

**B.M.S. COLLEGE OF ENGINEERING
BENGALURU-560019**
Autonomous Institute, Affiliated to VTU



Lab Record

Artificial Intelligence

(22CS5PCAIN)

Submitted in partial fulfillment for the 5th Semester Laboratory

Bachelor of Technology
in
Computer Science and Engineering

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Nov 23-Feb 2024

B.M.S. COLLEGE OF ENGINEERING
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CERTIFICATE

This is to certify that the Artificial Intelligence (22CS5PCAIN) laboratory has been carried out by Tanisha Gotadke (1BM21CS229) during the 5th Semester November - February 2024.

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Program-1

Implement Vacuum cleaner problem for 2 rooms ,any type of agent can be considered simple reflex or model based etc.

Code:

```
def clean(floor, row, col):
    i, j, m, n = row, col, len(floor), len(floor[0])
    goRight = goDown = True
    cleaned = [not any(f) for f in floor]
    while not all(cleaned):
        while any(floor[i]):
            print_floor(floor, i, j)
            if floor[i][j]:
                floor[i][j] = 0
                print_floor(floor, i, j)
            if not any(floor[i]):
                cleaned[i] = True
                break
        if j == n - 1:
            j = 1
            goRight = False
        elif j == 0:
            j += 1
            goRight = True
        else:
            j += 1 if goRight else -1
        if all(cleaned):
            break
        if i == m - 1:
            i = 1
            goDown = False
        elif i == 0:
            i += 1
```

```

goDown = True

else:
    i += 1 if goDown else -1

if cleaned[i]:
    print_floor(floor, i, j)

def print_floor(floor, row, col): # row, col represent the current
    vacuum cleaner position for r in range(len(floor)):
        for c in range(len(floor[r])):
            if r == row and c == col:
                print(f">{floor[r][c]}<", end = "")
            else:
                print(f" {floor[r][c]} ", end = "")
        print(end = '\n')
    print(end = '\n')

# Test 1
floor = [[1, 0, 0, 0],
          [0, 1, 0, 1],
          [1, 0, 1, 1]]

print("Room Condition: ")
for row in floor:
    print(row)
    print("\n")
clean(floor, 1, 2)

```

Output:

```
→ Enter Location of VacuumA
Enter status of A1
Enter status of other room1
Initial Location Condition{'A': '0', 'B': '0'}
Vacuum is placed in Location A
Location A is Dirty.
Cost for CLEANING A 1
Location A has been Cleaned.
Location B is Dirty.
Moving right to the Location B.
COST for moving RIGHT2
COST for SUCK 3
Location B has been Cleaned.
```

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Program - 2 — Vacuum cleaner

```

def vacuum_world():
    # initializing goal-state
    # 0 indicates clean and 1
    # indicates Dirty
    goal_state = { 'A': '0', 'B': '0' }
    cost = 0

    location_input = input ("Enter location of vacuum")
    # user input of location vacuum is placed
    status_input = input ("Enter status of " + location_input)
    # user input if location is dirty or clean
    status_input_complement = input ("Enter status
of other room")
    print ("Initial location condition" + str(goal_state))

    if location_input == 'A':
        # location A is Dirty:
        print ("vacuum is placed in location A")
        if status_input == '1':
            print ("Location A is Dirty")
            # suck the dirt and mark it as clean
            goal_state ['A'] = '0'
            cost += 1
            print ("cost for suck")
            print ("cost for CLEANING A" + str(cost))
            print ("Location A has been cleaned.")
            if status_input_complement == '1':
                # if B is dirty
                print ("Location B is Dirty")
                print ("Moving right to the Location B")
                cost += 1
                print ("cost for moving RIGHT" + str(cost))
                goal_state ['B'] = '0'

```

```

cost += 1
print("cost for suck" + str(cost))
print("location B has been cleaned")
else:
    print("No action" + str(cost))
    print("location B is already clean")
if status - input_complement == '1':
    print("Moving RIGHT to the location B")
cost += 1
print("cost for moving RIGHT" + str(cost))
goal_state['B'] = '0'
cost += 1
print("cost for suck" + str(cost))
print("location B has been cleaned")
else:
    print("No action" + str(cost))
    print(cost)
    print("location B is already clean")
else:
    print("vacuum is placed in location B")
if status - input_complement == '1':
    print("location B is Dirty")
goal_state['B'] = '0'
cost += 1
print("cost for cleaning" + str(cost))
print("location B has been cleaned")
if status - input_complement == '1':
    print("location A is Dirty")
print("Moving left to the location A")
cost += 1
print("cost for moving Left" + str(cost))
goal_state['A'] = '0'
cost += 1

```

```
print("cost for suck" + str(cost))
print("Location A has been cleaned:")
else:
    print(cost)
    print("Location B is already clean")
    if status_input_complement == '1':
        print("Location A is Dirty")
        print("Moving left to the location A")
        cost += 1
    print("cost for moving LEFT" + str(cost))
    goal_state['A'] = '0'
    cost += 1
    print("cost for suck" + str(cost))
    print("Location A has been cleaned")
else:
    print("No action" + str(cost))
    print("Location A is already clean")
    #done cleaning
    print("GOAL STATE:")
    print(goal_state)
    print("Performance measurement : " + str(cost))
vacuum_world()
```

OUTPUT:

Enter location of vacuum A
Enter status of A
Enter status of other room 1
Initial location condition { 'A': '0', 'B': '0' }
vacuum is placed in location A
location A is Dirty
cost for cleaning A
location A has been cleaned
location B is Dirty
Moving right to the location B
cost for moving RIGHT?

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cost for suck 3

Location B has been cleaned

Goal State:

$S_A = '0' \quad S_B = '0' \}$

Performance measurement = 3

Program- 2

Explore the working of Tic Tac Toe using Min max strategy

Code: import math

import copy

X = "X"

O = "O"

EMPTY = None

def initial_state():

 return [[EMPTY, EMPTY, EMPTY],
 [EMPTY, EMPTY, EMPTY],
 [EMPTY, EMPTY, EMPTY]]

def player(board):

 countO = 0

 countX = 0

 for y in [0, 1, 2]:

 for x in board[y]:

 if x == "O":

 countO = countO + 1

 elif x == "X":

 countX = countX + 1

 if countO >= countX:

 return X

 elif countX > countO:

 return O

def actions(board):

 freeboxes = set()

```

for i in [0, 1, 2]:
    for j in [0, 1, 2]:
        if board[i][j] == EMPTY:
            freeboxes.add((i, j))
return freeboxes

```

```

def result(board, action):
    i = action[0]
    j = action[1]
    if type(action) == list:
        action = (i, j)
    if action in actions(board):
        if player(board) == X:
            board[i][j] = X
        elif player(board) == O:
            board[i][j] = O
    return board

```

```

def winner(board):
    if (board[0][0] == board[0][1] == board[0][2] == X or
        board[1][0] == board[1][1] == board[1][2] == X or board[2][0] ==
        board[2][1] == board[2][2] == X):
        return X
    if (board[0][0] == board[0][1] == board[0][2] == O or
        board[1][0] == board[1][1] == board[1][2] == O or board[2][0] ==
        board[2][1] == board[2][2] == O):
        return O
    for i in [0, 1, 2]:
        s2 = []
        for j in [0, 1, 2]:
            s2.append(board[j][i])

```

s2.append(board[j][i])

```

if (s2[0] == s2[1] == s2[2]):
    return s2[0]

strikeD = []
for i in [0, 1, 2]:
    strikeD.append(board[i][i])
if (strikeD[0] == strikeD[1] == strikeD[2]):
    return strikeD[0]
if (board[0][2] == board[1][1] == board[2][0]):
    return board[0][2]
return None

```

```

def terminal(board):
    Full = True
    for i in [0, 1, 2]:
        for j in board[i]:
            if j is None:
                Full = False
    if Full:
        return True
    if (winner(board) is not None):
        return True
    return False

```

```

def utility(board):
    if (winner(board) == X):
        return 1
    elif winner(board) == O:
        return -1
    else:

```

```
    return 0
```

```
def minimax_helper(board):
    isMaxTurn = True if player(board) == X else False
    if terminal(board):
        return utility(board)

    scores = []
    for move in actions(board):
        result(board, move)
        scores.append(minimax_helper(board))
        board[move[0]][move[1]] = EMPTY
    return max(scores) if isMaxTurn else min(scores)
```

```
def minimax(board):
    isMaxTurn = True if player(board) == X else False
    bestMove = None
    if isMaxTurn:
        bestScore = -math.inf
        for move in actions(board):
            result(board, move)
            score = minimax_helper(board)
            board[move[0]][move[1]] = EMPTY
            if (score > bestScore):
                bestScore = score
                bestMove = move
    return bestMove
else:
    bestScore = +math.inf
```

```

for move in actions(board):
    result(board, move)
    score = minimax_helper(board)
    board[move[0]][move[1]] = EMPTY
    if (score < bestScore):
        bestScore = score
        bestMove = move
return bestMove

def print_board(board):
    for row in board:
        print(row)

# Example usage:
game_board = initial_state()
print("Initial Board:")
print_board(game_board)

while not terminal(game_board):
    if player(game_board) == X:
        user_input = input("\nEnter your move (row, column): ")
        row, col = map(int, user_input.split(','))
        result(game_board, (row, col))
    else:
        print("\nAI is making a move...")
move = minimax(copy.deepcopy(game_board))
result(game_board, move)

print("\nCurrent Board:")

```

```
print_board(game_board)

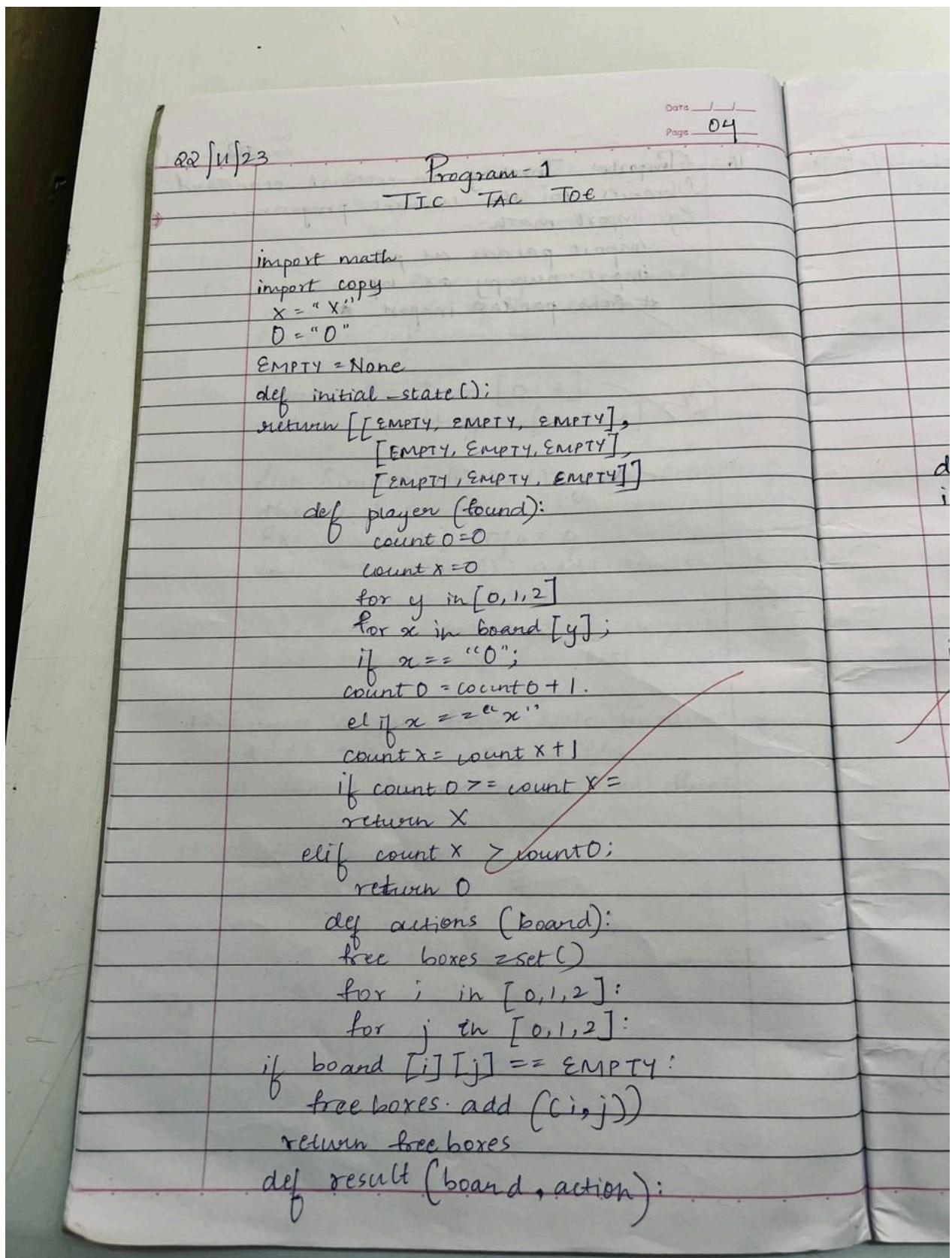
# Determine the winner
if winner(game_board) is not None:
    print(f"\nThe winner is: {winner(game_board)}")
else:
    print("\nIt's a tie!")
```

Output:

```
→ 0,0|0,1|0,2
  1,0|1,1|1,2
  2,0|,2,1|2,2

  | |
-----
  | |
-----
  | |
-----
Enter row (0, 1, or 2): 0
Enter column (0, 1, or 2): 1
0|X|
-----
  | |
-----
  | |
-----
Enter row (0, 1, or 2): 1
Enter column (0, 1, or 2): 2
0|X|
-----
  | |X
-----
0| |
-----
Enter row (0, 1, or 2): 2
Enter column (0, 1, or 2): 1
0|X|
-----
0| |X
-----
0|X|
-----
AI wins!
```

Notes:



```
i = action[0]
j = action[1]
if type(action) == list:
    action = (i, j)
if action in actions(board):
    if player(board) == X:
        board[i][j] = X
    elif player(board) == O:
        board[i][j] = O
    return board

def winner(board):
    if (board[0][0] == board[0][1] == board[0][2] == X or
        board[1][0] == board[1][1] == board[1][2] == X or
        board[2][0] == board[2][1] == board[2][2] == X):
        return X
    if (board[0][0] == board[0][1] == board[0][2] == O or
        board[1][0] == board[1][1] == board[1][2] == O or
        board[2][0] == board[2][1] == board[2][2] == O):
        return O
    return None

for i in [0, 1, 2]:
    s2 = []
    for j in [0, 1, 2]:
        s2.append(board[j][i])
    if (s2[0] == s2[1] == s2[2] == X):
        return s2[0]
    if (s2[0] == s2[1] == s2[2] == O):
        return s2[0]
    strikeD = []
    for i in [0, 1, 2]:
        strikeD.append(board[i][i])
    if (strikeD[0] == strikeD[1] == strikeD[2] == X):
        return strikeD[0]
```

```

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if (board[0][2] == board[1][1] == board[2][0]):
    return board[0][2]
    return None

def terminal(board):
    Full = True
    for i in [0, 1, 2]:
        for j in board[i]:
            if j is None:
                Full = False
    if Full:
        return True
    if (winner(board) is not None):
        return True
    return False

def utility(board):
    if (winner(board) == X):
        return 1
    elif (winner(board) == O):
        return -1
    else:
        return 0

def minimax_helper(board):
    isMaxTurn = True if player(board) == X else False
    if terminal(board):
        return utility(board)

    Scores = []
    for move in actions(board):
        result(board, move)
        scores.append(minimax_helper(board))
    if isMaxTurn:
        return max(scores)
    else:
        return min(scores)

```

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 board [2][0])

```

def minimax (board):
  is Max Turn = True if player (board)
  z = x else FALSE
  best Move = None
  if is Max Turn:
    best Score = -math.inf
    for move in actions (board)
      result (board, move)
      score =
      minimax - helper (board)
      board [move[0]][move[1]] = EMPTY
      if (score > best Score)
        best Score = Score
        best Move = move
      return best Move
    else:
      best Score = +math.inf
      for move in actions (board):
        result (board, move)
        score =
        minimax - helper (board)
        board [move[0]][move[1]] = EMPTY.
        if (score < best Score):
          best Score = Score
          best Move = more move
        return best Move
  def print - board (board)
    for row in board:
      print (row)
  # Example usage:
  game - board = initial - state ()
  
```

```

print ("Initial Board:")
print_board (game-board)
while not terminal (game-board):
    if player (game-board) == X:
        user-input = input ("\n Enter your move (row, column):")
        row, col = map (int, user-input.split (' '))
        result (game-board, (row, col))
    else:
        print ("\n AI is making a move...")
        move =
        minimax (copy.deepcopy (game-board))
        result (game-board, move)
    print ("\n Current Board:")
    print_board (game-board)

# Determine the winner
if winner (game-board) is not None:
    print (f "\n The winner is {winner (game-board)}")
else:
    print ("\n It's a tie!")

```

Output:

Initial Board:

```

[None, None, None]
[None, None, None]
[None, None, None]

```

Enter your move (row, column): 0, 0

Current Board

```

[X, None, None]
[None, None, None]
[None, None, None]

```

current Board:

`['X', None, None]`

`[None, 'O', None]`

`[None, None, None]`

d):

out ('')

....")

d))

me:

Enter your move (row, column): 1, 0.

current Board:

`['X', None, None]`

`['X', 'O', None]`

`[None, None, None]`

A] is making a move....

current Board:

`['X', None, 'X']`

`['X', 'O', None]`

`['O', None, None]`

Enter your move (row, column): 0, 2.

current Board:

`['X', None, 'X']`

`['X', 'O', None]`

`['O', None, None]`

current Board

`['X', 'O', 'X']`

`['X', 'O', None]`

`['O', None, None]`

Enter your move (row, column): 2, 1.

current Board:

`['X', 'O', 'X']`

`['X', 'O', None]`

`['O', 'X', None]`

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AI is making a move....

current Board:

['X', 'O', 'X']

['X', 'O', 'O']

['O', 'X', None]

Enter your move (row, column): 2,2

current Board:

['X', 'O', 'X']

['X', 'O', 'O']

['O', 'X', 'X']

It's a tie!

(X) ✓

def

#

sta

inf

sta

q

p

...

...

...

...

...

...

...

...

...

...

...

...

...

...

Program- 3

Implement the 8 Puzzle Breadth First Search Algorithm.

Code:

```
def bfs(src,target):
    queue = []
    queue.append(src)

    exp = []

    while len(queue) > 0:
        source = queue.pop(0)
        exp.append(source)

        print(source)

        if source==target:
            print("Success")
            return

        poss_moves_to_do = []
        poss_moves_to_do = possible_moves(source,exp)

        for move in poss_moves_to_do:
            if move not in exp and move not in queue:
                queue.append(move)

def possible_moves(state,visited_states):
    #index of empty spot
    b = state.index(0)

    #directions array
```

```

d = []
#Add all the possible directions

if b not in [0,1,2]:
    d.append('u')
if b not in [6,7,8]:
    d.append('d')
if b not in [0,3,6]:
    d.append('l')
if b not in [2,5,8]:
    d.append('r')

# If direction is possible then add state to move
pos_moves_it_can = []

# for all possible directions find the state if that move is played
#### Jump to gen function to generate all possible moves in the given directions

for i in d:
    pos_moves_it_can.append(gen(state,i,b))

    return [move_it_can for move_it_can in pos_moves_it_can
            if move_it_can not in visited_states]

def gen(state, m, b):
    temp = state.copy()

    if m=='d':
        temp[b+3],temp[b] = temp[b],temp[b+3]

    if m=='u':

```

```

temp[b-3],temp[b] = temp[b],temp[b-3]

if m=='l':
    temp[b-1],temp[b] = temp[b],temp[b-1]

if m=='r':
    temp[b+1],temp[b] = temp[b],temp[b+1]

# return new state with tested move to later check if "src == target"
return temp

print("Example 1")
src= [2,0,3,1,8,4,7,6,5]
target=[1,2,3,8,0,4,7,6,5]
print("Source: " , src)
print("Goal State: " , target)
bfs(src, target)

print("\nExample 2")
src = [1,2,3,0,4,5,6,7,8]
target = [1,2,3,4,5,0,6,7,8]
print("Source: " , src)
print("Goal State: " , target)
bfs(src, target)

```

Output:

```
➡ Queue contents:  
1 | 2 | 3  
5 | 6 | 0  
7 | 8 | 4  
  
Queue contents:  
1 | 2 | 0  
5 | 6 | 3  
7 | 8 | 4  
  
Queue contents:  
1 | 2 | 3  
5 | 6 | 4  
7 | 8 | 0  
  
Queue contents:  
1 | 2 | 3  
5 | 0 | 6  
7 | 8 | 4  
  
Queue contents:  
1 | 0 | 2  
5 | 6 | 3  
7 | 8 | 4  
  
Queue contents:  
1 | 2 | 3  
5 | 6 | 4  
7 | 0 | 8  
  
Queue contents:  
1 | 0 | 3  
5 | 2 | 6  
7 | 8 | 4  
  
Queue contents:  
1 | 2 | 3  
5 | 8 | 6  
7 | 0 | 4
```

```
Queue contents:
```

1	6	2
5	0	3
7	8	4

```
Queue contents:
```

0	1	2
5	6	3
7	8	4

```
Queue contents:
```

1	2	3
5	0	4
7	6	8

```
Queue contents:
```

1	2	3
5	6	4
0	7	8

```
Queue contents:
```

0	1	3
5	2	6
7	8	4

```
Queue contents:
```

1	3	0
5	2	6
7	8	4

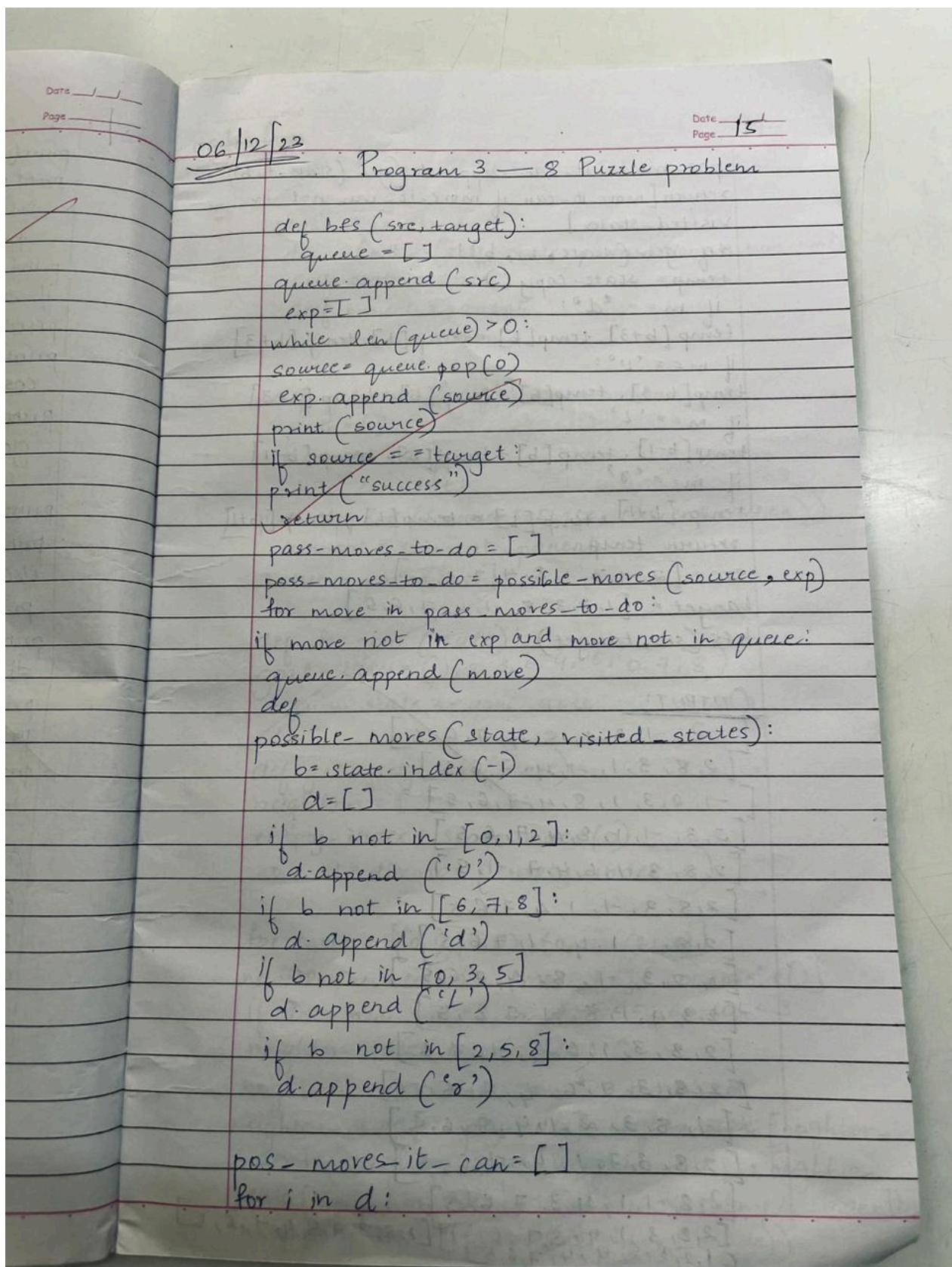
```
Queue contents:
```

1	2	3
5	8	6
0	7	4

```
success
```

```
Cost: 16
```

Notes:



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pos-moves-it-can.append (gen (state, t, b))
return [move-it-can if move-it-can not in
visited-states]
def gen (state, m, b):
temp = state.copy()
if m == 'd':
temp[b+3], temp[b] = temp[b], temp[b+3]
if m == 'u':
temp[b-3], temp[b] = temp[b], temp[b-3]
if m == 'l':
temp[b-1], temp[b] = temp[b], temp[b-1]
if m == 'r':
temp[b+1], temp[b] = temp[b], temp[b+1]
return temp
src = [2, -1, 3, 1, 8, 4, 7, 6, 5]
target = [1, 2, 3, 8, -1, 4, 7, 6, 5]
bfs (src, target)

OUTPUT:

[2, -1, 3, 1, 8, 4, 7, 6, 5]
[2, 8, 3, 1, -1, 4, 7, 6, 5]
[-1, 2, 3, 1, 8, 4, 7, 6, 5]
[2, 3, -1, 1, 8, 4, 7, 6, 5]
[2, 8, 3, 1, 6, 4, 7, -1, 5]
[2, 8, 3, -1, 1, 4, 7, 6, 5]
[2, 8, 3, 1, 4, -1, 7, 6, 5]
[1, 2, 3, -1, 8, 4, 7, 6, 5]
[2, 3, 4, 1, 8, -1, 7, 6, 5]
[2, 8, 3, 1, 6, 4, -1, 7, 5]
[2, 8, 3, 1, 6, 4, 7, 5, -1]
[-1, 8, 3, 2, 1, 4, 7, 6, 5]
[2, 8, 3, 7, 1, 4, -1, 6, 5]
[2, 8, -1, 1, 4, 3, 7, 6, 5]
[2, 8, 3, 1, 4, 5, 7, 6, -1]
[1, 2, 3, 8, -1, 4, 7, 6, 5] [1, 2, 3, 7, 8, 9, -1, 6, 5]

Program- 4

Implement Iterative deepening search algo.

Code:

```
def iterative_deepening_search(src, target):  
    depth_limit = 0  
    while True:  
        result = depth_limited_search(src, target, depth_limit, [])  
        if result is not None:  
            print("Success")  
            return  
        depth_limit += 1  
        if depth_limit > 30: # Set a reasonable depth limit to  
            avoid an infinite loop print("Solution not found  
            within depth limit.")  
            return  
  
def depth_limited_search(src, target, depth_limit, visited_states):  
    if src == target:  
        print_state(src)  
        return src  
  
    if depth_limit == 0:  
        return None  
  
    visited_states.append(src)  
    poss_moves_to_do = possible_moves(src, visited_states)  
  
    for move in poss_moves_to_do:  
        if move not in visited_states:  
            print_state(move)
```

```

        result = depth_limited_search(move, target,
                                      depth_limit - 1, visited_states) if result is not None:
                                         
                                         
    return result

return None

def possible_moves(state, visited_states):
    b = state.index(0)
    d = []

    if b not in [0, 1, 2]:
        d.append('u')
    if b not in [6, 7, 8]:
        d.append('d')
    if b not in [0, 3, 6]:
        d.append('l')
    if b not in [2, 5, 8]:
        d.append('r')

    pos_moves_it_can = []

    for i in d:
        pos_moves_it_can.append(gen(state, i, b))

    return [move_it_can for move_it_can in pos_moves_it_can
            if move_it_can not in visited_states]

```

```

def gen(state, m, b):
    temp = state.copy()

```

```

if m == 'd':
    temp[b + 3], temp[b] = temp[b], temp[b + 3]
elif m == 'u':
    temp[b - 3], temp[b] = temp[b], temp[b - 3]
elif m == 'l':
    temp[b - 1], temp[b] = temp[b], temp[b - 1]
elif m == 'r':
    temp[b + 1], temp[b] = temp[b], temp[b + 1]

return temp

```

```

def print_state(state):
    print(f"{{state[0]}} {{state[1]}} {{state[2]}}\n{{state[3]}} {{state[4]}}
{{state[5]}}\n{{state[6]}} {{state[7]}} {{state[8]}}\n")

print("Example 1")
src = [1,2,3,0,4,5,6,7,8]
target = [1,2,3,4,5,0,6,7,8]
print("Source: " , src)
print("Goal State: " , target)
iterative_deepening_search(src, target)

```

Output:

```

█ Enter the number of vertices:7
Enter the first vertex:0
Enter the second vertex:1
Enter the first vertex:0
Enter the second vertex:2
Enter the first vertex:1
Enter the second vertex:3
Enter the first vertex:1
Enter the second vertex:4
Enter the first vertex:2
Enter the second vertex:5
Enter the first vertex:2
Enter the second vertex:6
Enter the target vertex:6
Enter the max depth:3
Target is NOT reachable from source within 1
Target is NOT reachable from source within 2
Target is reachable from source within 3
COST:6

```


Program- 5

Implement A* search algo.

```
def print_grid(src):

    state = src.copy()
    state[state.index(-1)] = ' '
    print(
        f"""
{state[0]} {state[1]} {state[2]}
{state[3]} {state[4]} {state[5]}
{state[6]} {state[7]} {state[8]}
"""
    )

def h(state, target):
    #Manhattan distance
    dist = 0
    for i in state:
        d1, d2 = state.index(i), target.index(i)
        x1, y1 = d1 % 3, d1 // 3
        x2, y2 = d2 % 3, d2 // 3

        dist += abs(x1-x2) + abs(y1-y2)

    return dist

def astar(src, target):
    states = [src]
    g = 0
    visited_states = set()
    while len(states):
        moves = []
```

```
for state in states:
```

```
    visited_states.add(tuple(state))
```

```
    print_grid(state)
```

```
    if state == target:
```

```
        print("Success")
```

```
        return
```

```
    moves += [move for move in possible_moves(state,  
visited_states) if move not in moves]
```

```
    costs = [g + h(move, target) for move in moves]
```

```
    states = [moves[i] for i in range(len(moves)) if costs[i] == min(costs)]
```

```
    g += 1
```

```
print("Fail")
```

```
def possible_moves(state, visited_states):
```

```
    b = state.index(-1)
```

```
    d = []
```

```
    if 9 > b - 3 >= 0:
```

```
        d += 'u'
```

```
    if 9 > b + 3 >= 0:
```

```
        d += 'd'
```

```
    if b not in [2,5,8]:
```

```
        d += 'r'
```

```
    if b not in [0,3,6]:
```

```
        d += 'l'
```

```
    pos_moves = []
```

```
    for move in d:
```

```
        pos_moves.append(gen(state, move, b))
```

```
    return [move for move in pos_moves if tuple(move) not in visited_states]
```

```
def gen(state, direction, b):
```

```
    temp = state.copy()
```

```

if direction == 'u':
    temp[b-3], temp[b] = temp[b], temp[b-3]
if direction == 'd':
    temp[b+3], temp[b] = temp[b], temp[b+3]
if direction == 'r':
    temp[b+1], temp[b] = temp[b], temp[b+1]
if direction == 'l':
    temp[b-1], temp[b] = temp[b], temp[b-1]
return temp

```

```

#Test 1
print("Example 1")
src = [1,2,3,-1,4,5,6,7,8]
target = [1,2,3,4,5,-1,6,7,8]
print("Source: " , src)
print("Goal State: " , target)
astar(src, target)

```

```

# Test 2
print("Example 2")
```

```

src = [1,2,3,-1,4,5,6,7,8]
target=[1,2,3,6,4,5,-1,7,8]
print("Source: " , src)
print("Goal State: " , target)
astar(src, target)
```

```

# Test 3
print("Example 3")
```

```
src = [1,2,3,7,4,5,6,-1,8]
target=[1,2,3,6,4,5,-1,7,8]
print("Source: " , src)
print("Goal State: " , target)
astar(src, target)
```

Output:

```
✉ Input vals from 0-8 for start state
enter vals :1
enter vals :2
enter vals :3
enter vals :5
enter vals :6
enter vals :0
enter vals :7
enter vals :8
enter vals :4
Input vals from 0-8 for goal state
Enter vals :1
Enter vals :2
Enter vals :3
Enter vals :5
Enter vals :8
Enter vals :6
Enter vals :0
Enter vals :7
Enter vals :4
1. Manhattan distance
2. Misplaced tiles2
The 8 puzzle is solvable

1 2 3
5 6 0
7 8 4

1 2 3
5 0 6
7 8 4

1 2 3
5 8 6
7 0 4

1 2 3
5 8 6
0 7 4
Steps to reach goal: 3
Total nodes visited: 3

Total generated: 8
```

Notes :

Program - G - A

```
import heapq
class FuxileNode:
    def __init__(self, state, parent = None):
        g = 0, h = 0
        self.state = state
        self.parent = parent
        self.g = g
        self.h = h
        self.f = self.g + self.h
    def __lt__(self, other):
        return self.f < other.f
def manhattan_distance(state, goal_state):
    distance = 0
    for i in range(3):
        for j in range(3):
            if state[i][j] != goal_state[i][j] and state[i][j] != 0:
                x, y = divmod(goal_state[i][j], 3)
                distance += abs(x-i) + abs(y-j)
    return distance
def get_blank_position(state):
    for i in range(3):
        for j in range(3):
            if state[i][j] == 0:
                return i, j
def get_neighbors(node):
    i, j = get_blank_position(node.state)
    neighbors = []
    for x, y in [(i+1, j), (i-1, j), (i, j+1), (i, j-1)]:
        if 0 <= x < 3 and 0 <= y < 3:
            neighbor_state = [row[:] for row in node.state]
            neighbor_state[i][j], neighbor_state[x][y] = neighbor_state[x][y], neighbor_state[i][j]
            neighbors.append(FuxileNode(neighbor_state, node))
    return neighbors
```

```
neighbor-state[x][y] = neighbor-state[x][y],  
neighbor-state[i][j],  
neighbors.append(PuzzleNode(neighbor-state,  
parent=none))  
return neighbors  
def a_star_search(initial-state, goal-state,  
heuristic):  
    initial-node = puzzleNode(initial-state,  
    g=0, h=heuristic(initial-state, goal-state))  
    goal-node = puzzleNode(goal-state)  
    if initial-state == goal-state:  
        return [initial-state]  
    priority-queue = [initial-node]  
    visited-states = set()  
    while priority-queue:  
        current-node = heapq.heappop(priority-queue)  
        if current-node.state == goal-state:  
            path = [current-node.state]  
            while current-node.parent:  
                current-node = current-node.parent  
                path.append(current-node.state)  
            path.reverse()  
            return path  
        visited-states.add(tuple((map(tuple,  
        current-node.state))))  
        neighbors = get_neighbors(current-node)  
        for neighbor in neighbors:  
            if tuple((map(tuple, neighbor.state))) not  
            in visited-states:  
                neighbor.g = current-node.g + 1  
                neighbor.h = heuristic(neighbor.state,  
                goal-state)
```

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```
neighbor_f = neighbor_g + neighbor_h
heapq.heappush(priority_queue, neighbor)
return None.
```

Example usage

initial_state = [

[1, 2, 3]

[4, 0, 5]

[6, 7, 8]

] goal_state = [

[1, 2, 3]

[4, 5, 6]

[7, 8, 0]

]

heuristic function = manhattan_distance

path = a_star_search(initial_state,
goal_state, heuristic_function)

if path:

print ("Solution found: ")

for state in path:

for row in state:

print (row)

print ()

else:

print ("No solution found")

Output:

Solution found

[1, 2, 3]

[4, 0, 5]

[6, 7, 8]

$$\begin{bmatrix} 1, 2, 3 \\ 5, 0, 6 \\ 4, 7, 8 \end{bmatrix}$$
$$\begin{bmatrix} 1, 2, 3 \\ 0, 5, 6 \\ 4, 7, 8 \end{bmatrix}$$
$$\begin{bmatrix} 1, 2, 3 \\ 4, 5, 6 \\ 0, 7, 8 \end{bmatrix}$$
$$\begin{bmatrix} 1, 2, 3 \\ 4, 5, 6 \\ 7, 0, 8 \end{bmatrix}$$
$$\begin{bmatrix} 1, 2, 3 \\ 4, 5, 6 \\ 7, 8, 0 \end{bmatrix}$$

Program- 6

Create a knowledge base using prepositional logic and show that the given query entails the knowledge base or not .

Code:

```
def evaluate_expression(p, q, r):
    expression_result = (p or q) and (not r or p)
    return expression_result

def generate_truth_table():
    print(" p | q | r | Expression (KB) | Query (p^r)")
    print("----|---|---|-----|-----")
    for p in [True, False]:
        for q in [True, False]:
            for r in [True, False]:
                expression_result = evaluate_expression(p, q, r)
                query_result = p and r
                print(f" {p} | {q} | {r} | {expression_result} | {query_result}")

def query_entails_knowledge():
    for p in [True, False]:
        for q in [True, False]:
            for r in [True, False]:
                expression_result = evaluate_expression(p, q, r)
                query_result = p and r
                if expression_result and not query_result:
                    return False
    return True
```

```
def main():
    generate_truth_table()

    if query_entails_knowledge():
        print("\nQuery entails the knowledge.")
    else:
        print("\nQuery does not entail the knowledge.")

if __name__ == "__main__":
    main()
```

Notes:

Program 7 — Propositional logic

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Create KB using propositional logic
and show the given KB entails
Query / NOT .

```
def evaluate_expression(q, p, r)
    expression_result = (p or q) and (not r or p)
    return expression_result
```

```
def generate_truth_table():
    print("1 t Expression(kB)")
    print("-----|-----|-----|-----")
    for q in [True, False]:
        for p in [True, False]:
            for r in [True, False]:
                expression_result = evaluate_expression(q, p, r)
                query_result = p and r
                print(f'{expression_result}|{query_result}'")
```

```
def query_entails_knowledge():
    for q in [True, False]:
        for p in [True, False]:
            for r in [True, False]:
                expression_result = evaluate_expression(q, p, r)
                query_result = p and r
                if expression_result and not query_result:
                    return False
    return True
```

```
if expression_result and not
query_result:
    return False
return True
```

```
Date _____  
Page _____  
  
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def main():  
    generate_truth_table()  
    if query_entails_knowledge():  
        print("In Query entails the knowledge")  
    else:  
        print("In Query does not entail the  
knowledge if name == 'main'"  
main()
```

Output:

True | True

True | False

False | False

True | False

True | True

True | False

False | False

False | False

Query does not entail the knowledge.

Output:

```
Enter rule: pvq
Enter the Query: q
*****Truth Table Reference*****
kb alpha
*****
True True
-----
True True
-----
True False
-----
The Knowledge Base does not entail query
```

Program- 7

Create a knowledge base using prepositional logic and prove the given query using resolution

Code:

```
import re

def main(rules, goal):
    rules = rules.split(' ')
    steps = resolve(rules, goal)
    print("\nStep\tClause\tDerivation\t")
    print('-' * 30)
    i = 1
    for step in steps:
        print(f' {i}.\t{step}\t{steps[step]}\t')
        i += 1

def negate(term):
    return f'~{term}' if term[0] != '~' else term[1]

def reverse(clause):
    if len(clause) > 2:
        t = split_terms(clause)
        return f'{t[1]}v{t[0]}'
    return ""

def split_terms(rule):
    exp = '(~*[PQRS])'
    terms = re.findall(exp, rule)
    return terms

split_terms('~PvR')

def contradiction(goal, clause):
    contradictions = [ f'{goal}v{negate(goal)}', f'{negate(goal)}v{goal}' ]
    return clause in contradictions or reverse(clause) in contradictions

def resolve(rules, goal):
```

```

temp = rules.copy()
temp += [negate(goal)]
steps = dict()
for rule in temp:
    steps[rule] = 'Given.'
steps[negate(goal)] = 'Negated conclusion.'
i = 0
while i < len(temp):
    n = len(temp)
    j = (i + 1) % n
    clauses = []
    while j != i:
        terms1 = split_terms(temp[i])
        terms2 = split_terms(temp[j])
        for c in terms1:
            if negate(c) in terms2:
                t1 = [t for t in terms1 if t != c]
                t2 = [t for t in terms2 if t != negate(c)]
                gen = t1 + t2
                if len(gen) == 2:
                    if gen[0] != negate(gen[1]):
                        clauses += [f'{gen[0]} ∨ {gen[1]}']
                    else:
                        if contradiction(goal, f'{gen[0]} ∨ {gen[1]}'):
                            temp.append(f'{gen[0]} ∨ {gen[1]}')
                steps[""] = f"Resolved {temp[i]} and {temp[j]} to {temp[-1]}, which is in turn null.\n"
    \nA contradiction is found when {negate(goal)} is assumed as true.  

Hence, {goal} is true."
    return steps
    elif len(gen) == 1:
        clauses += [f'{gen[0]}']

```

```

else:
    if contradiction(goal,f' {terms1[0]} v {terms2[0]})':
        temp.append(f' {terms1[0]} v {terms2[0]}')
        steps[""] = f"Resolved {temp[i]} and {temp[j]} to
{temp[-1]}, which is in turn null. \
\nA contradiction is found when {negate(goal)} is
assumed as true. Hence, {goal} is true."
    return steps

for clause in clauses:
    if clause not in temp and clause != reverse(clause) and
        reverse(clause) not in temp: temp.append(clause)
    steps[clause] = f'Resolved from {temp[i]} and {temp[j]}.'

    j = (j + 1) % n
    i += 1

return steps

rules = 'Rv~P Rv~Q ~RvP ~RvQ' #(P^Q)<=>R :
(Rv~P)v(Rv~Q)^(~RvP)^(~RvQ) goal = 'R'
print('Rules: ',rules)
print("Goal: ",goal)
main(rules, goal)

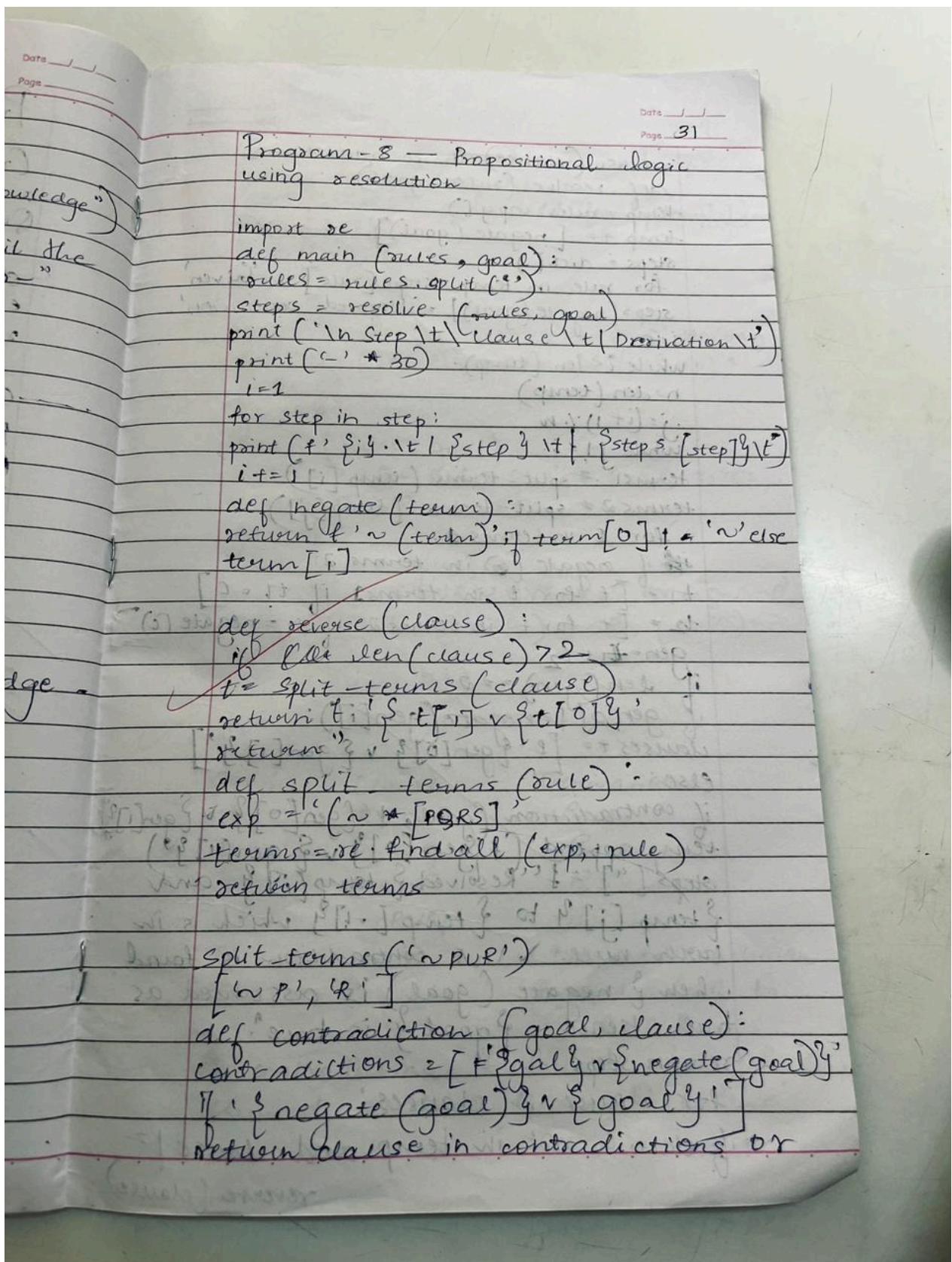
rules = 'PvQ ~PvR ~QvR' #P=vQ, P=>Q : ~PvQ, Q=>R, ~QvR
goal = 'R'
print('Rules: ',rules)
print("Goal: ",goal)
main(rules, goal)

rules = 'PvQ PvR ~PvR RvS Rv~Q ~Sv~Q' # (P=>Q)=>Q,
(P=>P)=>R, (R=>S)=>~(S=>Q) goal = 'R'
print('Rules: ',rules)

print("Goal: ",goal)
main(rules, goal)

```

Notes:



reverse (clause) in contradictions

def resolve (rules, goal)

temp = rules. copy ()

temp += [negate (goal)]

steps = dict ()

for rule in temp = steps [rule] = "Given"

steps [negate (goal)] = "Negated conclusion"

i = 0

while i < len (temp):

n = len (temp)

j = (i + 1) % n

while j != i:

terms1 = split - terms (-temp [i])

terms2 = split - terms (-temp [j])

form C in terms1 :

if negate (C) in terms2:

t1 = [t for t in terms1 if t == C]

t2 = [t for t in terms2 if t == negate (C)]

gen = t1 + t2

if len (gen) == 0:

if gen[0] is negate (gen[i]):

clauses += [f' {gen[0]} \vee {gen[i]}']

else:

if contradiction (goal, f'{gen[0]} \vee {gen[i]}')

temp.append (f'{gen[0]} \vee {gen[i]}')

steps [""] = f"Resolved {temp[i]} and

{temp[j]} to {temp[-1]} which is in

turn null. A contradiction is found

when {negate (goal)} is assumed as

true. Hence, {goal} is true".

return steps

for clause in clauses:

if clause not in temp and clause !=

reverse (clause)

and
temp
steps

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and reverse clause
temp. append clause not in temp:
steps [clause] = p Resolved from [temp[i:j]]
temp[i:j]
 $j = (j+1) \mod n$
 $i+1$

return steps
rules = $R \vee \neg P \quad P \vee \neg Q \sim R \vee P \sim R \vee Q' \# (P \wedge Q)$
 $\Leftarrow \Rightarrow R : (R \vee \neg P) \vee (R \vee \neg Q) \sim (\neg R \vee P) \sim (\neg R \vee Q)$

goal = R
main (rules, goal)

rules = $P \vee Q \sim P \vee R \vee Q \vee R' \# P = \neg Q, P \Rightarrow Q = \neg P \vee Q, Q \Rightarrow R \sim Q \vee R$

goal = R

main (rules, goal)

rules = $P \vee Q \sim P \vee R \sim P \vee S \sim R \vee S \sim Q \sim R \sim S \# (P \Rightarrow Q) \Rightarrow Q, (P \Rightarrow R) \Rightarrow R, (R \Rightarrow S) \Rightarrow S$

$\sim (S \Rightarrow Q)$
main (rules, 'R')

Output:

Step	Clause	Derivation
1	$R \vee \neg P$	Given
2	$R \vee \neg Q$	Given
3	$\neg R \vee P$	Given
4	$\neg R \vee Q$	Given
5	$\neg R$	Negated conclusion Resolved $R \vee \neg P$ to
6	$R \vee \neg R$	

A contradiction is found when $\neg R$ is assumed as true. Hence, R is true.

Output:

True

Program- 8

Implement unification in first order logic

Code:

```
import re

def getAttributes(expression):
    expression = expression.split("(")[1:]
    expression = (".".join(expression)
    expression = expression[:-1]
    expression = re.split("(?<!\\(.),(?!\\.))", expression)
    return expression

def getInitialPredicate(expression):
    return expression.split("(")[0]

def isConstant(char):
    return char.isupper() and len(char) == 1

def isVariable(char):
    return char.islower() and len(char) == 1

def replaceAttributes(exp, old, new):
    attributes = getAttributes(exp)
    for index, val in enumerate(attributes):
        if val == old:
            attributes[index] = new
    predicate = getInitialPredicate(exp)
    return predicate + "(" + ",".join(attributes) + ")"

def apply(exp, substitutions):
    for substitution in substitutions:
```

```

new, old = substitution
exp = replaceAttributes(exp, old, new)
return exp

def checkOccurs(var, exp):
    if exp.find(var) == -1:
        return False
    return True

def getFirstPart(expression):
    attributes = getAttributes(expression)
    return attributes[0]

def getRemainingPart(expression):
    predicate = getInitialPredicate(expression)
    attributes = getAttributes(expression)
    newExpression = predicate + "(" + ",".join(attributes[1:]) + ")"
    return newExpression

def unify(exp1, exp2):
    if exp1 == exp2:
        return []
    if isConstant(exp1) and isConstant(exp2):
        if exp1 != exp2:
            return False
    if isConstant(exp1):
        return [(exp1, exp2)]

```

```

if isConstant(exp2):
    return [(exp2, exp1)]


if isVariable(exp1):
    if checkOccurs(exp1, exp2):
        return False
    else:
        return [(exp2, exp1)]


if isVariable(exp2):
    if checkOccurs(exp2, exp1):
        return False
    else:
        return [(exp1, exp2)]


if getInitialPredicate(exp1) != getInitialPredicate(exp2):
    print("Predicates do not match. Cannot be unified")
    return False


attributeCount1 = len(getAttributes(exp1))
attributeCount2 = len(getAttributes(exp2))
if attributeCount1 != attributeCount2:
    return False


head1 = getFirstPart(exp1)
head2 = getFirstPart(exp2)
initialSubstitution = unify(head1, head2)
if not initialSubstitution:

```

Output:

```
Enter the first expression
knows(y,f(x))
Enter the second expression
knows(nithin,N)
The substitutions are:
['nithin / y', 'N / f(x)']
```

Notes :

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10/01/2024 Program 9 — Unification in first
order logic

classification error (exception):
pass

def unify_var (var, x, theta):
 if var in theta:
 return unify (theta[var], x, theta)
 elif x in theta:
 return unify (var, theta[x], theta)
 else:
 theta[var] = x
 return theta

def unify (x, y, theta):
 if theta is None:
 return None
 elif x == y:
 return theta
 elif isinstance (x, str) and x.isalpha ():
 return unify_var (x, y, theta)
 elif isinstance (y, str) and y.isalpha ():
 return unify_var (y, x, theta)
 elif isinstance (x, list) and isinstance (y, list) and len(x) == len(y):
 return unify (x[1:], y[1:], unify (x[0], y[0], theta))
 else:
 raise UnificationError ("Unification failed")

if name
try theta
print (theta)
except print
Output
Subst
[CA]

if name == "main":

try:

theta = unify(['P', 'n', 'y'], ['P', 'A'; 'B's])

print("Unification successful, substitution:", theta)

except UnificationError as e:

print("Unification failed:", str(e))

Output:

Substitutions:

~~[('A', 'y'), ('y', 'n')]~~

(*)

Program- 9

Convert a given first order logic statement into Conjunctive Normal Form (CNF).

```
Code: def getAttributes(string):
expr = '\([^\)]+\)'
matches = re.findall(expr, string)
return [m for m in str(matches) if m.isalpha()]

def getPredicates(string):
expr = '[a-zA-Z~]+\([A-Za-z,]+\)'
return re.findall(expr, string)

def Skolemization(statement):
SKOLEM_CONSTANTS = [f'{chr(c)}' for c in range(ord('A'), ord('Z')+1)]
matches = re.findall('[\exists].', statement)
for match in matches[::-1]:
statement = statement.replace(match, "")
for predicate in getPredicates(statement):
attributes = getAttributes(predicate)
if ".join(attributes).islower()":
statement = statement.replace(match[1],SKOLEM_CONSTANTS.pop(0))
return statement

import re

def fol_to_cnf(fol):
statement = fol.replace("=>", "-")
expr = '\([^\)]+\)'
statements = re.findall(expr, statement)
for i, s in enumerate(statements):
if '[' in s and ']' not in s:
statements[i] += ']'
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for s in statements:
statement = statement.replace(s, fol_to_cnf(s))
while '-' in statement:
i = statement.index('-')
br = statement.index('[') if '[' in statement else 0
new_statement = '~' + statement[br:i] + ']' + statement[i+1:]
```

```

statement = statement[:br] + new_statement if br > 0 else new_statement
return Skolemization(statement)
print(fol_to_cnf("bird(x)=>~fly(x)"))
print(fol_to_cnf(" ∃ x[bird(x)=>~fly(x)]"))
print(Skolemization(fol_to_cnf("animal(y)<=>loves(x,y)")))
print(Skolemization(fol_to_cnf(" ∀ x[ ∀ y[animal(y)=>loves(x,y)]]=>[ ∃ z[loves(z,x)]]")))
print(fol_to_cnf("[american(x)&weapon(y)&sells(x,y,z)&hostile(z)]=>criminal(x)"))

```

Output:

Example 1

FOL: $\text{bird}(x)=>\sim\text{fly}(x)$
 CNF: $\sim\text{bird}(x) \mid \sim\text{fly}(x)$

Example 2

FOL: $\exists x[\text{bird}(x)=>\sim\text{fly}(x)]$
 CNF: $[\sim\text{bird}(A) \mid \sim\text{fly}(A)]$

Example 3

FOL: $\text{animal}(y)<=>\text{loves}(x,y)$
 CNF: $\sim\text{animal}(y) \mid \text{loves}(x,y)$

Example 4

FOL: $\forall x[\forall y[\text{animal}(y)=>\text{loves}(x,y)]]=>[\exists z[\text{loves}(z,x)]]$
 CNF: $\forall x \sim [\forall y [\sim\text{animal}(y) \mid \text{loves}(x,y)]] \mid [\text{loves}(A,x)]$

Example 5

FOL: $[\text{american}(x) \& \text{weapon}(y) \& \text{sells}(x,y,z) \& \text{hostile}(z)] \Rightarrow \text{criminal}(x)$
 CNF: $\sim[\text{american}(x) \& \text{weapon}(y) \& \text{sells}(x,y,z) \& \text{hostile}(z)] \mid \text{criminal}(x)$

Notes :

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Program 10 : Convert given first order logic statement into Conjunctive Normal Form (CNF).

```

def get_attributes(string):
    expr = '\([^\)]+\)'
    matches = re.findall(expr, string)
    return [m for m in str(matches) if m.isalpha()]

def get_predicates(string):
    expr = '[a-zA-Z]+(\[a-zA-Z\]+\w*)'
    matches = re.findall(expr, string)
    return [m for m in str(matches) if m.isalpha()]

def Skolemization(statement):
    SKOLEM_CONSTANTS = [f'{chr(c)}' for c in range(ord('A'), ord('Z')+1)]
    matches = re.findall('[\w]', statement)
    for match in matches[:: -1]:
        statement = statement.replace(match, '')
    for predicate in get_predicates(statement):
        attributes = get_attributes(predicate)
        if ''.join(attributes).islower():
            statement = statement.replace(match[0], SKOLEM_CONSTANTS.pop(0))
    return statement

import re
def fol_to_cnf(fol):
    statement = fol.replace("=>", "-")
    expr = '\((\w+)\)\+'
    statements = re.findall(expr, statement)
    for i, s in enumerate(statements):
        if '[' in s and ']' not in s:

```

First order
ve Normal

m.isalpha()

for

)

ent).

n, ' ').

ement):

e)

ach[1].

statements[i] += ']'
for s in statements:

statement = statement.replace(s, fol_to_inf(s))
while '-' in statement:

i = statement.index('-')

br = statement.index('[') if '[' in
statement else 0

new_statement = ' ~' + statement[br:i]
+ ']' + statement[i+1:]

statement = statement[:br] + new_statement

if br > 0 else new_statement

return Skolemization(statement)

print(fol_to_inf("bird(x) > ~fly(x)"))
print(fol_to_inf("Ex(bird(x) > ~fly(x)))

Output.

~bird(x) | ~fly(x)

[abird(A) | ~fly(A)]

Ex
~fly

Program-10

Create a knowledge base consisting of first order logic statements and prove the given query using forward reasoning.

Code:

```
import re

def isVariable(x):
    return len(x) == 1
        and x.islower()
        and x.isalpha()

def getAttributes(string):
    expr = '\([^\)]+\)'
    matches =
        re.findall(expr,
                    string)
    return matches

def getPredicates(string):
    expr =
        '([a-zA-Z~]+)\([^\&| ]+\''
    return
        re.findall(expr,
                    string)

class Fact:
    def __init__(self,
                 expression):
        self.expression =
            expression
        predicate, params =
            self.splitExpress
            ion(expression)
        self.predicate =
            predicate
        self.params = params
        self.result =
            any(self.getConst
                ants())
    def splitExpression(s
                       elf, expression):
```

```

predicate =
    getPredicates(exp
        ression)[0]
params =
    getAttributes(exp
        ression)[0].strip
    ('()' .split(',')
return [predicate,
    params]

def getResult(self):
39
    return self.result

def
    getConstants(self
        ) :
return [None if
    isVariable(c)
    else c for c in
    self.params]

def
    getVariables(self
        ) :
return [v if
    isVariable(v)
    else None for v
    in self.params]

def substitute(self,
    constants):
c = constants.copy()
f =
    f"{{self.predicate
        }({','.join([cons
            tants.pop(0) if
            isVariable(p)
            else p for p in
            self.params])}}"
return Fact(f)

class Implication:
def __init__(self,
    expression):
    self.expression =

```

```

        expression
l =
    expression.split(
        '>=')
self.lhs = [Fact(f)
    for f in
        l[0].split('&')]
self.rhs =
    Fact(l[1])

def evaluate(self,
            facts):
constants = {}
new_lhs = []
for fact in facts:
    for val in self.lhs:
        if val.predicate ==
            fact.predicate:
            for i, v in
                enumerate(val.get
                    Variables()):
                if v:
                    constants[v] =
                        fact.getConstants
                        ()[i]
            new_lhs.append(fact)
40
predicate,
    attributes =
        getPredicates(sel
            f.rhs.expression)
            [0],
str(getAttributes(sel
            f.rhs.expression)
            [0])
for key in
    constants:
if constants[key]:
    attributes =
        attributes.replace
        (key,
            constants[key])
expr =
    f'{predicate}{att
        ributes}'
return Fact(expr) if

```

```

        len(new_lhs) and
        all([f.getResult(
            ) for f in
            new_lhs]) else
        None
    class KB:
        def __init__(self):
            self.facts = set()
            self.implications =
                set()

        def tell(self, e):
            if '=>' in e:

                self.implications
                .add(Implication(
                    e))
            else:

                self.facts.add(Fa
                    ct(e))
            for i in
                self.implications
                :
            res =
                i.evaluate(self.f
                    acts)
            if res:
                self.facts.add(res)
        def query(self, e):
            facts =
                set([f.expression
                    for f in
                    self.facts])
            i = 1
            print(f'Querying
                {e}:')
            for f in facts:
                if Fact(f).predicate
                    ==
                    Fact(e).predicate
                    :
            print(f'\t{i}. {f}')
            i += 1

```

```

def display(self):
    print("All facts: ")
    for i, f in
        enumerate(set([f.
            expression for f
            in self.facts])):
    print(f'\t{i+1}).
        {f} ')
kb = KB()
kb.tell('missile(x)=>
    weapon(x)')
kb.tell('missile(M1)'
)
kb.tell('enemy(x,Amer
ica)=>hostile(x)'
)
kb.tell('american(Wes
t)')
kb.tell('enemy(Nono,A
merica)')
kb.tell('owns(Nono,M1
)')
kb.tell('missile(x)&o
wns(Nono,x)=>sell
s(West,x,Nono)')
kb.tell('american(x) &
    weapon(y)&sells(x
,y,z)&hostile(z)=
>criminal(x)')
kb.query('criminal(x)
')
kb.display()
kb_ = KB()
kb_.tell('king(x)&gre
edy(x)=>evil(x)')
kb_.tell('king(John)'
)
kb_.tell('greedy(John
)')
kb_.tell('king(Richar
d)')
kb_.query('evil(x)')

```

Output:

```
Enter KB: (enter e to exit)
missile(x)=>weapon(x)
missile(m1)
enemy(x,america)=>hostile(x)
american(west)
enemy(china,america)
owns(china,m1)
missile(x)&owns(china,x)=>sells(west,x,china)
american(x)&weapon(y)&sells(x,y,z)&hostile(z)=>criminal(x)
e
Enter Query:
criminal(x)
Querying criminal(x):
1. criminal(west)
All facts:
1. criminal(west)
2. weapon(m1)
3. owns(china,m1)
4. enemy(china,america)
5. sells(west,m1,china)
6. american(west)
7. hostile(china)
8. missile(m1)
```

Notes:

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24/01/29 Program - 11

Create a knowledge base consisting of first order logic statements and prove the given query using forward reasoning.

import re

def isVariable(x):

 return len(x) == 1 and x.islower() and x.isalpha()

def getAttributes(string):

 expr = 'V[^]+'

 matches = re.findall(expr, string)

 return matches

getPredicates(string):

expr = '([a-zA-Z]+)\w([A-Z]+)'

return re.findall(expr, string)

class Fact:

def __init__(self, expression):

 self.expr = expr

 pred, params = self.splitExpr(expr)

 self.pred = pred

 self.params = params

 self.result = self.getConstants()

def splitExpression(self, expression):

def getResult(self):
 return self.result

and

def getConstants(self):
 if len(self.constants) == 0:
 None if isVariable(c) else C
 for c in self.constants]

def substitute(self, constants):
 c = constants.copy()
 f = f" {self.predicate} ({'?'}, join
 [constants.pop(0) if isVariable(p)
 else p for p in self.constants])))"
 return fact(f).

str(getAttributes(self.rhs.expression)[0])
for key in constants:

if constants[key]:
 attributes = attributes.replace(key,
 constants[key])
expr = f'{predicate} {attributes}'
return fact(expr) if len(newlhs) and
all(f.getResults() for f in newlhs)
else None

class KB:

def __init__(self):
 self.facts = set()
 self.implications = set()

def main():

kb = KB()
print("Enter KB : (enter etc
exit)")
while True:

```
t = input()  
if (t == 'e'):  
    break  
kb.tell(t)  
print ("Enter Query:")  
q = input()  
kb.query(q)  
kb.display()  
main()
```

Output:

Enter RB: (enter e to exit)
missile (x) \Rightarrow weapon (x)
missile (m)
enemy (x, america) \Rightarrow hostile (x)
american (west)
enemy (china, america)
owns (china, m)
missile (x) & owns (china, m) \Rightarrow sells
(west, x, china)
american (x) & weapon (y) & sells (x, y, z)
& hostile (z) \Rightarrow criminal (x) e

Enter Query:

criminal (x)
Querying criminal (x):
1. criminal (west)

All facts:

1. criminal (west)
2. weapon (m)
3. owns (china, m)
4. enemy (china, america)

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5. sells (west, mi, china)
6. american (west)
7. hostile (china)
8. missile (mi)

