

# gotta catch em all

sachit and tanays ODT summative 1



# why pokemon?

We wanted to make paper Pokémon models and assign different values to them that could be read using a sensor (like capacitive touch). Since we both love Pokémon, it was an easy theme to go with plus, the 30th anniversary of Pokémon is in just two days.

*Sachits favourite pokemon*



*Tanays favourite pokemon*





# how it works?



1. IR sensor reads a  
Pokemon near it



2. Signals to the neopixel that  
a Pokemon is detected  
causing it to flash red and  
display text

3. Pressing a button then starts  
the scanning process where  
the neopixel lights up green in  
sequencce

4. Using capacitive touch,  
each Pokemon is  
assigned a material with  
different ranges.

5. 1 of 3 value ranges is  
sensed and based on the  
range, a defined colour is  
displayed on the neopixel



# technical feasibility

All the elements we used here are things we've worked with before, so we already knew how to handle them. We explored capacitive touch a bit more to understand the different ranges and how the components interact.





# how it works ? Circuit 2

IR sensor detects when a Pokémon is physically near the device.

When the Pokédex is ON, the IR sensor lights all NeoPixels red and prints "Pokemon found!" whenever something comes close.

- Bulbasaur range → first half of the ring glows green, second half purple.
- Charmander range → whole ring glows orange.
- Squirtle range → whole ring glows blue.

A button turns the Pokédex ON and OFF, when OFF, all NeoPixels stay dark and no sensing happens.

capacitive touch pad reads different value ranges based on the material each Pokémon is associated with  
(bulbasaur= eraser  
charmander= aluminium foil  
squirtle= human touch)



# how it works ?

## Circuit 2

Once all three Pokémon have been detected at least once, the `game_khatam` state turns on.

In the win state, the NeoPixels celebrate by cycling through red, green, and blue across the whole ring and printing "Caught em all!"



# technical feasibility

We built on the sensors and NeoPixel patterns we've used before, so those were familiar. The capacitive touch ranges took some experimentation to get the right values for each Pokémon material. Adding the counting system was trickier than expected, so we simplified by using two dedicated buttons (power toggle + reset) instead of complex long-press timing, making the code much cleaner and more reliable.

capacitive





# pain points

Ooooooooooh, let me tell you , capacitance is a mess! There's no object that has consistent capacitance except for the three we have.

We wanted to add a stepper motor to make a stand for the Pokémon models, but it didn't work out, so we couldn't include that part





# Thank you



# Bye now