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# Design and Analysis of Algorithms

## Lecture 4

### Heaps

## Topics

- Heaps
- Building Heaps
- Maintaining heaps
- Heapsort
  - Algorithm
  - Analysis
- Priority Queues

# Heaps - Introduction

- The heap is a data structure for implementing a Partially Ordered Tree or Leftist tree (plus priority queue!)
  - Popular for use as an efficient priority queue
  - A heap is an example of a weakly ordered tree
  - It is special because its structure can be represented in an array
- Each node of a heap tree corresponds to an element of the array that stores the value in the node
  - The tree is stored implicitly
    - But it can be represented explicitly as a standard binary tree with left and right pointers, i.e., represented conceptually as a binary tree
    - The tree is filled on all levels except possibly the lowest, which are filled from left to right up to a point
- An array  $A$  that represents a heap is an object with two attributes:
  - $A.length \rightarrow$  the number of *allocated* elements in the array
  - $A.heap\_size \rightarrow$  the number of elements in the heap stored within the array
  - $A.heap\_size \leq A.length$

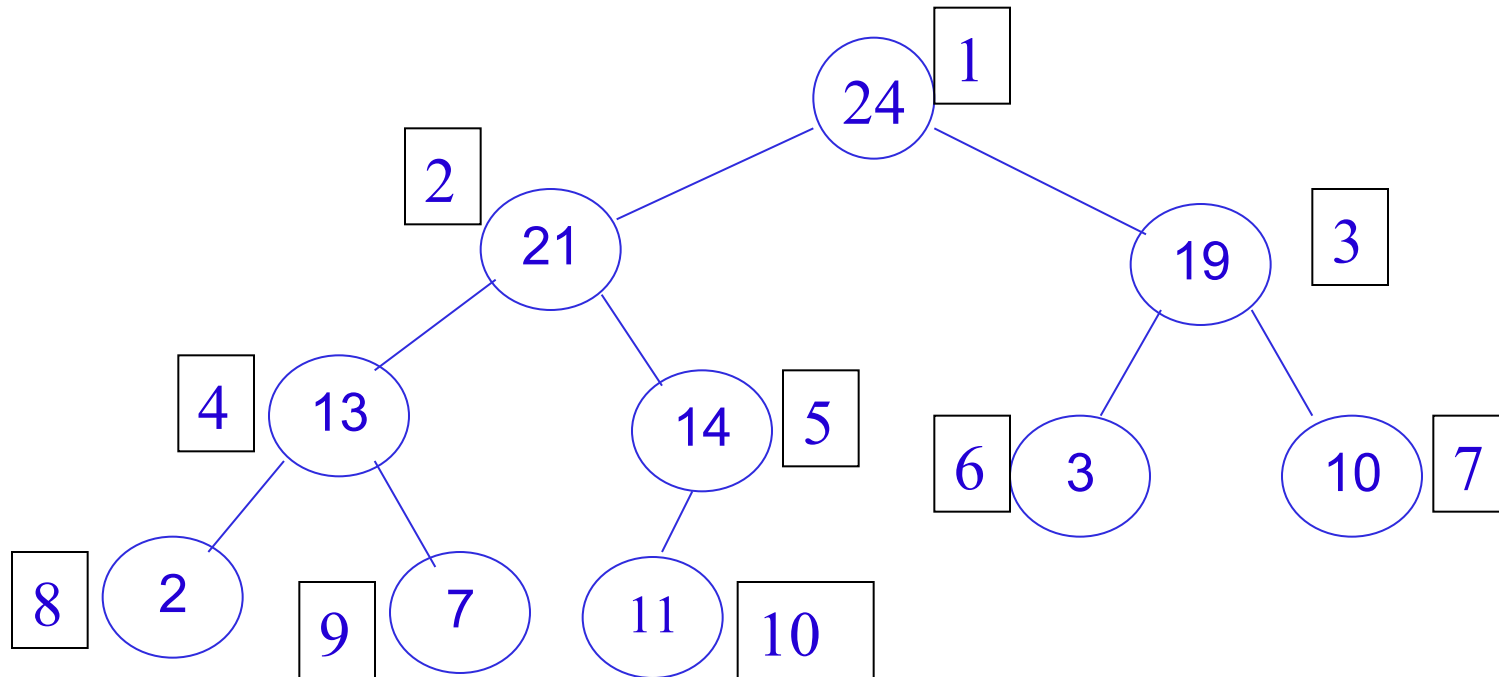
# Heaps (cont.)

- $A[1]$  is the **root** of the tree
- For a node with index  $i$ :
  - $\text{PARENT}(i)$  is the index of the parent of  $i$
  - $\text{PARENT}(i) = \lfloor i/2 \rfloor$
  - $\text{LEFT\_CHILD}(i)$  is the index of the left child of  $i$
  - $\text{LEFT\_CHILD}(i) = 2 \times i$
  - $\text{RIGHT\_CHILD}(i)$  is the index of the right child of  $i$
  - $\text{RIGHT\_CHILD}(i) = 2 \times i + 1$

## Example:

<i>Index</i>	1	2	3	4	5	6	7	8	9	10
<i>Value</i>	24	21	19	13	14	3	10	2	7	11

# Heaps (cont.)



1	2	3	4	5	6	7	8	9	10
24	21	19	13	14	3	10	2	7	11

# Binary Heap Properties

- Two kinds of binary heaps:

**Max-heap:**  $A[\text{PARENT}(i)] \geq A[i]$

**Min-heap:**  $A[\text{PARENT}(i)] \leq A[i]$

- The binary heap is based on a binary tree
- The height of a heap is the number of edges on the longest simple downward path from the root to a leaf
- The height of a heap with  $n$  nodes is  $O(\log n)$
- All basic operations on heaps run in  $O(\log n)$  time

# Binary Heap Tree

Height

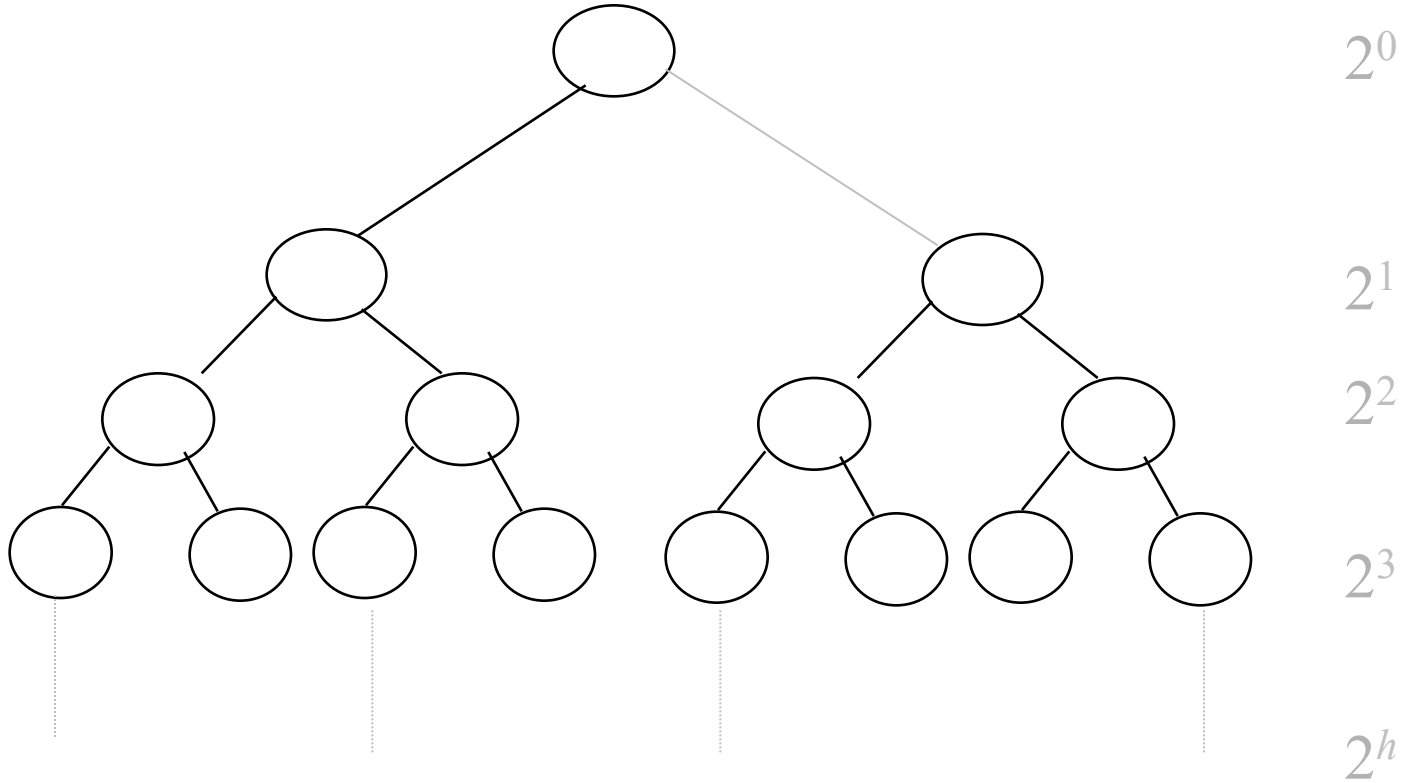
$h$

$h-1$

$h-2$

$h-3$

0



$$n = 2^0 + 2^1 + 2^2 + 2^3 + \dots + 2^h = 2^{h+1} - 1 \rightarrow \text{Geometric Series}$$

$$\sum_{i=0}^h x^i = \frac{x^{h+1} - 1}{x - 1} \Rightarrow \frac{2^{h+1} - 1}{2 - 1} = 2^{h+1} - 1$$



# Heap Algorithms

## MAX-HEAPIFY

- maintains the max-heap property
- $O(\log n)$

## BUILD-MAX-HEAP

- produces a max-heap from an unordered input array
- $O(n)$

## HEAPSORT

- sorts an array in place
- $O(n \log n)$

## HEAP-EXTRACT-MAX

- used for priority queue
- $O(\log n)$

## MAX-HEAP-INSERT

- inserts an element to the heap
- $O(\log n)$

# MAX-HEAPIFY

- MAX-HEAPIFY checks the heap elements for violation of the heap property and restores the property.

## MAX-HEAPIFY ( $A, i$ )

### Input:

- An array  $A$  and index  $i$  to the array
  - $i = 1$  if we want to max-heapify the whole tree
- Sub-trees rooted at  $\text{LEFT\_CHILD}(i)$  and  $\text{RIGHT\_CHILD}(i)$  are heaps
  - Assume that the sub-trees are already Max-Heaps.

### Output:

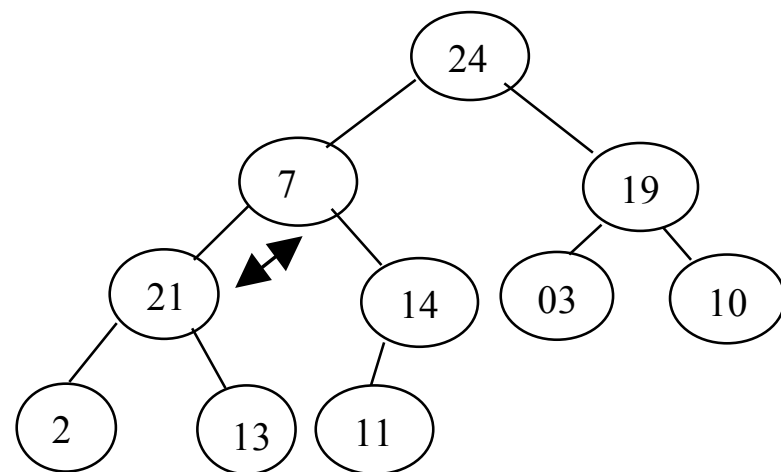
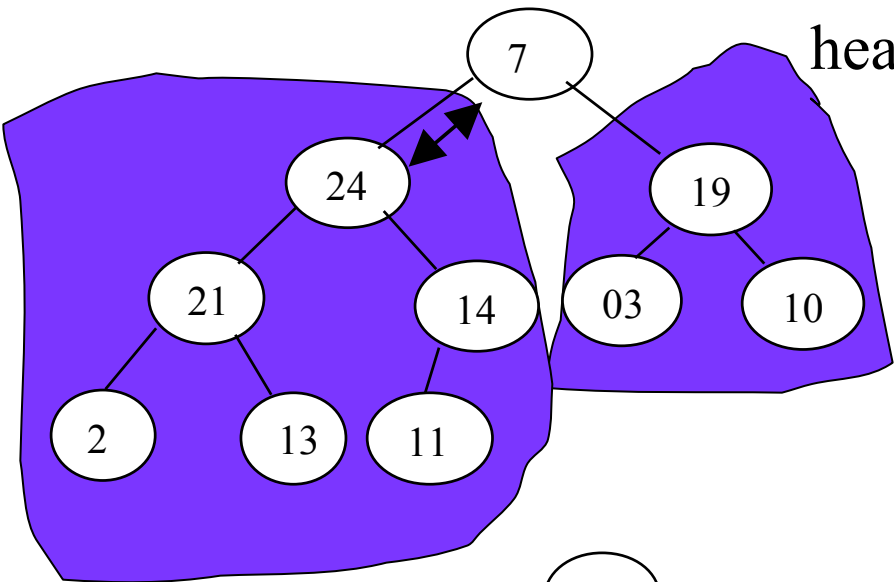
- The elements of array  $A$  forming a sub-tree rooted at  $i$  that satisfy the heap property.

# MAX-HEAPIFY (Trickle-down)

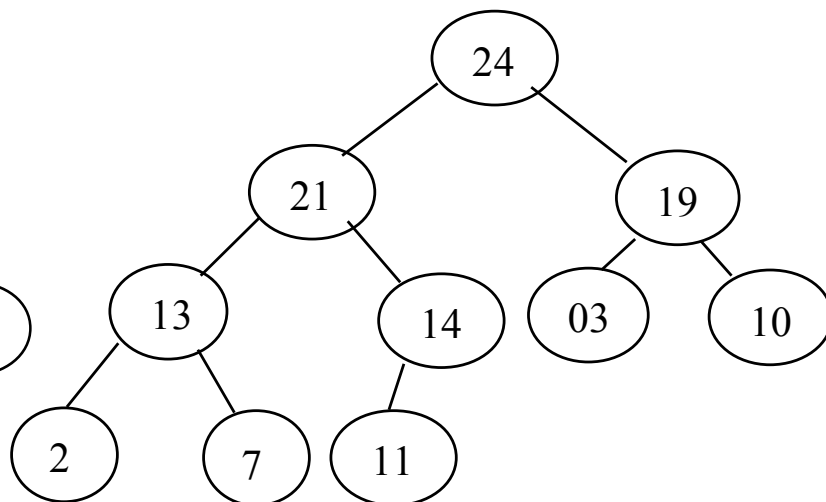
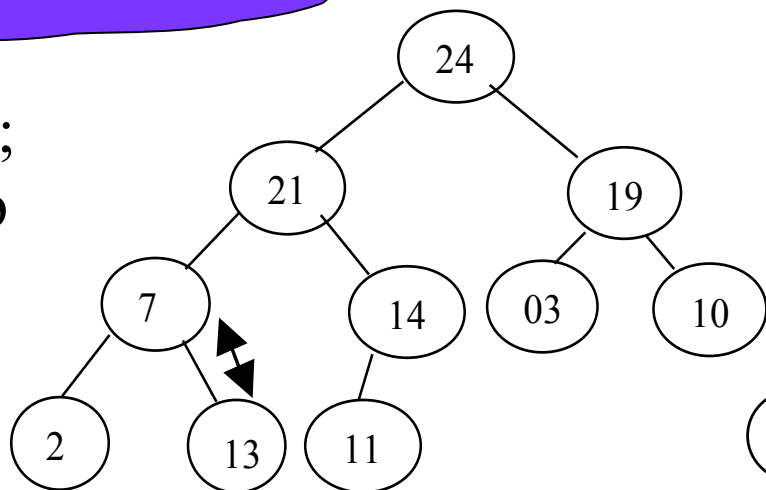
**MAX-HEAPIFY** ( $A, i$ )                      // trickle down process

1.  $l = \text{LEFT\_CHILD}(i)$                       // left heap in relation to node  $i$
2.  $r = \text{RIGHT\_CHILD}(i)$                       // right heap in relation to node  $i$
3. **if**  $l \leq A.\text{heap\_size}$  and  $A[l] > A[i]$
4.     **then**  $\text{largest} = l$                       // parent > child
5.     **else**  $\text{largest} = i$                       // parent  $\leq$  child
6. **if**  $r \leq A.\text{heap\_size}$  and  $A[r] > A[\text{largest}]$
7.     **then**  $\text{largest} = r$                       // lines 3-7 = choose largest of  $A[i], A[l], A[r]$
8. **if**  $\text{largest} \neq i$
9.     **then** exchange  $A[i]$  with  $A[\text{largest}]$
10.     **MAX-HEAPIFY** ( $A, \text{largest}$ ) // continue trickle-down

RST,  
heap



LST;  
heap



# Running time of MAX-HEAPIFY

<u>7</u>	<u>24</u>	19	21	14	03	10	02	13	11
24	<u>7</u>	19	<u>21</u>	14	03	10	02	13	11
24	21	19	<u>07</u>	14	03	10	02	<u>13</u>	11
24	21	19	13	14	03	10	02	07	11

Total running time = steps 1 ... 9 + recursive call

$$T(n) = T(n/2) + \Theta(1) \quad // \text{ recursion + steps}$$

Solving the recurrence, we get  $T(n) = O(\log n)$

→ Can use the Master Theorem

# Running time of MAX-HEAPIFY

Show  $T(n) = \Theta(1) + T(\lfloor n/2 \rfloor)$  is  $O(\log n)$

Assume  $T(x) \leq c \log x$  holds when  $x = \lfloor n/2 \rfloor$

$$\begin{aligned} T(n) &\leq \Theta(1) + c \log \lfloor n/2 \rfloor \\ &\leq c \log n \quad \text{if } c > 0 \end{aligned}$$

Now for the base case when  $n = 2$

$$T(2) = \Theta(1) + T(1) = \Theta(1)$$

**Exercise:** so what is  $n_0$  and  $c$ ?

# BUILD-MAX-HEAP

## BUILD-MAX-HEAP ( $A$ )

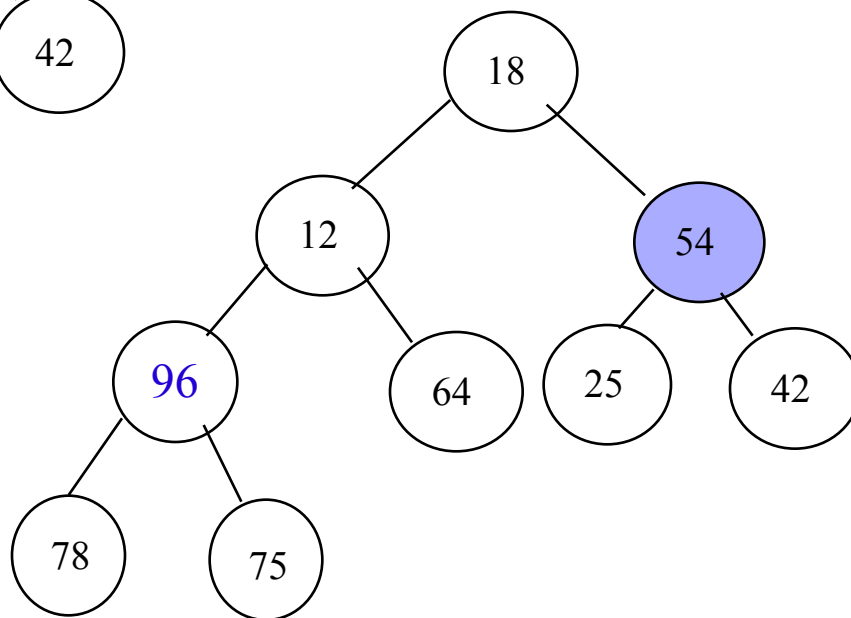
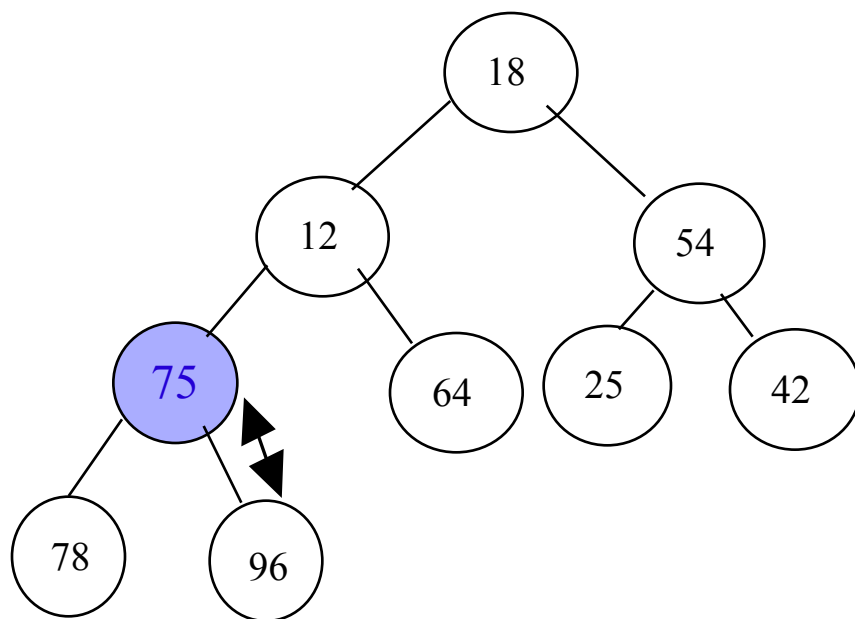
**Input:** An array  $A$  of size  $n = A.length$ ;  $A.heap\_size$

**Output:** A max-heap of size  $n$

1.  $A.heap\_size = A.length$
2. **for**  $i = \lfloor A.length/2 \rfloor$  **downto** 1   // start at last non-leaf, go backwards
3.     **do** MAX-HEAPIFY( $A, i$ )   // put  $i^{th}$  element in correct place in heap

18	12	54	<u>75</u>	64	25	42	78	<u>96</u>
18	12	<u>54</u>	96	64	25	42	78	75
18	<u>12</u>	54	<u>96</u>	64	25	42	78	75
18	96	54	<u>12</u>	64	25	42	<u>78</u>	75
<u>18</u>	<u>96</u>	54	78	64	25	42	12	75
96	<u>18</u>	54	<u>78</u>	64	25	42	12	75
96	78	54	<u>18</u>	64	25	42	12	<u>75</u>
96	78	54	75	64	25	42	12	18

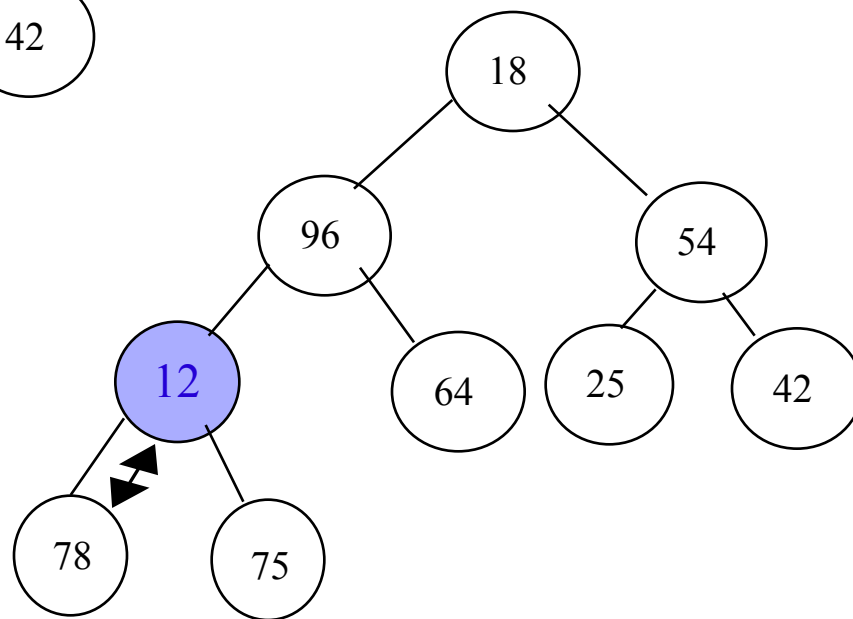
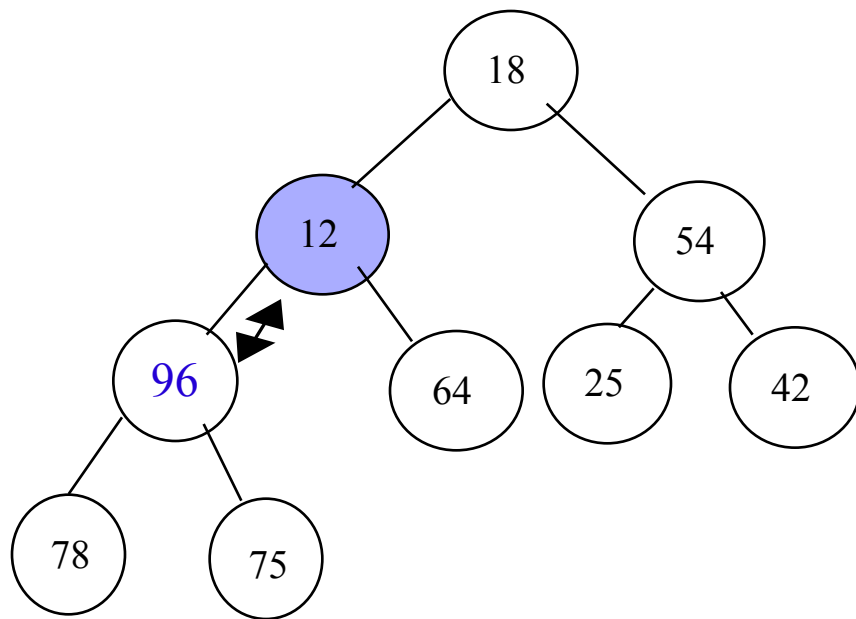
18      12      54      75      64      25      42      78      96



18      12      54      96      64      25      42      78      75

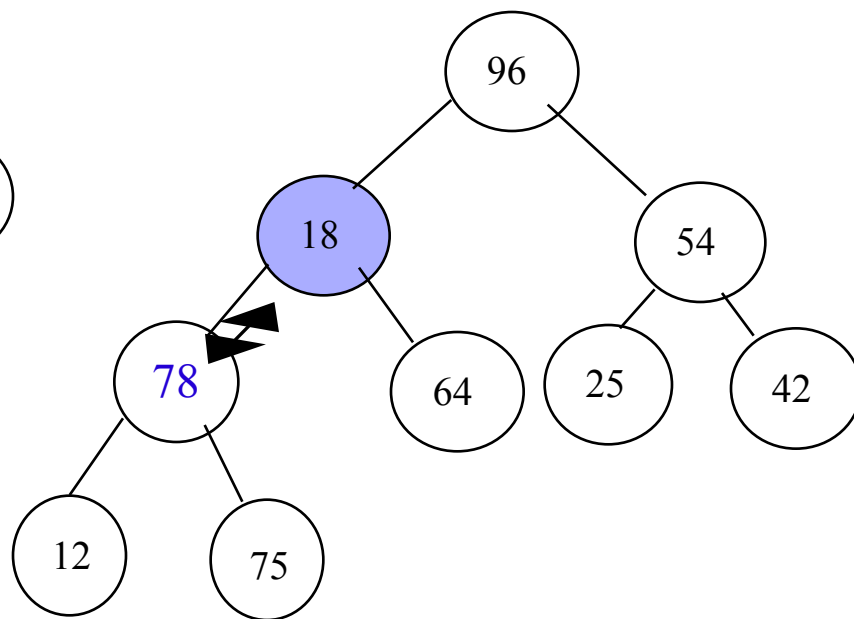
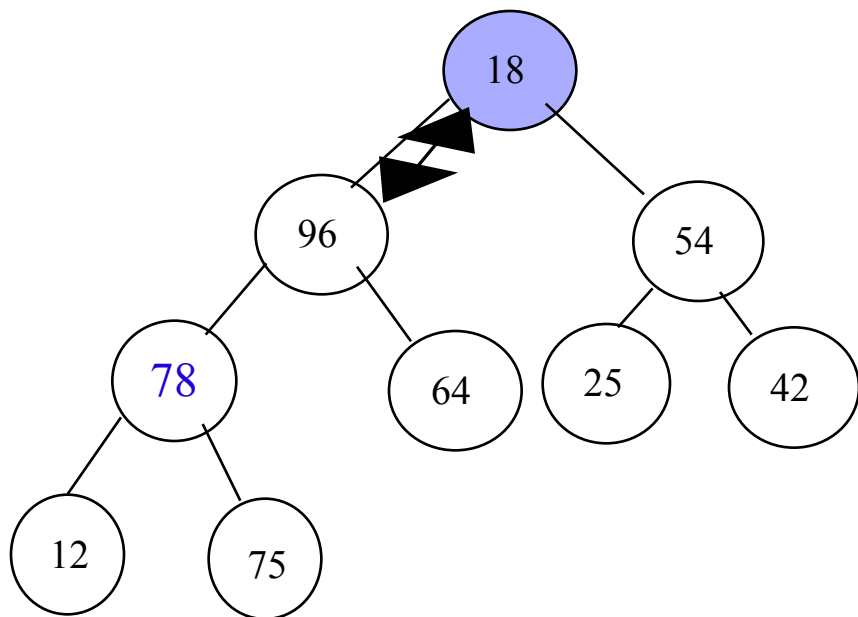


18      12      54      96      64      25      42      78      75



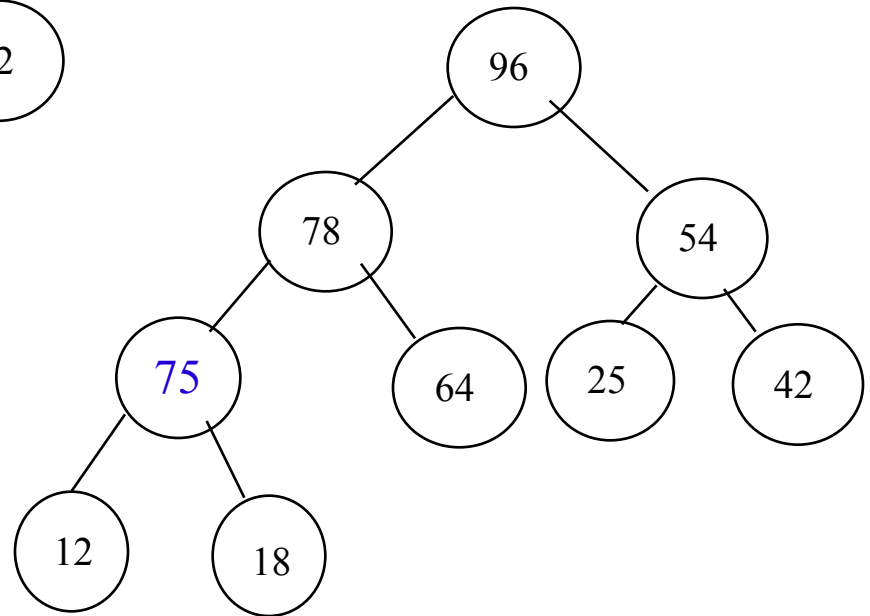
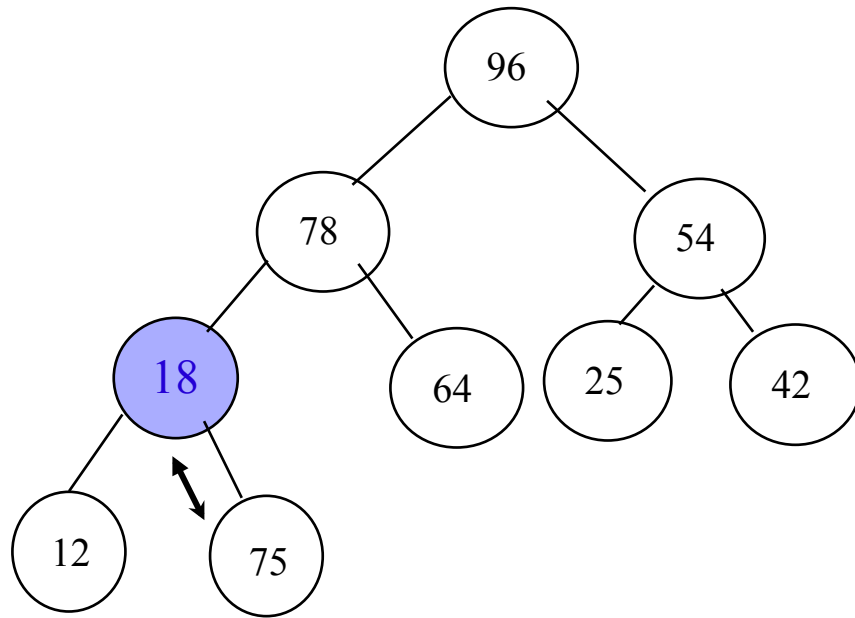
18      96      54      12      64      25      42      78      75

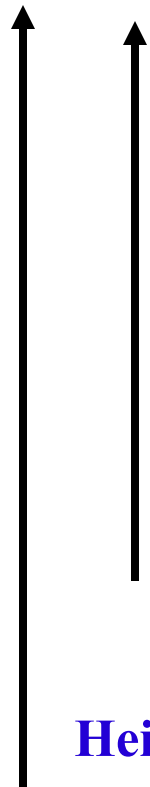
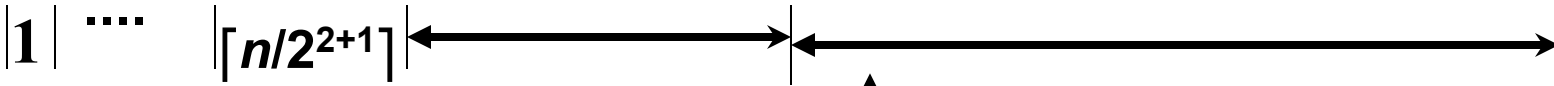
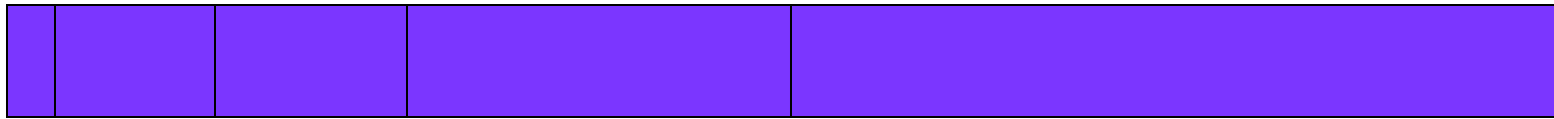
**18      96      54      78      64      25      42      12      75**



**96      18      54      78      64      25      42      12      75**

96      78      54      18      64      25      42      12      75





$\lceil n/2^{1+1} \rceil$

There are  $\lceil n/2 \rceil$  nodes

Height of each node=0, NO comparison

Height of each node = 1, at most 1 comparison

Height of each node = 2, at most 2 comparisons

Height of each node =  $i$ , at most  $i$  comparisons,  $1 \leq i \leq h$

Height of the root node =  $h$ , at most  $h$  comparisons

# Running time (Proof)

- In an  $n$  element heap there are at most  $\lceil n/2^{h+1} \rceil$  nodes of height  $h$
- The time required to heapify a sub-tree whose root is at a height  $h$  is  $O(h)$  (this was proved in the analysis for MAX\_HEAPIFY)
- So the total time taken for BUILD\_MAX\_HEAP is given by,

$$\sum_{h=0}^{\lfloor \log n \rfloor} \left\lceil \frac{n}{2^{h+1}} \right\rceil \cdot h \leq \frac{n}{2} \cdot \sum_{h=0}^{\lfloor \log n \rfloor} \frac{h}{2^h} \leq \frac{n}{2} \cdot \sum_{h=0}^{\infty} \frac{h}{2^h} = \frac{n}{2} \cdot 2 = O(n)$$

Note:  $\sum_{h=0}^{\infty} \frac{h}{2^h} = 2$

Thus the running time of  
BUILD\_MAX\_HEAP is given by  $O(n)$

# HEAPSORT

## Idea:

- Build max-heap on  $A[1 .. n]$ , where  $n = A.length$
- Exchange  $A[n]$  with  $A[1]$ ; Note:  $A[1]$  contains **max** element
- Discard  $A[n]$  from the heap  $\rightarrow$  decrement  $A.heap\_size$
- Make  $A[1 .. n-1]$  into a max-heap; call MAX-HEAPIFY ( $A, 1$ )
- Repeat the process down to a heap of size 2

# HEAPSORT Algorithm

## HEAPSORT( $A$ )

**Input:** Array  $A[1 \dots n]$ ,  $n = A.length$

**Output:** Sorted array  $A[1 \dots n]$

1. BUILD-MAX-HEAP[ $A$ ]
2. **for**  $i = A.length$  downto 2
3.     **do** exchange  $A[1]$  with  $A[i]$
4.          $A.heap\_size = A.heap\_size - 1$
5.         MAX-HEAPIFY( $A, 1$ )

# HEAPSORT-example

<b>Input</b>	1	2	3	4	5	6	7	8	9
	12	16	3	11	10	1	2	5	4

<b>After Build</b>	1	2	3	4	5	6	7	8	9
	16	12	3	11	10	1	2	5	4

<b>After 1<sup>st</sup> swap</b>	1	2	3	4	5	6	7	8	9
	4	12	3	11	10	1	2	5	16

<b>After heapify</b>	1	2	3	4	5	6	7	8	9
	12	11	3	5	10	1	2	4	16



**After  
heapify**

1	2	3	4	5	6	7	8	9
12	11	3	5	10	1	2	4	16

**After 2<sup>nd</sup>  
swap**

1	2	3	4	5	6	7	8	9
4	11	3	5	10	1	2	12	16

**After  
heapify**

1	2	3	4	5	6	7	8	9
11	10	3	5	4	1	2	12	16

**After 3<sup>rd</sup>  
swap**

1	2	3	4	5	6	7	8	9
2	10	3	5	4	1	11	12	16

**After  
heapify**

1	2	3	4	5	6	7	8	9
10	5	3	2	4	1	11	12	16

**After  
heapify**

1	2	3	4	5	6	7	8	9
10	5	3	2	4	1	11	12	16

**After 4<sup>th</sup>  
swap**

1	2	3	4	5	6	7	8	9
1	5	3	2	4	10	11	12	16

**After  
heapify**

1	2	3	4	5	6	7	8	9
5	4	3	2	1	10	11	12	16

**After 5<sup>th</sup>  
swap**

1	2	3	4	5	6	7	8	9
1	4	3	2	5	10	11	12	16

**After  
heapify**

1	2	3	4	5	6	7	8	9
4	2	3	1	5	10	11	12	16

# HEAPSORT-complexity

- **Running Time:**

- Step 1: BUILD\_MAX\_HEAP takes  $O(n)$  time
- Steps 2 to 5: there are  $(n-1)$  calls to MAX\_HEAPIFY which takes  $O(\log n)$  time

Therefore running time takes  $O(n \log n)$

# Priority Queues

A priority queue is:

- An abstract data type which consists of a set of elements.
- Each element of the set has an associated priority or key
- Priority is the value of the element or value of some component of an element

Operations performed on priority queues:

- Inserting an element into the set → `HEAP_INSERT`
- Finding and deleting from the set an element of highest priority → `HEAP_EXTRACT_MAX`
- Merging priority queues

# Example

**S: {(Brown, 20), (Gray, 22), (Green, 21)} → priority based on name**  
**{(Brown, 20), (Green, 21), (Gray, 22)} → priority based on age**

Each element could be a record and the priority could be based on one of the fields of the record

## A Student's record:

<b>Attributes :</b>	<b>Name</b>	<b>Age</b>	<b>Sex</b>	<b>Student No.</b>	<b>Marks</b>
<b>Values :</b>	<b>John Brown</b>	<b>20</b>	<b>M</b>	<b>94XYZ23</b>	<b>75</b>

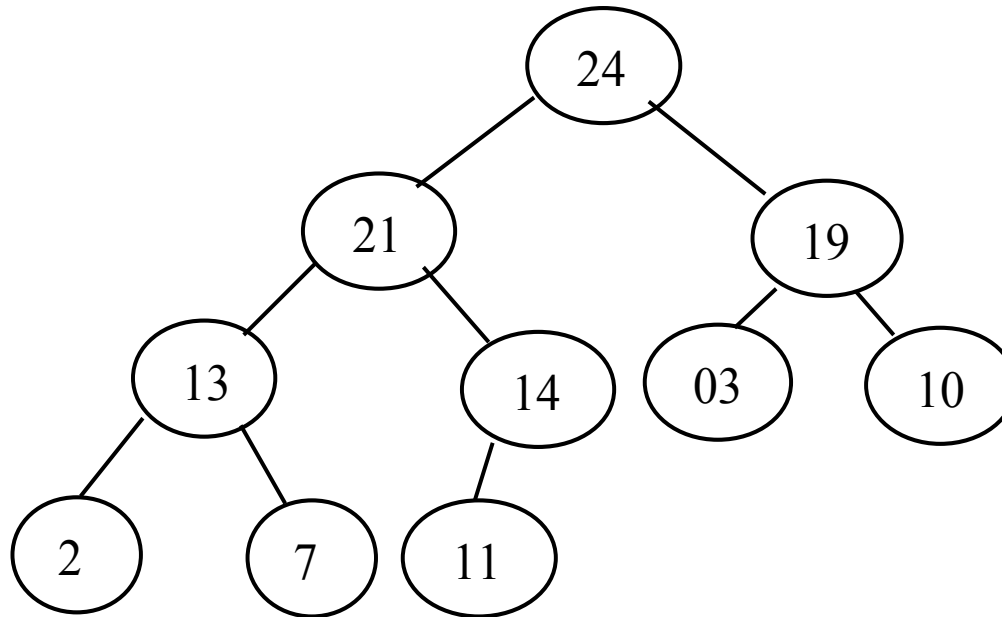
Priority can be based on name, age, student number, or marks

# Priority Queues (cont.)

Priority queues are implemented on partially ordered trees (POTs).

- POTs are labeled binary trees.
- The labels of the nodes are elements with a priority.
- The element stored at a node has at least as large a priority as the elements stored at the children of that node.
- The element with the highest priority is at the root of the tree.

# Example



# HEAP\_EXTRACT\_MAX

**Procedure** HEAP\_EXTRACT\_MAX( $A[1..n]$ )

**Input** : heap( $A$ )

**Output** : The maximum element or root, and heap ( $A[1..n-1]$ )

1.   **if**  $A.heap\_size \geq 1$
2.        $max = A[1];$
3.        $A[1] = A(A.heap\_size);$
4.        $A.heap\_size = A.heap\_size - 1;$
5.       MAX-HEAPIFY( $A, 1$ )
6.       **return** max

Running Time :  $O(\lg n)$  time



# HEAP\_INSERT

## HEAP\_INSERT( $A, key$ )

Input: heap ( $A[1 \dots n]$ ),  $key$  - the new element

Output: heap ( $A[1 \dots n+1]$ ) with  $key$  in the heap

1.  $A.heap\_size = A.heap\_size + 1;$
2.  $i = A.heap\_size;$
3. **while**  $i > 1$  and  $A[PARENT(i)] < key$
4.      $A[i] = A[PARENT(i)];$
5.      $i = PARENT(i);$
6.      $A[i] = key$

## Example?

Running Time:  $O(\lg n)$  time

# Merging two PQs

- What is the cost of merging two PQs that are implemented as heaps
  - Assume  $m$  elements in one and  $n$  in the other

- One possible way:

**BRUTE-FORCE-MERGE** ( $A, n, B, m$ )

for  $i = 1$  to  $n$

    HEAP\_INSERT ( $B, \text{HEAP\_EXTRACT\_MAX}(A)$ )

## Analysis:

$i$	Cost of Extract	Cost of insert
1	$\log n$	$\log m$
2	$\log(n - 1)$	$\log(m+1)$
3	$\log(n - 2)$	$\log(m+2)$
...	...	...
$n$	$O(1)$	$\log(m+n)$

$$\sum_{i=1}^n \log i + \sum_{i=m}^{m+n} \log i$$

# Merging two PQs – Analysis (cont. )

$i$	Cost of Extract	Cost of insert
1	$\log n$	$\log m$
2	$\log(n - 1)$	$\log(m+1)$
3	$\log(n - 2)$	$\log(m+2)$
...	...	...
$n$	$O(1)$	$\log(m+n)$

$$\sum_{i=1}^n \log i + \sum_{i=m}^{m+n} \log i$$

$$= \sum_{i=1}^n \log i + \sum_{i=1}^{m+n} \log i - \sum_{i=1}^m \log i$$

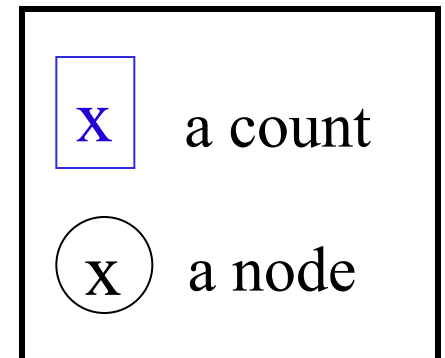
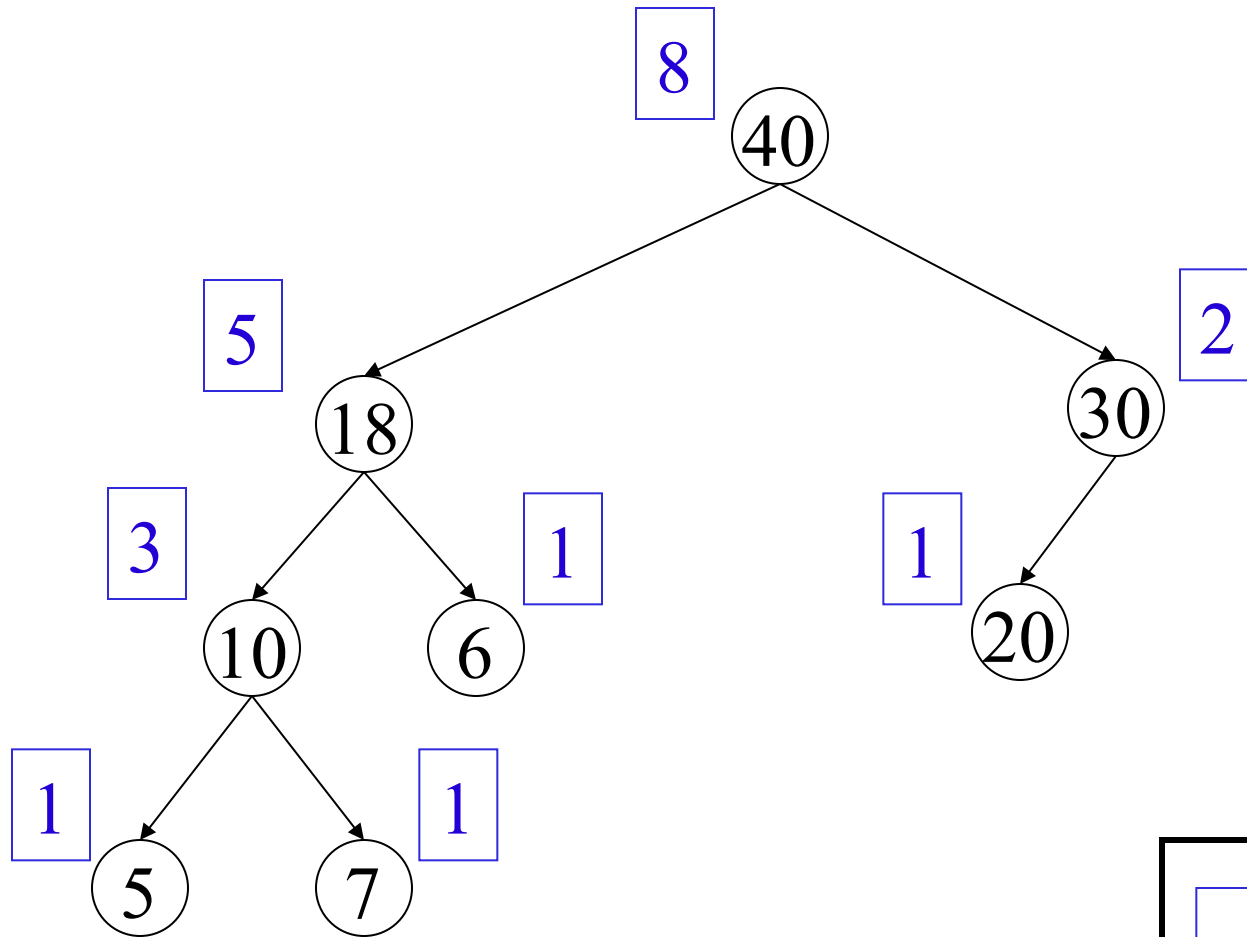
$$= O(n \log n) + O((m+n) \log(m+n)) - O(m \log m)$$

$$= O((m+n) \log(m+n))$$

**Can we improve this?**

# Leftist tree

- Has heap condition:
  - all children less than parent (max heap)
  - all children greater than parent (min heap)
- *count* of nodes in left tree  $\geq$  *count* in right
  - *count* is  $1 + \text{sum of child counts}$



# How does that help?

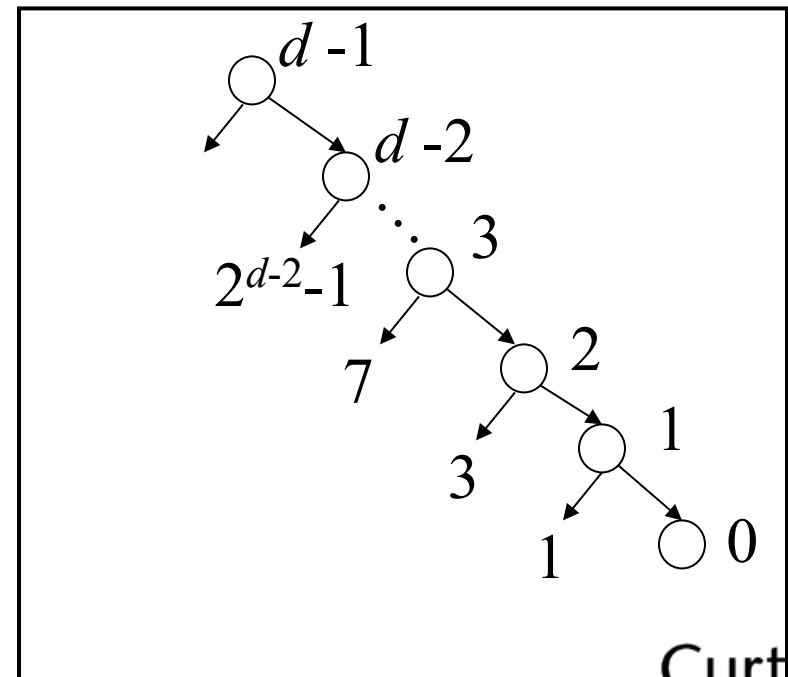
- Length of rightmost path from root is at most  $\lg(n+1) \rightarrow$  when the leftist tree is a complete binary tree with  $n$  nodes.
- **Proof by contradiction**
  - Assume there is a depth  $\lg(n+1) + 1$  right node
  - To keep the leftist tree property, we have to add in the min number of left nodes that exist
  - As a result there are more than  $n$  nodes in total, and therefore original assumption wrong

# Alternative proof

- Assume there is a right path of length  $d$
- Label nodes on the path  $d - 1$  (the root) down to 0 (the rightmost node)
- Each left tree must have at least  $2^i - 1$  left nodes; for  $i = 0, 1, 2, \dots, d - 1$ .

$$\sum_{i=0}^{d-1} (2^i - 1) \leq n - d$$

- Use *Geometric Series* to show  $d \leq \lg(n + 1)$



# So ...

- We can join two leftist trees by only traversing right path
  - Only do  $O(1)$  work for each node
- If joining two trees of  $n$  and  $m$  items then visit at most  $\lg(n+1) + \lg(m+1)$  nodes
  - So we can join them in  $O(\lg mn)$  time
  - If  $n \geq m$ , merge costing is  $O(\lg n)$
- However, a leftist tree needs pointers while a binary heap does not need explicit pointers.



# Note

$$\lg m \leq c \lg (m + n) \quad \forall m > m_0 \text{ and } n > n_0$$

$$\lg n \leq c' \lg (m + n) \quad \forall m > m_1 \text{ and } n > n_1 \quad +$$

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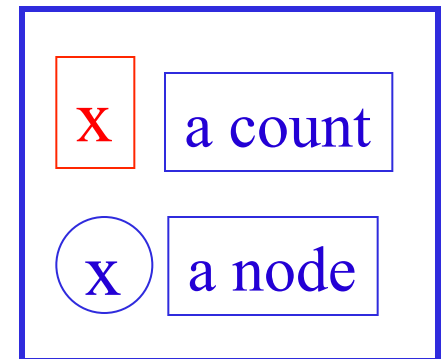
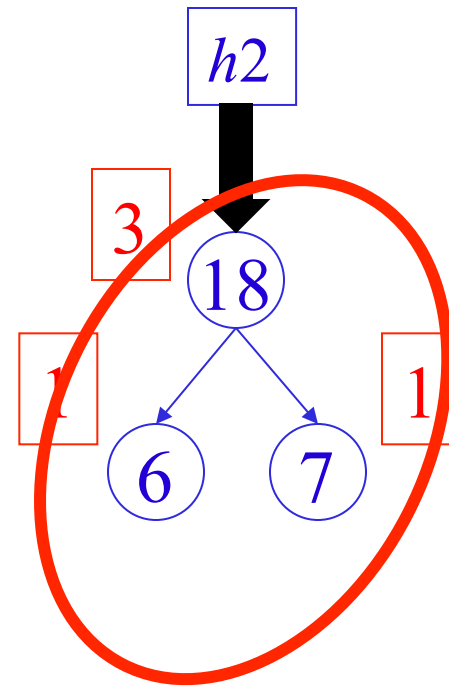
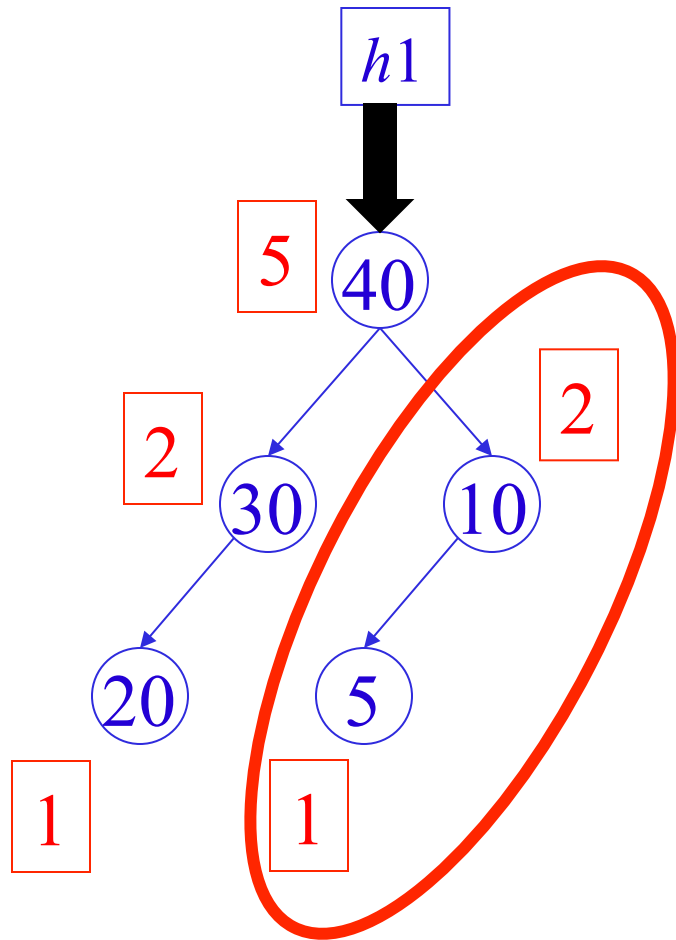
$$\lg mn = \lg m + \lg n \leq (c + c') \lg(m + n)$$

$$\forall m > \max(m_0, m_1) \text{ and } n > \max(n_0, n_1)$$

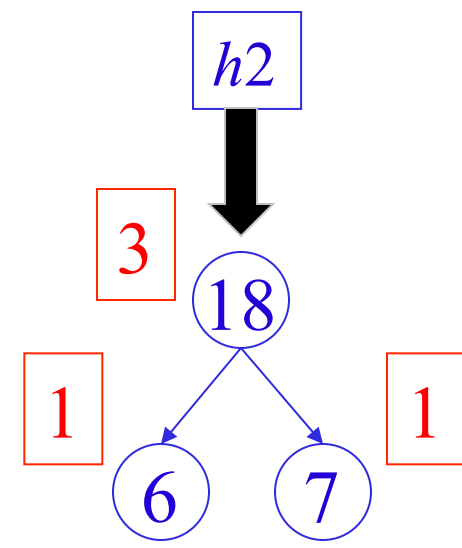
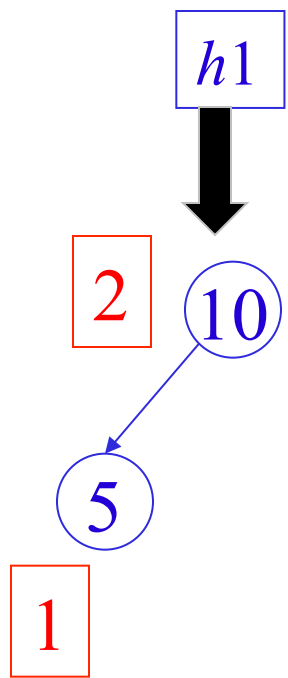
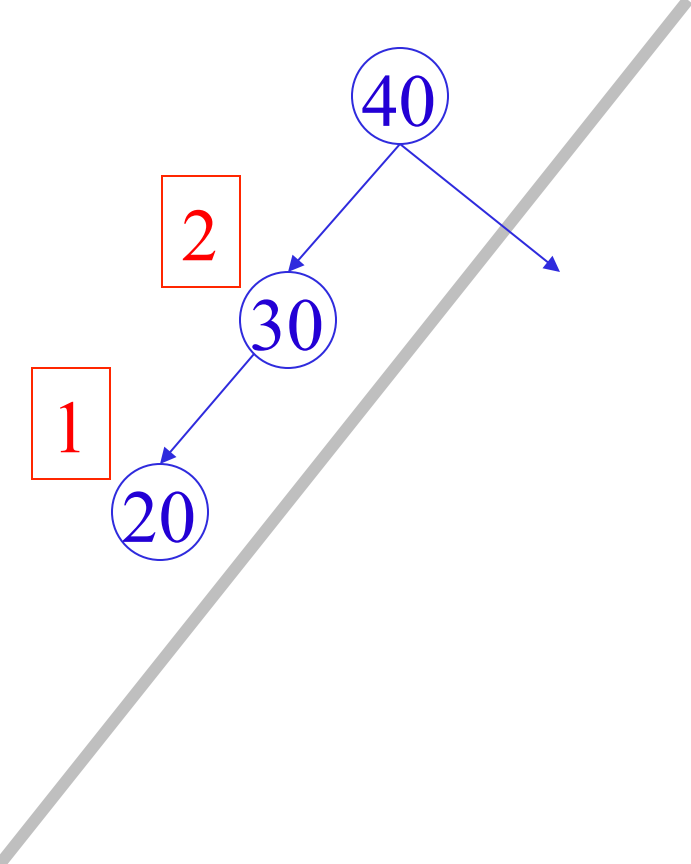
$$\Rightarrow O(\lg mn) \text{ is } O(\lg(m + n))$$

# MELD Algorithm

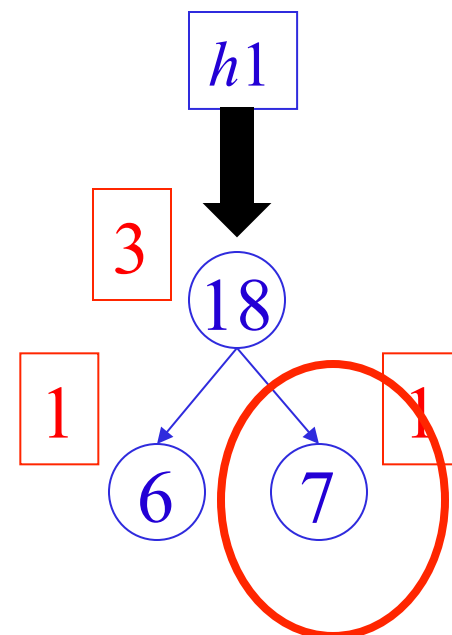
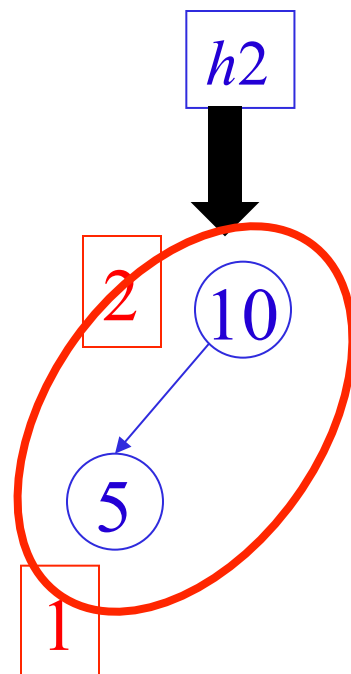
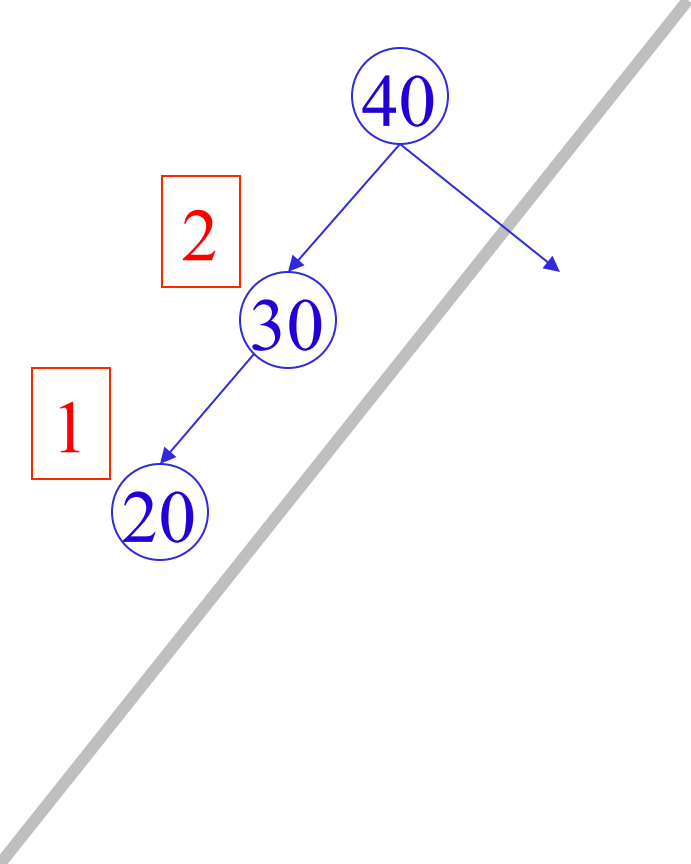
1. **MELD** ( $h1, h2$ )
2.     **if**  $h1$  is empty **return**  $h2$
3.     **if**  $h2$  is empty **return**  $h1$
4.     **if** ( $h1.\text{root} < h2.\text{root}$ )
5.          $\text{swap}(h1, h2)$
6.      $h1.\text{right} = \text{MELD}(h1.\text{right}, h2)$
7.     **if** ( $h1.\text{left}.\text{count} < h1.\text{right}.\text{count}$ )
8.          $\text{swap}(h1.\text{left}, h1.\text{right})$
9.     update  $h1.\text{count}$



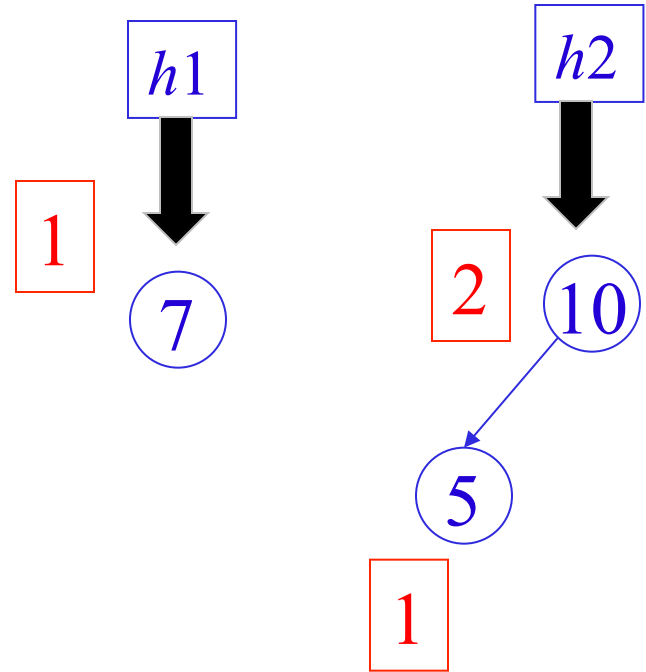
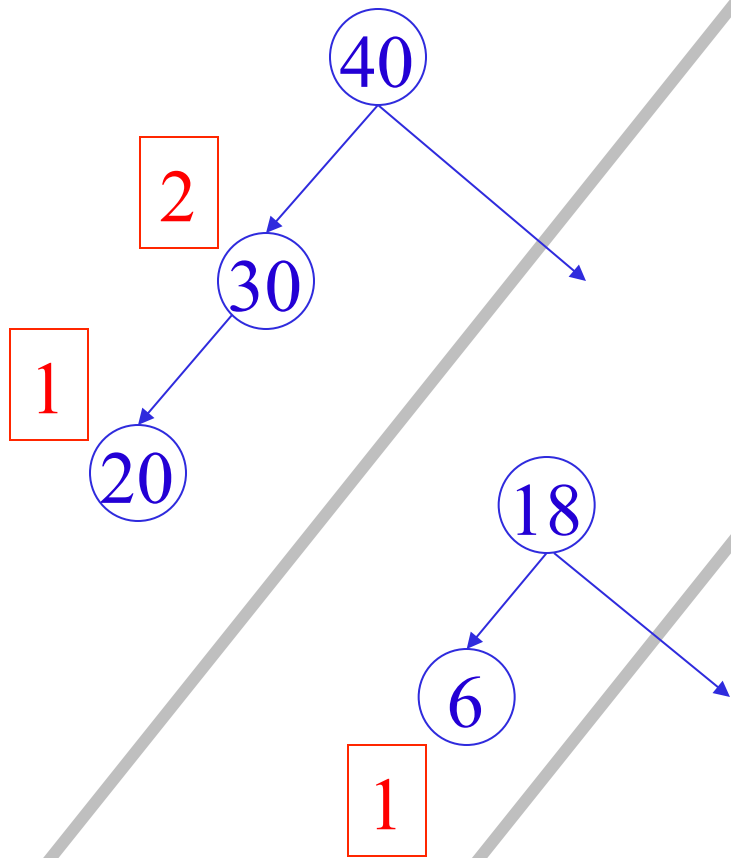
$h1.root > h2.root$ , meld  $h1.right$  and  $h2$



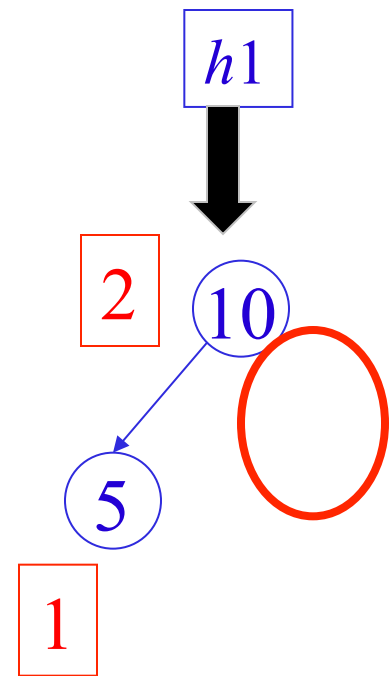
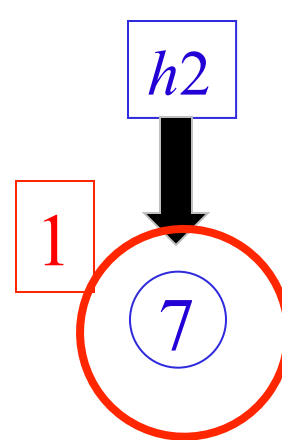
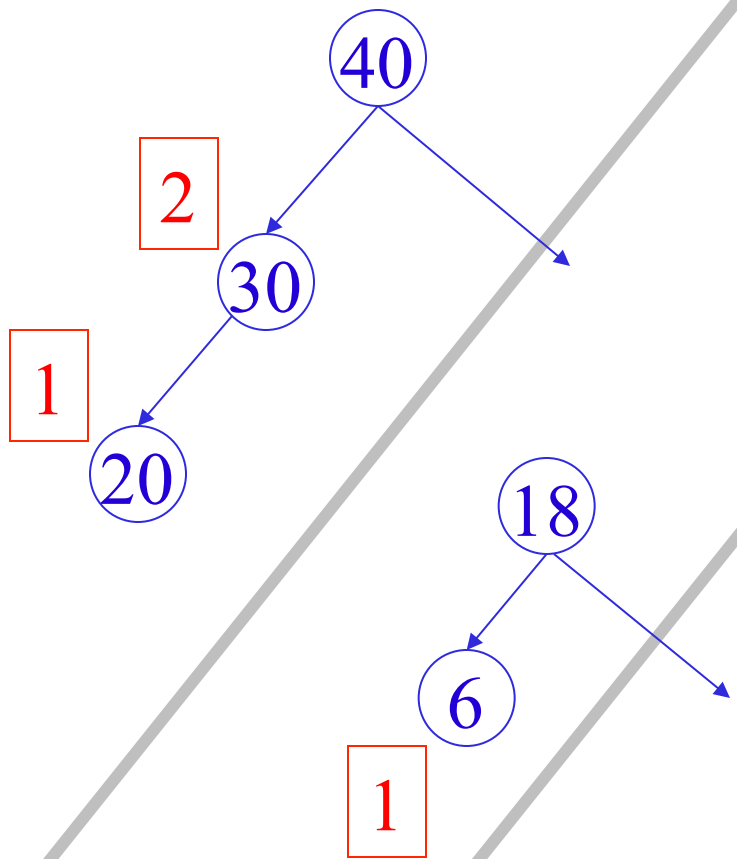
$h1.root < h2.root$ , swap  $h1$  and  $h2$



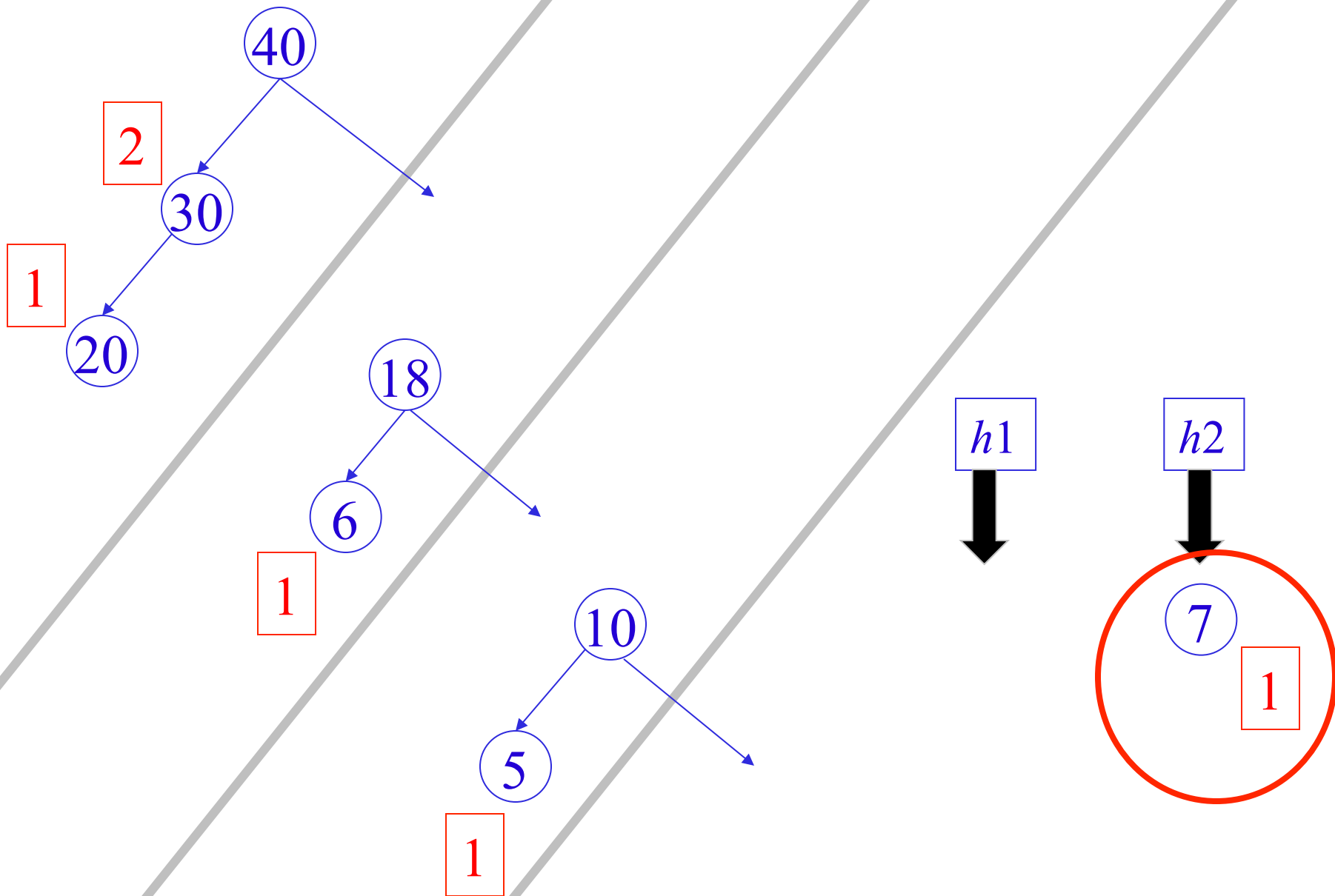
$h1.root > h2.root$ , meld  $h1.right$  and  $h2$



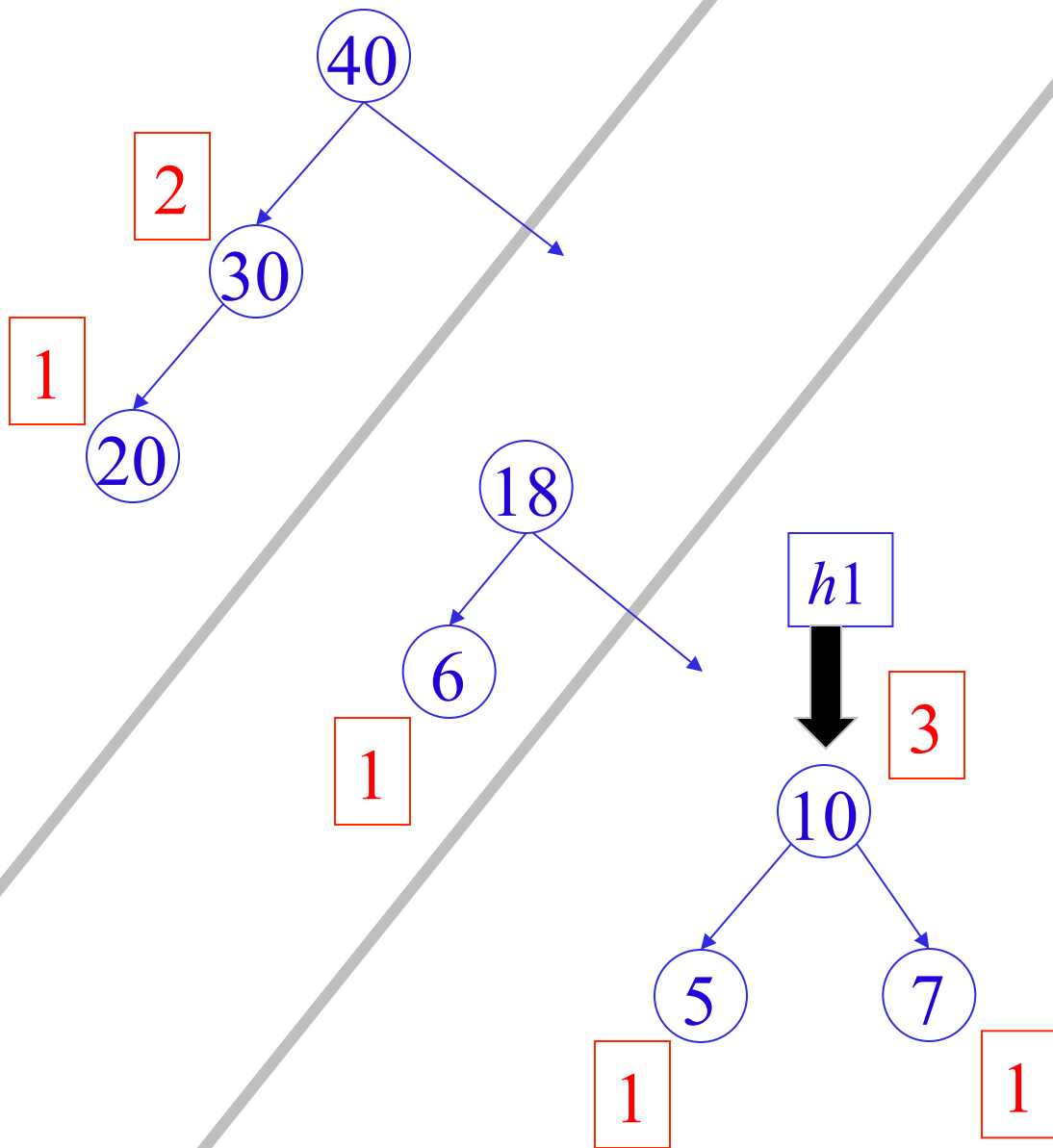
$h1.root < h2.root$ , swap  $h1$  &  $h2$



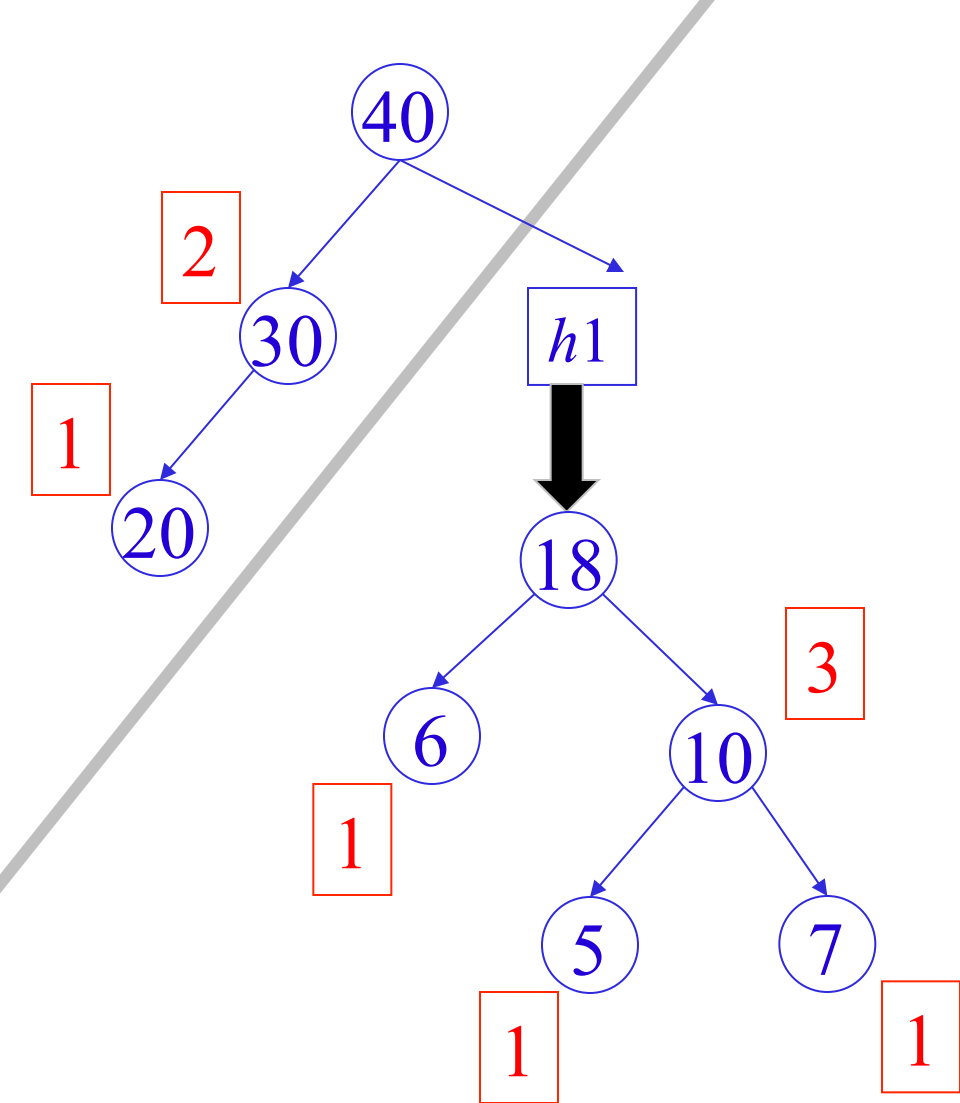
$h1.root > h2.root$ , meld  $h1.right$  and  $h2$



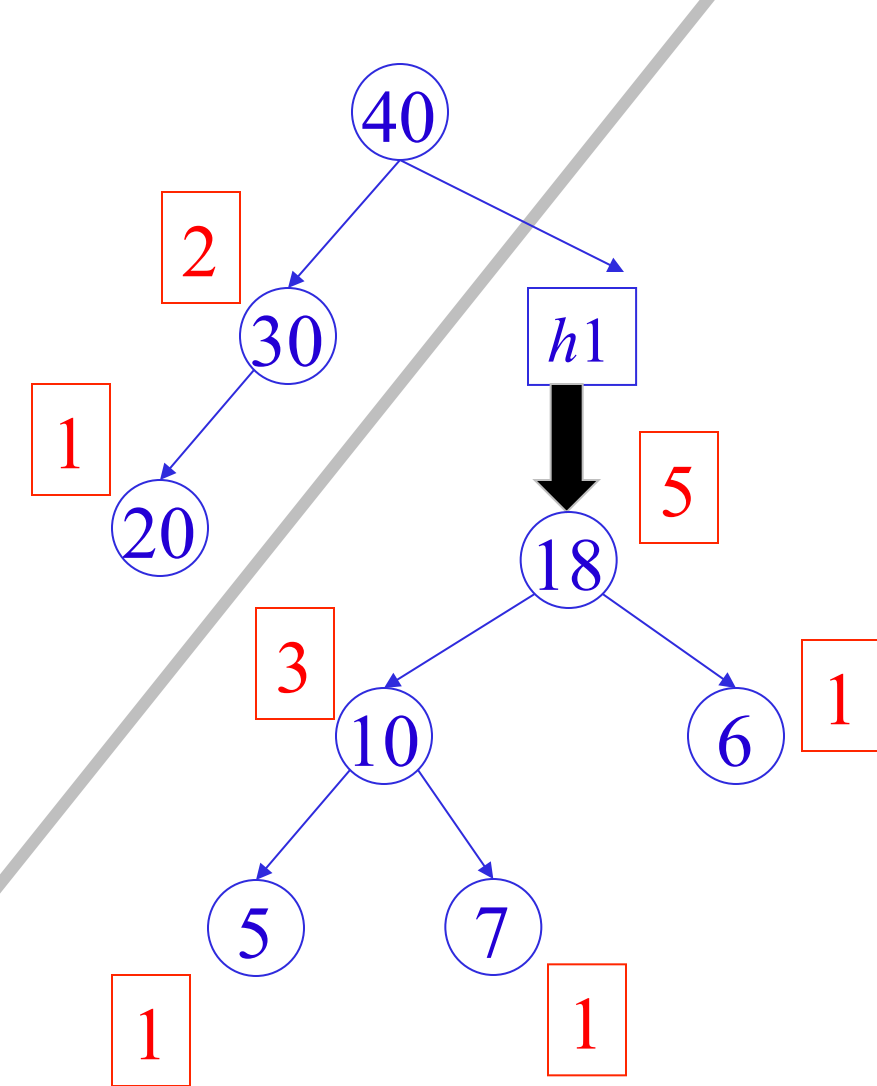




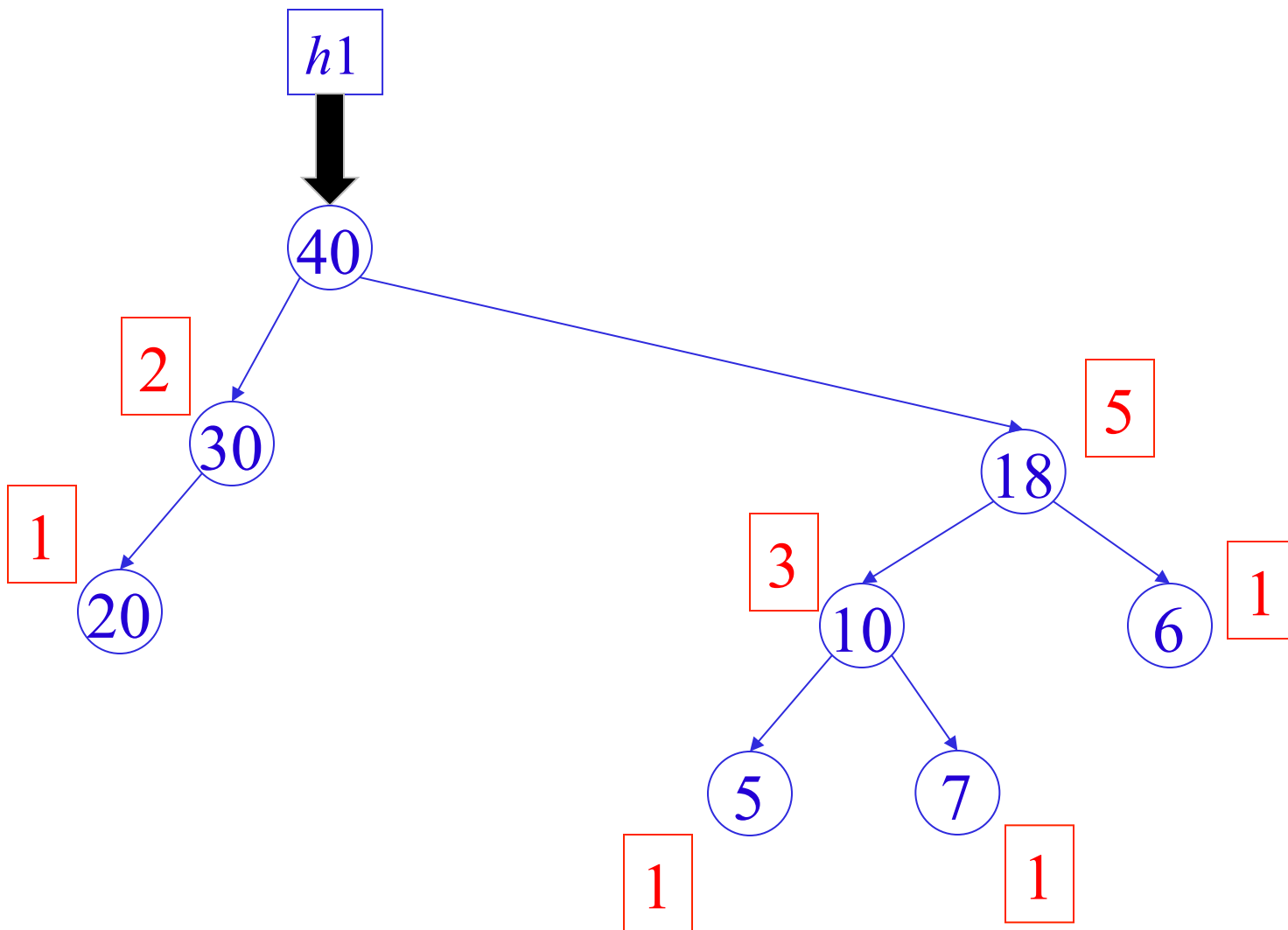
left  $\geq$  right, update  $h1$  count

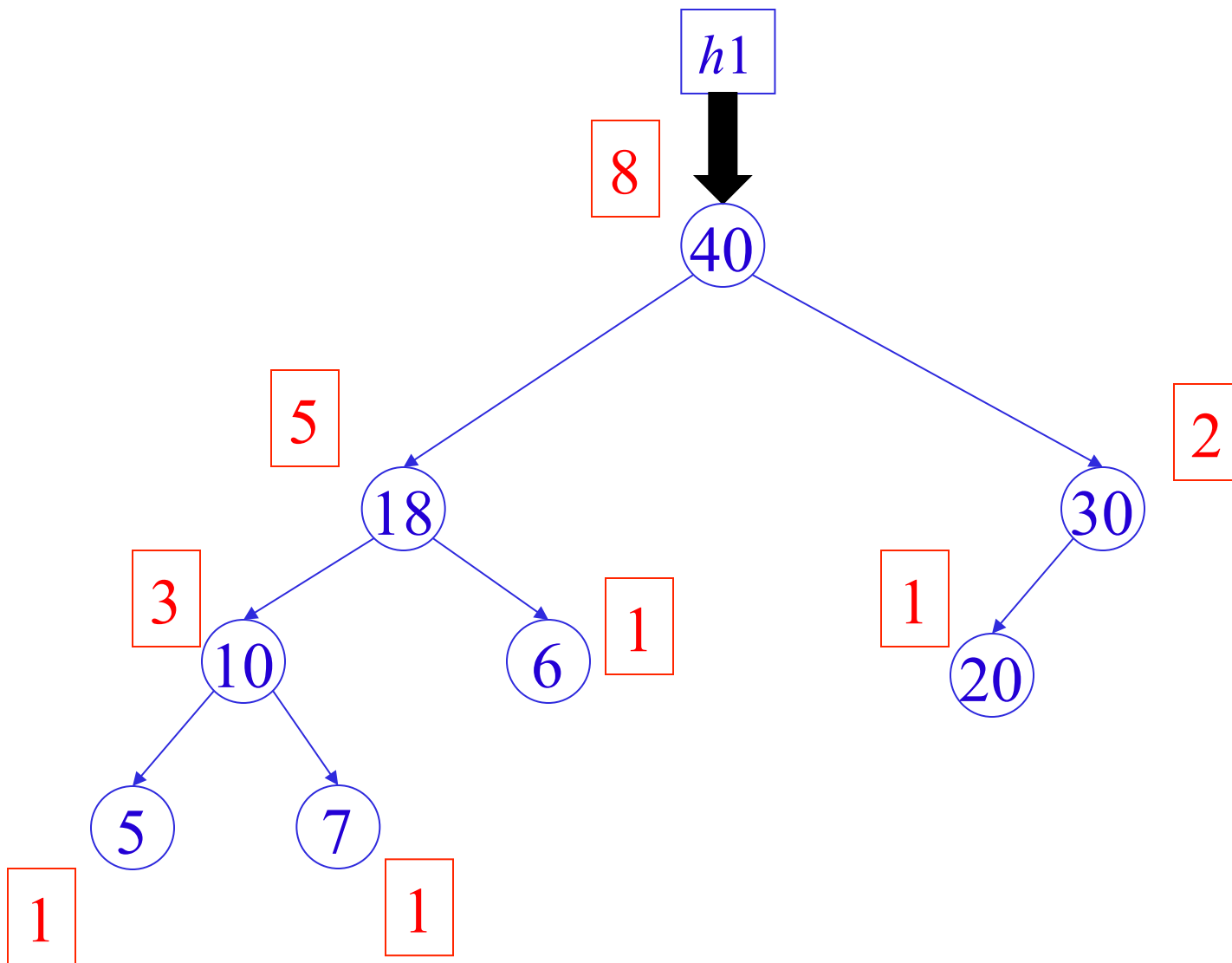


left < right, swap



left  $\geq$  right, update  $h1$  count





left  $\geq$  right, update  $h1$  count

# MELD -complexity

1.	<b>MELD(<math>h1, h2</math>)</b>	$O(1)$
2.	<b>if</b> $h1$ is empty <b>return</b> $h2$	$O(1)$
3.	<b>if</b> $h2$ is empty <b>return</b> $h1$	$O(1)$
4.	<b>if</b> ( $h1.root < h2.root$ )	$O(1)$
5.	swap( $h1, h2$ )	$O(1)$
6.	$h1.right = \mathbf{MELD}(h1.right, h2)$	$O(1)$
7.	<b>if</b> ( $h1.left.count < h1.right.count$ )	$O(1)$
8.	swap( $h1.left, h1.right$ )	$O(1)$
9.	update $h1.count$	$O(1)$

Called  $\log m + \log n$  times =  $O(\log mn) = O(\log(m+n))$

# Other algorithms

- **INSERT**( $A, k$ ) = MELD( $A$ , new node containing  $k$ )
- **EXTRACT-MAX**( $A$ ) = MELD( $A$ .left,  $A$ .right)
- **BUILD-LEFT-TREE**( $B[1..n], A$ )
  - MELD( $B[1], B[2]$ ) ... MELD( $B[n-1], B[n]$ )
  - then MELD  $n/4$  trees of 4 nodes
  - then MELD  $n/8$  trees of 8 nodes
  - *etc.*