

# CSC263: Problem Set 2

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## 1 Problem 1

- (a) Let  $Q$  be an array whose indices start from 1. Assume all keys in  $Q$  are distinct integers.

```
1 ExtractSecondLargest(Q):  
2   if Q.length < 2 then  
3     return None  
4   else then  
5     first = EXTRACT_MAX(Q)  
6     second = EXTRACT_MAX(Q)  
7     INSERT(Q, first)  
8     return second
```

- (b) Assume the length of array,  $Q$ , is greater than 2. Then we enter the else conditional on line 5 of the code. Line 5 of the code first extracts the element of  $Q$  with the largest key, and stores it in the variable *first*. Line 6 of the code, extracts the element with the largest key of the modified array,  $Q$ , and stores it in the variable *second*. We note here that *second* is the element of  $Q$  with the second largest key, when compared with the original  $Q$ . Note that at this point,  $Q$  is missing two elements with the largest keys, since they were extracted in lines 5 and 6. Then on line 7, the INSERT function, inserts the element with the largest key from the original  $Q$  back into  $Q$ . Thus, the resulting  $Q$  is only missing the element with the second largest key. In Line 8 of the code, the element with the second largest key is returned, thus it has been extracted from  $Q$ .

We note that the heap structure is preserved at every line because of the functions used to create  $EXTRACT\_SECOND\_LARGEST(Q)$ . First, we focus on the  $EXTRACT\_MAX(Q)$  function. This function preserves the heap structure through the  $MAX\_HEAPIFY(Q, i)$  function, where  $i$  is an index into the array. Once the maximal element has been extracted, the  $MAX\_HEAPIFY(Q, i)$  function works by determining the largest of elements  $Q[i]$ ,  $Q[LEFT(i)]$ , and  $Q[RIGHT(i)]$ , and the largest element's index is stored. If  $Q[i]$  is the largest, then the subtree rooted at node  $i$  is already a max heap and so the function terminates. Otherwise, if one of the two children are larger than  $Q[i]$  is swapped with the largest of its'

children ( $Q[LEFT(i)]$  or  $Q[RIGHT(i)]$ ). This causes the original node at index  $i$  and its children to satisfy the max-heap property. However, the node indexed by one of the children now has the original value  $Q[i]$  and the subtree now rooted at one of the children could possibly violate the max-heap property and so *MAX\_HEAPIFY* is called recursively on that subtree. In this way, the heap structure is maintained.

Next, we focus on the *INSERT*( $Q, x$ ) function, where  $x$  is an element that is to be inserted into the array,  $Q$ . The element is inserted at the very end of the array, i.e. a new leaf to the tree, but because of the *INCREASE\_KEY*( $Q, i, key$ ) (where  $i$  is an index into the array) function call inside *INSERT*( $Q, x$ ), the heap structure is maintained because *INCREASE\_KEY*( $Q, i, key$ ) sets the key of the new node to its correct value and thus maintains the max-heap property.

In this way, at the end of each line of code that is executed in the else condition, the heap structure is maintained.

- (c) Suppose  $Q$  has a length of  $n > 2$ . Then we skip lines 2 and 3 of the code which run in constant time and enter the else conditional. From lecture and the textbook, we know that *EXTRACT\_MAX*( $Q$ ) and *INSERT*( $Q, x$ ) run in  $O(\log(n))$  time (see pages 163 and 164 from CLRS). Thus, from the pseudo-code we can see that on lines 5 and 6 we run *EXTRACT\_MAX*( $Q$ ) twice and on line 7 *INSERT*( $Q, x$ ), thus we get a run-time of  $c \log(n)$ , where  $c$  is some constant. Accounting for other lines of code like the return statement on line 8, we get  $T(n) = c \log(n) + d \in O(\log(n))$ , for some constant  $d$ .