

1.

a)

b.

$$A = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{bmatrix}$$

$$AA^T = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\det(A - I\lambda) = 0$$

$$\det \begin{pmatrix} \frac{1}{\sqrt{2}} - \lambda & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} - \lambda \end{pmatrix} = 0$$

$$(\frac{1}{\sqrt{2}} - \lambda)(-\frac{1}{\sqrt{2}} - \lambda) - (\frac{1}{\sqrt{2}})^2 = 0$$

$$-\frac{1}{2} - \frac{1}{\sqrt{2}}\lambda + \frac{1}{\sqrt{2}}\lambda + \lambda^2 - \frac{1}{2} = 0$$

$$\lambda^2 = 1$$

$$\lambda = \pm 1$$

$$\lambda_1 = 1 \quad Ax = \lambda x$$

$$\frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 1 \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$\frac{1}{\sqrt{2}}(x_1 + x_2) = x_1 \Rightarrow x_2 = \sqrt{2}x_1 - x_1 \Rightarrow x_2 - (\sqrt{2} - 1)x_1 = 0$$

$$x_1 - x_2 = \sqrt{2}x_1 - x_1 \Rightarrow x_1(\sqrt{2} - 1) = 0$$

$$\bar{\sigma}_2(x_1 - x_2) = x_2 \Rightarrow x_1 = 0.2x_2 + x_2 \Rightarrow x_1 - (0.2 + 1)x_2 = 0$$

$$x_2 = 1 \\ x_1 = \sqrt{2} + 1 \quad a = \begin{bmatrix} \sqrt{2} + 1 \\ 1 \end{bmatrix}$$

$$\lambda_1 = -1 \\ \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = -1 \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$\frac{1}{\sqrt{2}} (x_1 + x_2) = -x_1 \Rightarrow x_2 = -\sqrt{2} x_1 - x_1 \Rightarrow x_2 + (1 + \sqrt{2})x_1 = 0$$

$$\frac{1}{\sqrt{2}} (x_1 - x_2) = -x_2 \Rightarrow x_1 = -\sqrt{2}x_2 + x_2 \Rightarrow x_1 + (-1 + \sqrt{2})x_2 = 0$$

$$x_2 = 1 \\ x_1 = 1 - \sqrt{2} \quad b = \begin{bmatrix} 1 - \sqrt{2} \\ 1 \end{bmatrix}$$

i.i. $Ax = \lambda x$

$$\|Ax\|^2 = \|\lambda x\|^2$$

$$(Ax)^T (Ax) = \|\lambda x\|^2$$

$$x^T A^T Ax = \|\lambda x\|^2$$

$$x^T I x = |\lambda|^2 \|x\|^2$$

~~$$\|x\|^2 = |\lambda|^2 \|x\|^2$$~~

$$1 = |\lambda|^2$$

$$|\lambda| = 1$$

$$\text{iii. } Ax_1 = \gamma_1 x_1, \quad Ax_2 = \gamma_2 x_2$$

$$x_1^T x_2 = 0$$

$$(Ax_1)^T (Ax_2) = \gamma_1 \gamma_2 x_1^T x_2$$

$$x_1^T x_2 = \gamma_1 \gamma_2 x_1^T x_2$$

$$\gamma_1 \gamma_2 x_1^T x_2 - x_1^T x_2 = 0$$

$$x_1^T x_2 (\gamma_1 \gamma_2 - 1) = 0$$

$$\Rightarrow x_1^T x_2 = 0 \text{ since}$$

$|\gamma_1| = 1$ and $|\gamma_2| = 1$
and they are distinct
so $\gamma_1 = 1, \gamma_2 = -1$

iv. A either rotates x or reflects x , or does some combination of both.

b.
i. $A = U \Sigma V^T$

$$AA^T = U \Sigma^T V^T V \Sigma U^T$$

$$= U \Sigma^T \Sigma U^T$$

$$AA^T = V \Sigma^T U^T U \Sigma V^T$$

$$= V \Sigma^T \Sigma V$$

Eigenvalues (AA^T) = $U \Sigma^T U^T$

$$\lambda_i(AA^T) \sim \sigma_i^2(A)$$

The left singular vectors of A are eigenvectors of AA^T

The right singular vectors of A
are eigenvectors of $-A^T A$

ii. Singular values of A are
the square roots of the eigenvalues
of $A^T A$ and $A A^T$

c.
i. [False], $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ has eigenvalues 1, 1

ii

$$A\lambda_1 x_1 = \lambda_1 Ax_1$$

$$A\lambda_2 x_2 = \lambda_2 Ax_2$$

$$A(x_1 + x_2) = Ax_1 + Ax_2 = \lambda_1 x_1 + \lambda_2 x_2$$

False, impossible to rewrite in the form

$$Ax = \lambda x \text{ unless } \lambda_1 = \lambda_2$$

iii. $x^T A x \geq 0$

since we know $Ax = \lambda x$

$$x^T \lambda x \geq 0$$

$$\lambda \|x\|^2 \geq 0$$

since $\|x\|^2 > 0 \Rightarrow \lambda > 0$

True

iv.

I_2 has 1 distinct

Eigenvalue: 1, but

its rank is 2.

True

v. $Ax_1 = \lambda_1 x_1$

$Ax_2 = \lambda_2 x_2$

$A(x_1 + x_2) = \lambda_1 x_1 + \lambda_2 x_2$ $\lambda_1 = \lambda_2 = \lambda$

$A(x_1 + x_2) = \lambda x_1 + \lambda x_2$

$= \lambda(x_1 + x_2)$

$\Rightarrow x_1 + x_2$ is an eigenvector

IF $\lambda_1 = \lambda_2$

(True)

2.

a). Let $x = HSD$ $y = H60$

i. $n = head$, $t = tail$

$$p(t|x) = 0.5 \quad p(t|y) = 0.6$$

$$p(x) = 0.5 \quad p(y) = 0.5$$

$$p(x|t) = \frac{p(t|x) \cdot p(x)}{p(t)}$$

$$= \frac{p(t|x) \cdot p(x)}{p(t|x)p(x) + p(t|y)p(y)}$$

$$= \frac{(0.5)(0.5)}{(0.5)(0.5) + (0.4)(0.5)}$$

$$= \frac{\frac{1}{4}}{\frac{1}{4} + \frac{2}{10}} = \frac{\frac{1}{4}}{\frac{5}{20} + \frac{4}{20}} = \frac{\frac{1}{4}}{\frac{9}{20}} = \frac{1}{\frac{9}{20}}$$

$$= \left(\frac{5}{9} \right)$$

ii. let $a = \text{THHTH}$

$$p(a|x) = (0.5)^4 = 0.0625$$

$$p(a|y) = (0.4)^1 (0.6)^3 = 0.0864$$

$$p(a) = p(a|x) p(x)$$

$$\begin{aligned}
 p(x|a) &= \frac{p(a)}{p(a|x)p(x)} \\
 &= \frac{p(a|x)p(x)}{p(a|x)p(x) + p(a|y)p(y)} \\
 &\stackrel{(0.0625)(0.5)}{=} \frac{(0.0625)(0.5) + (0.0875)(0.5)}{(0.0625)(0.5) + (0.0875)(0.5)} \\
 &= \frac{0.0625}{0.0625 + 0.0875} = 0.42
 \end{aligned}$$

iii Let b = Heads 9 times

$z = HSS$

$$p(b|x) = (0.5)^{10}$$

$$p(b|y) = (0.4)^1 (0.6)^9$$

$$p(b|z) = (0.45)^1 (0.55)^9$$

$$p(x|b) = \frac{(0.5)^{10}}{(0.4)^1 (0.6)^9 + (0.45)^1 (0.55)^9 + (0.5)^{10}}$$

$$p(y|b) = \frac{(0.4)^1 (0.6)^9}{(0.4)^1 (0.6)^9 + (0.45)^1 (0.55)^9 + (0.5)^{10}}$$

$$p(z|b) = \frac{(0.45)^1 (0.55)^9}{(0.4)^1 (0.6)^9 + (0.45)^1 (0.55)^9 + (0.5)^{10}}$$

... want ... - a close test

b. $X = \text{pregnant}$ $Y = \text{positive test}$

$$\begin{aligned} p(x|y) &= \frac{p(y|x)p(x)}{p(y)} \\ &= \frac{p(y|x)p(x)}{p(y|x)p(x) + p(y|\neg x)p(\neg x)} \\ &= \frac{(0.99)(0.01)}{(0.99)(0.01) + (0.1)(0.99)} \\ &= \boxed{0.091} \end{aligned}$$

There is a relatively high number of nonpregnant women and false positive rate is relatively high.

c. $E(Ax+b) = A E(x) + b$

d. $\text{cov}(x) = E((x - E(x))(x - E(x))^T)$

$$\begin{aligned} \text{cov}(Ax+b) &= E((Ax+b - E(Ax+b))(Ax+b - E(Ax+b))^T) \\ &= E((Ax+b - AE(x)-b)(Ax+b - AE(x)-b)^T) \end{aligned}$$

$$= E((A(x-E(x)))(A(x-E(x))^T)$$

$$= A E((x-E(x))(x-E(x))^T) A^T$$

$$= A \text{cov}(x) A^T$$

3.

$$\text{a) } f = \mathbf{x}^T A \mathbf{y} = \begin{bmatrix} x_1 & x_2 & \dots & x_n \end{bmatrix} \begin{bmatrix} a_{11} & a_{1m} \\ a_{n1} & a_{nm} \end{bmatrix} \begin{bmatrix} y_1 \\ y_m \end{bmatrix}$$

$$= \sum_{j=1}^m \sum_{i=1}^n x_i a_{ij} y_j$$

$$\nabla_{\mathbf{x}} f = \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \vdots \\ \frac{\partial f}{\partial x_n} \end{bmatrix} = \begin{bmatrix} \sum_{j=1}^m a_{1j} y_j \\ \vdots \\ \sum_{j=1}^m a_{nj} y_j \end{bmatrix} = [A \mathbf{y}]$$

$$\text{b) } f = \mathbf{x}^T A \mathbf{y} = \sum_{j=1}^m \sum_{i=1}^n x_i a_{ij} y_j$$

$$\nabla_{\mathbf{y}} f = \begin{bmatrix} \frac{\partial f}{\partial y_1} \\ \vdots \\ \frac{\partial f}{\partial y_m} \end{bmatrix} = \begin{bmatrix} \sum_{i=1}^n x_i a_{i1} \\ \vdots \\ \sum_{i=1}^n x_i a_{im} \end{bmatrix} = [A^T \mathbf{x}]$$

$$\text{c) } f = \mathbf{x}^T A \mathbf{y} = \sum_{j=1}^m \sum_{i=1}^n x_i a_{ij} y_j$$

$$\nabla_A f = \begin{bmatrix} \frac{\partial f}{\partial a_{11}} & \cdots & \frac{\partial f}{\partial a_{1m}} \\ \vdots & \ddots & \vdots \\ \frac{\partial f}{\partial a_{n1}} & \cdots & \frac{\partial f}{\partial a_{nm}} \end{bmatrix} = \begin{bmatrix} x_1 y_1 & \cdots & x_1 y_m \\ \vdots & \ddots & \vdots \\ x_n y_1 & \cdots & x_n y_m \end{bmatrix}$$

$$= \begin{bmatrix} X & Y^T \end{bmatrix}$$

d) $f = x^T A x + b^T x$

$$\begin{aligned}\frac{\partial f}{\partial x} &= \frac{\partial f}{\partial x}(x^T A x) + \frac{\partial f}{\partial x}(b^T x) \\ &= (A + A^T)x + b\end{aligned}$$

e) $f = \text{tr}(AB)$

$$A \in \mathbb{R}^{n \times m}, B \in \mathbb{R}^{m \times n}$$

$$= \text{tr} \left(\begin{bmatrix} \sum_{i=1}^m a_{1i} b_{i1} & \dots & \sum_{i=1}^m a_{1i} b_{in} \\ \vdots & & \vdots \\ \sum_{i=1}^m a_{ni} b_{i1} & \dots & \sum_{i=1}^m a_{ni} b_{in} \end{bmatrix} \right)$$

$$f = \sum_{j=1}^n \sum_{i=1}^m a_{ji} b_{ij}$$

$$\frac{\partial f}{\partial A} = \begin{bmatrix} \frac{\partial f}{\partial a_{11}} & \dots & \frac{\partial f}{\partial a_{1m}} \\ \vdots & & \vdots \\ \frac{\partial f}{\partial a_{n1}} & \dots & \frac{\partial f}{\partial a_{nm}} \end{bmatrix} = \begin{bmatrix} b_{11} & \dots & b_{m1} \\ \vdots & & \vdots \\ b_{1n} & \dots & b_{mn} \end{bmatrix} = \boxed{B^T}$$

4.

n

?

$$\begin{aligned}
 L &= \frac{1}{2} \sum_{i=1}^n \|y^{(i)} - w_x^{(i)}\|^2 = \frac{1}{2} \sum_{i=1}^n \|y^{(i)} - x^{(i)}w\|^2 \\
 &= \frac{1}{2} (Y - Xw)^T (Y - Xw) \\
 &= \frac{1}{2} (Y^T Y - 2Y^T Xw + X^T Xw)
 \end{aligned}$$

$$\begin{aligned}
 \frac{\partial L}{\partial w} &= \frac{1}{2} (0 - 2X^T Y + 2X^T Xw) \\
 &= -X^T Y + X^T Xw
 \end{aligned}$$

$$-X^T Y + X^T Xw = 0$$

$$\begin{aligned}
 X^T Xw &= X^T Y \\
 \boxed{w = (X^T X)^{-1} X^T Y}
 \end{aligned}$$

linear_regression

January 16, 2021

0.1 Linear regression workbook

This workbook will walk you through a linear regression example. It will provide familiarity with Jupyter Notebook and Python. Please print (to pdf) a completed version of this workbook for submission with HW #1.

ECE C147/C247, Winter Quarter 2021, Prof. J.C. Kao, TAs: N. Evirgen, A. Ghosh, S. Mathur, T. Monsoor, G. Zhao

```
[1]: import numpy as np
import matplotlib.pyplot as plt

#allows matlab plots to be generated in line
%matplotlib inline
```

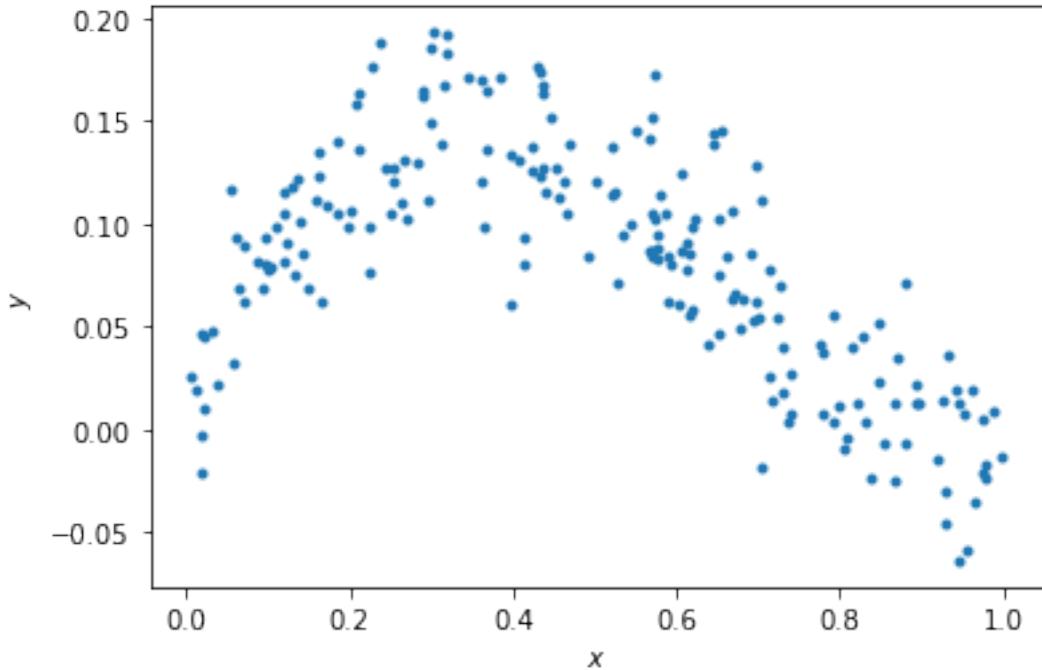
0.1.1 Data generation

For any example, we first have to generate some appropriate data to use. The following cell generates data according to the model: $y = x - 2x^2 + x^3 + \epsilon$

```
[2]: np.random.seed(0)    # Sets the random seed.
num_train = 200          # Number of training data points

# Generate the training data
x = np.random.uniform(low=0, high=1, size=(num_train,))
y = x - 2*x**2 + x**3 + np.random.normal(loc=0, scale=0.03, size=(num_train,))
f = plt.figure()
ax = f.gca()
ax.plot(x, y, '.')
ax.set_xlabel('$x$')
ax.set_ylabel('$y$')
```

```
[2]: Text(0, 0.5, '$y$')
```



0.1.2 QUESTIONS:

Write your answers in the markdown cell below this one:

- (1) What is the generating distribution of x ?
- (2) What is the distribution of the additive noise ϵ ?

0.1.3 ANSWERS:

- (1) Uniform Distribution
- (2) Normal Distribution

0.1.4 Fitting data to the model (5 points)

Here, we'll do linear regression to fit the parameters of a model $y = ax + b$.

```
[3]: # xhat = (x, 1)
xhat = np.vstack((x, np.ones_like(x)))

# ===== #
# START YOUR CODE HERE #
# ===== #
# GOAL: create a variable theta; theta is a numpy array whose elements are [a, ↴b]
```

```

theta = np.dot(np.dot(np.linalg.inv(np.dot(xhat,xhat.T)),xhat),y) # please
→ modify this line

# ===== #
# END YOUR CODE HERE #
# ===== #

```

[4]: # Plot the data and your model fit.

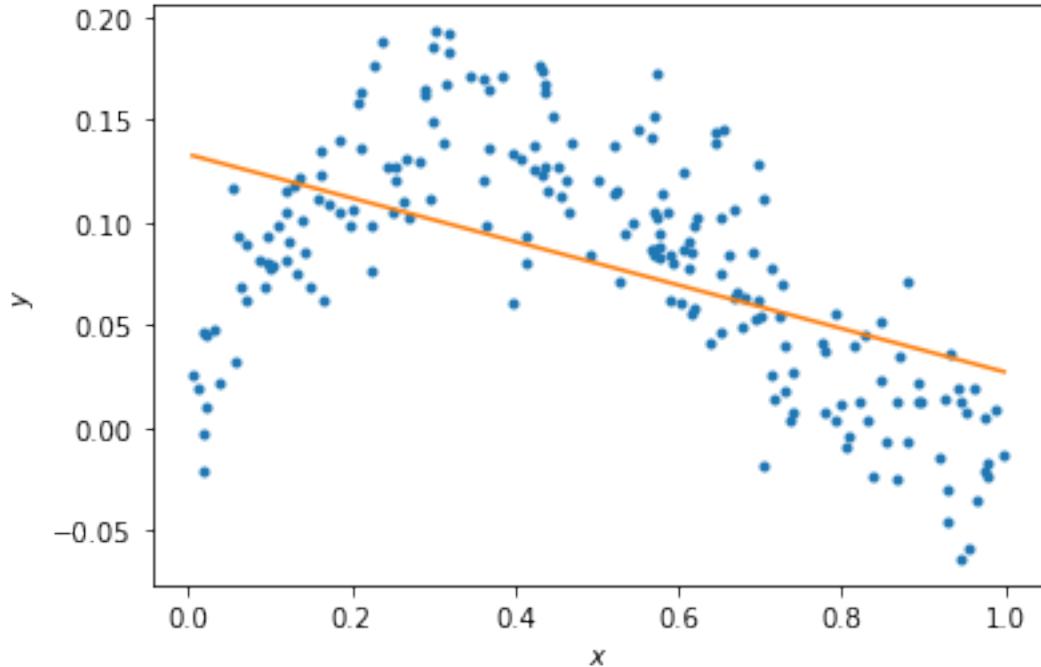
```

f = plt.figure()
ax = f.gca()
ax.plot(x, y, '.')
ax.set_xlabel('$x$')
ax.set_ylabel('$y$')

# Plot the regression line
xs = np.linspace(min(x), max(x), 50)
xs = np.vstack((xs, np.ones_like(xs)))
plt.plot(xs[0, :], theta.dot(xs))

```

[4]: [<matplotlib.lines.Line2D at 0x7ff40b2da550>]



0.1.5 QUESTIONS

- (1) Does the linear model under- or overfit the data?

- (2) How to change the model to improve the fitting?

0.1.6 ANSWERS

- (1) Underfit
- (2) Add two more parameters to estimate x^2 and x^3

0.1.7 Fitting data to the model (10 points)

Here, we'll now do regression to polynomial models of orders 1 to 5. Note, the order 1 model is the linear model you prior fit.

```
[5]: N = 5
xhats = []
thetas = []

# ===== #
# START YOUR CODE HERE #
# ===== #

for i in range(1, N+1):
    xhats.append(np.vstack([x**deg for deg in range(i, -1, -1)]))

for xhat in xhats:
    thetas.append(np.dot(np.dot(np.linalg.inv(np.dot(xhat, xhat.T)), xhat), y))

# GOAL: create a variable thetas.
# thetas is a list, where theta[i] are the model parameters for the polynomial
# fit of order i+1.
# i.e., thetas[0] is equivalent to theta above.
# i.e., thetas[1] should be a length 3 np.array with the coefficients of the
# x^2, x, and 1 respectively.
# ... etc.

# ===== #
# END YOUR CODE HERE #
# ===== #
```

```
[6]: # Plot the data
f = plt.figure()
ax = f.gca()
ax.plot(x, y, '.')
ax.set_xlabel('$x$')
ax.set_ylabel('$y$')

# Plot the regression lines
plot_xs = []
for i in np.arange(N):
```

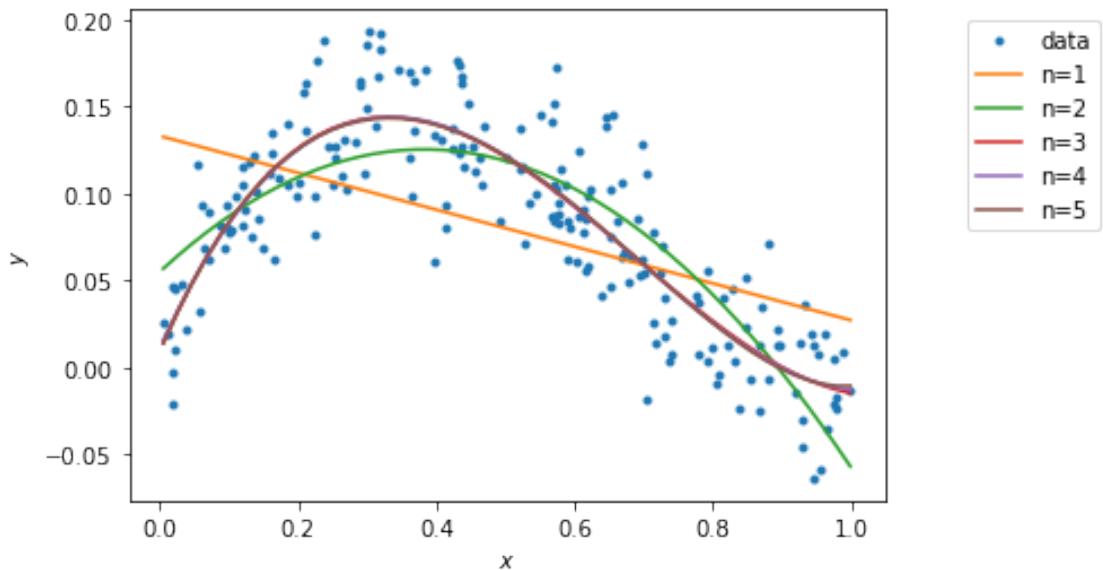
```

if i == 0:
    plot_x = np.vstack((np.linspace(min(x), max(x), 50), np.ones(50)))
else:
    plot_x = np.vstack((plot_x[-2]**(i+1), plot_x))
plot_xs.append(plot_x)

for i in np.arange(N):
    ax.plot(plot_xs[i][-2, :], thetas[i].dot(plot_xs[i]))

labels = ['data']
[labels.append('n={}'.format(i+1)) for i in np.arange(N)]
bbox_to_anchor=(1.3, 1)
lgd = ax.legend(labels, bbox_to_anchor=bbox_to_anchor)

```



0.1.8 Calculating the training error (10 points)

Here, we'll now calculate the training error of polynomial models of orders 1 to 5.

```

[7]: training_errors = []

# ===== #
# START YOUR CODE HERE #
# ===== #

# GOAL: create a variable training_errors, a list of 5 elements,
# where training_errors[i] are the training loss for the polynomial fit of
# order i+1.
for i in range(5):

```

```

theta = thetas[i]
xhat = xhats[i]
training_errors.append(np.sum((y-theta.dot(xhat))**2))

# ===== #
# END YOUR CODE HERE #
# ===== #

print ('Training errors are: \n', training_errors)

```

Training errors are:
[0.4759922176725402, 0.21849844418537057, 0.16339207602210737,
0.16330707470593964, 0.16322958391050588]

0.1.9 QUESTIONS

- (1) What polynomial has the best training error?
- (2) Why is this expected?

0.1.10 ANSWERS

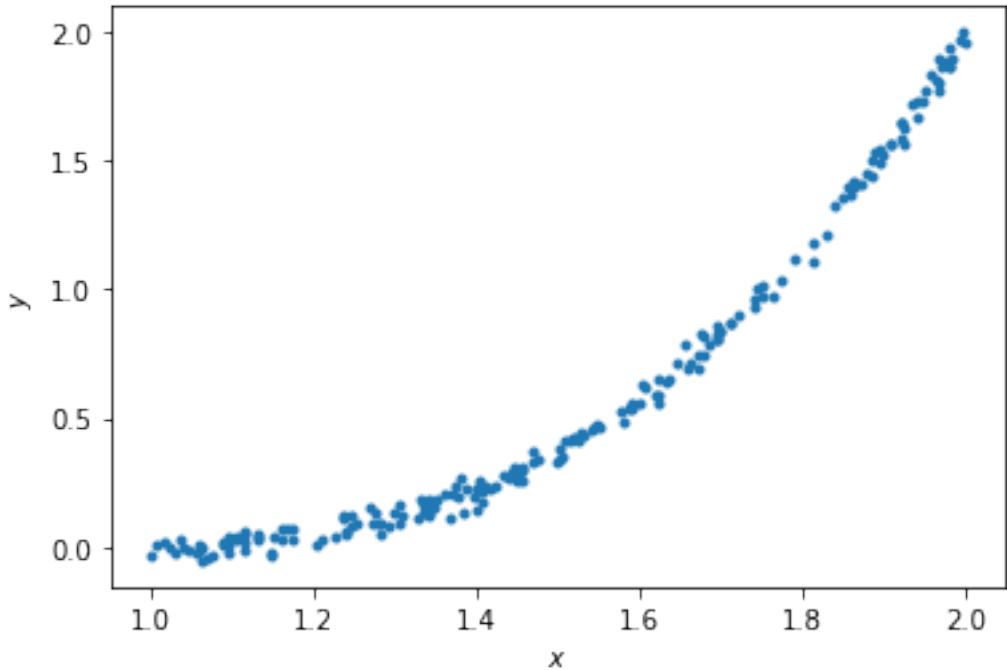
- (1) Order 5 Polynomial
- (2) Higher order polynomials can model higher order (non-linear) patterns in the data as well as lower order patterns

0.1.11 Generating new samples and testing error (5 points)

Here, we'll now generate new samples and calculate testing error of polynomial models of orders 1 to 5.

```
[8]: x = np.random.uniform(low=1, high=2, size=(num_train,))
y = x - 2*x**2 + x**3 + np.random.normal(loc=0, scale=0.03, size=(num_train,))
f = plt.figure()
ax = f.gca()
ax.plot(x, y, '.')
ax.set_xlabel('$x$')
ax.set_ylabel('$y$')
```

[8]: Text(0, 0.5, '\$y\$')



```
[9]: xhats = []
for i in np.arange(N):
    if i == 0:
        xhat = np.vstack((x, np.ones_like(x)))
        plot_x = np.vstack((np.linspace(min(x), max(x), 50), np.ones(50)))
    else:
        xhat = np.vstack((x***(i+1), xhat))
        plot_x = np.vstack((plot_x[-2]***(i+1), plot_x))

    xhats.append(xhat)
```

```
[10]: # Plot the data
f = plt.figure()
ax = f.gca()
ax.plot(x, y, '.')
ax.set_xlabel('$x$')
ax.set_ylabel('$y$')

# Plot the regression lines
plot_xs = []
for i in np.arange(N):
    if i == 0:
        plot_x = np.vstack((np.linspace(min(x), max(x), 50), np.ones(50)))
    else:
        plot_x = np.vstack((plot_x[-2]***(i+1), plot_x))
```

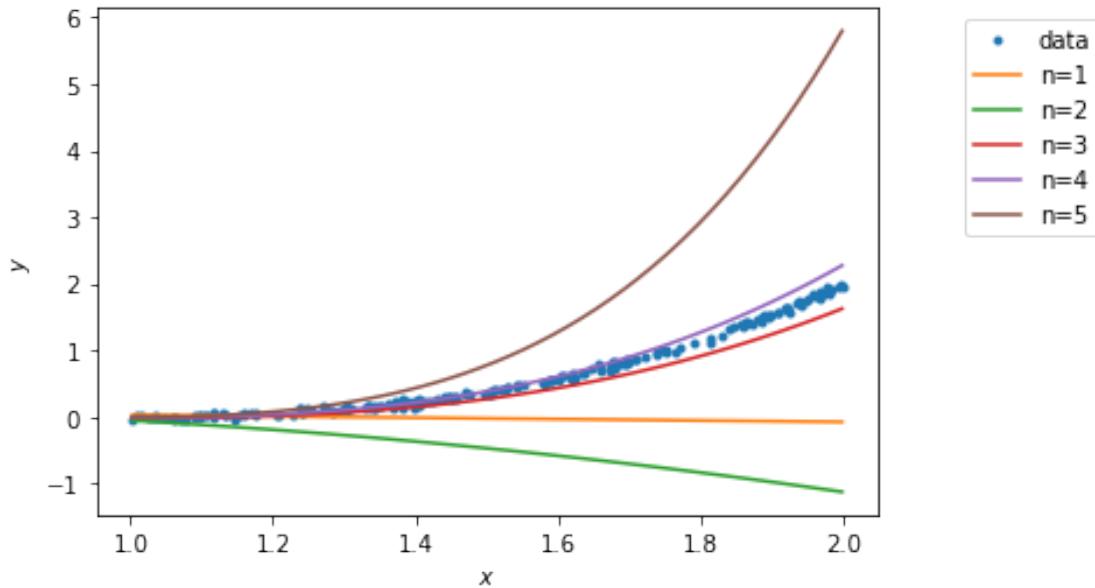
```

plot_xs.append(plot_x)

for i in np.arange(N):
    ax.plot(plot_xs[i][-2,:], thetas[i].dot(plot_xs[i]))

labels = ['data']
[labels.append('n={}'.format(i+1)) for i in np.arange(N)]
bbox_to_anchor=(1.3, 1)
lgd = ax.legend(labels, bbox_to_anchor=bbox_to_anchor)

```



```

[11]: testing_errors = []

# ===== #
# START YOUR CODE HERE #
# ===== #

# GOAL: create a variable testing_errors, a list of 5 elements,
# where testing_errors[i] are the testing loss for the polynomial fit of order  $\hookrightarrow i+1$ .
for i in range(5):
    theta = thetas[i]
    xhat = xhats[i]
    testing_errors.append(np.sum((y-theta.dot(xhat))**2))

# ===== #
# END YOUR CODE HERE #
# ===== #

```

```
print ('Testing errors are: \n', testing_errors)
```

Testing errors are:
[161.72330369101167, 426.38384890115805, 6.251394216818595, 2.374153042237893,
429.8204349731892]

0.1.12 QUESTIONS

- (1) What polynomial has the best testing error?
- (2) Why polynomial models of orders 5 does not generalize well?

0.1.13 ANSWERS

- (1) Order 3 Polynomial
- (2) Order 5 polynomial overfits the data because the data is generated from an order 3 polynomial equation

[]: