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### **WORKSHOP 11b**

This workshop will build on material from Lecture 12: Plane Transformations & Least Squares.

During this workshop, students will work towards the following learning outcomes:

- determine least squares solutions to inconsistent systems of linear equations.
- calculate a least squares line for given data points.
- determine a best fit quadratic approximation for given data points.

## Inconsistent systems

1. Use the pseudoinverse  $pinv(A) = (A^T A)^{-1} A^T$  to find the least squares solution for the following inconsistent systems of linear equations.

2. For the following inconsistent linear systems, solve the normal system of equations  $A^T A \mathbf{x} = A^T \mathbf{b}$  using Gaussian Elimination to determine the least squares solution.

3. The following system of linear equations is consistent and has a unique solution.

$$x_1 + x_2 + x_3 = 6$$
  

$$x_1 - x_2 + x_3 = 2$$
  

$$x_1 + 2x_2 - x_3 = 2$$

- (i) Solve the system Ax = b using Gaussian Elimination to find this unique solution x.
- (ii) Determine the least square solution  $\hat{x}$  to the normal system of equations by using Gaussian Elimination.
- (iii) What do you notice when you compare the unique solution  $\boldsymbol{x}$  from (i) to the least squares solution  $\hat{\boldsymbol{x}}$  from (ii).

## Least squares lines

- 4. For each of the following given sets of data points, find the least squares line  $y = a_0 + a_1 x$  by (a) using the pseudoinverse, and (b) solving the normal system using Gaussian Elimination.
  - (i) (1,1), (2,5), (3,9)
  - (ii) (-3,8), (-1,5), (1,3), (3,0)
  - (iii) (-2,3), (-1,1), (0,0), (1,-2), (2,-4)

# Quadratic approximations

5. Find a quadratic least squares approximating polynomial  $y = a_0 + a_1x + a_2x^2$  for the data points (-3,1), (-2,0), (0,1), (2,3), (3,5).