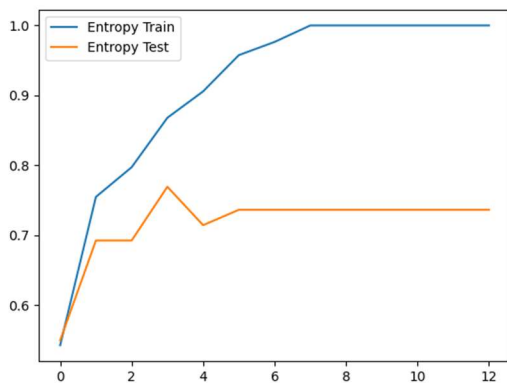
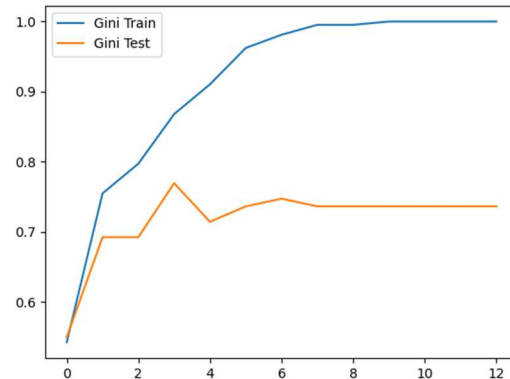
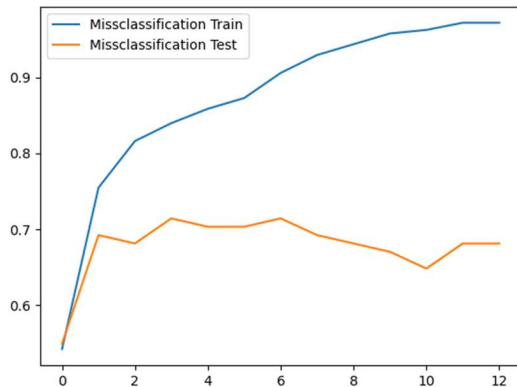


Exercise 1

a)



x-axis: max depth, y-axis: accuracy

In general, all the loss functions increase in test accuracy as they increase in training accuracy up until a point where further increases in training accuracy is correlated with decreased testing accuracy. As max depth increases, training accuracy increases and test accuracy also increases to a certain point, then decreases. The Gini and Entropy loss functions seem to perform similarly in test and training accuracy.

b)

Without Random Forests

Median: 0.8351648351648352, Minimum: 0.8241758241758241, Maximum: 0.8351648351648352

By using Bagging without Random Forests, the accuracy is greater than that of the non-ensemble methods, even at worst.

With Random Forests

Median: 0.7692307692307693, Minimum: 0.7692307692307693, Maximum:
0.8131868131868132

By using Bagging with Random Forests, the accuracy can potentially be better than that of the non-ensemble methods and on average and at worst perform about as well as the non-ensemble methods.

Comparing the use of random forest, it seems that not using random forests provides a better accuracy across the board.

Exercise 2

$$b/ E[e^{-yH} | X=x]$$

$$= \sum_{y \in \{-1, 1\}} e^{-yH} p(y|X=x)$$

$$= e^{-H} p(y=1|X=x) + e^H p(y=-1|X=x)$$

$$\Rightarrow \frac{\partial}{\partial H} E[e^{-yH} | X=x] = \frac{\partial}{\partial H} (e^{-H} p(y=1|X=x) + e^H p(y=-1|X=x))$$

$$\text{set to 0} \rightarrow 0 = -e^{-H} p(y=1|X=x) + e^H p(y=-1|X=x)$$

$$e^{-H} p(y=1|X=x) = e^H p(y=-1|X=x)$$

$$e^{2H} = \frac{p(y=1|X=x)}{p(y=-1|X=x)}$$

$$2H = \log \frac{p(y=1|X=x)}{p(y=-1|X=x)}$$

$$H = \frac{1}{2} \log \frac{p(y=1|X=x)}{p(y=-1|X=x)}$$

Thus the minimizer of the exponential loss is the log odds ratio.

✓ let $\bar{E}_t = E_t(\bar{h}_t)$
 since $E_t > 1/2 \Rightarrow \bar{E}_t < \frac{1}{2} \Leftarrow \bar{E}_t = 1 - E_t$

$$\bar{B}_t = \frac{1}{2} \log \frac{1 - \bar{E}_t}{\bar{E}_t}$$

$$= \frac{1}{2} \log \frac{1 - (1 - E_t)}{1 - E_t}$$

$$= \frac{1}{2} \log \frac{E_t}{1 - E_t}$$

$$= -\frac{1}{2} \log \frac{1 - E_t}{E_t}$$

$$= -\bar{B}_t$$

$$\bar{E}_t = E_t(\bar{h}_t) = E(-\bar{h}_t) = \sum_{i=1}^n P_i^t \mathbb{I}[-h_t(x_i) \neq y_i]$$

consider the update rule

$$\exp(-y_i \bar{B}_t \bar{h}_t(x_i)) = \exp(-y_i (-B_t) (-h(x_i))) = \exp(y_i B_t h(x_i))$$

\therefore we have the same update for w in (4)

$$d/ E_t \exp[-y_i B h_t(x)] \quad (x, y) \sim p^t$$

$$= \sum_{i=1}^n \exp[-y_i B h_t(x)] p^t(y_i)$$

$$= \sum_{i: h_t(x_i) = y_i}^n \exp[-y_i B h_t(x)] p^t(y_i) + \sum_{i: h_t(x_i) \neq y_i}^n \exp[-y_i B h_t(x)] p^t(y_i)$$

$$= \sum_{i: h_t(x_i) = y_i}^n e^{-B} p_i^t + \sum_{i: h_t(x_i) \neq y_i}^n e^B p_i^t$$

Partial derivative wrt β and set to 0

$$0 = \frac{\partial}{\partial \beta} \left(\sum_{i: h_t(x_i) = y_i}^n e^{-B} p_i^t + \sum_{i: h_t(x_i) \neq y_i}^n e^B p_i^t \right)$$

$$0 = \sum_{i: h_t(x_i) = y_i}^n -e^{-B} p_i^t + \sum_{i: h_t(x_i) \neq y_i}^n e^B p_i^t \Rightarrow \sum_{i: h_t(x_i) = y_i}^n e^{-B} p_i^t = \sum_{i: h_t(x_i) \neq y_i}^n e^B p_i^t$$

$$\log \left(\sum_{i: h_t(x_i) = y_i}^n e^{-B} p_i^t \right) = \log \left(\sum_{i: h_t(x_i) \neq y_i}^n e^B p_i^t \right)$$

$$-B + \log \left(\sum_{i: h_t(x_i) = y_i}^n p_i^t \right) = B + \log \left(\sum_{i: h_t(x_i) \neq y_i}^n p_i^t \right)$$

ϵ_t by eqn (2)

$$-B + \log(1 - \epsilon_t) = B + \log(\epsilon_t)$$

$$2B = \log(1 - \epsilon_t) - \log(\epsilon_t)$$

$$B = \frac{1}{2} \log \frac{1 - \epsilon_t}{\epsilon_t}$$

\therefore the optimal β in (12) is given in (3) as desired

$$e/ \frac{\partial}{\partial \beta} E_t \exp[-y \beta h_t(x_i)] = \exp(-y \beta h_t(x_i)) (-y h_t(x_i)) p_i^t$$

$$\text{by eqn (1)} \quad = \exp(-y \beta h_t(x_i)) (-y h_t(x_i)) \frac{w_i^t}{\sum_{j=1}^n w_j^t}$$

$$\text{set to 0} \Rightarrow 0 = \frac{1}{\sum_{j=1}^n w_j^t} \sum_{i=1}^n w_i^{t+1} (-y h_t(x_i))$$

$$0 = \sum_{i=1}^n w_i^{t+1} (-y h_t(x_i))$$

$$\text{divide by } \sum_{j=1}^n w_j^{t+1} \Rightarrow 0 = \sum_{i=1}^n p_i^{t+1} (y h_t(x_i))$$

$$0 = \sum_{i: y_i \neq h_t(x_i)} p_i^{t+1} + \sum_{i: y_i = h_t(x_i)} p_i^{t+1}$$

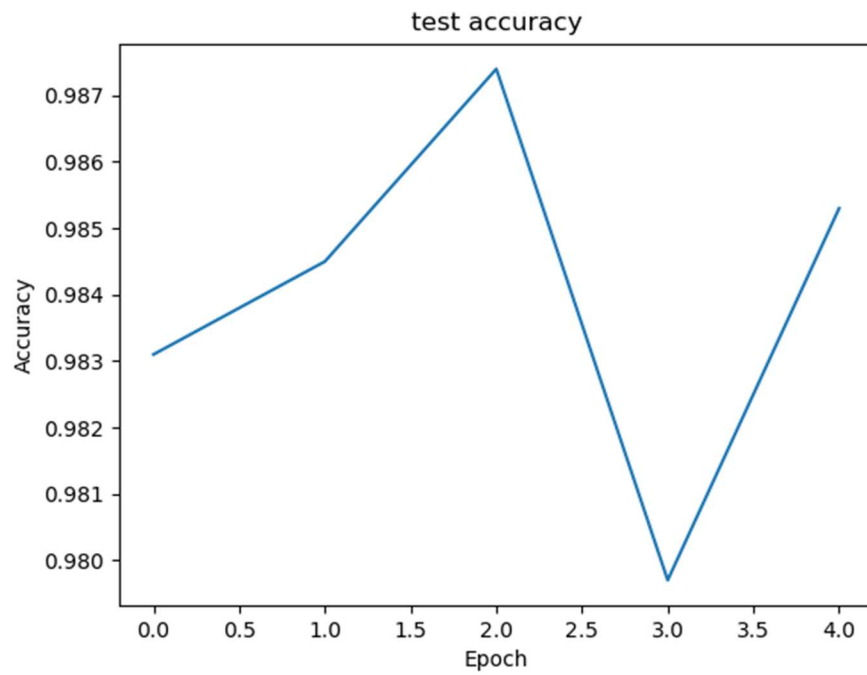
$$0 = -\epsilon_{t+1} + 1 - \epsilon_{t+1}$$

$$\epsilon_{t+1} = \frac{1}{2}$$

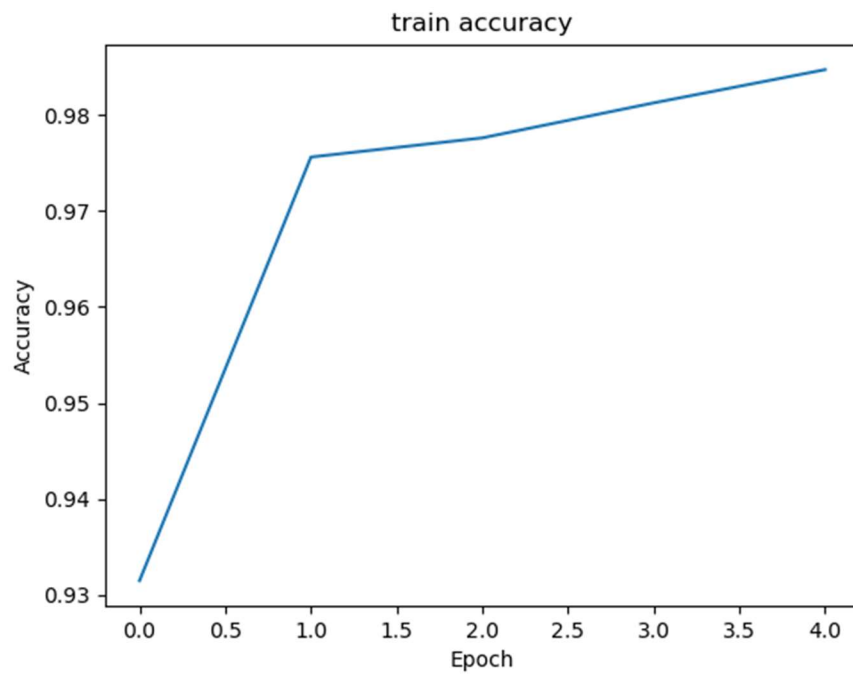
Exercise 3

b) 5 epochs

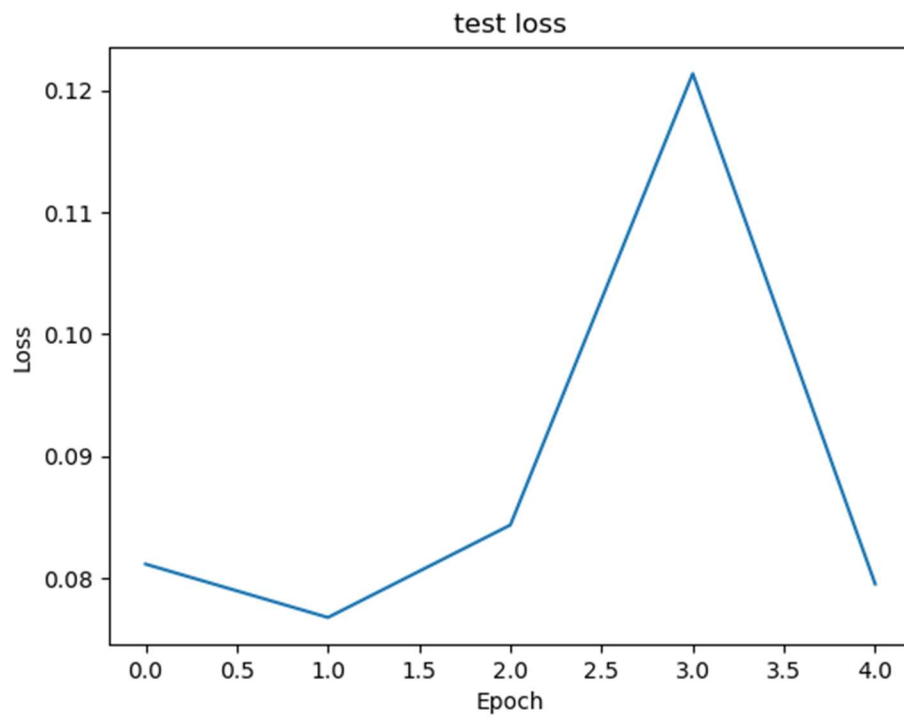
i.



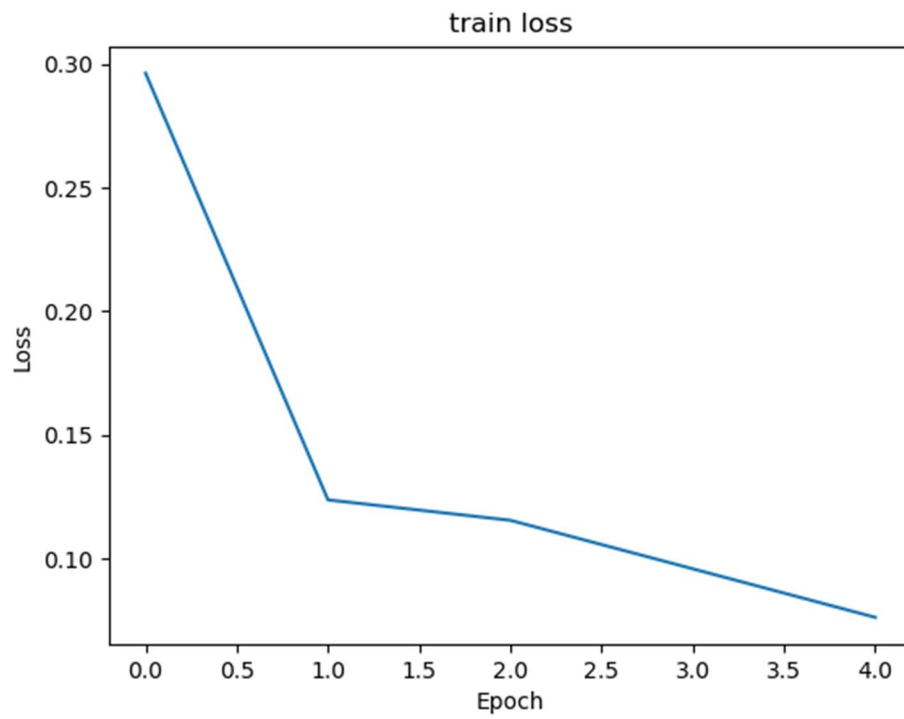
ii.



iii.



iv.



c)

Results after flips:

test_horizontal loss, test_horizontal acc: [5.478106498718262, 0.392300009727478]

test_vertical loss, test_vertical acc: [4.790810585021973, 0.41999998688697815]

There is a large amount of loss and low accuracy across both horizontal and vertical flips.

d)

Results after Gaussian noise:

test_gn0.01 loss, test_gn0.01 acc: [0.08179637789726257, 0.9830999970436096]

test_gn0.1 loss, test_gn0.1 acc: [0.6923056840896606, 0.8141000270843506]

test_gn1 loss, test_gn1 acc: [2.7780394554138184, 0.2563999891281128]

As more noise is added to the test datasets, the loss increases and accuracy decreases.

e)

test loss, test acc: [0.04784698039293289, 0.988099992275238]

test_h loss, test_h acc: [0.04738935828208923, 0.9873999953269958]

test_v loss, test_v acc: [0.06509146094322205, 0.9815999865531921]

test_gn0.01 loss, test_gn0.01 acc: [0.023918500170111656, 0.993399977684021]

test_gn0.1 loss, test_gn0.1 acc: [0.03706265985965729, 0.9900000095367432]

test_gn1 loss, test_gn1 acc: [0.3881167769432068, 0.879800021648407]

I retrained the model by making training sets with each of the modifications made in part 3 and 4, and added them into a final dataset including the original dataset, ie. a dataset of 6 combined data sets. The resulting test accuracies are as you can see above. The datasets saw a decrease in test loss and increase in test accuracy across all modifications.