ESP32-WROOM-32D & ESP32-WROOM-32U

Datasheet Version 2.6





Module Overview

Note:

Check the link or the QR code to make sure that you use the latest version of this document: https://espressif.com/documentation//esp32-wroom-32d_esp32-wroom-32u_datasheet_en.pdf



1.1 **Features**

CPU and On-Chip Memory

- ESP32-DOWD embedded, Xtensa dual-core 32-bit LX6 microprocessor, up to 240 MHz
- 448 KB ROM
- 520 KB SRAM
- 8 KB SRAM in RTC

Wi-Fi

- 802.11b/g/n
- Bit rate: 802.11n up to 150 Mbps
- A-MPDU and A-MSDU aggregation
- 0.4 μ s guard interval support
- Center frequency range of operating channel: 2412 ~ 2484 MHz

Bluetooth®

- Bluetooth V4.2 BR/EDR and Bluetooth LE specification
- Class-1, class-2 and class-3 transmitter
- AFH
- CVSD and SBC

Peripherals

• Up to 32 GPIOs

- 5 strapping GPIOs
- SD card, UART, SPI, SDIO, I2C, LED PWM, Motor PWM, I2S, IR, pulse counter, GPIO, capacitive touch sensor, ADC, DAC, TWAI® (compatible with ISO 11898-1, i.e. CAN Specification 2.0)

Integrated Components on Module

- 40 MHz crystal oscillator
- 4 MB SPI flash

Antenna Options

- ESP32-WROOM-32D: On-board PCB antenna
- ESP32-WROOM-32U: External antenna via a connector

Operating Conditions

- Operating voltage/Power supply: 3.0 ~ 3.6 V
- Operating ambient temperature: −40 ~ 85 °C

Certification

• RF certification: See certificates

Green certification: REACH/RoHS

Test

• HTOL/HTSL/uHAST/TCT/ESD

Series Comparison

ESP32-WROOM-32D and ESP32-WROOM-32U are powerful, generic Wi-Fi + Bluetooth® + Bluetooth LE MCU modules that target a wide variety of applications, ranging from low-power sensor networks to the most demanding tasks, such as voice encoding, music streaming and MP3 decoding.

ESP32-WROOM-32D comes with a PCB antenna. ESP32-WROOM-32U comes with a connector for an external antenna. The modules feature a 4 MB external SPI flash.

The series comparison for the modules is as follows:

Table 1: ESP32-WROOM-32D (ANT) Series Comparison

Ordering Code	Flash ³	Ambient Temp. ¹ (°C)	Size ² (mm)	
ESP32-WROOM-32D	4 MB	-40 ~ 85	18 × 25.5 × 3.1	

¹ Ambient temperature specifies the recommended temperature range of the environment immediately outside the Espressif module.

Table 2: ESP32-WROOM-32U (CONN) Series Comparison⁴

Ordering Code	Flash ³	Ambient Temp. ¹ (°C)	Size ² (mm)
ESP32-WROOM-32U	4 MB	-40 ~ 85	18 × 19.2 × 3.2

⁴ This table shares the same notes presented in Table 1 above.

At the core of the modules is ESP32-DOWD *, an Xtensa® 32-bit LX7 CPU that operates at up to 240 MHz. You can power off the CPU and make use of the low-power coprocessor to constantly monitor the peripherals for changes or crossing of thresholds.

Note:

- For details on the part numbers of the ESP32 family of chips, please refer to the document ESP32 Datasheet.
- For chip revision identification, ESP-IDF release that supports a specific chip revision, and other information on chip revisions, please refer to ESP32 Series SoC Errata > Section Chip Revision Identification.

Applications 1.3

- Smart Home
- Industrial Automation
- Health Care
- Consumer Electronics
- Smart Agriculture
- POS Machines
- Service Robot

- Audio Devices
- Generic Low-power IoT Sensor Hubs
- Generic Low-power IoT Data Loggers
- Cameras for Video Streaming
- Speech Recognition
- Image Recognition
- SDIO Wi-Fi + Bluetooth Networking Card

² For details, refer to Section 9.1 Module Dimensions.

³ For specifications, refer to Section 5.5 Memory Specifications.

Contents

1.1 1.2 1.3	Module Overview Features Series Comparison Applications	2 2 2 3
2 2.1 2.2	Pin Definitions Pin Layout Pin Description	8 8 8
3.1 3.2 3.3 3.4 3.5 3.6	Boot Configurations Chip Boot Mode Control Internal LDO (VDD_SDIO) Voltage Control UOTXD Printing Control Timing Control of SDIO Slave JTAG Signal Source Control Chip Power-up and Reset	10 11 12 13 13 13
4 4.1 4.2	Peripherals Peripheral Overview Digital Peripherals 4.2.1 General Purpose Input / Output Interface (GPIO) 4.2.2 Serial Peripheral Interface (SPI) 4.2.3 Universal Asynchronous Receiver Transmitter (UART) 4.2.4 I2C Interface 4.2.5 I2S Interface 4.2.6 Remote Control Peripheral 4.2.7 Pulse Counter Controller (PCNT) 4.2.8 LED PWM Controller 4.2.9 Motor Control PWM 4.2.10 SD/SDIO/MMC Host Controller 4.2.11 SDIO/SPI Slave Controller 4.2.12 TWAI® Controller 4.2.13 Ethernet MAC Interface	15 15 15 15 15 16 16 17 17 18 18 19 20 20 21
4.3	Analog Peripherals 4.3.1 Analog-to-Digital Converter (ADC) 4.3.2 Digital-to-Analog Converter (DAC) 4.3.3 Touch Sensor	22 22 23 24
5 5.1 5.2 5.3 5.4	Electrical Characteristics Absolute Maximum Ratings Recommended Operating Conditions DC Characteristics (3.3 V, 25 °C) Current Consumption Characteristics	25 25 25 25 25 26

5.5	Memory Specifications	26
6 6.1	RF Characteristics Wi-Fi Radio 6.1.1 Wi-Fi RF Transmitter (TX) Characteristics 6.1.2 Wi-Fi RF Receiver (RX) Characteristics Bluetooth LE Radio 6.2.1 Receiver 6.2.2 Transmitter	27 27 27 28 29 29
7	Module Schematics	31
8	Peripheral Schematics	33
9 9.1 9.2	Physical Dimensions Module Dimensions Dimensions of External Antenna Connector	34 34 36
10 10.1 10.2	PCB Layout Recommendations PCB Land Pattern Module Placement for PCB Design	38 38 39
11 11.1 11.2 11.3 11.4	Product Handling Storage Conditions Electrostatic Discharge (ESD) Reflow Profile Ultrasonic Vibration	4C 4C 4C 4C 4C
Dat	tasheet Versioning	42
Rel	ated Documentation and Resources	43
Rev	vision History	44

List of Tables

1	ESP32-WROOM-32D (ANT) Series Comparison	3
2	ESP32-WROOM-32U (CONN) Series Comparison ⁴	3
3	Pin Definitions	8
4	Default Configuration of Strapping Pins	10
5	Description of Timing Parameters for the Strapping Pins	11
6	Chip Boot Mode Control	11
7	UOTXD Printing Control	13
8	Timing Control of SDIO Slave	13
9	Description of Timing Parameters for Power-up and Reset	14
10	ADC Characteristics	23
11	ADC Calibration Results	23
12	Capacitive-Sensing GPIOs Available on ESP32	24
13	Absolute Maximum Ratings	25
14	Recommended Operating Conditions	25
15	DC Characteristics (3.3 V, 25 °C)	25
16	Flash Specifications	26
17	Wi-Fi RF Characteristics	27
18	TX Power with Spectral Mask and EVM Meeting 802.11 Standards	27
19	TX EVM Test ¹	27
20	RX Sensitivity	28
21	Maximum RX Level	29
22	RX Adjacent Channel Rejection	29
23	Receiver Characteristics - Bluetooth LE	29
24	Transmitter Characteristics - Bluetooth LF	30

List of Figures

1	ESP32-WROOM-32D Pin Layout (Top View)	8
2	Visualization of Timing Parameters for the Strapping Pins	11
3	Chip Boot Flow	12
4	Visualization of Timing Parameters for Power-up and Reset	13
5	ESP32-WROOM-32D Schematics	31
6	ESP32-WROOM-32U Schematics	32
7	ESP32-WROOM-32D & ESP32-WROOM-32U Peripheral Schematics	33
8	Physical Dimensions of ESP32-WROOM-32D	34
9	Physical Dimensions of ESP32-WROOM-32U	35
10	Dimensions of External Antenna Connector	36
11	Recommended PCB Land Pattern of ESP32-WROOM-32D	38
12	Recommended PCB Land Pattern of ESP32-WROOM-32U	39
13	Reflow Profile	40

2 Pin Definitions

2.1 Pin Layout

The pin diagram below shows the approximate location of pins on the module. For the actual diagram drawn to scale, please refer to Figure 9.1 *Module Dimensions*.

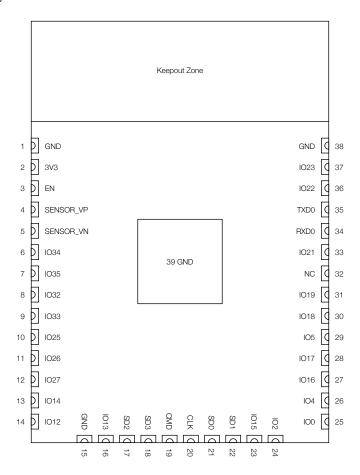


Figure 1: ESP32-WROOM-32D Pin Layout (Top View)

Note:

The pin layout of ESP32-WROOM-32U is the same as that of ESP32-WROOM-32D, except that ESP32-WROOM-32U has no keepout zone.

2.2 Pin Description

The module has 38 pins. See pin definitions in Table 3 Pin Description.

Table 3: Pin Definitions

Name	No.	Туре	Function
GND	1	Р	Ground
3V3	2	Р	Power supply

Name	No.	Туре	Function	
EN	3	1	Module-enable signal. Active high.	
SENSOR_VP	4	I	GPIO36, ADC1_CHO, RTC_GPIOO	
SENSOR_VN	5	I	GPIO39, ADC1_CH3, RTC_GPIO3	
1034	6	1	GPIO34, ADC1_CH6, RTC_GPIO4	
1035	7	1	GPIO35, ADC1_CH7, RTC_GPIO5	
1020	0	1/0	GPIO32, XTAL_32K_P (32.768 kHz crystal oscillator input), ADC1_CH4,	
1032	8	1/0	TOUCH9, RTC_GPIO9	
1033		1/0	GPIO33, XTAL_32K_N (32.768 kHz crystal oscillator output), ADC1_CH5,	
1033	9	1/0	TOUCH8, RTC_GPI08	
1025	10	1/0	GPIO25, DAC_1, ADC2_CH8, RTC_GPIO6, EMAC_RXDO	
1026	11	1/0	GPIO26, DAC_2, ADC2_CH9, RTC_GPIO7, EMAC_RXD1	
1027	12	1/0	GPIO27, ADC2_CH7, TOUCH7, RTC_GPIO17, EMAC_RX_DV	
1014	10	1/0	GPI014, ADC2_CH6, TOUCH6, RTC_GPI016, MTMS, HSPICLK, HS2_CLK,	
IO14	13	1/0	SD_CLK, EMAC_TXD2	
1010	14	1/0	GPI012, ADC2_CH5, TOUCH5, RTC_GPI015, MTDI, HSPIQ, HS2_DATA2,	
IO12	14	1/0	SD_DATA2, EMAC_TXD3	
GND	15	Р	Ground	
1010	10	1/0	GPIO13, ADC2_CH4, TOUCH4, RTC_GPIO14, MTCK, HSPID, HS2_DATA3,	
IO13	16	1/0	SD_DATA3, EMAC_RX_ER	
SHD/SD2*	17	1/0	GPIO9, SD_DATA2, SPIHD, HS1_DATA2, U1RXD	
SWP/SD3*	18	1/0	GPIO10, SD_DATA3, SPIWP, HS1_DATA3, U1TXD	
SCS/CMD* 19 I/O GPI011, SD_CMD, SPICSO, HS1_CMD, U1RTS		GPIO11, SD_CMD, SPICSO, HS1_CMD, U1RTS		
SCK/CLK* 20 I/O GPIO6, SD_CLK, SPICLK, HS1_CLK, U1CTS		GPIO6, SD_CLK, SPICLK, HS1_CLK, U1CTS		
SDO/SDO*)* 21 I/O GPIO7, SD_DATAO, SPIQ, HS1_DATAO, U2RTS		GPIO7, SD_DATAO, SPIQ, HS1_DATAO, U2RTS	
SDI/SD1* 22 I/O GPI08, SD_DATA1, SPID, HS1_DATA1, U2CTS		GPIO8, SD_DATA1, SPID, HS1_DATA1, U2CTS		
1015	23	1/0	GPI015, ADC2_CH3, TOUCH3, MTD0, HSPICSO, RTC_GPI013, HS2_CMD,	
	23	1/0	SD_CMD, EMAC_RXD3	
102	24	1/0	GPIO2, ADC2_CH2, TOUCH2, RTC_GPIO12, HSPIWP, HS2_DATAO, SD_DATAO	
100	25	1/0	GPIOO, ADC2_CH1, TOUCH1, RTC_GPIO11, CLK_OUT1, EMAC_TX_CLK	
104	26	1/0	GPIO4, ADC2_CHO, TOUCHO, RTC_GPIO10, HSPIHD, HS2_DATA1, SD_DATA1,	
104	20	20	1/0	EMAC_TX_ER
1016	27	1/0	GPIO16, HS1_DATA4, U2RXD, EMAC_CLK_OUT	
IO17	28	1/0	GPIO17, HS1_DATA5, U2TXD, EMAC_CLK_OUT_180	
105	29	1/0	GPIO5, VSPICSO, HS1_DATA6, EMAC_RX_CLK	
IO18	D18 30 I/O GPIO18, VSPICLK, HS1_DATA7		GPIO18, VSPICLK, HS1_DATA7	
IO19	31	1/0	GPIO19, VSPIQ, UOCTS, EMAC_TXDO	
NC	32	_	-	
IO21	33	1/0	GPIO21, VSPIHD, EMAC_TX_EN	
RXDO	34	1/0	GPIO3, UORXD, CLK_OUT2	
TXDO 35 I/O		1/0	GPIO1, UOTXD, CLK_OUT3, EMAC_RXD2	
1022	36	1/0	GPIO22, VSPIWP, UORTS, EMAC_TXD1	
1023	37	1/0	GPIO23, VSPID, HS1_STROBE	
GND	38	Р	Ground	

3 Boot Configurations

Note:

The content below is excerpted from <u>ESP32 Series Datasheet</u> > Section Boot Configurations. For the strapping pin mapping between the chip and modules, please refer to Chapter 7 Module Schematics.

The chip allows for configuring the following boot parameters through strapping pins and eFuse bits at power-up or a hardware reset, without microcontroller interaction.

• Chip boot mode

- Strapping pin: GPIOO and GPIO2

• Internal LDO (VDD_SDIO) Voltage

- Strapping pin: MTDI

- eFuse bit: EFUSE_SDIO_FORCE and EFUSE_SDIO_TIEH

UOTXD printing

- Strapping pin: MTDO

• Timing of SDIO Slave

- Strapping pin: MTDO and GPIO5

· JTAG signal source

- eFuse bit: EFUSE_DISABLE_JTAG

The default values of all the above eFuse bits are 0, which means that they are not burnt. Given that eFuse is one-time programmable, once an eFuse bit is programmed to 1, it can never be reverted to 0. For how to program eFuse bits, please refer to ESP32 Technical Reference Manual > Chapter eFuse Controller.

The default values of the strapping pins, namely the logic levels, are determined by pins' internal weak pull-up/pull-down resistors at reset if the pins are not connected to any circuit, or connected to an external high-impedance circuit.

Table 4: Default Configuration of Strapping Pins

Strapping Pin	Default Configuration	Bit Value
GPI00	Pull-up	1
GPI02	Pull-down	0
MTDI	Pull-down	0
MTDO	Pull-up	1
GPIO5	Pull-up	1

To change the bit values, the strapping pins should be connected to external pull-down/pull-up resistances. If the ESP32 is used as a device by a host MCU, the strapping pin voltage levels can also be controlled by the host MCU.

All strapping pins have latches. At system reset, the latches sample the bit values of their respective strapping pins and store them until the chip is powered down or shut down. The states of latches cannot be changed in any other way. It makes the strapping pin values available during the entire chip operation, and the pins are freed up to be used as regular IO pins after reset.

The timing of signals connected to the strapping pins should adhere to the setup time and hold time specifications in Table 5 and Figure 2.

Table 5: Description of Timing Parameters for the Strapping Pins

Parameter	Description	Min (ms)
+	Setup time is the time reserved for the power rails to stabilize be-	0
t_{SU}	fore the CHIP_PU pin is pulled high to activate the chip.	
	Hold time is the time reserved for the chip to read the strapping	
t_H	pin values after CHIP_PU is already high and before these pins	1
	start operating as regular IO pins.	

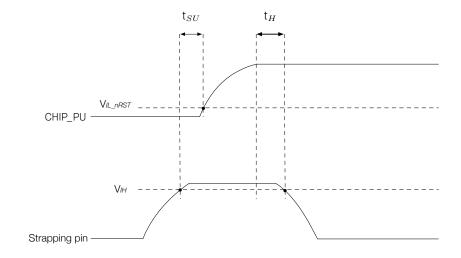


Figure 2: Visualization of Timing Parameters for the Strapping Pins

3.1 Chip Boot Mode Control

GPIOO and GPIO2 control the boot mode after the reset is released. See Table 6 *Chip Boot Mode Control*.

Table 6: Chip Boot Mode Control

Boot Mode	GPI00	GPI02
SPI Boot Mode	1	Any value
Joint Download Boot Mode ²	0	0

¹ **Bold** marks the default value and configuration.

- SDIO Download Boot
- UART Download Boot

In Joint Download Boot mode, the detailed boot flow of the chip is put below 3.

² Joint Download Boot mode supports the following download methods:

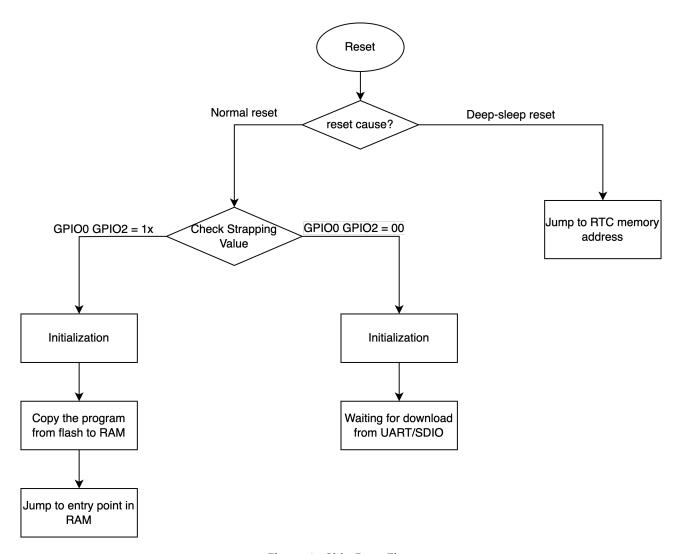


Figure 3: Chip Boot Flow

uart_download_dis controls boot mode behaviors:

It permanently disables Download Boot mode when uart_download_dis is set to 1 (valid only for ESP32 chip revisions v3.0 and higher).

3.2 Internal LDO (VDD_SDIO) Voltage Control

MTDI is used to select the VDD_SDIO power supply voltage at reset:

- MTDI = 0 (by default), VDD_SDIO pin is powered directly from VDD3P3_RTC. Typically this voltage is 3.3 V. For more information, see *ESP32 Series Datasheet* > Section *Power Scheme*.
- MTDI = 1, VDD_SDIO pin is powered from internal 1.8 V LDO.

This functionality can be overridden by setting EFUSE_SDIO_FORCE to 1, in which case the EFUSE_SDIO_TIEH determines the VDD_SDIO voltage:

- EFUSE_SDIO_TIEH = 0, VDD_SDIO connects to 1.8 V LDO.
- EFUSE_SPI_TIEH = 1, VDD_SDIO connects to VDD3P3_RTC.

UOTXD Printing Control 3.3

During booting, the strapping pin MTDO can be used to control the UOTXD Printing, as Table 7 shows.

Table 7: UOTXD Printing Control

UOTXD Printing Control	MTDO
Enabled ¹	1
Disabled	0

Bold marks the default value and configuration.

Timing Control of SDIO Slave 3.4

The strapping pin MTDO and GPIO5 can be used to control the timing of SDIO slave, see Table 8 Timing Control of SDIO Slave.

Table 8: Timing Control of SDIO Slave

Edge behavior	MTDO	GPI05
Falling edge sampling, falling edge output	0	0
Falling edge sampling, rising edge output	0	1
Rising edge sampling, falling edge output	1	0
Rising edge sampling, rising edge output	1	1

¹ **Bold** marks the default value and configuration.

JTAG Signal Source Control

If EFUSE_DISABLE_JTAG is set to 1, the source of JTAG signals can be disabled.

3.6 Chip Power-up and Reset

Once the power is supplied to the chip, its power rails need a short time to stabilize. After that, CHIP_PU - the pin used for power-up and reset - is pulled high to activate the chip. For information on CHIP_PU as well as power-up and reset timing, see Figure 4 and Table 9.

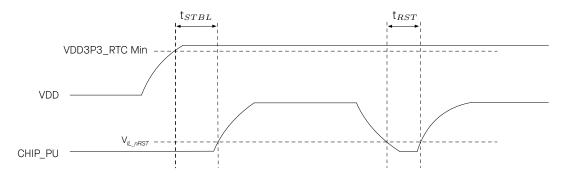


Figure 4: Visualization of Timing Parameters for Power-up and Reset

Table 9: Description of Timing Parameters for Power-up and Reset

Parameter	Description	Min (µs)
t_{STBL}	Time reserved for the 3.3 V rails to stabilize before the CHIP_PU pin is pulled high to activate the chip	50
t_{RST}	Time reserved for CHIP_PU to stay below V_{IL_nRST} to reset the chip (see Table 15)	50

For details, please refer to <u>ESP32 Series Datasheet</u> > Section Chip Power-up and Reset.

Peripherals

4.1 Peripheral Overview

ESP32-DOWD chip integrates a rich set of peripherals including SPI, I2S, UART, I2C, pulse count controller, TWAI®, ADC, DAC, touch sensor, etc.

To learn more about on-chip components, please refer to ESP32 Series Datasheet > Section Functional Description.

Note:

- The content below is sourced from ESP32 Series Datasheet > Section Functional Description. Some information may not be applicable to ESP32-WROOM-32D and ESP32-WROOM-32U as not all the IO signals are exposed on the module.
- To learn more about peripheral signals, please refer to ESP32 Technical Reference Manual > Section Peripheral Signal List.

4.2 **Digital Peripherals**

General Purpose Input / Output Interface (GPIO)

ESP32 has 34 GPIO pins which can be assigned various functions by programming the appropriate registers. There are several kinds of GPIOs: digital-only, analog-enabled, capacitive-touch-enabled, etc. Analog-enabled GPIOs and Capacitive-touch-enabled GPIOs can be configured as digital GPIOs.

Most of the digital GPIOs can be configured as internal pull-up or pull-down, or set to high impedance. When configured as an input, the input value can be read through the register. The input can also be set to edge-trigger or level-trigger to generate CPU interrupts. Most of the digital IO pins are bi-directional, non-inverting and tristate, including input and output buffers with tristate control. These pins can be multiplexed with other functions, such as the SDIO, UART, SPI, etc. (More details can be found in ESP32 Series Datasheet > Appendix, Table IO_MUX.) For low-power operations, the GPIOs can be set to hold their states.

For details, see ESP32 Series Datasheet > Section Peripheral Pin Configurations, ESP32 Series Datasheet > Appendix A - ESP32 Pin Lists and ESP32 Technical Reference Manual > Chapter IO_MUX and GPIO Matrix.

4.2.2 Serial Peripheral Interface (SPI)

ESP32 integrates four SPI controllers which can be used to communicate with external devices that use the SPI protocol. Controller SPIO is used as a buffer for accessing external memory. Controller SPI1 can be used as a master. Controllers SPI2 and SPI3 can be configured as either a master or a slave.

SPI1, SPI2, and SPI3 use signal buses prefixed with SPI, HSPI, and VSPI, respectively.

Features of General Purpose SPI (GP-SPI)

• Programmable data transfer length, in multiples of 1 byte

- - Four-line full-duplex/half-duplex communication and three-line half-duplex communication support
 - Master mode and slave mode
 - Programmable CPOL and CPHA
 - Programmable clock

For details, see ESP32 Technical Reference Manual > Chapter SPI Controller.

Pin Assignment

For SPI, the pins are multiplexed with GPIO6 ~ GPIO11 via the IO MUX. For HSPI, the pins are multiplexed with GPIO2, GPIO4, GPIO12 ~ GPIO15 via the IO MUX. For VSPI, the pins are multiplexed with GPIO5, GPIO18 ~ GPI019, GPI021 ~ GPI023 via the IO MUX.

For more information about the pin assignment, see ESP32 Series Datasheet > Section Peripheral Pin Configurations and ESP32 Technical Reference Manual > Chapter IO_MUX and GPIO Matrix.

Universal Asynchronous Receiver Transmitter (UART)

The UART in the ESP32 chip facilitates the transmission and reception of asynchronous serial data between the chip and external UART devices. It consists of two UARTs in the main system, and one low-power LP UART.

Feature List

- Programmable baud rate
- RAM shared by TX FIFOs and RX FIFOs
- Supports input baud rate self-check
- Support for various lengths of data bits and stop bits
- Parity bit support
- Asynchronous communication (RS232 and RS485) and IrDA support
- Supports DMA to communicate data in high speed
- Supports UART wake-up
- Supports both software and hardware flow control

For details, see ESP32 Technical Reference Manual > Chapter UART Controller.

Pin Assignment

The pins for UART can be chosen from any GPIOs via the GPIO Matrix.

For more information about the pin assignment, see <u>ESP32 Series Datasheet</u> > Section Peripheral Pin Configurations and ESP32 Technical Reference Manual > Chapter IO_MUX and GPIO Matrix.

4.2.4 I2C Interface

ESP32 has two I2C bus interfaces which can serve as I2C master or slave, depending on the user's configuration.

- Two I2C controllers: one in the main system and one in the low-power system
- Standard mode (100 Kbit/s)
- Fast mode (400 Kbit/s)
- Up to 5 MHz, yet constrained by SDA pull-up strength
- Support for 7-bit and 10-bit addressing, as well as dual address mode
- Supports continuous data transmission with disabled Serial Clock Line (SCL)
- Supports programmable digital noise filter

Users can program command registers to control I2C interfaces, so that they have more flexibility.

For details, see <u>ESP32 Technical Reference Manual</u> > Chapter I2C Controller.

Pin Assignment

For regular I2C, the pins used can be chosen from any GPIOs via the GPIO Matrix.

For more information about the pin assignment, see <u>ESP32 Series Datasheet</u> > Section Peripheral Pin Configurations and ESP32 Technical Reference Manual > Chapter IO_MUX and GPIO Matrix.

4.2.5 I2S Interface

The I2S Controller in the ESP32 chip provides a flexible communication interface for streaming digital data in multimedia applications, particularly digital audio applications.

Feature List

- Master mode and slave mode
- Full-duplex and half-duplex communications
- · A variety of audio standards supported
- Configurable high-precision output clock
- Supports PDM signal input and output
- Configurable data transmit and receive modes

For details, see ESP32 Technical Reference Manual > Chapter I2S Controller.

Pin Assignment

The pins for the I2S Controller can be chosen from any GPIOs via the GPIO Matrix.

For more information about the pin assignment, see <u>ESP32 Series Datasheet</u> > Section Peripheral Pin Configurations and ESP32 Technical Reference Manual > Chapter IO_MUX and GPIO Matrix.

4.2.6 Remote Control Peripheral

The Remote Control Peripheral (RMT) controls the transmission and reception of infrared remote control signals.

Feature List

- Eight channels for sending and receiving infrared remote control signals
- Independent transmission and reception capabilities for each channel
- Clock divider counter, state machine, and receiver for each RX channel
- Supports various infrared protocols

For details, see ESP32 Technical Reference Manual > Chapter Remote Control Peripheral.

Pin Assignment

The pins for the Remote Control Peripheral can be chosen from any GPIOs via the GPIO Matrix.

For more information about the pin assignment, see ESP32 Series Datasheet > Section Peripheral Pin Configurations and ESP32 Technical Reference Manual > Chapter IO_MUX and GPIO Matrix.

4.2.7 Pulse Counter Controller (PCNT)

The pulse counter controller (PCNT) is designed to count input pulses by tracking rising and falling edges of the input pulse signal.

Feature List

- Eight independent pulse counter units
- Each pulse counter unit has a 16-bit signed counter register and two channels
- Counter modes: increment, decrement, or disable
- Glitch filtering for input pulse signals and control signals
- Selection between counting on rising or falling edges of the input pulse signal

For details, see ESP32 Technical Reference Manual > Chapter Pulse Count Controller.

Pin Assignment

The pins for the Pulse Count Controller can be chosen from any GPIOs via the GPIO Matrix.

For more information about the pin assignment, see ESP32 Series Datasheet > Section Peripheral Pin Configurations and ESP32 Technical Reference Manual > Chapter IO_MUX and GPIO Matrix.

4.2.8 LED PWM Controller

The LED PWM Controller (LEDC) is designed to generate PWM signals for LED control.

Feature List

- Sixteen independent PWM generators
- Maximum PWM duty cycle resolution of 20 bits
- Eight independent timers with 20-bit counters, configurable fractional clock dividers and counter overflow values

- - Adjustable phase of PWM signal output
 - PWM duty cycle dithering
 - Automatic duty cycle fading

For details, see ESP32 Technical Reference Manual > Chapter LED PWM Controller.

Pin Assignment

The pins for the LED PWM Controller can be chosen from any GPIOs via the GPIO Matrix.

For more information about the pin assignment, see ESP32 Series Datasheet > Section Peripheral Pin Configurations and ESP32 Technical Reference Manual > Chapter IO_MUX and GPIO Matrix.

4.2.9 Motor Control PWM

The Pulse Width Modulation (PWM) controller can be used for driving digital motors and smart lights. The controller consists of PWM timers, the PWM operator and a dedicated capture sub-module. Each timer provides timing in synchronous or independent form, and each PWM operator generates a waveform for one PWM channel. The dedicated capture sub-module can accurately capture events with external timing.

Feature List

- Three PWM timers for precise timing and frequency control
 - Every PWM timer has a dedicated 8-bit clock prescaler
 - The 16-bit counter in the PWM timer can work in count-up mode, count-down mode, or count-up-down mode
 - A hardware sync can trigger a reload on the PWM timer with a phase register. It will also trigger the prescaler' restart, so that the timer's clock can also be synced, with selectable hardware synchronization source
- Three PWM operators for generating waveform pairs
 - Six PWM outputs to operate in several topologies
 - Configurable dead time on rising and falling edges; each set up independently
 - Modulating of PWM output by high-frequency carrier signals, useful when gate drivers are insulated with a transformer
- Fault Detection module
 - Programmable fault handling in both cycle-by-cycle mode and one-shot mode
 - A fault condition can force the PWM output to either high or low logic levels
- Capture module for hardware-based signal processing
 - Speed measurement of rotating machinery
 - Measurement of elapsed time between position sensor pulses
 - Period and duty cycle measurement of pulse train signals

- Decoding current or voltage amplitude derived from duty-cycle-encoded signals of current/voltage sensors
- Three individual capture channels, each of which with a 32-bit time-stamp register
- Selection of edge polarity and prescaling of input capture signals
- The capture timer can sync with a PWM timer or external signals

For details, see ESP32 Technical Reference Manual > Chapter Motor Control PWM.

Pin Assignment

The pins for the Motor Control PWM can be chosen from any GPIOs via the GPIO Matrix.

For more information about the pin assignment, see ESP32 Series Datasheet > Section Peripheral Pin Configurations and ESP32 Technical Reference Manual > Chapter IO_MUX and GPIO Matrix.

4.2.10 SD/SDIO/MMC Host Controller

An SD/SDIO/MMC host controller is available on ESP32.

Feature List

- Supports two external cards
- Supports SD Memory Card standard: version 3.0 and version 3.01)
- Supports SDIO Version 3.0
- Supports Consumer Electronics Advanced Transport Architecture (CE-ATA Version 1.1)
- Supports Multimedia Cards (MMC version 4.41, eMMC version 4.5 and version 4.51)

The controller allows up to 80 MHz clock output in three different data-bus modes: 1-bit, 4-bit, and 8-bit modes. It supports two SD/SDIO/MMC4.41 cards in a 4-bit data-bus mode. It also supports one SD card operating at 1.8 V.

For details, see ESP32 Technical Reference Manual > Chapter SD/MMC Host Controller.

Pin Assignment

The pins for SD/SDIO/MMC Host Controller are multiplexed with GPIO2, GPIO4, GPIO6 ~ GPIO15 via IO MUX.

For more information about the pin assignment, see ESP32 Series Datasheet > Section Peripheral Pin Configurations and ESP32 Technical Reference Manual > Chapter IO_MUX and GPIO Matrix.

4.2.11 SDIO/SPI Slave Controller

ESP32 integrates an SD device interface that conforms to the industry-standard SDIO Card Specification Version 2.0, and allows a host controller to access the SoC, using the SDIO bus interface and protocol. ESP32 acts as the slave on the SDIO bus. The host can access the SDIO-interface registers directly and can access shared memory via a DMA engine, thus maximizing performance without engaging the processor cores.

Feature List

The SDIO/SPI slave controller supports the following features:

- SPI, 1-bit SDIO, and 4-bit SDIO transfer modes over the full clock range from 0 to 50 MHz
- Configurable sampling and driving clock edge
- Special registers for direct access by host
- Interrupts to host for initiating data transfer
- Automatic loading of SDIO bus data and automatic discarding of padding data
- Block size of up to 512 bytes
- Interrupt vectors between the host and the slave, allowing both to interrupt each other
- Supports DMA for data transfer

For details, see ESP32 Technical Reference Manual > Chapter SDIO Slave Controller.

Pin Assignment

The pins for SDIO/SPI Slave Controller are multiplexed with GPIO2, GPIO4, GPIO6 ~ GPIO15 via IO MUX.

For more information about the pin assignment, see ESP32 Series Datasheet > Section Peripheral Pin Configurations and ESP32 Technical Reference Manual > Chapter IO_MUX and GPIO Matrix.

4.2.12 TWAI® Controller

The Two-wire Automotive Interface (TWAI®) is a multi-master, multi-cast communication protocol designed for automotive applications. The TWAI controller facilitates the communication based on this protocol.

Feature List

- Compatible with ISO 11898-1 protocol (CAN Specification 2.0)
- Standard frame format (11-bit ID) and extended frame format (29-bit ID)
- Bit rates:
 - From 25 Kbit/s to 1 Mbit/s in chip revision v0.0/v1.0/v1.1
 - From 12.5 Kbit/s to 1 Mbit/s in chip revision v3.0/v3.1
- Multiple modes of operation: Normal, Listen Only, and Self-Test
- 64-byte receive FIFO
- Special transmissions: single-shot transmissions and self reception
- Acceptance filter (single and dual filter modes)
- Error detection and handling: error counters, configurable error interrupt threshold, error code capture, arbitration lost capture

For details, see ESP32 Technical Reference Manual > Chapter Two-wire Automotive Interface (TWAI).

The pins for the Two-wire Automotive Interface can be chosen from any GPIOs via the GPIO Matrix.

For more information about the pin assignment, see <u>ESP32 Series Datasheet</u> > Section Peripheral Pin Configurations and <u>ESP32 Technical Reference Manual</u> > Chapter IO_MUX and GPIO Matrix.

4.2.13 Ethernet MAC Interface

An IEEE-802.3-2008-compliant Media Access Controller (MAC) is provided for Ethernet LAN communications. ESP32 requires an external physical interface device (PHY) to connect to the physical LAN bus (twisted-pair, fiber, etc.). The PHY is connected to ESP32 through 17 signals of MII or nine signals of RMII.

Feature List

- 10 Mbps and 100 Mbps rates
- Dedicated DMA controller allowing high-speed transfer between the dedicated SRAM and Ethernet MAC
- Tagged MAC frame (VLAN support)
- Half-duplex (CSMA/CD) and full-duplex operation
- MAC control sublayer (control frames)
- 32-bit CRC generation and removal
- Several address-filtering modes for physical and multicast address (multicast and group addresses)
- 32-bit status code for each transmitted or received frame
- Internal FIFOs to buffer transmit and receive frames. The transmit FIFO and the receive FIFO are both 512 words (32-bit)
- Hardware PTP (Precision Time Protocol) in accordance with IEEE 1588 2008 (PTP V2)
- 25 MHz/50 MHz clock output

For details, see ESP32 Technical Reference Manual > Chapter Ethernet Media Access Controller (MAC).

Pin Assignment

For information about the pin assignment of Ethernet MAC Interface, see <u>ESP32 Series Datasheet</u> > Section Peripheral Pin Configurations and <u>ESP32 Technical Reference Manual</u> > Chapter IO_MUX and GPIO Matrix.

4.3 Analog Peripherals

4.3.1 Analog-to-Digital Converter (ADC)

ESP32 integrates two 12-bit SAR ADCs and supports measurements on 18 channels (analog-enabled pins). The ULP coprocessor in ESP32 is also designed to measure voltage, while operating in the sleep mode, which enables low-power consumption. The CPU can be woken up by a threshold setting and/or via other triggers.

Table 10 describes the ADC characteristics.

Table 10: ADC Characteristics

Parameter	Description	Min	Max	Unit
DNL (Differential nonlinearity)	RTC controller; ADC connected to an	– 7	7	LSB
DIVE (Differential normineality)	external 100 nF capacitor; DC signal input;	-/	/	LOD
INL (Integral nonlinearity)	ambient temperature at 25 °C;	-12	12	LSB
inc (integral normineanty)	Wi-Fi&Bluetooth off	-12	۱۷	LOD
Sampling rate	RTC controller	_	200	ksps
Sampling rate	DIG controller	_	2	Msps

Notes:

- When atten = 3 and the measurement result is above 3000 (voltage at approx. 2450 mV), the ADC accuracy will be worse than described in the table above.
- To get better DNL results, users can take multiple sampling tests with a filter, or calculate the average value.
- The input voltage range of GPIO pins within VDD3P3_RTC domain should strictly follow the DC characteristics provided in Table 15. Otherwise, measurement errors may be introduced, and chip performance may be affected.

By default, there are ±6% differences in measured results between chips. ESP-IDF provides couple of calibration methods for ADC1. Results after calibration using eFuse Vref value are shown in Table 11. For higher accuracy, users may apply other calibration methods provided in ESP-IDF, or implement their own.

Table 11: ADC Calibration Results

Parameter	arameter Description		Max	Unit
	Atten = 0, effective measurement range of 100 \sim 950 mV	-23	23	mV
Total error	Atten = 1, effective measurement range of 100 \sim 1250 mV	-30	30	mV
Total elloi	Atten = 2, effective measurement range of 150 \sim 1750 mV	-40	40	mV
	Atten = 3, effective measurement range of 150 \sim 2450 mV	-60	60	mV

For details, see ESP32 Technical Reference Manual > Chapter On-Chip Sensors and Analog Signal Processing.

Pin Assignment

With appropriate settings, the ADCs can be configured to measure voltage on 18 pins maximum. For detailed information about the pin assignment, see ESP32 Series Datasheet > Section Peripheral Pin Configurations and ESP32 Technical Reference Manual > Chapter IO_MUX and GPIO Matrix.

Digital-to-Analog Converter (DAC) 4.3.2

Two 8-bit DAC channels can be used to convert two digital signals into two analog voltage signal outputs. The design structure is composed of integrated resistor strings and a buffer. This dual DAC supports power supply as input voltage reference. The two DAC channels can also support independent conversions.

For details, see ESP32 Technical Reference Manual > Chapter On-Chip Sensors and Analog Signal Processing.

Pin Assignment

The DAC can be configured by GPIO 25 and GPIO 26. For detailed information about the pin assignment, see ESP32 Series Datasheet > Section Peripheral Pin Configurations and ESP32 Technical Reference Manual > Chapter IO_MUX and GPIO Matrix.

4.3.3 Touch Sensor

ESP32 has 10 capacitive-sensing GPIOs, which detect variations induced by touching or approaching the GPIOs with a finger or other objects. The low-noise nature of the design and the high sensitivity of the circuit allow relatively small pads to be used. Arrays of pads can also be used, so that a larger area or more points can be detected.

Pin Assignment

The 10 capacitive-sensing GPIOs are listed in Table 12.

Table 12: Capacitive-Sensing GPIOs Available on ESP32

Capacitive-Sensing Signal Name	Pin Name
ТО	GPIO4
T1	GPI00
T2	GPI02
T3	MTDO
T4	MTCK
T5	MTDI
T6	MTMS
Т7	GPIO27
T8	32K_XN
T9	32K_XP

For details, see ESP32 Technical Reference Manual > Chapter On-Chip Sensors and Analog Signal Processing.

Note:

ESP32 Touch Sensor has not passed the Conducted Susceptibility (CS) test for now, and thus has limited application

5 Electrical Characteristics

5.1 Absolute Maximum Ratings

Stresses beyond the absolute maximum ratings listed in Table 13 *Absolute Maximum Ratings* below may cause permanent damage to the device. These are stress ratings only, and do not refer to the functional operation of the device that should follow the Table 14 *Recommended Operating Conditions*.

Table 13: Absolute Maximum Ratings

Symbol	Parameter	Min	Max	Unit
VDD33	Power supply voltage	-0.3	3.6	V
l _{output} 1	Cumulative IO output current	-	1,100	mA
T_{store}	Storage temperature	-40	105	°C

- 1. The module worked properly after a 24-hour test in ambient temperature at 25 °C, and the IOs in three domains (VDD3P3_RTC, VDD3P3_CPU, VDD_SDIO) output high logic level to ground. Please note that pins occupied by flash and/or PSRAM in the VDD_SDIO power domain were excluded from the test.
- 2. Please see Appendix IO_MUX of ESP32 Datasheet for IO's power domain.

5.2 Recommended Operating Conditions

Table 14: Recommended Operating Conditions

Symbol	Parameter	Min	Typical	Max	Unit
VDD33	Power supply voltage	3.0	3.3	3.6	V
$ V_{VDD} $	Current delivered by external power supply	0.5	-	-	А
Т	Operating ambient temperature	-40	-	85	°C

5.3 DC Characteristics (3.3 V, 25 °C)

Table 15: DC Characteristics (3.3 V, 25 °C)

Symbol	Parameter		Min	Тур	Max	Unit
C_{IN}	Pin capacitance		-	2	-	pF
\bigvee_{IH}	High-level input voltage		0.75×VDD ¹	-	VDD1+0.3	V
V_{IL}	Low-level input voltage		-0.3	-	0.25×VDD ¹	V
$ I_{IH} $	High-level input current		-	-	50	nA
$ I_{IL} $	Low-level input current		-	-	50	nA
V_{OH}	High-level output voltage		0.8×VDD ¹	-	-	V
V_{OL}	Low-level output voltage		-	-	0.1×VDD ¹	V
	High-level source current	VDD3P3_CPU power domain 1, 2	-	40	-	mΑ
1	$(VDD^1 = 3.3 \text{ V, V}_{OH} >= 2.64 \text{ V,}$	VDD3P3_RTC power domain 1, 2	-	40	-	mA
OH	output drive strength set to the maximum)	VDD_SDIO power domain 1, 3	-	20	-	mA

Symbol	Parameter	Min	Тур	Max	Unit
	Low-level sink current				
$ \cdot _{OL}$	$(VDD^1 = 3.3 \text{ V, } V_{OL} = 0.495 \text{ V,}$	-	28	-	mA
	output drive strength set to the maximum)				
R_{PU}	Resistance of internal pull-up resistor	-	45	-	kΩ
R_{PD}	Resistance of internal pull-down resistor	-	45	-	kΩ
\bigvee_{IL_nRST}	Low-level input voltage of CHIP_PU to shut down the chip	-	-	0.6	V

Notes:

- 1. Please see Appendix IO_MUX of <u>ESP32 Datasheet</u> for IO's power domain. VDD is the I/O voltage for a particular power domain of pins.
- 2. For VDD3P3_CPU and VDD3P3_RTC power domain, per-pin current sourced in the same domain is gradually reduced from around 40 mA to around 29 mA, V_{OH} >=2.64 V, as the number of current-source pins increases.
- 3. Pins occupied by flash and/or PSRAM in the VDD_SDIO power domain were excluded from the test.

5.4 Current Consumption Characteristics

Owing to the use of advanced power-management technologies, the module can switch between different power modes. For details on different power modes, please refer to Section RTC and Low-Power Management in ESP32 Series Datasheet.

5.5 Memory Specifications

The data below is sourced from the memory vendor datasheet. These values are guaranteed through design and/or characterization but are not fully tested in production. Devices are shipped with the memory erased.

Parameter Description Min Max Unit Typ Power supply voltage (1.8 V) 1.65 1.80 2.00 V VCC Power supply voltage (3.3 V) V 2.7 3.3 3.6 F_C Maximum clock frequency 80 MHz Program/erase cycles 100,000 cycles Data retention time T_{RET} 20 years T_{PP} Page program time 8.0 5 ms Sector erase time (4 KB) 70 500 T_{SE} ms Block erase time (32 KB) 0.2 2 T_{BE1} S Block erase time (64 KB) 0.3 3 T_{BE2} S Chip erase time (16 Mb) 7 20 S Chip erase time (32 Mb) 20 60 S Chip erase time (64 Mb) T_{CE} 25 100 S Chip erase time (128 Mb) 60 200 S Chip erase time (256 Mb) 70 300 S

Table 16: Flash Specifications

RF Characteristics

This section contains tables with RF characteristics of the Espressif product.

The RF data is measured at the antenna port, where RF cable is connected, including the front-end loss. The external antennas used for the tests on the modules with external antenna connectors have an impedance of 50 Ω.Devices should operate in the center frequency range allocated by regional regulatory authorities. The target center frequency range and the target transmit power are configurable by software. See ESP RF Test Tool and Test Guide for instructions.

Unless otherwise stated, the RF tests are conducted with a 3.3 V (±5%) supply at 25 °C ambient temperature.

6.1 Wi-Fi Radio

Table 17: Wi-Fi RF Characteristics

Name	Description
Center frequency range of operating channel	2412 ~ 2484 MHz
Wi-Fi wireless standard	IEEE 802.11b/g/n

6.1.1 Wi-Fi RF Transmitter (TX) Characteristics

Table 18: TX Power with Spectral Mask and EVM Meeting 802.11 Standards

Rate	Min (dBm)	Typ (dBm)	Max (dBm)
802.11b, 1 Mbps	_	19.5	
802.11b, 11 Mbps	_	19.5	
802.11g, 6 Mbps	_	18.0	
802.11g, 54 Mbps	_	14.0	_
802.11n, HT20, MCS0	_	18.0	
802.11n, HT20, MCS7	_	13.0	_
802.11n, HT40, MCS0	_	18.0	_
802.11n, HT40, MCS7	_	13.0	

Table 19: TX EVM Test1

	Min	Тур	Limit
Rate	(dB)	(dB)	(dB)
802.11b, 1 Mbps, DSSS	_	-25.0	-10.0
802.11b, 11 Mbps, CCK	_	-25.0	-10.0
802.11g, 6 Mbps, OFDM	_	-24.0	-5.0
802.11g, 54 Mbps, OFDM	_	-28.0	-25.0
802.11n, HT20, MCS0	_	-24.0	-5.0

Cont'd on next page

Table 19 - cont'd from previous page

	Min	Тур	Limit
Rate	(dB)	(dB)	(dB)
802.11n, HT20, MCS7	_	-30.0	-27.0
802.11n, HT40, MCS0	_	-24.0	-5.0
802.11n, HT40, MCS7	_	-30.0	-27.0

¹ EVM is measured at the corresponding typical TX power provided in Table 18 Wi-Fi RF Transmitter (TX) Characteristics above.

6.1.2 Wi-Fi RF Receiver (RX) Characteristics

For RX tests, the PER (packet error rate) limit is 8% for 802.11b, and 10% for 802.11g/n.

Table 20: RX Sensitivity

	Min	Тур	Max
Rate	(dBm)	(dBm)	(dBm)
802.11b, 1 Mbps, DSSS	_	-97.0	_
802.11b, 2 Mbps, DSSS	_	-94.0	_
802.11b, 5.5 Mbps, CCK	_	-91.0	_
802.11b, 11 Mbps, CCK	_	-88.0	_
802.11g, 6 Mbps, OFDM	_	-93.0	_
802.11g, 9 Mbps, OFDM	_	-91.0	_
802.11g, 12 Mbps, OFDM	_	-90.0	_
802.11g, 18 Mbps, OFDM	_	-87.0	_
802.11g, 24 Mbps, OFDM	_	-84.0	_
802.11g, 36 Mbps, OFDM	_	-81.0	_
802.11g, 48 Mbps, OFDM	_	-77.0	_
802.11g, 54 Mbps, OFDM	_	-75.0	_
802.11n, HT20, MCS0	_	-91.0	_
802.11n, HT20, MCS1	_	-88.0	_
802.11n, HT20, MCS2	_	-86.0	_
802.11n, HT20, MCS3	_	-83.0	_
802.11n, HT20, MCS4	_	-80.0	_
802.11n, HT20, MCS5	_	-75.0	_
802.11n, HT20, MCS6	_	-73.0	_
802.11n, HT20, MCS7	_	-72.0	_
802.11n, HT40, MCS0	_	-88.0	_
802.11n, HT40, MCS1	_	-85.0	_
802.11n, HT40, MCS2	_	-83.0	_
802.11n, HT40, MCS3		-80.0	
802.11n, HT40, MCS4	_	-76.0	_
802.11n, HT40, MCS5		-72.0	
802.11n, HT40, MCS6		-70.0	
802.11n, HT40, MCS7	_	-69.0	_

Table 21: Maximum RX Level

Rate	Min (dBm)	Typ (dBm)	Max (dBm)
802.11b, 1 Mbps	_	5	_
802.11b, 11 Mbps	_	5	
802.11g, 6 Mbps	_	0	_
802.11g, 54 Mbps	_	-8	
802.11n, HT20, MCS0	_	0	_
802.11n, HT20, MCS7	_	-8	_
802.11n, HT40, MCS0	_	0	_
802.11n, HT40, MCS7	_	-8	_

Table 22: RX Adjacent Channel Rejection

Rate	Min (dB)	Typ (dB)	Max (dB)
802.11b, 1 Mbps, DSSS	_	35	_
802.11b, 11 Mbps, CCK	_	35	_
802.11g, 6 Mbps, OFDM	_	27	_
802.11g, 54 Mbps, OFDM	_	13	_
802.11n, HT20, MCS0	_	27	_
802.11n, HT20, MCS7	_	12	_
802.11n, HT40, MCS0	_	16	_
802.11n, HT40, MCS7	_	7	_

6.2 Bluetooth LE Radio

6.2.1 Receiver

Table 23: Receiver Characteristics - Bluetooth LE

Parameter	Condition	Min	Тур	Max	Unit
Sensitivity @30.8% PER	-	-	-97	-	dBm
Maximum received signal @30.8% PER	-	0	-	-	dBm
Co-channel C/I	-	-	+10	-	dB
	F = FO + 1 MHz	-	-5	-	dB
	F = FO – 1 MHz	-	-5	-	dB
Adjacent channel selectivity C/I	F = F0 + 2 MHz	-	-25	-	dB
Adjacent charmer selectivity 6/1	F = F0 - 2 MHz	-	-35	-	dB
	F = F0 + 3 MHz	-	-25	-	dB
	F = FO - 3 MHz	-	-45	-	dB
	30 MHz ~ 2000 MHz	-10	_	-	dBm
Out-of-band blocking performance	2000 MHz ~ 2400	-27	-	-	dBm
Out-of-band blocking performance	MHz				

Parameter	Condition	Min	Тур	Max	Unit
	2500 MHz ~ 3000	-27	-	-	dBm
	MHz				
	3000 MHz ~ 12.5 GHz	-10	-	-	dBm
Intermodulation	-	-36	-	-	dBm

6.2.2 Transmitter

Table 24: Transmitter Characteristics - Bluetooth LE

Parameter	Condition	Min	Тур	Max	Unit
RF transmit power	-	-	0	-	dBm
Gain control step	-	-	3	-	dBm
RF power control range	-	-12	-	+9	dBm
	F = F0 ± 2 MHz	-	-52	-	dBm
Adjacent channel transmit power	$F = FO \pm 3 MHz$	-	-58	-	dBm
	$F = FO \pm > 3 MHz$	-	-60	-	dBm
$\Delta f1_{avg}$	-	-	-	265	kHz
$\Delta~f2_{ extsf{max}}$	-	247	-	-	kHz
$\Delta f 2_{\text{avg}}/\Delta f 1_{\text{avg}}$	-	-	-0.92	-	-
ICFT	-	-	-10	-	kHz
Drift rate	-	-	0.7	-	kHz/50 μs
Drift	-	-	2	-	kHz

7 Module Schematics

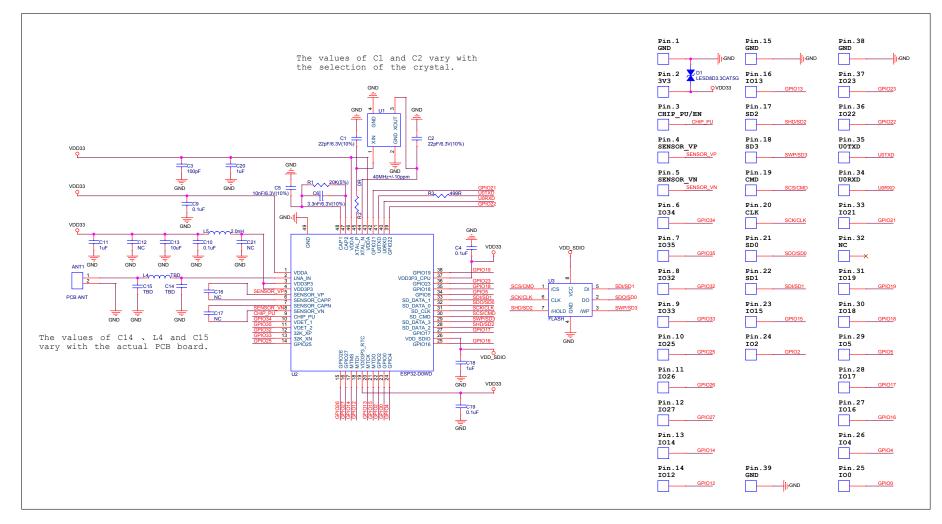


Figure 5: ESP32-WROOM-32D Schematics

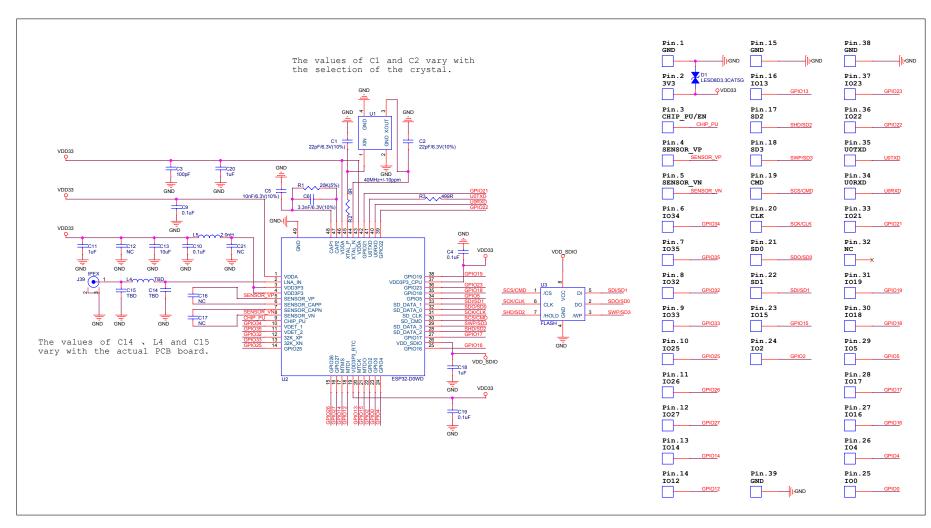


Figure 6: ESP32-WROOM-32U Schematics

8 Peripheral Schematics

This is the typical application circuit of the module connected with peripheral components (for example, power supply, antenna, reset button, JTAG interface, and UART interface).

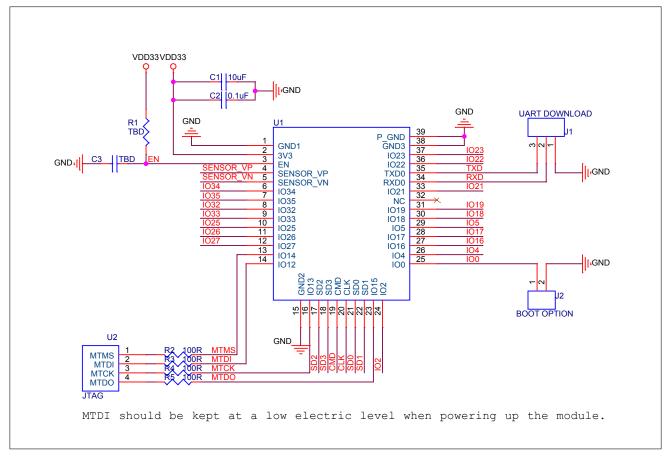


Figure 7: ESP32-WROOM-32D & ESP32-WROOM-32U Peripheral Schematics

- Soldering Pad 39 to the ground of the base board is not a must. If you choose to solder it, please apply
 the correct amount of soldering paste. Too much soldering paste may increase the gap between the
 module and the baseboard. As a result, the adhesion between other pins and the baseboard may be
 poor.
- To ensure the power supply to the ESP32 chip during power-up, it is advised to add an RC delay circuit at the EN pin. The recommended setting for the RC delay circuit is usually R = 10 k Ω and C = 1 μ F. However, specific parameters should be adjusted based on the power-up timing of the module and the power-up and reset sequence timing of the chip. For ESP32's power-up and reset sequence timing diagram, please refer to Section 3.6 *Chip Power-up and Reset*.
- UARTO is used to download firmware and log output. When using the AT firmware, note that the UART
 GPIO is already configured. It is recommended to use the default configuration. Please refer to
 ESP-AT User Guide for ESP32 > Section Hardware Connection.

Physical Dimensions

Module Dimensions 9.1

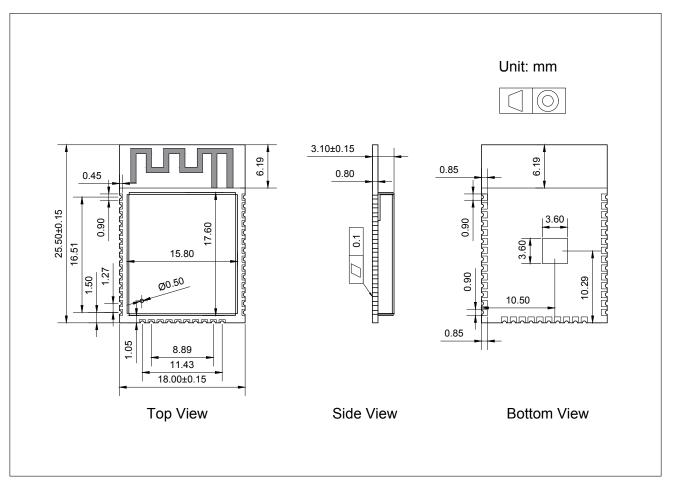


Figure 8: Physical Dimensions of ESP32-WROOM-32D

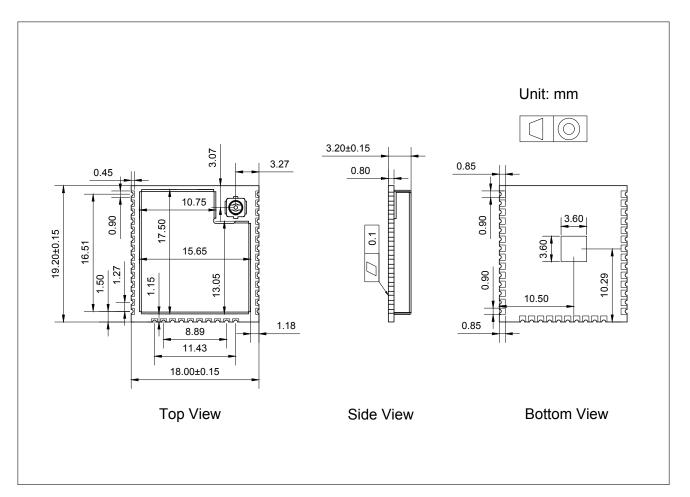


Figure 9: Physical Dimensions of ESP32-WROOM-32U

Note:

For information about tape, reel, and product marking, please refer to <u>ESP32 Module Packaging Information</u>.

9.2 Dimensions of External Antenna Connector

ESP32-WROOM-32U uses the first generation external antenna connector as shown in Figure 10 *Dimensions* of *External Antenna Connector*. This connector is compatible with the following connectors:

- U.FL Series connector from Hirose
- MHF I connector from I-PEX
- AMC connector from Amphenol

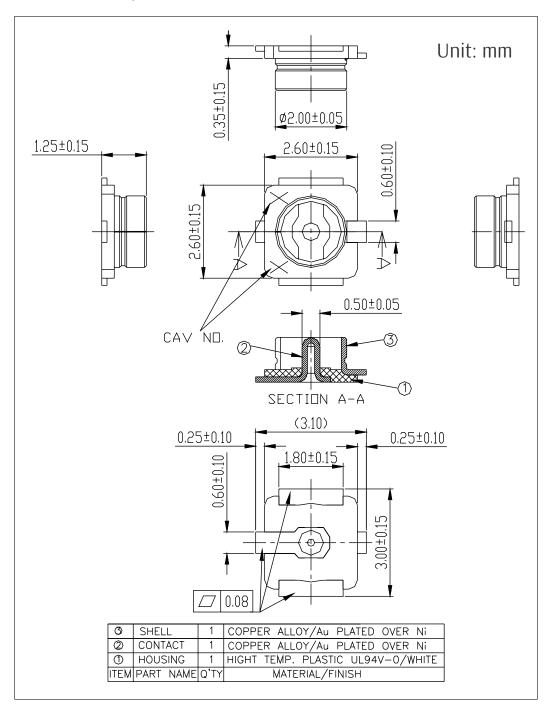


Figure 10: Dimensions of External Antenna Connector

The external antenna used for ESP32-WROOM-32U during certification testing is the first generation monopole antenna, with material code TFPD05H08750011.

The module does not include an external antenna upon shipment. If needed, select a suitable external antenna based on the product's usage environment and performance requirements.

It is recommended to select an antenna that meets the following requirements:

- 2.4 GHz band
- 50 Ω impedance
- The maximum gain does not exceed 2.33 dBi, the gain of the antenna used for certification
- The connector matches the specifications shown in Figure 10 *Dimensions of External Antenna Connector*

Note:

If you use an external antenna of a different type or gain, additional testing, such as EMC, may be required beyond the existing antenna test reports for Espressif modules. Specific requirements depend on the certification type.

10 PCB Layout Recommendations

10.1 PCB Land Pattern

This section provides the following resources for your reference:

- Figures for recommended PCB land patterns with all the dimensions needed for PCB design. See Figure 11 Recommended PCB Land Pattern of ESP32-WROOM-32D and Figure 12 Recommended PCB Land Pattern of ESP32-WROOM-32U.
- Source files of recommended PCB land patterns to measure dimensions not covered in Figure 11 and
 Figure 12. You can view the source files for <u>ESP32-WROOM-32D</u> and <u>ESP32-WROOM-32U</u> with <u>Autodesk</u>
 Viewer.
- 3D models of <u>ESP32-WROOM-32D</u>. Please make sure that you download the 3D model file in .STEP format (beware that some browsers might add .txt).

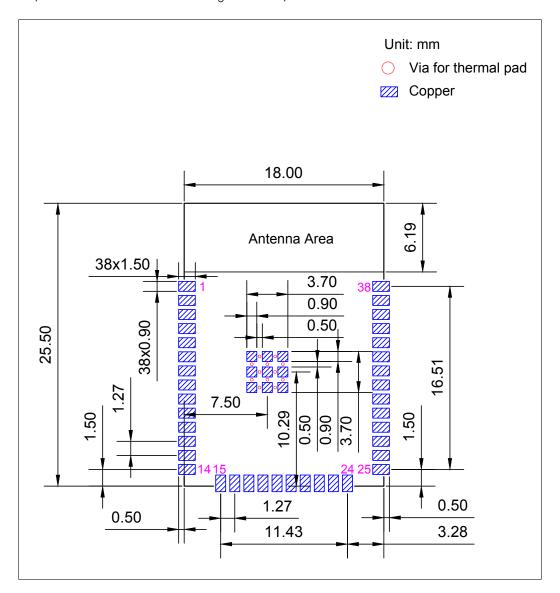


Figure 11: Recommended PCB Land Pattern of ESP32-WROOM-32D

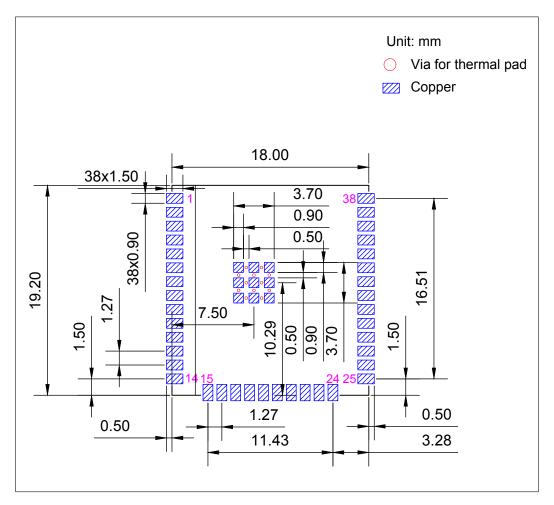


Figure 12: Recommended PCB Land Pattern of ESP32-WROOM-32U

Module Placement for PCB Design 10.2

If module-on-board design is adopted, attention should be paid while positioning the module on the base board. The interference of the base board on the module's antenna performance should be minimized.

For details about module placement for PCB design, please refer to ESP32 Hardware Design Guidelines > Section General Principles of PCB Layout for Modules.

11 Product Handling

11.1 Storage Conditions

The products sealed in moisture barrier bags (MBB) should be stored in a non-condensing atmospheric environment of < 40 °C and 90%RH. The module is rated at the moisture sensitivity level (MSL) of 3.

After unpacking, the module must be soldered within 168 hours with the factory conditions 25 ± 5 °C and 60 %RH. If the above conditions are not met, the module needs to be baked.

11.2 Electrostatic Discharge (ESD)

Human body model (HBM): ±2000 V
Charged-device model (CDM): ±500 V

11.3 Reflow Profile

Solder the module in a single reflow.

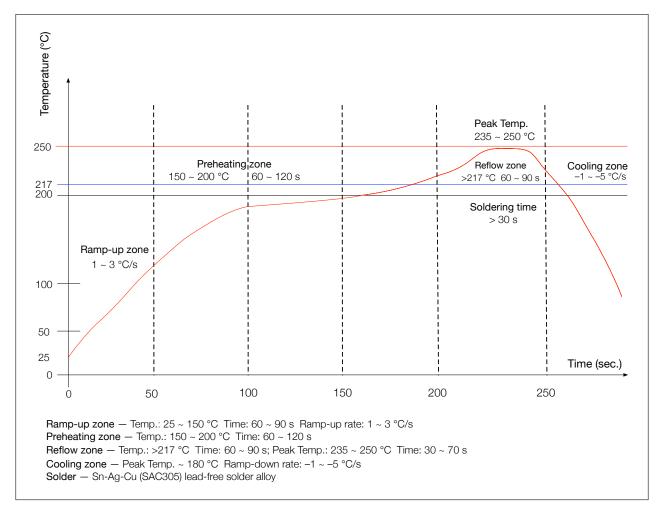


Figure 13: Reflow Profile

Ultrasonic Vibration 11.4

Avoid exposing Espressif modules to vibration from ultrasonic equipment, such as ultrasonic welders or ultrasonic cleaners. This vibration may induce resonance in the in-module crystal and lead to its malfunction or even failure. As a consequence, the module may stop working or its performance may deteriorate.

Datasheet Versioning

Datasheet Version	Status	Watermark	Definition
v0.1 ~ v0.5 (excluding v0.5)	Draft	Confidential	This datasheet is under development for products in the design stage. Specifications may change without prior notice.
v0.5 ~ v1.0 (excluding v1.0)	Preliminary release	Preliminary	This datasheet is actively updated for products in the verification stage. Specifications may change before mass production, and the changes will be documentation in the datasheet's Revision History.
v1.0 and higher	Official release	_	This datasheet is publicly released for products in mass production. Specifications are finalized, and major changes will be communicated via Product Change Notifications (PCN) .
Any version	_	Not Recommended for New Design (NRND) ¹	This datasheet is updated less frequently for products not recommended for new designs.
Any version	_	End of Life (EOL) ²	This datasheet is no longer mained for products that have reached end of life.

¹ Watermark will be added to the datasheet title page only when all the product variants covered by this datasheet are not recommended for new designs.

² Watermark will be added to the datasheet title page only when all the product variants covered by this datasheet have reached end of life.

Related Documentation and Resources

Related Documentation

- ESP32 Series Datasheet Specifications of the ESP32 hardware.
- ESP32 Technical Reference Manual Detailed information on how to use the ESP32 memory and peripherals.
- ESP32 Hardware Design Guidelines Guidelines on how to integrate the ESP32 into your hardware product.
- ESP32 ECO and Workarounds for Bugs Correction of ESP32 design errors.
- ESP32 Series SoC Errata Descriptions of known errors in ESP32 series of SoCs.
- Certificates

https://espressif.com/en/support/documents/certificates

• ESP32 Product/Process Change Notifications (PCN)

https://espressif.com/en/support/documents/pcns

• ESP32 Advisories - Information on security, bugs, compatibility, component reliability.

https://espressif.com/en/support/documents/advisories

 Documentation Updates and Update Notification Subscription https://espressif.com/en/support/download/documents

Developer Zone

- ESP-IDF Programming Guide for ESP32 Extensive documentation for the ESP-IDF development framework.
- ESP-IDF and other development frameworks on GitHub.

https://github.com/espressif

• ESP32 BBS Forum – Engineer-to-Engineer (E2E) Community for Espressif products where you can post questions, share knowledge, explore ideas, and help solve problems with fellow engineers.

https://esp32.com/

• ESP-FAQ - A summary document of frequently asked questions released by Espressif.

https://espressif.com/projects/esp-faq/en/latest/index.html

• The ESP Journal - Best Practices, Articles, and Notes from Espressif folks.

https://blog.espressif.com/

• See the tabs SDKs and Demos, Apps, Tools, AT Firmware.

https://espressif.com/en/support/download/sdks-demos

Products

• ESP32 Series SoCs - Browse through all ESP32 SoCs.

https://espressif.com/en/products/socs?id=ESP32

• ESP32 Series Modules - Browse through all ESP32-based modules.

https://espressif.com/en/products/modules?id=ESP32

• ESP32 Series DevKits - Browse through all ESP32-based devkits.

https://espressif.com/en/products/devkits?id=ESP32

• ESP Product Selector – Find an Espressif hardware product suitable for your needs by comparing or applying filters. https://products.espressif.com/#/product-selector?language=en

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Not Recommended For New Designs (NRND)

Revision History

Date	Version	Release notes
2025-08-05	v2.6	 Improved the wording and structure of following sections: 1: Module Overview: Updated Table "ESP32-WROOM-32D and ESP32-WROOM-32U Specifications" to Section 1.1: Features and added Section 1.2: Series Comparison Updated Section "Strapping Pins" and renamed to Boot Configurations Added Section 4: Peripherals Added Section 5.5: Memory Specifications Added Section 6: RF Characteristics Added a note about UART and pin 39 in Section 8: Peripheral Schematics Added notes about the external antenna connector in Section 9.2: Dimensions of External Antenna Connector Added Section Datasheet Versioning
2025-04-14	v2.5	Added notes about erase cycles and retention time for flash in Table "ESP32-WROOM-32D vs. ESP32-WROOM-32U" which later were moved to Section 5.5: Memory Specifications
2023.02	v2.4	 Major updates: Removed contents about hall sensor according to PCN20221202 Added Section 11: Product Handling Other updates: Added strapping pin timing in Section "Strapping Pins" Added source files of PCB land patterns and 3D models of the modules (if available) in Section 10.1: PCB Land Pattern
2022.03	v2.3	Updated Table "ESP32-WROOM-32D vs. ESP32-WROOM-32U" Added a link to RF certificates in Section 1.1: Features Updated Table 13 Added a note below Figure 9 Updated the description to the connector Added Section Related Documentation and Resources
2021.08	v2.2	Replaced Espressif Product Ordering Information with ESP Product Selector Updated the description of TWAI in Section 1.1: Features Labeled this document as (Not Recommended For New Designs)
2021.02	v2.1	Updated Figure 8: Physical Dimensions of ESP32-WROOM-32D, Figure 9: Physical Dimensions of ESP32-WROOM-32U, Figure 11: Recommended PCB Land Pattern of ESP32-WROOM-32D, and Figure 12: Recommended PCB Land Pattern of ESP32-WROOM-32U Modified the note below Figure: Reflow Profile Modified the note below Figure 7: ESP32-WROOM-32D & ESP32-WROOM-32U Peripheral Schematics Updated the trade mark from TWAI™ to TWAI®

Date	Version	Release notes
2020.11	v2.0	Added TWAI TM in Section 1.1: Features Added a note under Figure: Reflow Profile Updated the C value in RC delay circuit from 0.1 μ F to 1 μ F Provided feedback link
2019.09	v1.9	 Changed the supply voltage range from 2.7 V ~ 3.6 V to 3.0 V ~ 3.6 V Added Moisture sensitivity level (MSL) 3 in Section 1.1: Features Added notes about "Operating frequency range" and "TX power" under Table "Wi-Fi Radio Characteristics" which later was updated to several tables in Section 6: RF Characteristics Updated Section 8 Peripheral Schematics and added a note about RC delay circuit under it Updated Figure 11 and Figure 12 Recommended PCB Land Pattern
2019.01	v1.8	Changed the RF power control range in Table 24 from −12 ~ +12 to −12 ~ +9 dBm.
2018.10	V1.7	Added notice on module custom options under Section 1.1: Features Added "Cumulative IO output current" entry to Table 13: Absolute Maximum Ratings Added more parameters to Table 15: DC Characteristics
2018.09	V1.6	Updated the hole diameter in the shield from 1.00 mm to 0.50 mm, in Figure 8
2018.08	V1.5	 Added certifications and reliability test items the module has passed in Section 1.1: Features, and removed software-specific information Updated Section "RTC and Low-Power Management" which later renamed to 5.4: Current Consumption Characteristics Changed the modules' dimensions Updated Figure 8 and 9: Physical Dimensions Updated Table "Wi-Fi Radio Characteristics"
2018.06	V1.4	 Deleted Temperature Sensor in Section 1.1: Features Updated Chapter "Functional Description" Added notes to Chapter 8: Peripheral Schematics Added Chapter 10.1: Recommended PCB Land Pattern Changes to electrical characteristics: Updated Table 13: Absolute Maximum Ratings Added Table 14: Recommended Operating Conditions Added Table 15: DC Characteristics Updated the values of "Gain control step", "Adjacent channel transmit power" in Table 24: Transmitter Characteristics - BLE
2018.04	V1.3	Updated Figure 6 ESP32-WROOM-32U Schematics and Figure 5 ESP32-WROOM-32D Schematics
2018.02	v1.2	Update Figure 6 ESP32-WROOM-32U Schematics
2018.02	V1.1	Updated Chapter 7 <i>Module Schematics</i> Deleted description of low-noise amplifier Replaced the module name ESP-WROOM-32D with ESP32-WROOM-32D

Date	Version	Release notes
		Added information about module certification in Section 1.1: Features
		Updated the description of eFuse bits in Chapter "Functional Description"
2017.11	v1.0	First release



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