Sketch In, Sketch Out: Accelerating both Learning and Inference for Structured Prediction with Kernels

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Existing works: Energy-based models (Lafferty et al., 2001; Taskar et al., 2003; Tsochantaridis et al., 2004; LeCun et al., 2007; Belanger and McCallum, 2016):

$$f(x) = \operatorname*{argmin}_{y \in \mathcal{Y}} \; E(x, y) \tag{1}$$

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Input Output Kernel Regression

Given a p.d. kernel $k_{\mathcal{Y}} : \mathcal{Y} \times \mathcal{Y} \to \mathbb{R}$ defining a relevant similarity measure and $\psi_{\mathcal{Y}} : y \in \mathcal{Y} \mapsto k_{\mathcal{Y}}(\cdot, y) \in \mathcal{H}_{\mathcal{Y}}$,

we define $\Delta(y, y') = \|\psi_{\mathcal{Y}}(y) - \psi_{\mathcal{Y}}(y')\|_{\mathcal{H}_{\mathcal{Y}}}^2$ (Weston et al., 2003; Cortes et al., 2005), and solve

$$\min_{f:\mathcal{X}\to\mathcal{Y}} \mathbb{E}_{(X,Y)\sim\rho}[\|\psi_{\mathcal{Y}}(f(X)) - \psi_{\mathcal{Y}}(Y)\|_{\mathcal{H}_{\mathcal{Y}}}^2] \tag{2}$$
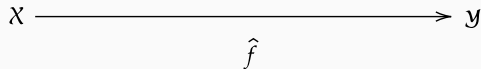
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$$\min_{f:\mathcal{X}\to\mathcal{Y}} \ \mathbb{E}_{(X,Y)\sim\rho}[\|\psi_{\mathcal{Y}}(f(X)) - \psi_{\mathcal{Y}}(Y)\|^2_{\mathcal{H}_{\mathcal{Y}}}] \tag{3}$$

How to learn f through $\psi_{\mathcal{Y}}$?

$$\mathcal{X} \xrightarrow{\quad\quad\quad\quad\quad} \mathcal{Y}$$
$$\hat{f}$$

$$\widehat{f} = d \circ \widehat{h} = \underset{y \in \mathcal{Y}}{\arg\min} \|\widehat{h}(\cdot) - \psi_{\mathcal{Y}}(y)\|^2_{\mathcal{H}_{\mathcal{Y}}}$$

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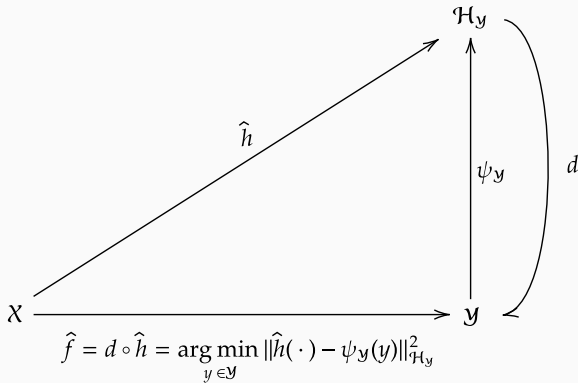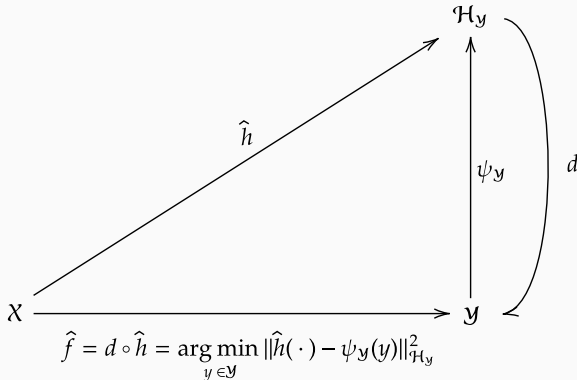
Which hypothesis space for $\hat{h}$?

How to deal with infinite-dimensional output feature space $\mathcal{H}_{\mathcal{Y}}$?

Diagram:

$$\mathcal{H}_\mathcal{X} \xrightarrow{\quad \widehat{H} \quad} \mathcal{H}_\mathcal{Y}$$

$$\widehat{h}(x) = \widehat{H}\psi_\mathcal{X}(x) = \sum_{i=1}^{n} \widehat{\alpha}_i(x)\psi_\mathcal{Y}(y_i)$$

$$\psi_\mathcal{X} \qquad \psi_\mathcal{Y} \qquad d$$

$$\mathcal{X} \xrightarrow{\quad \widehat{f} = d \circ \widehat{h} \quad} \mathcal{Y}$$
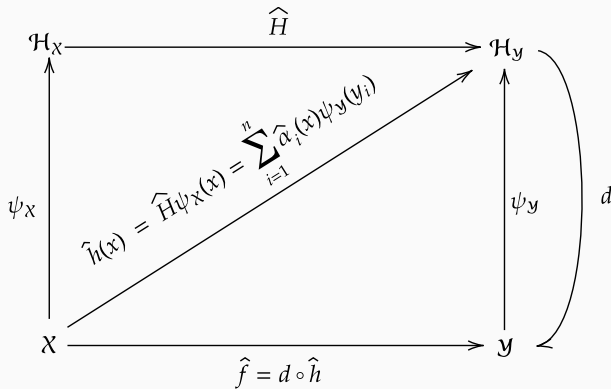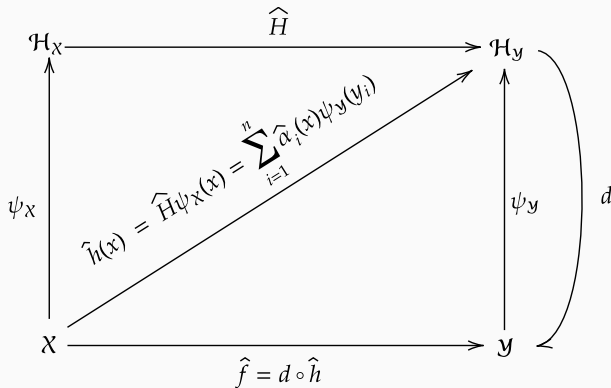
Input Output Kernel Regression

$$\hat{\alpha}(x) = (\underbrace{K_X + n\lambda I_n}_{n \times n})^{-1} k_X^x = \widehat{\Omega} k_X^x \tag{4}$$

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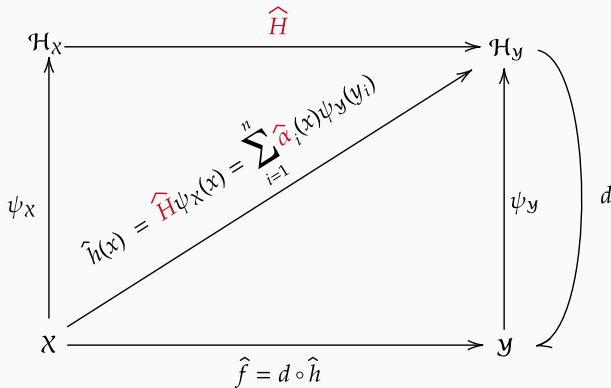
Training complexity: $\mathcal{O}\left(n^3\right)$

$$\hat{f}(x) = d(\hat{h}(x)) = \underset{y \in \mathcal{Y}}{\arg\min} \left\| \hat{h}(x) - \psi_{\mathcal{Y}}(y) \right\|^2_{\mathcal{H}_{\mathcal{Y}}} =$$

$$\underset{y \in \mathcal{Y}}{\arg\min} \; k_{\mathcal{Y}}(y, y) - 2k_X^{x\mathsf{T}} \widehat{\Omega} k_Y^y$$

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- Test set: X_{te} of size n_{te}
- Candidate set: $\mathcal{Y}_c \subseteq \mathcal{Y}$ of size n_c

$$\underbrace{K_{te,tr}}_{n_{te} \times n} \underbrace{\widehat{\Omega}}_{n \times n} \underbrace{K_{tr,c}^y}_{n \times n_c} \tag{6}$$

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- Test set: X_{te} of size n_{te}
- Candidate set: $\mathcal{Y}_c \subseteq \mathcal{Y}$ of size n_c

$$\underbrace{K_X^{te,tr}}_{n_{te} \times n} \; \underbrace{\hat{\Omega}}_{n \times n} \; \underbrace{K_Y^{tr,c}}_{n \times n_c} \tag{7}$$

Inference complexity: $\mathcal{O}\left(n_{te} n n_c\right)$ if $n_{te} < n \leq n_c$

Lemma 1 and Theorem 3 from Ciliberto et al. (2020). Let $\mathcal{Y}$ be compact, $k_{\mathcal{Y}} : \mathcal{Y} \times \mathcal{Y} \to \mathbb{R}$ be a p.d. kernel and $\psi_{\mathcal{Y}} : y \mapsto k_{\mathcal{Y}}(\cdot, y)$ s.t. $\|\psi_{\mathcal{Y}}(y)\|_{\mathcal{H}_{\mathcal{Y}}} = 1, \forall y \in \mathcal{Y}$, and

$$f^* = \underset{f : \mathcal{X} \to \mathcal{Y}}{\operatorname{arginf}} \ \mathcal{R}(f) = \underset{f : \mathcal{X} \to \mathcal{Y}}{\operatorname{arginf}} \ \mathbb{E}_{(x,y) \sim \rho}[\|\psi_{\mathcal{Y}}(f(x)) - \psi_{\mathcal{Y}}(y)\|^2_{\mathcal{H}_{\mathcal{Y}}}] \,.$$

Then,

$$f^*(x) = \underset{y \in \mathcal{Y}}{\operatorname{argmin}} \ \|h^*(x) - \psi_{\mathcal{Y}}(y)\|^2_{\mathcal{H}_{\mathcal{Y}}} = d \circ h^*(x) \,, \quad h^*(x) = \mathbb{E}_y[\psi_{\mathcal{Y}}(y)|x] \,,$$

almost surely with respect to $\rho_{\mathcal{X}}$.

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Then,

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almost surely with respect to $\rho_{\mathcal{X}}$.

Moreover, let $h : \mathcal{X} \to \mathcal{H}_{\mathcal{Y}}$ be measurable and $f : \mathcal{X} \to \mathcal{Y}$ such that, for any $x \in \mathcal{X}$,

$$f(x) = \operatorname*{argmin}_{y\in\mathcal{Y}} \|h(x) - \psi_{\mathcal{Y}}(y)\|^2_{\mathcal{H}_{\mathcal{Y}}} = d \circ h(x).$$

Then,

$$\mathcal{R}(f) - \mathcal{R}(f^*) \leq 12\sqrt{\mathcal{E}(h) - \mathcal{E}(h^*)},$$

where $\mathcal{E}(h) = \mathbb{E}_{(x,y)\sim\rho}[\|h(x) - \psi_{\mathcal{Y}}(y)\|^2_{\mathcal{H}_{\mathcal{Y}}}]$.

Advantages of IOKR

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2) Very general algorithm for structured prediction: ability to tackle many different tasks through an appropriate choice of the output kernel

3) Closed-form solution of kernel Ridge regression: no need for any optimization algorithm to be solved, unlike deep models (Belanger and McCallum, 2016; Belanger et al., 2017; Gygli et al., 2017)

Can we scale IOKR up at both the training and inference phases, especially since they employ not only an input but also an output kernel, while keeping an excess risk bound?

Sketched Input Sketched Output Kernel Regression

Motivation: build a **low-rank** approximation $\tilde{h}$ thanks to **input and output** random projectors $\widetilde{P}_X$ and $\widetilde{P}_Y$ to obtain a **scalable** predictor $\tilde{f}$ together with an excess risk bound

- For $\mathcal{Z}$ a Polish space, $k_{\mathcal{Z}} : \mathcal{Z} \times \mathcal{Z} \to \mathbb{R}$ a p.d. kernel, $\psi_{\mathcal{Z}}(z) := k_{\mathcal{Z}}(\cdot, z)$, $\mathcal{H}_{\mathcal{Z}}$ its RKHS

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- $S_Z : f \in \mathcal{H}_{\mathcal{Z}} \mapsto (1/\sqrt{n})(f(z_1), \ldots, f(z_n))^\top \in \mathbb{R}^n$ sampling operator

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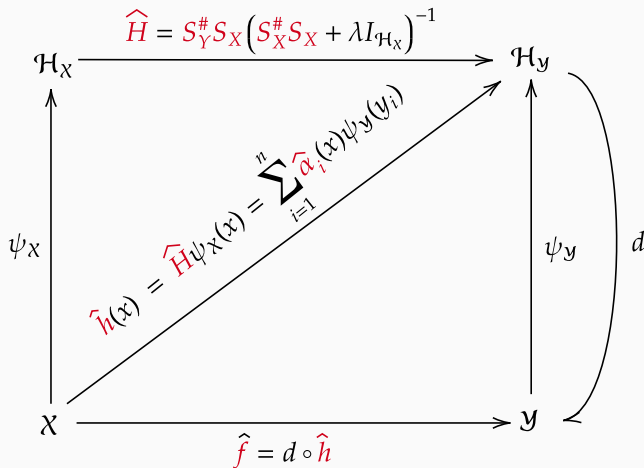- $C_{\mathcal{Z}} = \mathbb{E}_z[\psi_{\mathcal{Z}}(z) \otimes \psi_{\mathcal{Z}}(z)]$ covariance operator

Some notations

- For $\mathcal{Z}$ a Polish space, $k_{\mathcal{Z}} : \mathcal{Z} \times \mathcal{Z} \to \mathbb{R}$ a p.d. kernel, $\psi_{\mathcal{Z}}(z) := k_{\mathcal{Z}}(\cdot, z)$, $\mathcal{H}_{\mathcal{Z}}$ its RKHS
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- $C_{\mathcal{Z}} = \mathbb{E}_z[\psi_{\mathcal{Z}}(z) \otimes \psi_{\mathcal{Z}}(z)]$ covariance operator
- $\widehat{C}_Z = (1/n) \sum_{i=1}^n \psi_{\mathcal{Z}}(z_i) \otimes \psi_{\mathcal{Z}}(z_i) = S_Z^{\#} S_Z$ its empirical counterpart

$$\widehat{H} = S_Y^\# S_X \left(S_X^\# S_X + \lambda I_{\mathcal{H}_X} \right)^{-1}$$

$\mathcal{H}_X \xrightarrow{\hspace{4cm}} \mathcal{H}_Y$

$\widehat{h}(x) = \widehat{H}\psi_X(x) = \displaystyle\sum_{i=1}^{n} \widehat{\alpha}_i(x)\psi_Y(y_i)$

ψ_X

ψ_Y

d

$\mathcal{X} \xrightarrow{\hspace{4cm}} \mathcal{Y}$

$$\widehat{f} = d \circ \widehat{h}$$

The diagram shows:

$$\widetilde{H} = \widetilde{P}_Y S_Y^\sharp S_X \widetilde{P}_X \left(\widetilde{P}_X S_X^\sharp S_X \widetilde{P}_X + \lambda I_{\mathcal{H}_X} \right)^{-1}$$

$\mathcal{H}_X \longrightarrow \mathcal{H}_Y$

$\widetilde{P}_X \psi_X$

$\widetilde{h}(x) = \widetilde{H}\psi_X(x) = \sum_{i=1}^{n} \widetilde{\alpha}_i(x)\psi_Y(y_i)$

$\widetilde{P}_Y \psi_Y \quad d$

$\mathcal{X} \longrightarrow \mathcal{Y}$

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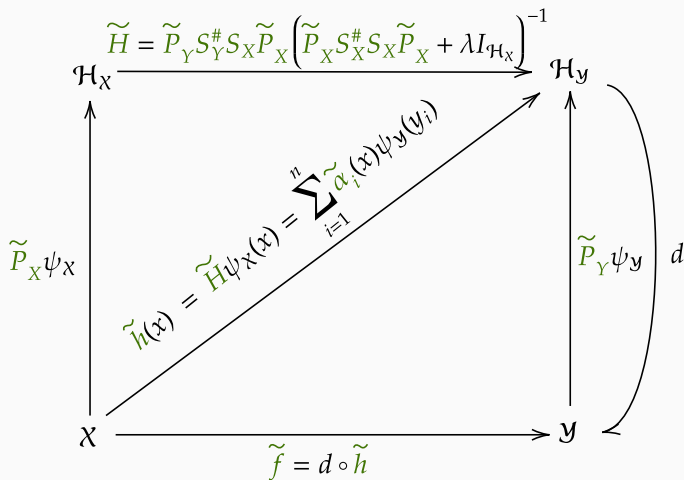
Sketching: random linear projections

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Sketching

Sketching: random linear projections

Let $m_{\mathcal{Z}} \ll n$, $R_{\mathcal{Z}} \in \mathbb{R}^{m_{\mathcal{Z}} \times n}$ be a random matrix and n data $(z_i)_{i=1}^n \in \mathcal{Z}$

Basic idea: Sketching-based operator $\widetilde{P}_Z$ projects onto the following linear subspace of $\mathcal{H}_{\mathcal{Z}}$

$$\sum_{j=1}^{n}(R_{\mathcal{Z}})_{ij}\psi_{\mathcal{Z}}(z_j) \in \mathcal{H}_{\mathcal{Z}}, \quad i = 1, \ldots, m_{\mathcal{Z}} \tag{8}$$

- $\widetilde{C}_Z = S_Z^{\#} R_{\mathcal{Z}}^{\top} R_{\mathcal{Z}} S_Z$

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- $\widetilde{K}_Z = R_{\mathcal{Z}} K_Z R_{\mathcal{Z}}^\top$, and $\left\{ \left(\sigma_i(\widetilde{K}_Z), \tilde{\mathbf{v}}_i^z \right), i \in [m_{\mathcal{Z}}] \right\}$ its eigenpairs

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- $p_Z = \mathsf{rank}\left(\widetilde{K}_Z \right)$, and for all $1 \leq i \leq p_Z$, $\tilde{e}_i^Z = \sqrt{\frac{n}{\sigma_i(\widetilde{K}_Z)}} S_Z^\# R_\mathcal{Z}^\top \tilde{\mathbf{v}}_i^Z \in \mathcal{H}_\mathcal{Z}$

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Proposition

The $\tilde{e}_i^Z$s are the eigenfunctions, associated to the eigenvalues $\sigma_i(\widetilde{K}_Z)/n$, of $\widetilde{C}_Z$.

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The $\tilde{e}_i^Z$s are the eigenfunctions, associated to the eigenvalues $\sigma_i(\widetilde{K}_Z)/n$, of $\widetilde{C}_Z$.
Furthermore, let $\widetilde{\mathcal{H}}_{\mathcal{Z}} = \text{span}\,(\tilde{e}_1^Z, \ldots, \tilde{e}_{p_Z}^Z)$, the orthogonal projector $\widetilde{P}_Z$ onto $\widetilde{\mathcal{H}}_{\mathcal{Z}}$ writes as

$$\widetilde{P}_Z = (R_{\mathcal{Z}} S_Z)^\# \left(R_{\mathcal{Z}} S_Z (R_{\mathcal{Z}} S_Z)^\# \right)^\dagger R_{\mathcal{Z}} S_Z \,. \tag{9}$$

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Related work on Nyström: Yang et al. (2012); Rudi et al. (2015)

Proposition (Expression of SISOKR)

$$\tilde{h}(x) = \sum_{i=1}^{n} \tilde{\alpha}_i(x) \psi_{\mathcal{Y}}(y_i), \quad \text{where} \quad \tilde{\alpha}(x) = R_{\mathcal{Y}}^{\top} \widetilde{\Omega} R_{\mathcal{X}} k_X^x, \qquad (10)$$

with

$$\widetilde{\Omega} = \underbrace{(R_{\mathcal{Y}} K_Y R_{\mathcal{Y}}^{\top})}_{m_{\mathcal{Y}} \times m_{\mathcal{Y}}}^{\dagger} R_{\mathcal{Y}} K_Y K_X R_{\mathcal{X}}^{\top} \underbrace{(R_{\mathcal{X}} K_X^2 R_{\mathcal{X}}^{\top} + n\lambda R_{\mathcal{X}} K_X R_{\mathcal{X}}^{\top})}_{m_{\mathcal{X}} \times m_{\mathcal{X}}}^{\dagger} \qquad (11)$$

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Inversion complexity: $\mathcal{O}(n^3) \to \mathcal{O}(\max(m_{\mathcal{X}}^3, m_{\mathcal{Y}}^3))$

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Complexity of $R_{\mathcal{Z}} K_Z$**:** depends on the sketch matrix, between $\mathcal{O}(nm_{\mathcal{Z}})$ and $\mathcal{O}(n^2 m_{\mathcal{Z}})$

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$$\tilde{h}(x) = \sum_{i=1}^{n} \tilde{\alpha}_i(x) \psi_{\mathcal{Y}}(y_i), \quad \text{where} \quad \tilde{\alpha}(x) = R_{\mathcal{Y}}^{\top} \widetilde{\Omega} R_{\mathcal{X}} k_X^x, \qquad (10)$$

with

$$\widetilde{\Omega} = \underbrace{(R_{\mathcal{Y}} K_Y R_{\mathcal{Y}}^{\top})^{\dagger}}_{m_{\mathcal{Y}} \times m_{\mathcal{Y}}} R_{\mathcal{Y}} K_Y K_X R_{\mathcal{X}}^{\top} \underbrace{(R_{\mathcal{X}} K_X^2 R_{\mathcal{X}}^{\top} + n\lambda R_{\mathcal{X}} K_X R_{\mathcal{X}}^{\top})^{\dagger}}_{m_{\mathcal{X}} \times m_{\mathcal{X}}} \qquad (11)$$

Inversion complexity: $\mathcal{O}(n^3) \to \mathcal{O}(\max(m_{\mathcal{X}}^3, m_{\mathcal{Y}}^3))$

Complexity of $R_{\mathcal{Z}} K_Z$: depends on the sketch matrix, between $\mathcal{O}(nm_{\mathcal{Z}})$ and $\mathcal{O}(n^2 m_{\mathcal{Z}})$

$$\implies \text{Training complexity reduced!}$$

- **Test set:** X_{te} of size n_{te}
- **Candidate set:** $\mathcal{Y}_c \subseteq \mathcal{Y}$ of size n_c

$$\underbrace{K_{te,tr}R_{\mathcal{X}}^{\top}}_{n_{te} \times m_{\mathcal{X}}} \underbrace{\widetilde{\Omega}}_{m_{\mathcal{X}} \times m_{\mathcal{Y}}} \underbrace{R_{\mathcal{Y}}K_{tr,c}^{y}}_{m_{\mathcal{Y}} \times n_c} \tag{12}$$

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Decoding complexity: $\mathcal{O}(n_{te}nn_c) \rightarrow \mathcal{O}(n_{te}m_{\mathcal{Y}}n_c)$ if
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$$\implies \text{ Inference complexity reduced!}$$

Theoretical Analysis

Asm. 1 (Attainability): Recall that $h^*(x) := \mathbb{E}_Y[\psi_{\mathcal{Y}}(Y) \mid X = x]$. $h^* \in \mathcal{H}$, i.e. there exists $H : \mathcal{H}_{\mathcal{X}} \to \mathcal{H}_{\mathcal{Y}}$ with $\|H\|_{\mathsf{HS}} < +\infty$ such that

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$$\psi_{\mathcal{Z}}(z) \otimes \psi_{\mathcal{Z}}(z) \preceq b_{\mathcal{Z}} C_{\mathcal{Z}}^{1-\mu_{\mathcal{Z}}}. \tag{16}$$

Assumptions

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Asm. 5 (Sub-Gaussian sketches): $R_{\mathcal{Z}} \in \mathbb{R}^{m_{\mathcal{Z}} \times n}$ composed with i.i.d. entries s.t. (i) $\mathbb{E}\left[R_{\mathcal{Z}_{ij}}\right] = 0$, (ii) $\mathbb{E}\left[R_{\mathcal{Z}_{ij}}^2\right] = 1/m_{\mathcal{Z}}$ and (iii) $R_{\mathcal{Z}_{ij}} \sim \frac{\nu_{\mathcal{Z}}^2}{m_{\mathcal{Z}}} -$ sub-Gaussian with $\nu_{\mathcal{Z}} \geq 1$.

Corollary (SISOKR learning rates)

*Under **Asm. 1, 2, 3, 4 and 5**, if for all $y \in \mathcal{Y}, \|\psi_{\mathcal{Y}}(y)\|_{\mathcal{H}_{\mathcal{Y}}} = \kappa_{\mathcal{Y}}$, for $n \in \mathbb{N}$ sufficiently large such that $\frac{9}{n} \log(n/\delta) \leq n^{-\frac{1}{1+\gamma_{\mathcal{X}}}} \leq \|C_{\mathcal{X}}\|_{\mathsf{op}}/2$, and $\frac{9}{n} \log(n/\delta) \leq n^{-\frac{1}{1+\gamma_{\mathcal{Y}}}} \leq \|C_{\mathcal{Y}}\|_{\mathsf{op}}/2$, and for sketching size $m_{\mathcal{X}}, m_{\mathcal{Y}} \in \mathbb{N}$ such that*

$$m_{\mathcal{X}} \gtrsim \max\left(\nu_{\mathcal{X}}^2 n^{\frac{\gamma_{\mathcal{X}}+\mu_{\mathcal{X}}}{1+\gamma_{\mathcal{X}}}}, \nu_{\mathcal{X}}^4 \log\left(1/\delta\right)\right), \tag{17}$$

$$m_{\mathcal{Y}} \gtrsim \max\left(\nu_{\mathcal{Y}}^2 n^{\frac{\gamma_{\mathcal{Y}}+\mu_{\mathcal{Y}}}{1+\gamma_{\mathcal{Y}}}}, \nu_{\mathcal{Y}}^4 \log\left(1/\delta\right)\right), \tag{18}$$

then with probability $1 - \delta$

$$\mathbb{E}[\|\tilde{h}(x) - h^*(x)\|_{\mathcal{H}_{\mathcal{Y}}}^2]^{\frac{1}{2}} \lesssim \log\left(4/\delta\right) n^{-\frac{1-\gamma_{\mathcal{X}} \vee \gamma_{\mathcal{Y}}}{2(1+\gamma_{\mathcal{X}} \vee \gamma_{\mathcal{Y}})}}, \tag{19}$$

and

$$\mathcal{R}(\tilde{f}) - \mathcal{R}(f^*) \lesssim \log\left(4/\delta\right) n^{-\frac{1-\gamma_{\mathcal{X}} \vee \gamma_{\mathcal{Y}}}{2(1+\gamma_{\mathcal{X}} \vee \gamma_{\mathcal{Y}})}}. \tag{20}$$

Experiments

Multi-Label Classification: Statistical Performance

Table 1: F_1 score on tag prediction from text data.

Method	Bibtex	Bookmarks
SISOKR	44.1 ± 0.07	$\mathbf{39.3 \pm 0.61}$
ISOKR	44.8 ± 0.01	NA
SIOKR	44.7 ± 0.09	39.1 ± 0.04
IOKR	**44.9**	NA
LR	37.2	30.7
NN	38.9	33.8
SPEN	42.2	34.4
PRLR	44.2	34.9
DVN	44.7	37.1

Multi-Label Classification: Computational Performance

Table 2: Comparison of training/inference computation times (in seconds).

Method	Bibtex	Bookmarks
SISOKR	$\mathbf{1.41 \pm 0.03}$ / $\mathbf{0.46 \pm 0.01}$	$\mathbf{118 \pm 1.5}$ / $\mathbf{20 \pm 0.2}$
ISOKR	2.51 ± 0.06 / 0.58 ± 0.01	NA
SIOKR	1.99 ± 0.07 / 1.22 ± 0.03	354 ± 2.1 / 297 ± 2.1
IOKR	2.54 / 1.18	NA

Conclusion

- Scale up surrogate kernel methods for structured prediction by leveraging **random projections**, in **both input and output** feature spaces, to **accelerate training and inference** phases

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- Derive **excess risk bounds** for the **sketched estimator**
- Show that **sub-Gaussian** sketches are admissible sketches in the sense that they lead to **close to optimal learning rates** with **sketching sizes** $m < n$
- Provide structured prediction **experiments** on **real-world data sets** showing **similar performances** as **IOKR** while **being faster** in **both training and inference** phases.

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Reminder: positive definite kernels and Reproducing Kernel Hilbert Space

Positive definite kernel: $k_{\mathcal{Z}} : \mathcal{Z} \times \mathcal{Z} \to \mathbb{R}$ such that

- for all $(z, z') \in \mathcal{Z}^2$, $k_{\mathcal{Z}}(z, z') = k_{\mathcal{Z}}(z', z)^{\top}$
- for all $n \in \mathbb{N}$ and any $(z_i, \alpha_i)_{i=1}^{n} \in (\mathcal{Z} \times \mathbb{R})^n$,
  $\sum_{i,j=1}^{n} \alpha_i \alpha_j k_{\mathcal{Z}}(z_i, z_j) \geqslant 0$

RKHS (Aronszajn, 1950): Hilbert space $\mathcal{H}_{\mathcal{Z}}$ of functions $f : \mathcal{Z} \to \mathbb{R}$ s. t. for all $f \in \mathcal{H}_{\mathcal{Z}}$ and $z \in \mathcal{Z}$

1. $z' \mapsto k_{\mathcal{Z}}(z, z') \in \mathcal{H}_{\mathcal{Z}}$,
2. $\langle f, k_{\mathcal{Z}}(\cdot, z) \rangle_{\mathcal{H}_{\mathcal{Z}}} = f(z)$ (reproducing property).

Operator-valued kernel (Senkene and Tempel'man, 1973; Micchelli and Pontil, 2005; Carmeli et al., 2006, 2010): $\mathcal{K} : \mathcal{X} \times \mathcal{X} \to \mathcal{L}(\mathcal{F})$, where $\mathcal{F}$ is a Hilbert space, such that

- for all $(x, x') \in \mathcal{X}^2$, $\mathcal{K}(x, x') = \mathcal{K}(x', x)^{\#}$
- for all $n \in \mathbb{N}$ and any $(x_i, \varphi_i)_{i=1}^n \in (\mathcal{X} \times \mathcal{F})^n$,
  $\sum_{i,j=1}^n \langle \varphi_i, \mathcal{K}(x_i, x_j) \varphi_j \rangle_{\mathcal{F}} \geqslant 0$

vv-RKHS: Hilbert space $\mathcal{H}$ of functions $f : \mathcal{X} \to \mathcal{F}$ s. t. for all $f \in \mathcal{H}$, $\varphi \in \mathcal{F}$ and $x \in \mathcal{X}$

1. $x' \mapsto \mathcal{K}(x, x') \varphi \in \mathcal{H}$,
2. $\langle f, \mathcal{K}(\cdot, x) \varphi \rangle_{\mathcal{H}} = \langle f(x), \varphi \rangle_{\mathcal{F}}$ (reproducing property).

Background: Scalability to large datasets

1) Random Fourier Features (Rahimi and Recht, 2007; Rudi and Rosasco, 2017; Sriperumbudur and Szabó, 2015; Brault et al., 2016; Li et al., 2021)

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1) Random Fourier Features (Rahimi and Recht, 2007; Rudi and Rosasco, 2017; Sriperumbudur and Szabó, 2015; Brault et al., 2016; Li et al., 2021)

2) Sketching (Mahoney et al., 2011; Woodruff, 2014): dimension reduction approach based on random linear projections

- Nyström approximation ($\iff$ sub-sampling sketch) (Williams and Seeger, 2001; Drineas et al., 2005; Bach, 2013; Rudi et al., 2017; Meanti et al., 2020)
- Gaussian, Randomized Orthogonal Systems, sparse sketches etc. (Yang et al., 2017; Lacotte et al., 2019; Kpotufe and Sriperumbudur, 2020; Lacotte and Pilanci, 2020; Chen and Yang, 2021a; Gazagnadou et al., 2021)

Representer theorem: $\hat{f} = \sum_{i=1}^{n} \hat{\alpha}_i k_x(\cdot, x_i)$, where

$$\hat{\alpha} = (\hat{\alpha}_1, \ldots, \hat{\alpha}_n)^\top = \underset{\alpha \in \mathbb{R}^n}{\text{argmin}}\ \alpha^\top \left(K_X^2 + n\lambda K_X\right) \alpha - 2Y^\top K_X \alpha$$

$$= \underbrace{\left(K_X + n\lambda I_n\right)^{-1}}_{n \times n} Y$$

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Let $m \ll n$, $R \in \mathbb{R}^{m \times n}$ be a random matrix: $\alpha \leftarrow R^\top \gamma$

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Let $m \ll n$, $R \in \mathbb{R}^{m \times n}$ be a random matrix: $\alpha \leftarrow R^{\top} \gamma$

$\hat{f} \leftarrow \tilde{f} = \sum_{i=1}^{n} [R^{\top} \tilde{\gamma}]_i k_x(\cdot, x_i)$, where

$$\tilde{\gamma} = (\tilde{\gamma}_1, \ldots, \tilde{\gamma}_m)^{\top} = \underset{\gamma \in \mathbb{R}^m}{\mathrm{argmin}} \; \gamma^{\top} \left(R K_X^2 R^{\top} + n\lambda R K_X R^{\top} \right) \gamma - 2Y^{\top} K_X R^{\top} \gamma$$

$$= \underbrace{(R K_X^2 R^{\top} + n\lambda R K_X R^{\top}}_{m \times m})^{\dagger} R K_X Y$$

Low-rank estimator

$$\hat{h}(x) = \sum_{i=1}^{n} \hat{\alpha}_i(x)\psi_{\mathcal{Y}}(y_i), \quad \text{where} \quad \hat{\alpha}(x) = (K_X + n\lambda I_n)^{-1}k_X^x$$

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$$= \sqrt{n} S_Y^{\#} \hat{\alpha}(x)$$
$$= \sqrt{n} S_Y^{\#} (n S_X S_X^{\#} + n\lambda I_n)^{-1} \sqrt{n} S_X \psi_{\mathcal{X}}(x)$$

$$\hat{h}(x) = \sum_{i=1}^{n} \hat{\alpha}_i(x)\psi_{\mathcal{Y}}(y_i), \quad \text{where} \quad \hat{\alpha}(x) = (K_X + n\lambda I_n)^{-1} k_X^x$$

$$= \sqrt{n} S_Y^{\#} \hat{\alpha}(x)$$

$$= \sqrt{n} S_Y^{\#} (n S_X S_X^{\#} + n\lambda I_n)^{-1} \sqrt{n} S_X \psi_{\mathcal{X}}(x)$$

$$\hat{h}(x) = S_Y^{\#} S_X (S_X^{\#} S_X + \lambda I_{\mathcal{H}_{\mathcal{X}}})^{-1} \psi_{\mathcal{X}}(x)$$

$$\hat{h}(x) = \sum_{i=1}^{n} \hat{\alpha}_i(x)\psi_{\mathcal{Y}}(y_i)\,, \quad \text{where} \quad \hat{\alpha}(x) = (K_X + n\lambda I_n)^{-1} k_X^x$$

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$$\hat{h}(x) = S_Y^{\#} S_X \left(S_X^{\#} S_X + \lambda I_{\mathcal{H}_{\mathcal{X}}}\right)^{-1} \psi_{\mathcal{X}}(x)$$

Goal: Given orthogonal projectors $\widetilde{P}_X$ and $\widetilde{P}_Y$ onto subspaces of $\mathcal{H}_{\mathcal{X}}$ and $\mathcal{H}_{\mathcal{Y}}$ resp.

$$\hat{h}(x) = \sum_{i=1}^{n} \hat{\alpha}_i(x)\psi_{\mathcal{Y}}(y_i)\,, \quad \text{where} \quad \hat{\alpha}(x) = (K_X + n\lambda I_n)^{-1}k_X^x$$

$$= \sqrt{n}S_Y^{\#}\hat{\alpha}(x)$$

$$= \sqrt{n}S_Y^{\#}(nS_XS_X^{\#} + n\lambda I_n)^{-1}\sqrt{n}S_X\psi_{\mathcal{X}}(x)$$

$$\textcolor{red}{\hat{h}(x)} = \textcolor{red}{S_Y^{\#}}\textcolor{green}{S_X}\big(\textcolor{green}{S_X^{\#}}\textcolor{green}{S_X} + \lambda I_{\mathcal{H}_{\mathcal{X}}}\big)^{-1}\psi_{\mathcal{X}}(x)$$

Goal: Given orthogonal projectors $\widetilde{P}_X$ and $\widetilde{P}_Y$ onto subspaces of $\mathcal{H}_{\mathcal{X}}$ and $\mathcal{H}_{\mathcal{Y}}$ resp.

$$\textcolor{red}{S_X^{\#}} \leftarrow \widetilde{P}_X S_X^{\#} \quad \text{and} \quad \textcolor{red}{S_Y^{\#}} \leftarrow \widetilde{P}_Y S_Y^{\#}$$

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Table 3: Time and space complexities at training and inference for the IOKR and SISOKR algorithms with sub-sampling, p-sparsified ($p \in (0, 1]$) or Gaussian sketching, for a test set of size n_{te} and a candidate set of size n_c, such that $n_{te} \leq m_{\mathcal{X}}, m_{\mathcal{Y}} < n \leq n_c$. For the sake of simplicity, we omit the $\mathcal{O}(\cdot)$ in the following.

Method	Training		Inference	
	Time	Space	Time	Space
IOKR	n^3	n^2	$n_{te}nn_c$	nn_c
SISOKR (sub-sampling)	$\max(m_{\mathcal{X}}, m_{\mathcal{Y}})n$	$\max(m_{\mathcal{X}}, m_{\mathcal{Y}})n$	$n_{te}m_{\mathcal{Y}}n_c$	$m_{\mathcal{Y}}n_c$
SISOKR (p-sparsified)	$\max(m_{\mathcal{X}}, m_{\mathcal{Y}})^2 pn$	$\max(m_{\mathcal{X}}, m_{\mathcal{Y}})pn$	$\max(n_{te}, nm_{\mathcal{Y}}p)m_{\mathcal{Y}}n_c$	$npm_{\mathcal{Y}}n_c$
SISOKR (Gaussian)	$\max(m_{\mathcal{X}}, m_{\mathcal{Y}})n^2$	n^2	$nm_{\mathcal{Y}}n_c$	nn_c

Related works and differences

Rudi et al. (2015):

1. **scalar** kernel Ridge regression
2. sketching **only** applied in the **input** feature space
3. **Nyström** approximation with **uniform** or **approximate leverage scores** sampling

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This work:

1. **vector-valued** kernel Ridge regression, with possibly infinite-dimensional outputs
2. sketching applied in **both** the **input and output** feature space
3. generic **sub-Gaussian** sketches

Theorem (SISOKR excess-risk bound)

*Let $\delta \in [0, 1]$, $n \in \mathbb{N}$ sufficiently large such that $\lambda = n^{-1/(1+\gamma_\mathcal{X})} \geq \frac{9\kappa_\mathcal{X}^2}{n} \log(\frac{n}{\delta})$. Under **Asm. 1, 2, 3 and 4**, the following holds with probability at least $1 - \delta$*

$$\mathbb{E}[\|\tilde{h}(x) - h^*(x)\|_{\mathcal{H}_\mathcal{Y}}^2]^{\frac{1}{2}} \leq S(n) + c_2 A_{\rho_x}^{\psi_\mathcal{X}}(\widetilde{P}_X) + A_{\rho_y}^{\psi_\mathcal{Y}}(\widetilde{P}_Y)$$

where

$S(n) = c_1 \log(4/\delta) n^{-\frac{1}{2(1+\gamma_\mathcal{X})}}$ *(regression error)*

$A_{\rho_z}^{\psi_\mathcal{Z}}(\widetilde{P}_Z) = \mathbb{E}_z[\|(\widetilde{P}_Z - I_{\mathcal{H}_z})\psi_\mathcal{Z}(z)\|_{\mathcal{H}_z}^2]^{\frac{1}{2}}$ *(sketching reconstruction error)*

and $c_1, c_2 > 0$ are constants independent of n and δ defined in the proofs.

Sub-Gaussian sketch

Definition

A sub-Gaussian sketch $R_{\mathcal{Z}} \in \mathbb{R}^{m_{\mathcal{Z}} \times n}$ is composed with i.i.d. entries such that

$$\mathbb{E}\left[R_{\mathcal{Z}_{ij}}\right] = 0 \tag{22}$$

$$\mathbb{E}\left[R_{\mathcal{Z}_{ij}}^2\right] = 1/m \tag{23}$$

$$R_{\mathcal{Z}_{ij}} \sim \frac{\nu_{\mathcal{Z}}^2}{m} - \text{sub-Gaussian}, \quad \text{with} \quad \nu_{\mathcal{Z}} \geq 1 \tag{24}$$

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- matrix composed with i.i.d. Gaussian entries
- matrix composed with i.i.d. bounded random variables

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Examples:

- matrix composed with i.i.d. Gaussian entries
- matrix composed with i.i.d. bounded random variables
- matrix composed with i.i.d. Gaussian/bounded r.v. multiplied with independent Bernoulli r.v. (El Ahmad et al., 2023)

Theorem (Sub-Gaussian sketching reconstruction error)

*Under **Asm. 1, 2, 3 and 4**, for $\delta \in (0, 1/e)$, $n \in \mathbb{N}$ sufficiently large such that $\frac{9}{n} \log(n/\delta) \leq n^{-\frac{1}{1+\gamma_{\mathcal{Z}}}} \leq \|C_{\mathcal{Z}}\|_{\mathrm{op}}/2$, then if*

$$m_{\mathcal{Z}} \geq c_4 \max \left(\nu_{\mathcal{Z}}^2 n^{\frac{\gamma_{\mathcal{Z}} + \mu_{\mathcal{Z}}}{1+\gamma_{\mathcal{Z}}}}, \nu_{\mathcal{Z}}^4 \log\left(1/\delta\right) \right), \tag{25}$$

then with probability $1 - \delta$

$$\mathbb{E}_z[\|(\widetilde{P}_Z - I_{\mathcal{H}_{\mathcal{Z}}})\psi_{\mathcal{Z}}(z)\|_{\mathcal{H}_{\mathcal{Z}}}^2] \leq c_3 n^{-\frac{1-\gamma_{\mathcal{Z}}}{(1+\gamma_{\mathcal{Z}})}} \tag{26}$$

where $c_3, c_4 > 0$ are constants independents of $n, m_{\mathcal{Z}}, \delta$ defined in the proofs.

1) $n = 10,000$, $\mathcal{X} = \mathcal{Y} = \mathbb{R}^d$, $d = 300$, $k_\mathcal{X}$ and $k_\mathcal{Y}$ linear kernels $\implies$ $\mathcal{H}_\mathcal{X} = \mathcal{H}_\mathcal{Y} = \mathbb{R}^d$

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Synthetic Least Squares Regression

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3) Draw $H_0 \sim \mathcal{N}(0, I_d)$, and for $i \leq n$, $x_i \sim \mathcal{N}(0, C_\mathcal{X})$, $\epsilon_i \sim \mathcal{N}(0, E)$,

$$y_i = C_\mathcal{X} H_0 x_i + \epsilon_i \tag{27}$$

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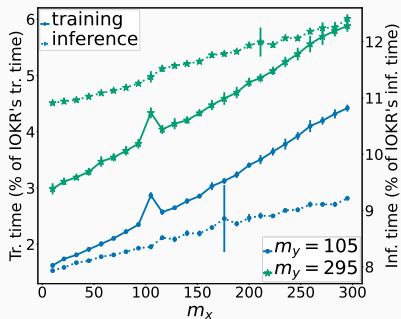
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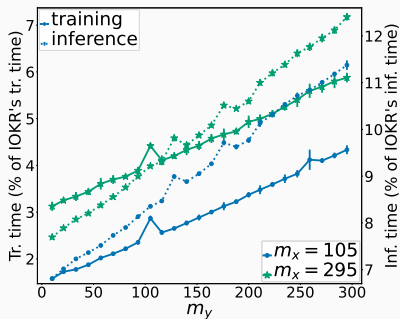
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4) $(2 \cdot 10^{-2})$-SR input and output sketches

(a) Training and inference time w.r.t. $m_{\mathcal{X}}$ for $m_{\mathcal{Y}} \in \{105, 295\}$

(b) Training and inference time w.r.t. $m_{\mathcal{Y}}$ for $m_{\mathcal{X}} \in \{105, 295\}$
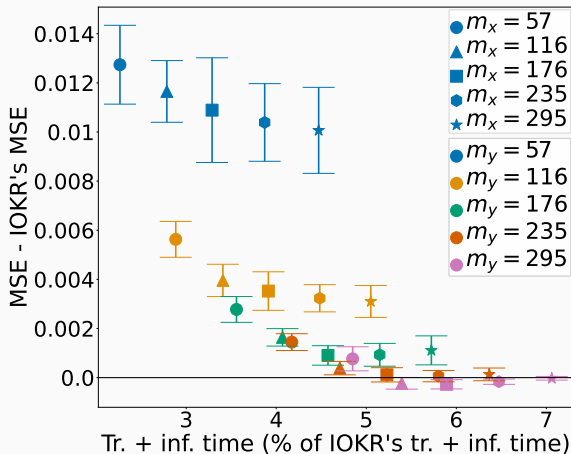
Figure 2: MSE w.r.t. learning time for different values of $m_{\mathcal{X}}$ and $m_{\mathcal{Y}}$

Synthetic Least Squares Regression
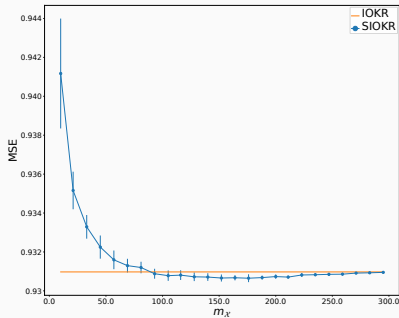
(a) SIOKR
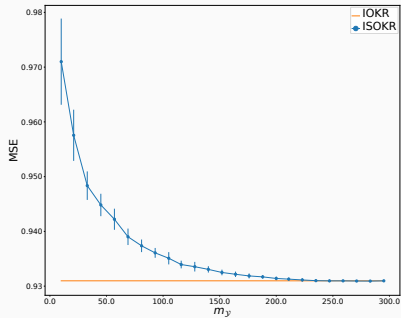
(b) ISOKR

Multi-Label Classification

Bibtex and Bookmarks (Katakis et al., 2008): tag recommendation problems

Mediamill: detection of semantic concepts in a video

Table 4: Multi-label data sets description.

Data set	n	n_{te}	$n_{features}$	n_{labels}
Bibtex	4880	2515	1836	159
Bookmarks	60000	27856	2150	298
Mediamill	30993	12914	120	101

Table 5: F_1 scores on tag prediction from text data.

Method	Bibtex	Bookmarks	Mediamill
LR	37.2	30.7	NA
SPEN	42.2	34.4	NA
PRLR	44.2	34.9	NA
DVN	44.7	37.1	NA
SISOKR	44.1 ± 0.07	$\mathbf{39.3} \pm 0.61$	57.26 ± 0.04
ISOKR	44.8 ± 0.01	NA	58.02 ± 0.01
SIOKR	44.7 ± 0.09	39.1 ± 0.04	57.33 ± 0.04
IOKR	**44.9**	NA	**58.17**

Table 6: Training/inference times (in seconds).

Method	Bibtex	Bookmarks	Mediamill
SISOKR	**1.41 $\pm$ 0.03 / 0.46 $\pm$ 0.01**	**118 $\pm$ 1.5 / 20 $\pm$ 0.2**	**66 $\pm$ 0.1 / 4 $\pm$ 0.01**
ISOKR	2.51 $\pm$ 0.06 / 0.58 $\pm$ 0.01	NA	636 $\pm$ 3.7 9 $\pm$ 0.2
SIOKR	1.99 $\pm$ 0.07 / 1.22 $\pm$ 0.03	354 $\pm$ 2.1 / 297 $\pm$ 2.1	199 $\pm$ 0.1 / 121 $\pm$ 0.02
IOKR	2.54 / 1.18	NA	621 / 204

Metabolite identification

Inputs: tandem mass spectrum of a metabolite (small molecule

Outputs: molecular structure, i.e. fingerprints, encoded by binary vectors of length $d = 7593$

$n = 6974$ and each molecule is associated to a candidate set: median size = 292 and largest = 36,918 fingerprints

Table 7: MSE and standard errors for the metabolite identification problem. SPEN directly predicts outputs in $\mathcal{Y}$, then MSE is not defined.

Method	MSE	Tanimoto-Gaussian loss	Top-1 | 5 | 10 accuracies
SISOKR	0.813 ± 0.002	0.566 ± 0.007	25.1% | 54.2% | 64.7%
ISOKR	0.794 ± 0.003	0.509 ± 0.009	28.0% | 58.9% | 68.9%
SIOKR	0.793 ± 0.002	0.492 ± 0.008	29.5% | 61.3% | 70.9%
IOKR	$\mathbf{0.780} \pm 0.002$	$\mathbf{0.486} \pm 0.008$	**29.6%** | **61.6%** | **71.4%**
SPEN	NA	0.537 ± 0.008	25.9% | 54.1% | 64.3%

Table 8: Comparison of training/inference computation times (in seconds).

Method	Metabolite
SISOKR	4.05 ± 0.05 / $\mathbf{1112 \pm 29}$
ISOKR	6.25 ± 50.31 / 1133 ± 32
SIOKR	$\mathbf{1.25 \pm 0.02}$ / 1179 ± 37
IOKR	3.54 ± 0.15 / 1191 ± 38

Let $m < n$, and $p \in (0, 1]$. A p-sparsified sketch $R \in \mathbb{R}^{m \times n}$ is composed of i.i.d. entries

$$R_{ij} = \frac{1}{\sqrt{sp}} \, B_{ij} S_{ij} \, ,$$

where $B_{ij} \overset{\text{i.i.d.}}{\sim} \text{Ber}(p)$ and $S_{ij} \overset{\text{i.i.d.}}{\sim} \text{Rad}(\frac{1}{2})$ (p-SR) or $\mathcal{N}(0, 1)$ (p-SG).

Let $m' = \sum_{j=1}^{n} \mathbb{I}\{R_{\cdot j} \neq 0_s\}$,

$$R = R_{\mathrm{SG}} \, R_{\mathrm{SS}} \,,$$

where

- $R_{\mathrm{SG}} \in \mathbb{R}^{m \times m'} \leftarrow$ deleting the null columns from R
- $R_{\mathrm{SS}} \in \mathbb{R}^{m' \times n} \leftarrow$ sampling the rows of I_n corresponding to the indices of non-zero columns of R.

Example:

$$\begin{pmatrix} 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & -1 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \end{pmatrix}$$

$$m' \sim \mathrm{Binom}\left(n, 1 - (1-p)^m\right) \implies \mathbb{E}\left[m'\right] = n(1 - (1-p)^m) \underset{p \to 0}{\sim} nmp$$

Advantages of sub-sampling sketch

Let $X = \{x_1, \ldots, x_5\}$, $k_X^{x_i} = (k(x_i, x_1), \ldots, k(x_i, x_5))$ and
$$R_{SS} = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \end{pmatrix}$$

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$\Longleftrightarrow$

1. Sample $X' = \{x_1, x_4\}$
2. Directly construct sub-Gram matrices $K_{X',X} \in \mathbb{R}^{2 \times 5}$ and $K_{X',X'} \in \mathbb{R}^{2 \times 2}$

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$\Longrightarrow$ No need to compute costly matrix multiplications!

$\Longrightarrow$ No need to compute the whole K and store it in memory!

Let C_k be the cost of computing $k(x, x')$ for a couple $(x, x') \in \mathcal{X}^2$

- Standard sketch (e.g. Gaussian): $\mathcal{O}\left(C_k n^2 + n^2 m\right)$ and $\mathcal{O}\left(n^2\right)$,
- p-sparsified sketch: $\mathcal{O}\left(C_k n^2 m p + n^2 m^2 p\right)$ and $\mathcal{O}\left(n^2 m p\right)$.

$\implies$ Complexity reduction if $p < 1/m$

p-sparsified sketch's goal $\rightarrow$ best of both worlds:

1. computational efficiency of sub-sampling sketch
2. statistical accuracy of Rademacher or Gaussian sketch

p-sparsified sketch's goal → best of both worlds:

1. computational efficiency of sub-sampling sketch
2. statistical accuracy of Rademacher or Gaussian sketch

Related works:

1. sub-sampling sketch with data-dependent sampling schemes (e.g. leverage scores) (Alaoui and Mahoney, 2015; Musco and Musco, 2017; Rudi et al., 2018; Chen and Yang, 2021b)
2. accumulation sketch (Chen and Yang, 2021a): sum of sub-sampling sketches