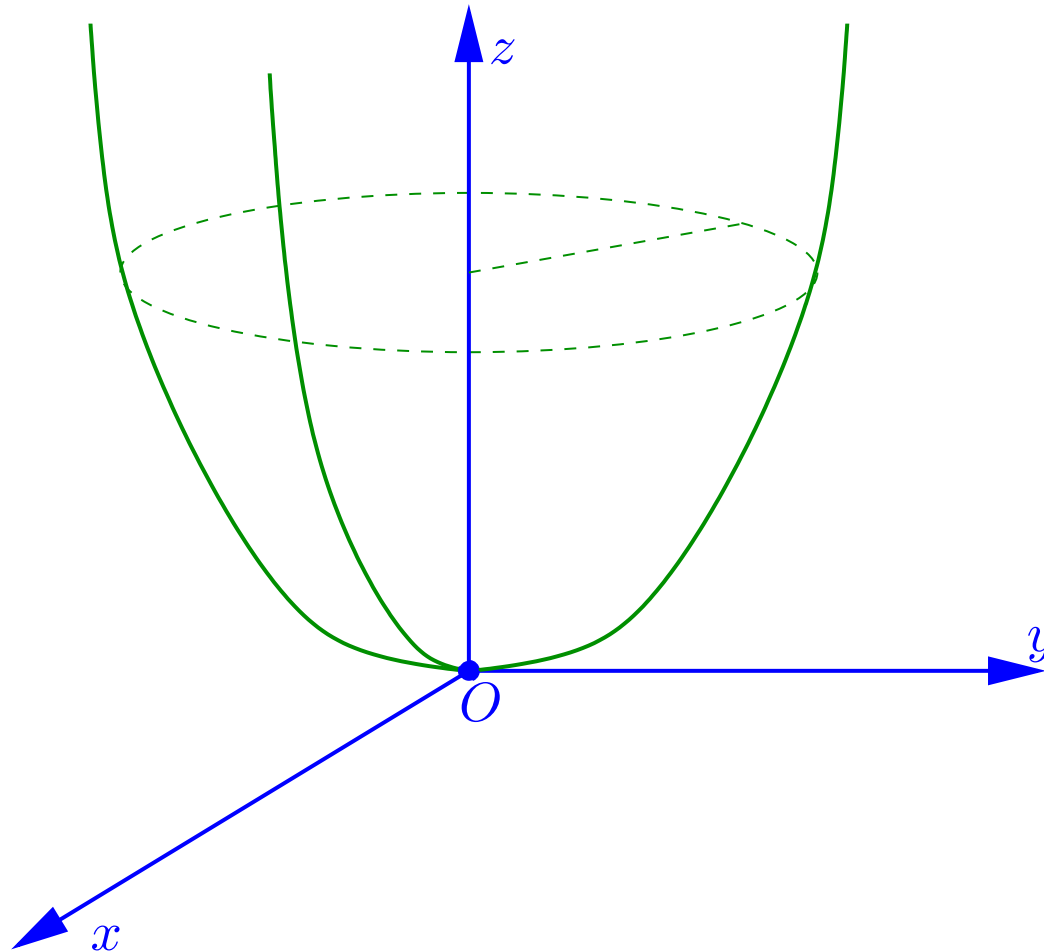
- add first row to the other rows
- Orientation $(abcd)$

$$= \det \begin{pmatrix} 1 & a_x & a_y & a_z \\ 1 & b_x & b_y & b_z \\ 1 & c_x & c_y & c_z \\ 1 & d_x & d_y & d_z \end{pmatrix}$$

- note that it generalizes the counterclockwise (CCW) predicate in \mathbb{R}^2 (see lecture 1)

Paraboloid \mathcal{P}

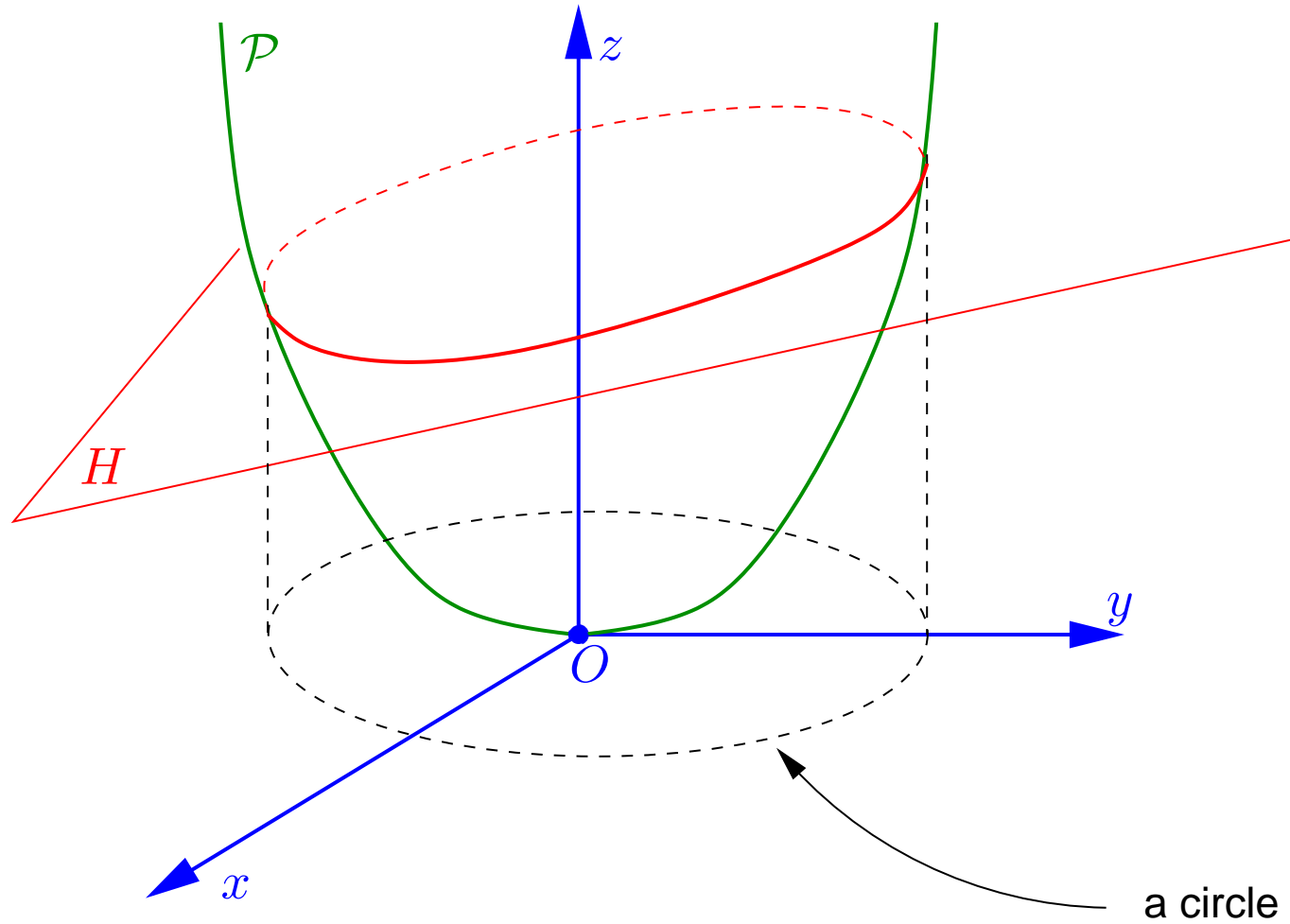
- in \mathbb{R}^3 , let \mathcal{P} be the paraboloid with equation $z = x^2 + y^2$



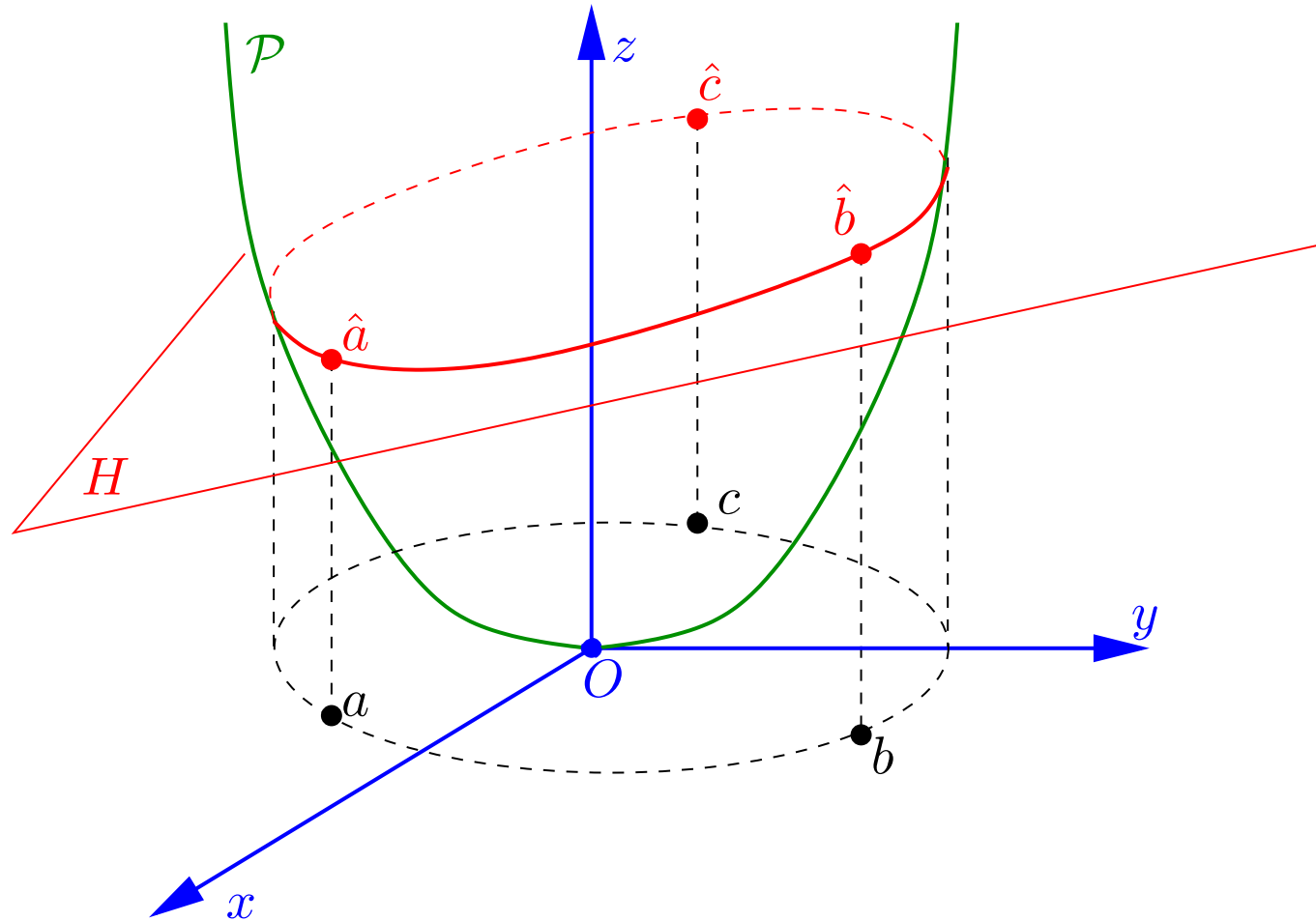
Property

- let H be a non-vertical plane
- H has equation $z = \alpha x + \beta y + \gamma$
- the projection of $H \cap \mathcal{P}$ onto plane Oxy has equation $x^2 + y^2 = \alpha x + \beta y + \gamma$
 - this is a circle
- property: the projection of $H \cap \mathcal{P}$ onto plane Oxy is a circle

Property



Proof



Proof

- let $p = (p_x, p_y)$
- we lift p onto \mathcal{P} and obtain $\hat{p} = (p_x, p_y, p_x^2 + p_y^2)$
- the transformation $p \rightarrow \hat{p}$ is called the *lifting map*

Proof

- we lift a, b, c and d :

$$\hat{a} = (a_x, a_y, a_x^2 + a_y^2)$$

$$\hat{b} = (b_x, b_y, b_x^2 + b_y^2)$$

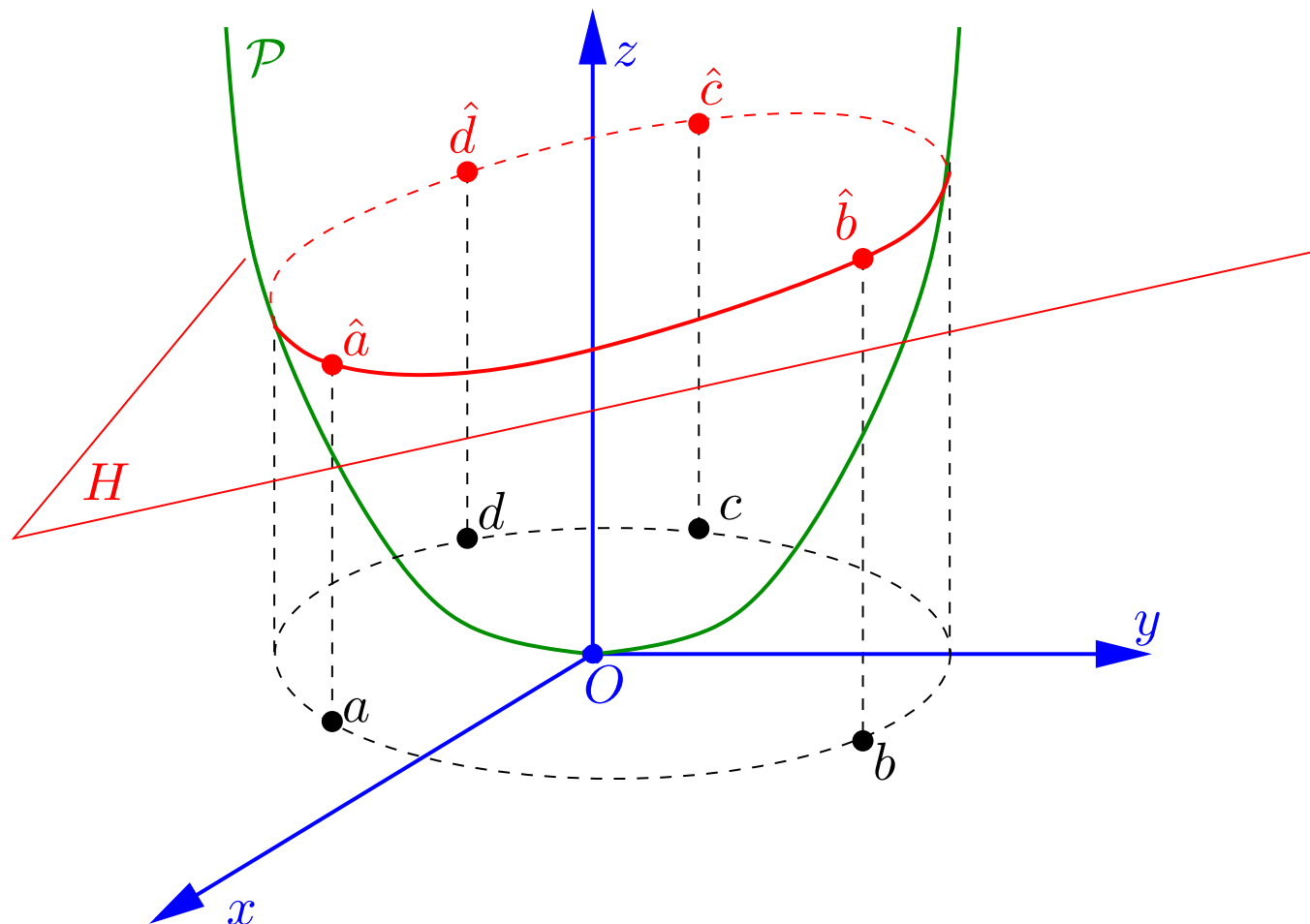
$$\hat{c} = (c_x, c_y, c_x^2 + c_y^2)$$

$$\hat{d} = (d_x, d_y, d_x^2 + d_y^2)$$

- we denote by H the plane through $\{\hat{a}, \hat{b}, \hat{c}\}$
- $\text{inCircle}(a, b, c, d) = 0$ means that
 $\text{Orientation}(\hat{a}, \hat{b}, \hat{c}, \hat{d}) = 0$
 - so $\hat{d} \in H$
 - we project to horizontal
 - we obtain that d is in the circumcircle of abc

Proof: first case

- a, b, c, d cocircular if $\hat{a}, \hat{b}, \hat{c}, \hat{d}$ coplanar

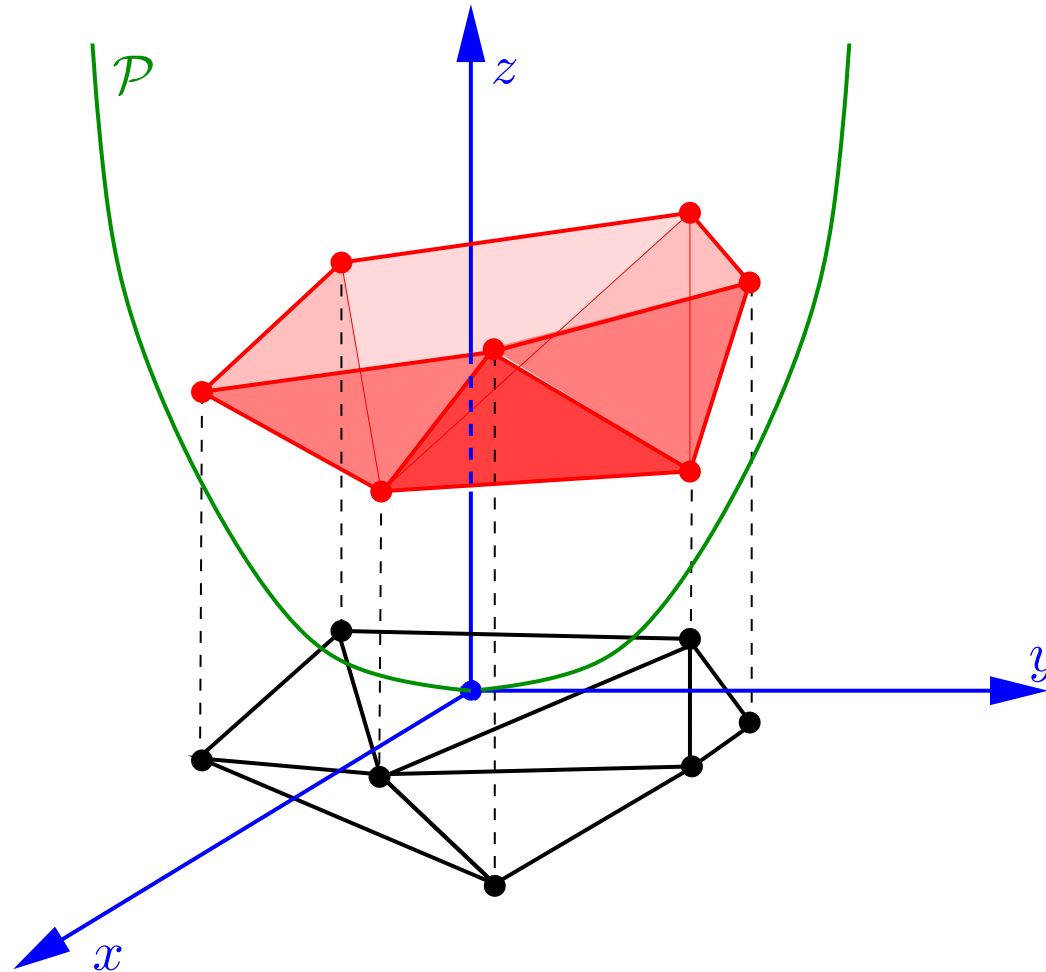


Proof: other cases

- $\text{inCircle}(a, b, c, d) > 0$ means that $\text{Orientation}(\hat{a}, \hat{b}, \hat{c}, \hat{d}) > 0$
 - then \hat{d} is above H
 - so d is outside the circumcircle of abc
- $\text{inCircle}(a, b, c, d) < 0$ means that $\text{Orientation}(\hat{a}, \hat{b}, \hat{c}, \hat{d}) < 0$
 - then \hat{d} is below H
 - so d is inside the circumcircle of abc

New interpretation of the Delaunay triangulation

Lifting $\mathcal{DT}(P)$

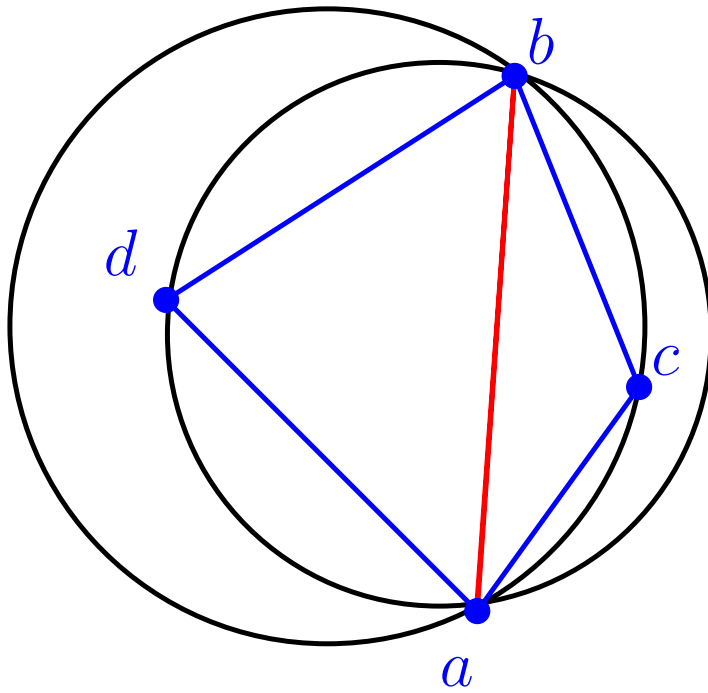


Circumcircle property

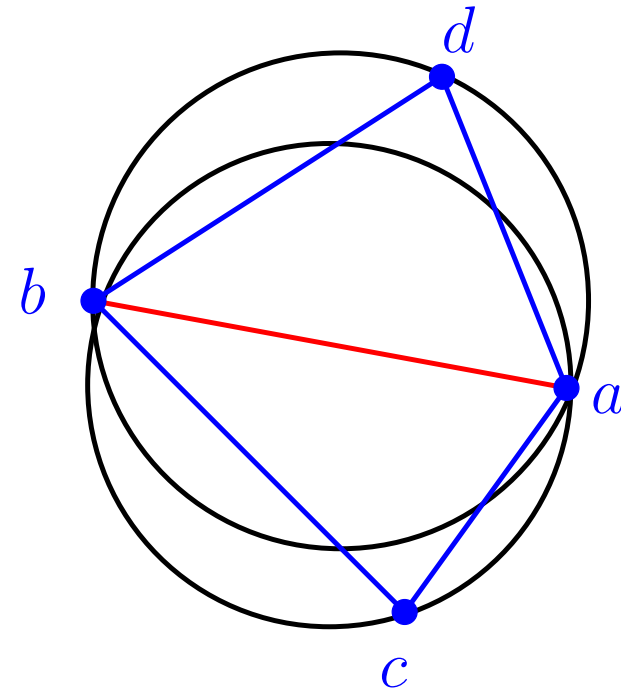
- $P = \{p_1, p_2, \dots, p_n\}$ is a set of points in the plane in general position
- we denote $\hat{P} = \{\hat{p}_1, \hat{p}_2, \dots, \hat{p}_n\}$
- last lecture: triangle $p_i p_j p_k$ is a face of $\mathcal{DT}(P)$ iff its circumcircle is empty
 - it means that $\forall p \in P \setminus \{p_i, p_j, p_k\}$, \hat{p} is above the plane through $\hat{p}_i \hat{p}_j \hat{p}_k$
 - in other words, $\hat{p}_i \hat{p}_j \hat{p}_k$ is a facet of the lower hull of \hat{P}
- Theorem: $\mathcal{DT}(P)$ is the projection of the edges of the lower hull of \hat{P} onto the plane $z = 0$

Edge flip

Property



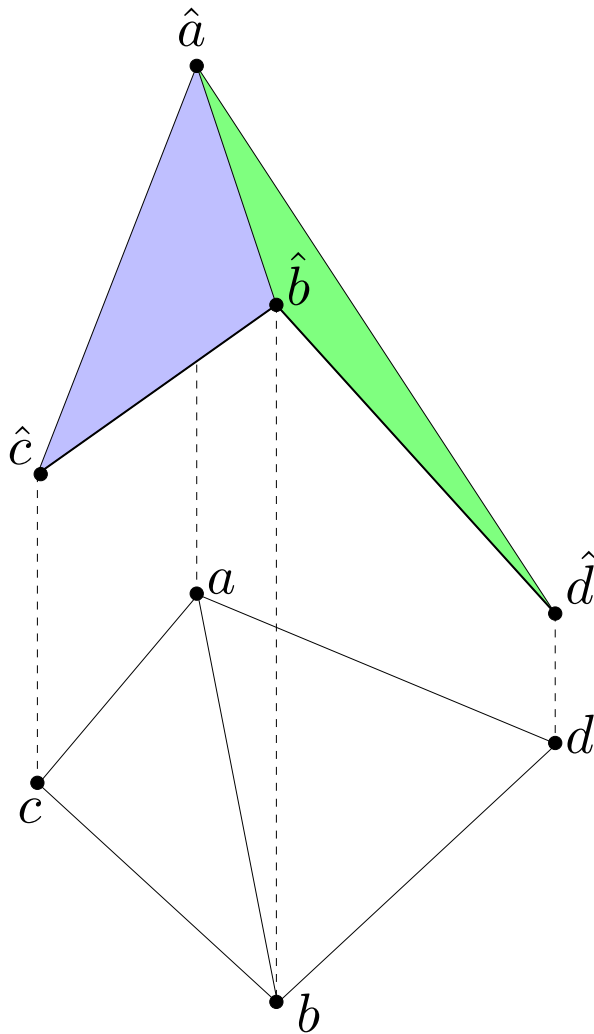
or



Property

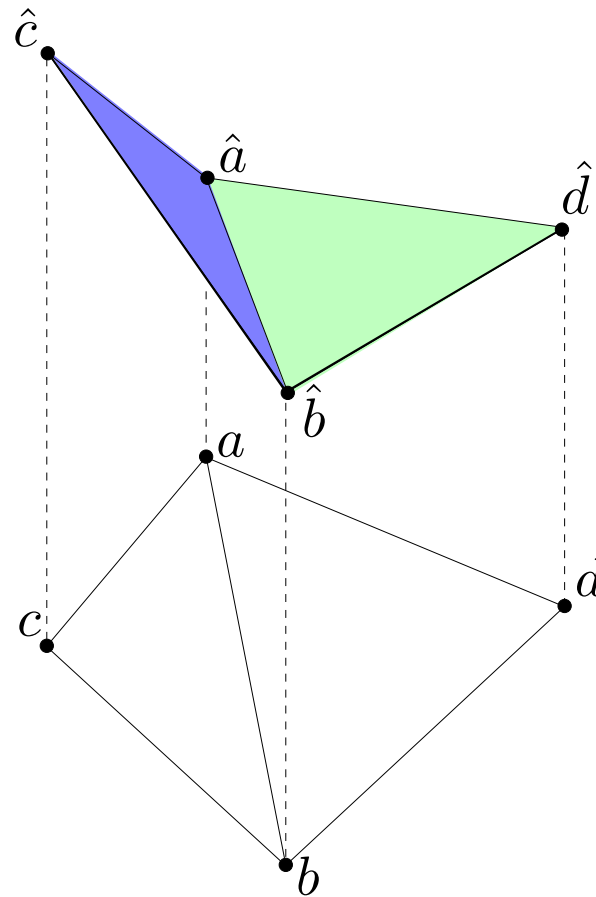
- let $acbd$ be a quadrilateral with diagonal \overline{ab}
- then either
 - c is inside the circumcircle of abd and d is inside the circumcircle of abc
 - or c is outside circumcircle of abd and d is outside the circumcircle of abc

Proof (by picture)



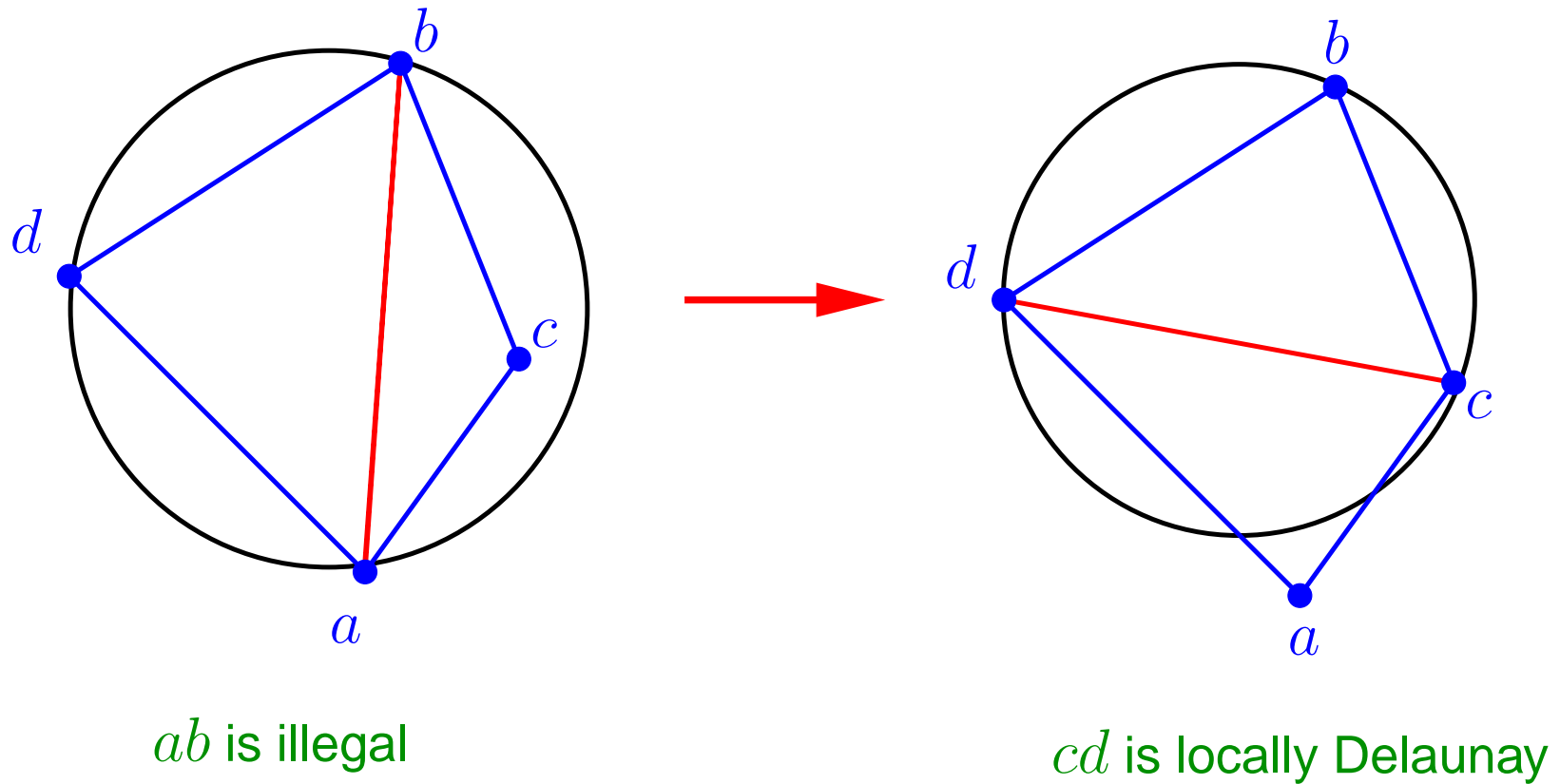
Concave

OR



Convex

Edge flip: definition

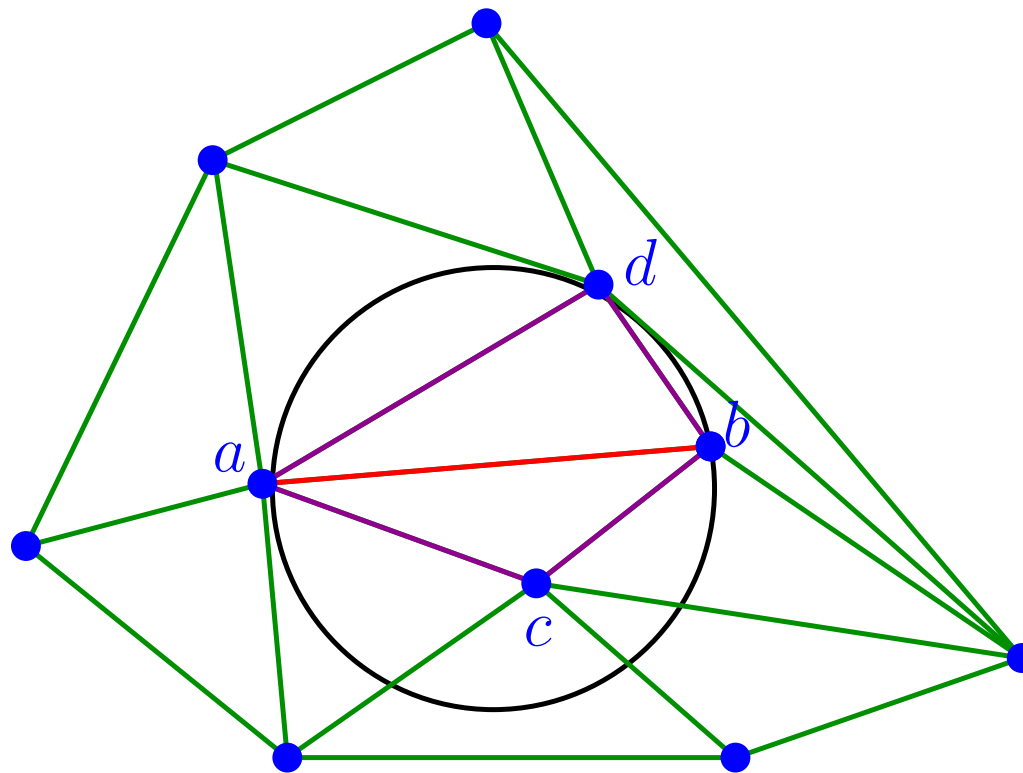


Definitions

- let P be a set of n points in \mathbb{R}^2
- P is in general position: no 4 points are cocircular
- let \mathcal{T} be a triangulation of P
- let ab be an edge of \mathcal{T}
- let $(c, d) \in P^2$ such that abc and abd are triangles of \mathcal{T}
- ab is *locally Delaunay* iff d is outside the circumcircle of abc
- ab is *illegal* iff d is inside the circumcircle of abc
- note that we can decide whether ab is locally Delaunay or illegal by computing the sign of $CCW(abc)$ and the sign of $\text{inCircle}(a, b, c, d)$

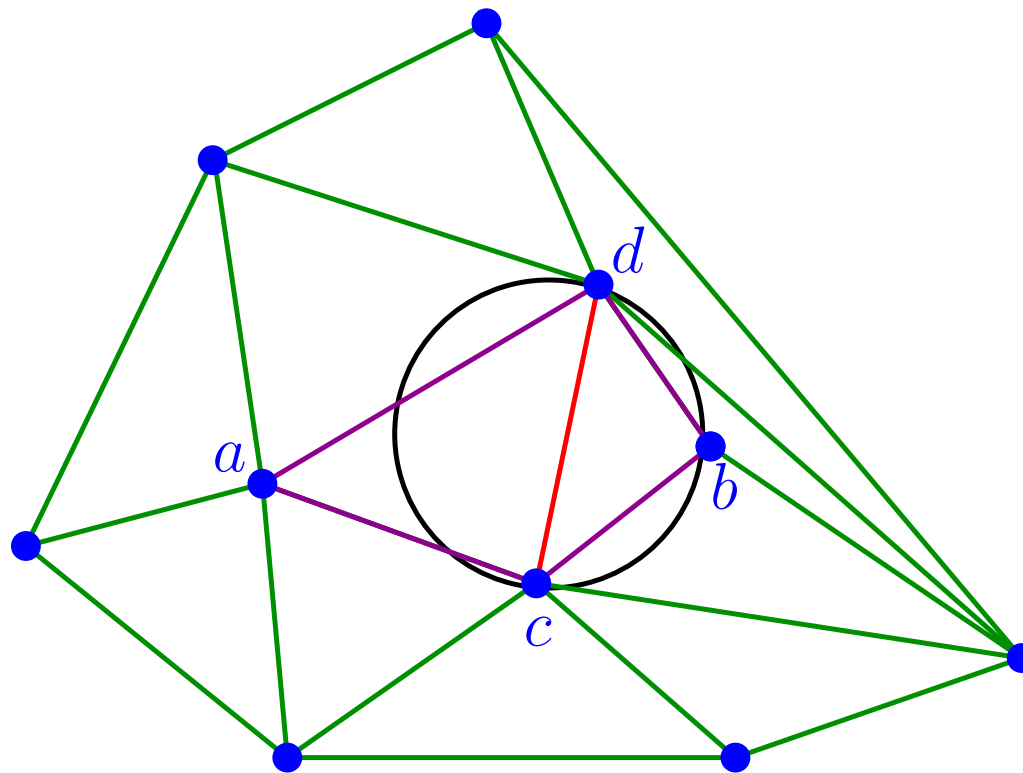
Definition

- if ab is illegal, we can perform an *edge flip*:
remove ab from \mathcal{T} and insert cd
- now cd is locally Delaunay

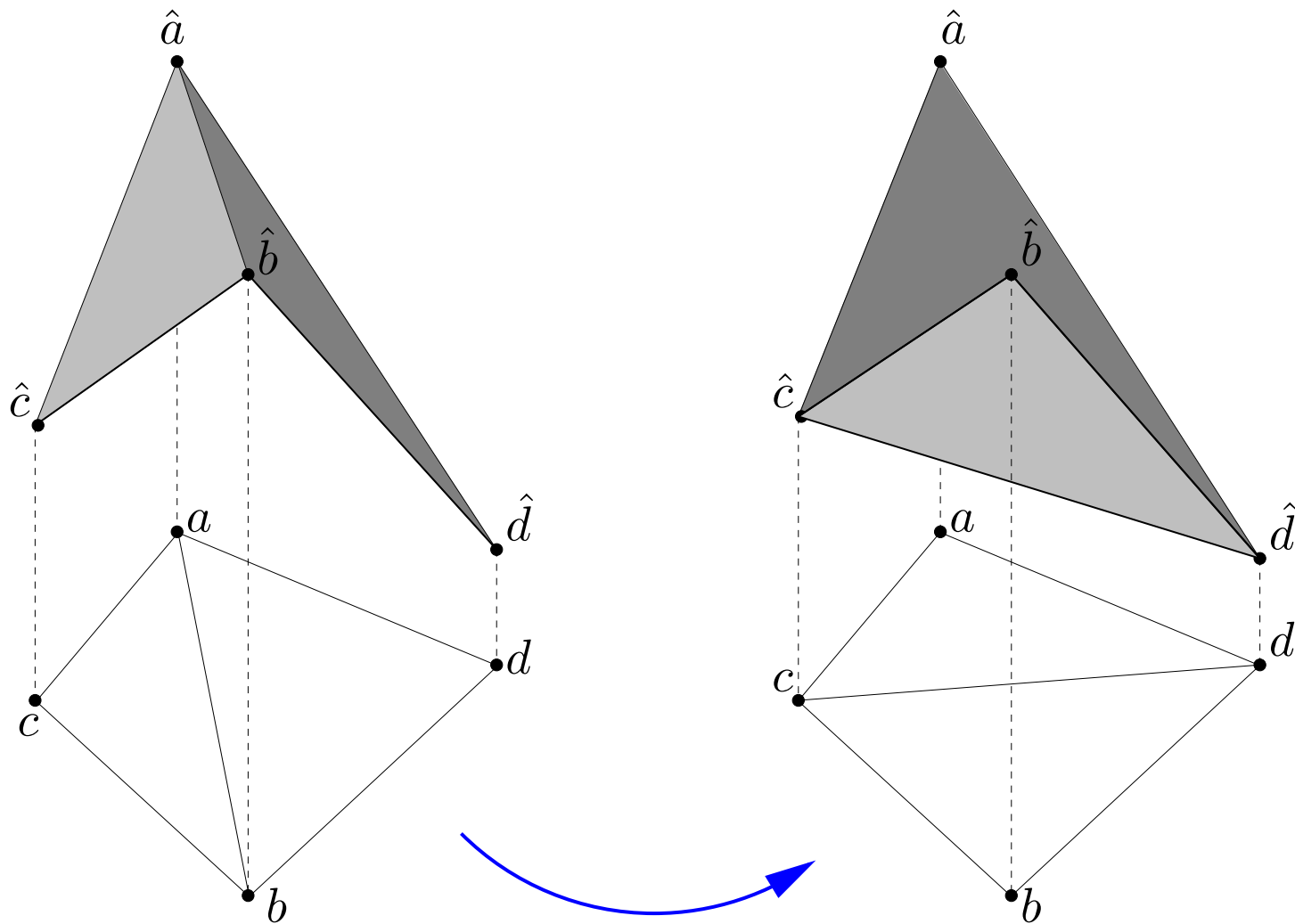


Definition

- if ab is illegal, we can perform an *edge flip*:
remove ab from \mathcal{T} and insert cd
- now cd is locally Delaunay



Edge flip: interpretation



the lifted triangulation gets lower
the upper envelope becomes convex

A first algorithm

Theorem

- let \mathcal{T} be a triangulation of P
- $\mathcal{T} = \mathcal{DT}(P)$ iff all the edges of \mathcal{T} are locally Delaunay
- proof:
 - if \mathcal{T} is Delaunay, then clearly all edges are locally Delaunay (by definition)
 - other direction: non trivial
 - see textbook Theorem 9.8
 - or use the lifting map: locally Delaunay \Leftrightarrow locally convex \Leftrightarrow globally convex \Leftrightarrow globally Delaunay

Idea

- draw a triangulation \mathcal{T} of P
- if all the edges of \mathcal{T} are locally Delaunay, we are done
- otherwise, pick an illegal edge and flip it
- repeat this process until all edges are locally Delaunay

Pseudocode

Algorithm *SlowDelaunay*(P)

Input: a set P of n points in \mathbb{R}^2

Output: $DT(P)$

1. compute a triangulation \mathcal{T} of P
2. initialize a stack containing all the edges of \mathcal{T}
3. **while** stack is non-empty
4. **do** pop ab from stack and unmark it
5. **if** ab is illegal **then**
6. **do** flip ab to cd
7. **for** $xy \in \{ac, cb, bd, da\}$
8. **do if** xy is not marked
9. **then** mark xy and push it on stack
10. **return** \mathcal{T}

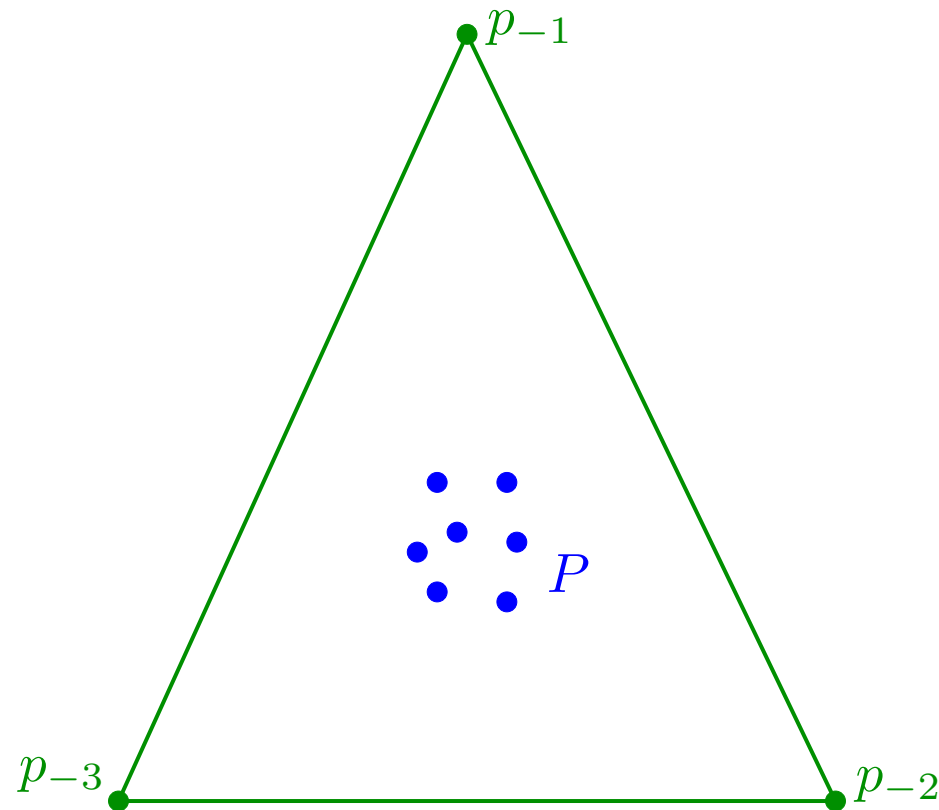
Analysis

- it is not obvious that this program halts!
- in fact runs in $\Theta(n^2)$ time
- proof using lifting map
 - each time we flip an edge, the lifted triangulation gets lower
 - so an edge can be flipped only once: afterward it remains above the lifted triangulation
 - there are $O(n^2)$ edges
 - so the algorithm runs in $O(n^2)$ time
 - lower bound left as an exercise

Randomized incremental algorithm

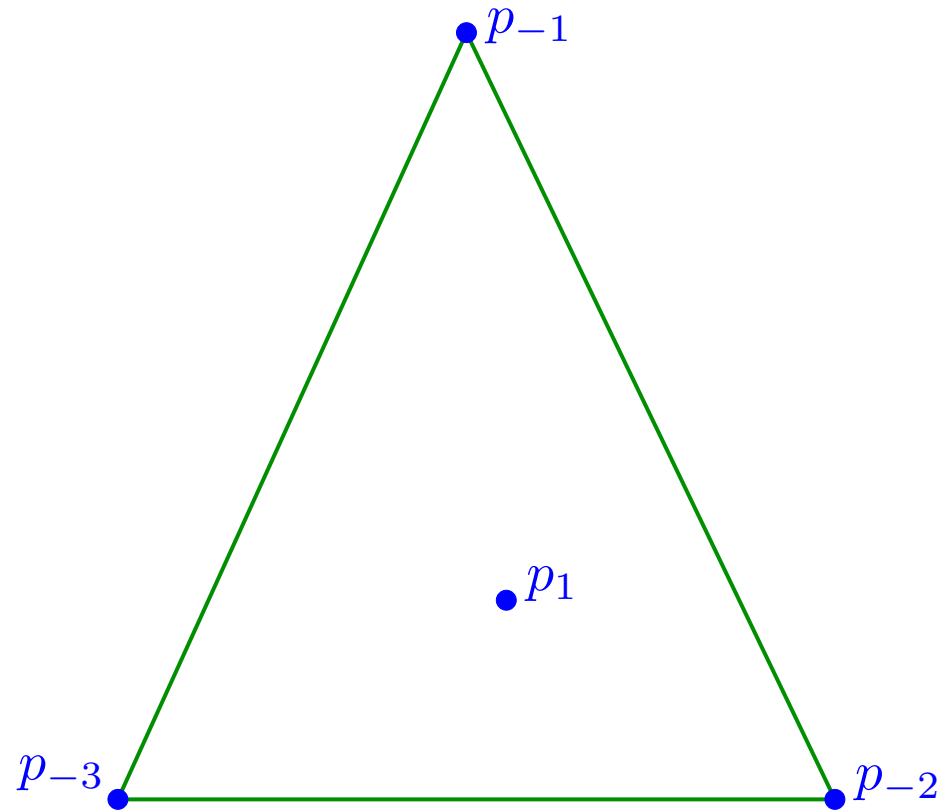
Preliminary

- let $(p_1, p_2, p_3 \dots p_n)$ be a random permutation of P
- let $p_{-3}p_{-2}p_{-1}$ be a large triangle containing P

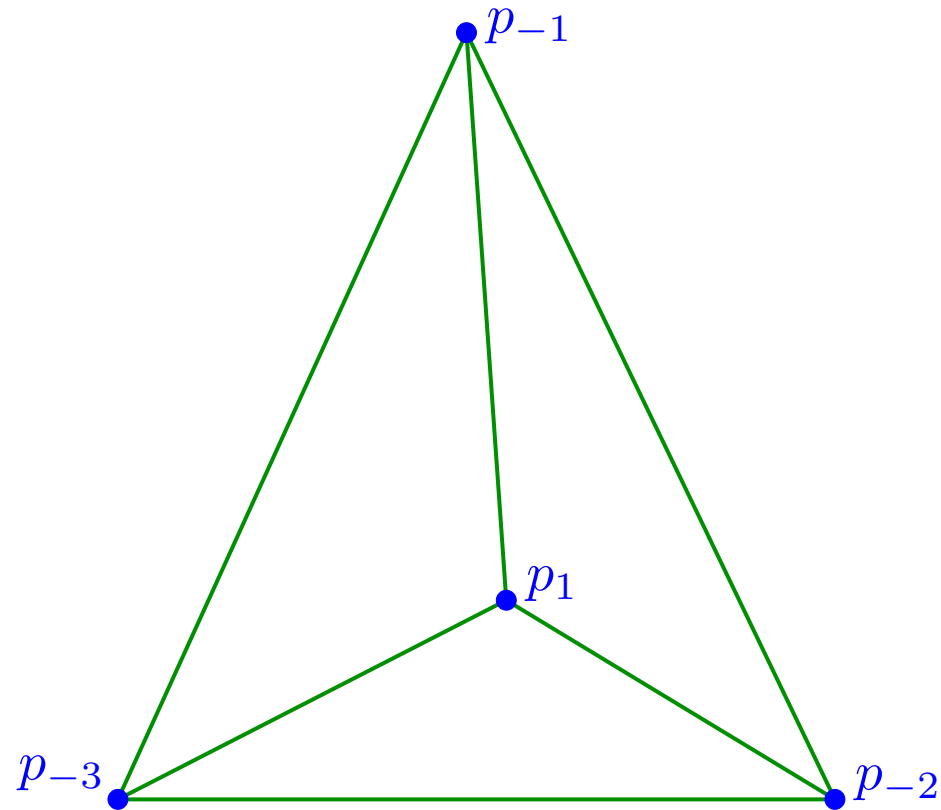


- for all i we denote $P_i = \{p_{-3}, p_{-2}, p_{-1}, p_1, p_2, \dots p_i\}$

First step



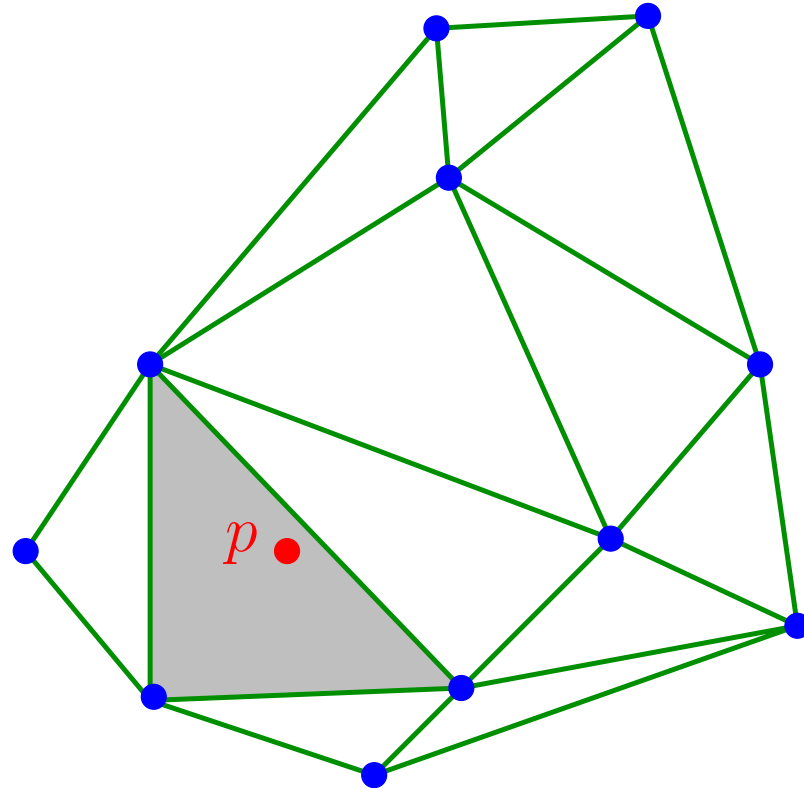
First step



Idea

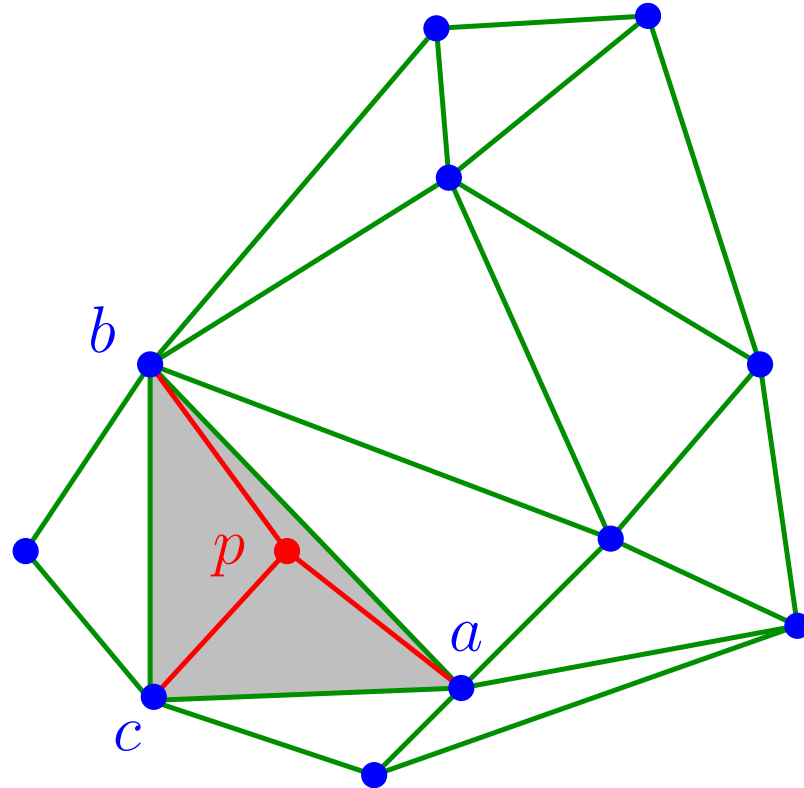
- insert p_1 , then $p_2 \dots$ and finally p_n
- suppose we have computed $\mathcal{DT}(P_{i-1})$
- insert $p_i \Rightarrow$ splits a triangle into three
 - find this triangle using conflict lists
 - each non inserted point has a pointer to the triangle in $\mathcal{DT}(P_{i-1})$ that contains it
 - each triangle in $\mathcal{DT}(P_{i-1})$ is associated with the list of all the non-inserted points that it contains
- perform edge flips until no illegal edge remains
 - we only need to perform flips around p_i
 - on average, this step takes constant time
- we have just computed $\mathcal{DT}(P_i)$
- repeat the process until $i = n$

Example



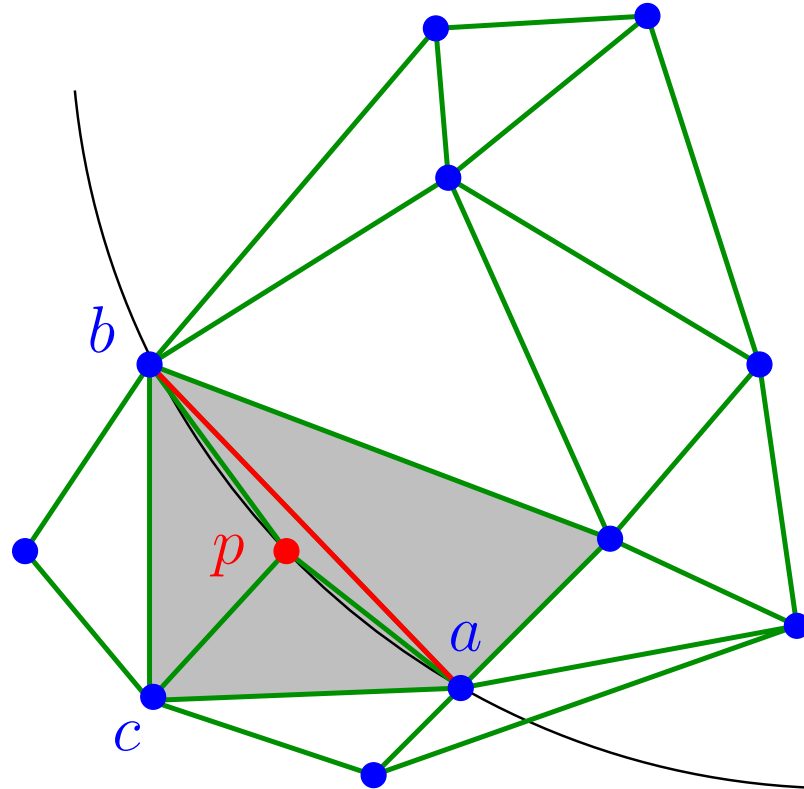
- inserting p_i
- to simplify the notations, we denote $p = p_i$
- we do not draw $p_{-1}p_{-2}p_{-3}$

Example



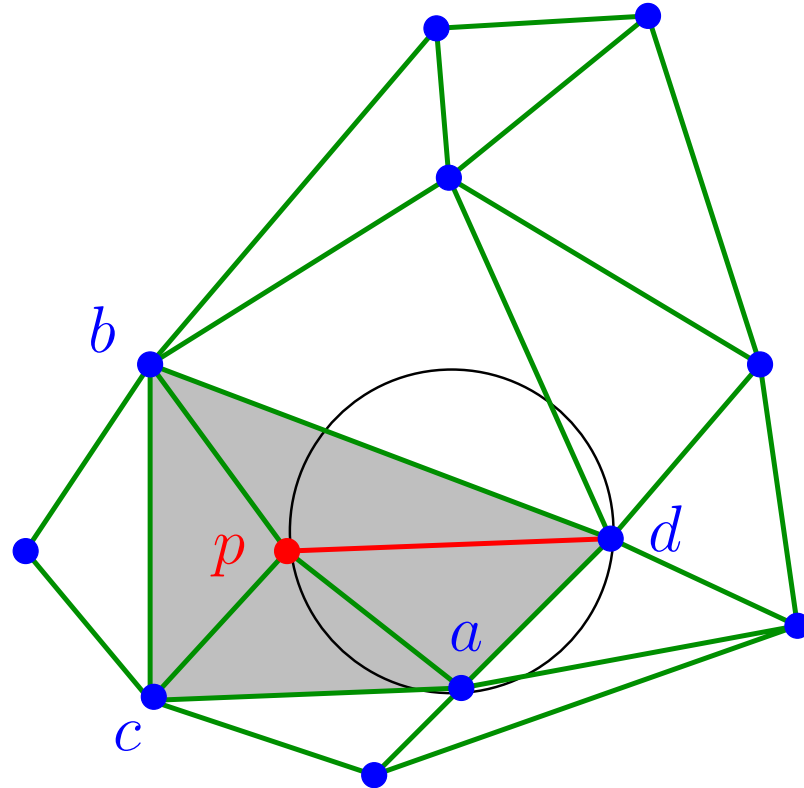
- use the pointer from p to the triangle abc that contains it
- split abc into abp , bcp and cap
- split the conflict list of abc accordingly

Example



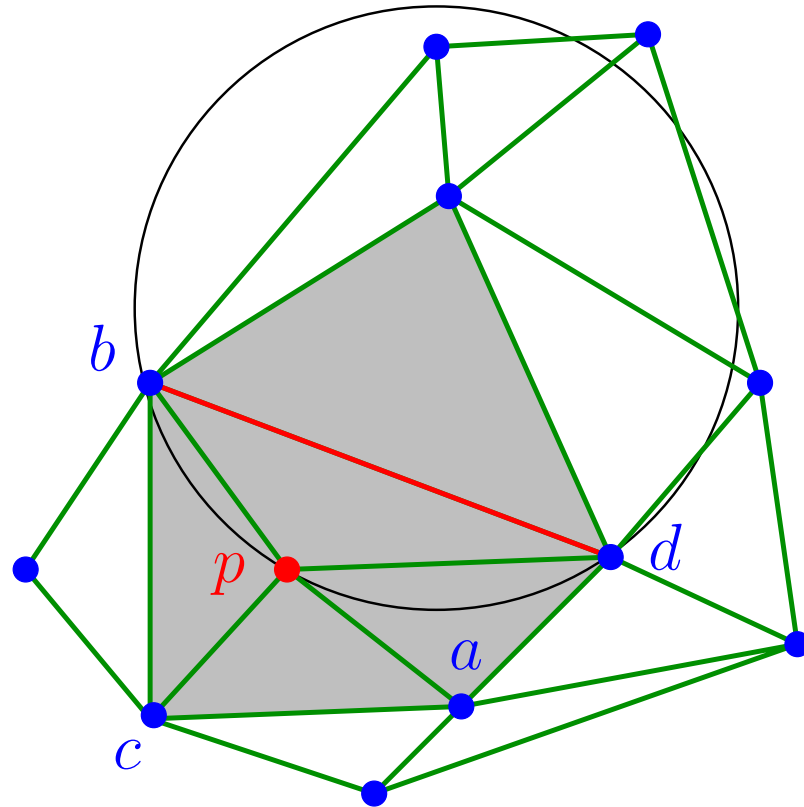
- edge ab is illegal
- flip it

Example



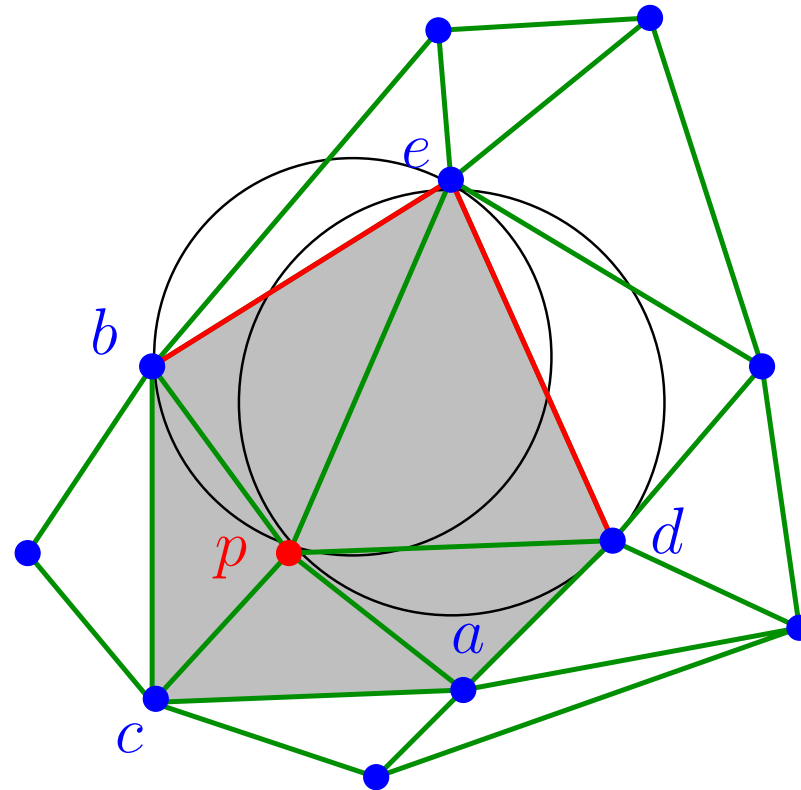
- edge ab has been flipped into pd
- ad is locally Delaunay, we keep it

Example



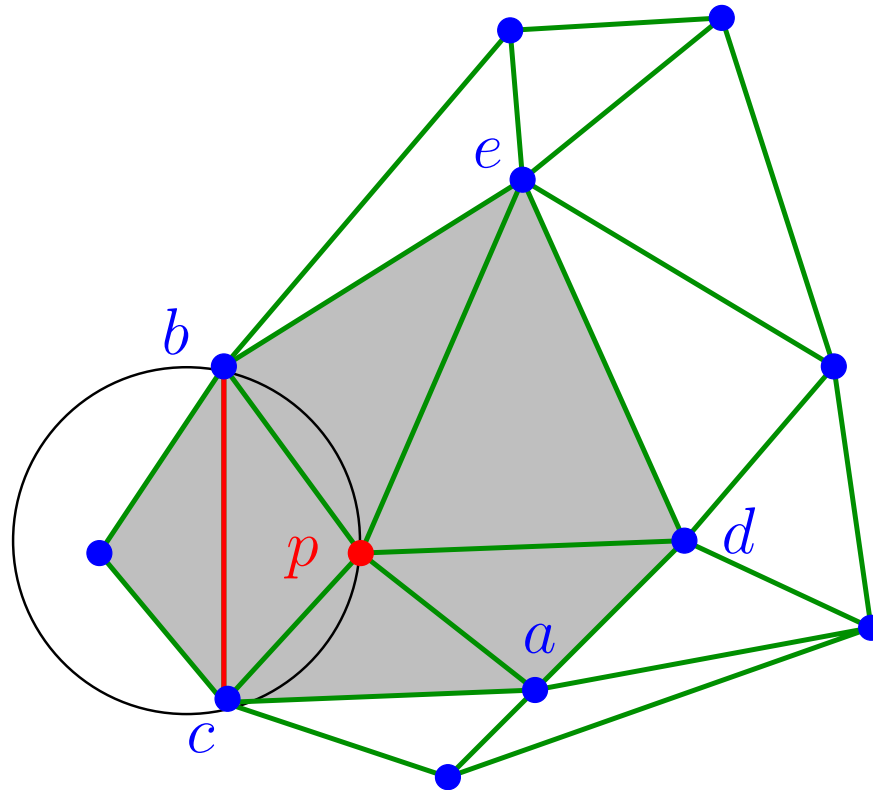
- edge bd is illegal

Example



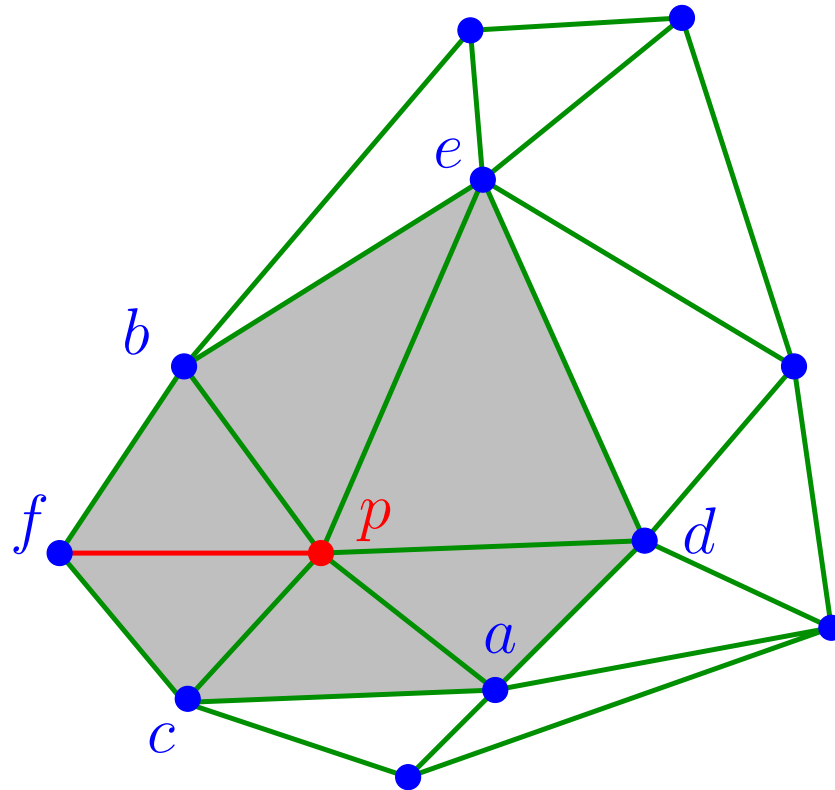
- edge bd has been flipped into pe
- edges de and be are locally Delaunay, we keep them

Example



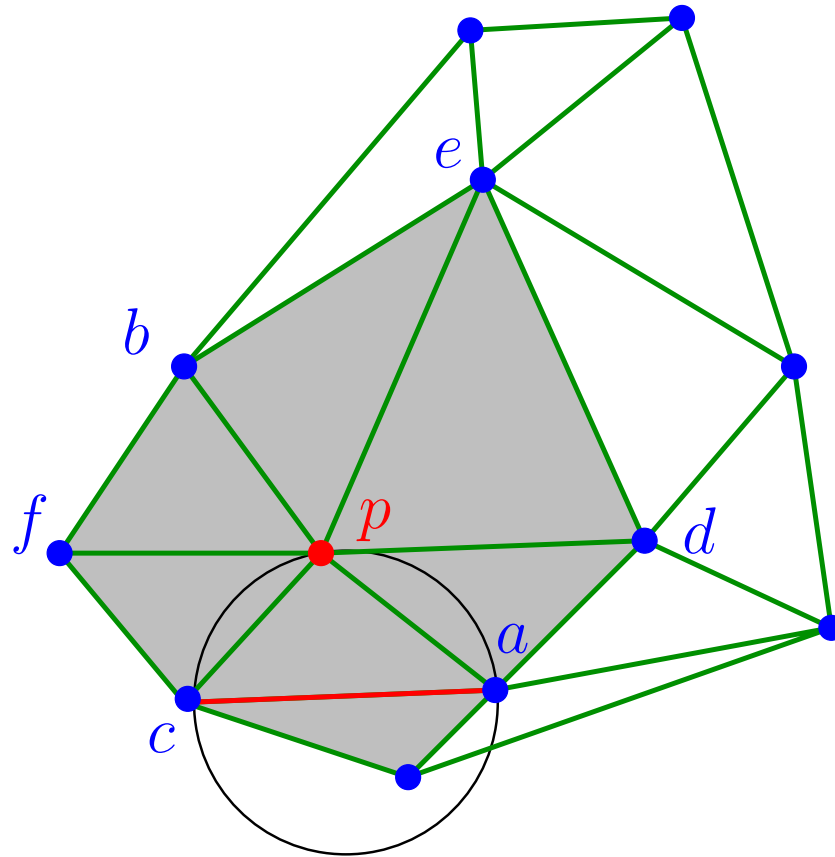
- edge bc is illegal

Example



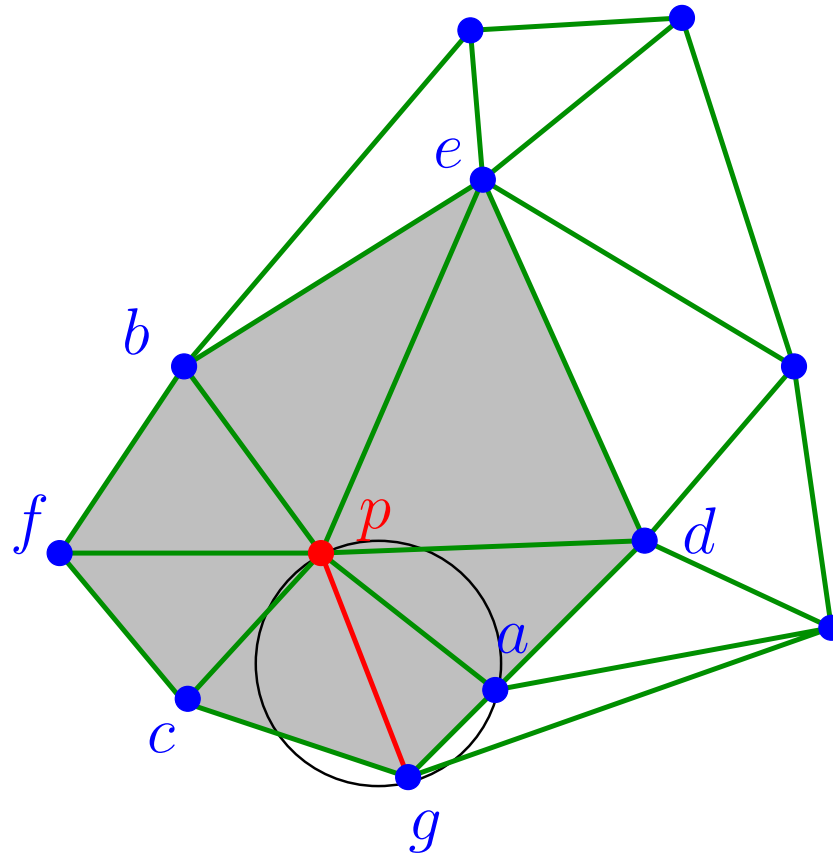
- edge bc has been flipped into pf

Example



- edge ac is illegal

Example



- edge ag is locally Delaunay
- no more edge to flip: we are done

Explanation

- we considered triangles in counterclockwise order around p and flipped illegal edges
- why is it enough to consider only triangles adjacent to p ?
- see proof later
- the pseudocode for this algorithm is very simple
- see next slide

Pseudocode

Algorithm *Insert*(p)

Input: a point p , a set of point P and $\mathcal{T} = \mathcal{DT}(P)$

Output: $\mathcal{DT}(P \cup \{p\})$

1. Find the triangle abc of $\mathcal{DT}(P \cup \{p\})$ containing p
(* use reverse pointers from conflict lists *)
(* abc is chosen to be counterclockwise *)
2. Insert edges pa, pb and pc
(* it includes conflict lists updates *)
3. *SwapTest*(ab)
(* pseudocode of this procedure next slide *)
4. *SwapTest*(bc)
5. *SwapTest*(ca)

Pseudocode

Algorithm *SwapTest(ab)*

1. **if** ab is an edge of the exterior face
2. **do return**
3. $d \leftarrow$ the vertex to the right of edge ab
4. **if** $\text{inCircle}(p, a, b, d) < 0$
5. **do Flip edge** ab for pd
- (* it includes conflict lists update *)
6. $\text{SwapTest}(ad)$
7. $\text{SwapTest}(db)$

Proof

- we only flipped edges of triangles that contain p
- why is it sufficient?
- remember Theorem slide 26: locally Delaunay implies Delaunay
- any edge between two triangles that do not contain p was locally Delaunay before insertion of p
- so it is still locally Delaunay
- thus the triangulation we obtain is the Delaunay triangulation

Analysis

- we look at t_i : time taken to update the current triangulation while inserting p_i
- it does not account for conflict lists updates
- each new edge (after splitting abc or after a flip) contains p_i
- so t_i is proportional to the degree of p_i in $\mathcal{DT}(p_i)$
 - degree of p_i : number of edges that contain p_i

Analysis

- we use backward analysis: P_i is fixed, p_i is random
- each edge has two vertices
- so each edge contains p_i with probability $\frac{2}{i}$
- there are $O(i)$ edges in the whole triangulation (by Euler formula)
- so by backward analysis

$$E[t_i] = \frac{O(i)}{i} = O(1)$$

- so the time for updating the triangulation is $O(n)$ over the course of the whole algorithm
- similar with trapezoidal map: what takes $\Theta(n \log n)$ time is the update of conflict lists (see next slide)

Analysis

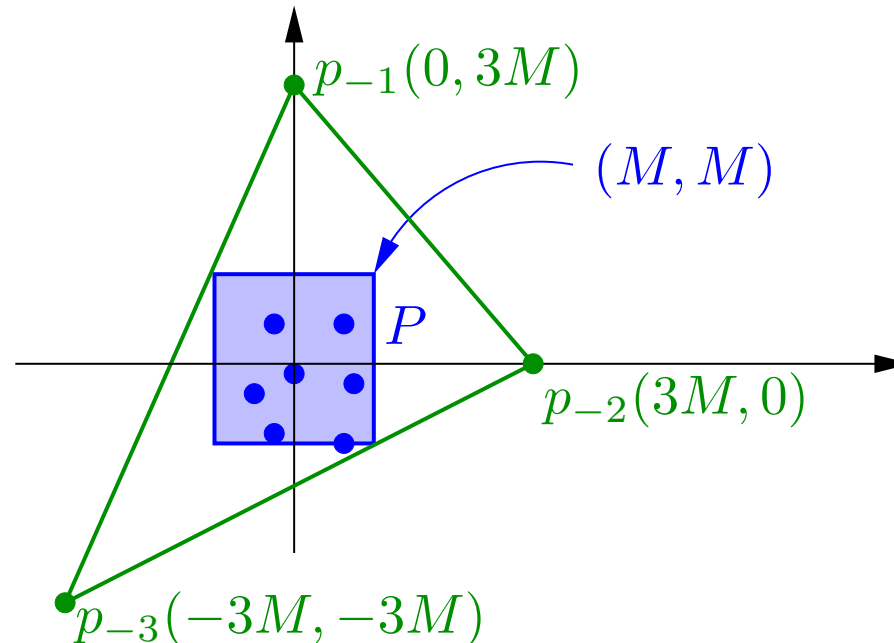
- while inserting p_i , what is the probability that $p \in P \setminus P_i$ is rebucketed?
- backward analysis
 - assume p is in triangle abc
 - this is the probability that $p_i \in \{a, b, c\}$
 - so it is $3/i$
- so while inserting p_i , we rebucket less than $3n/i$ sites on average

Analysis

- problem: a site may be rebucketed several times at step i
 - intuition: only a constant number of flips at each step so it only account for a constant factor
 - detailed proof in textbook
- so overall, rebucketing takes expected time

$$O\left(\sum_{i=1}^n \frac{n}{i}\right) = O(n \log n)$$

Choice of $p_{-1}p_{-2}p_{-3}$



- M : max of any coordinate of any point in P
- For incircle test, do as if these three points are outside any circle defined by three points in P

Conclusion

Conclusion

- the Delaunay triangulation of n points can be computed in expected time $O(n \log n)$
- it holds for worst case input, the expectation is over the random choices made by the algorithm
- it can also be done in $O(n \log n)$ deterministic time
- knowing the Delaunay triangulation of P , we can find the Voronoi diagram of P in $O(n)$ time
 - left as an exercise

Conclusion

- combining with the point location data structure of lecture 8, we can answer proximity queries in the plane (see lecture 9) with
 - $O(\log n)$ expected query time
 - $O(n \log n)$ expected preprocessing time
 - $O(n)$ expected space usage
- all these bounds can be made deterministic
 - harder, less practical