		ours e learning, this week			ask how you would act. We	1 / 1 po
Tryiagains "simulate could be like! take the quiz in 7h 43r You are employed crossing sign, cons	or" of working in a mach n by a startup building se	ine learning project lf-driving cars. You a d traffic signals (red a	will give you an ide re in charge of det and green lights) in	ea of what leading ecting road signs (n images. The goal	a machine learning project stop sign, pedestrian is to recognize which of	1/1/0
Pass 80% or higher				$\begin{bmatrix} 0 \\ 1 \end{bmatrix}$ "stop s	sign" strian crossing sign"	
			$y^{(i)} =$	1 "red tra	ruction ahead sign" affic light" traffic light"	
meet abouted pigget training even if the Suppose that you o	well on Yo kebinkayกเรรมี distribution of internet came from working with	gight be able to get a data is not the same a project for humar	n much larger data e. n detection in city p	set off the internet parks, so you know	stribution of data you care c, which could be helpful for that detecting humans in e steps below would take	
Train a basic n	nount of time (a few days	error analysis.	nard it will be to in	clude more pedesi	trians in your dataset.	
	g pedestrian detection, e pedestrian detection,		·		em alone.	
Correct Correct. As d	liscussed in the lecture,	it is better to create	your first system o	juickly and then ite	erate.	
lights) in images. T with ReLU units in	he goal is to recognize we the hidden layers. er, a softmax activation we	vhich of these object	s appear in each i	mage. You plan to	raffic signals (red and green use a deep neural network is a multi-task learning	1 / 1 poi
False True Correct						
Softmax wou	uld be a good choice if o nd red light) was preser	-	he possibilities (sto	op sign, speed bun	np, pedestrian crossing,	
should manually go	o through and carefully chosen images	examine, one image		akes. Which of the	se datasets do you think you	1 / 1 poi
10,000 images	which the algorithm me on which the algorithm algorithm algorithm only chosen images					
	ages that the algorithm ably no need to look at			you a good initial s	sense of the error statistics.	
• 100,000 labeled	ne data for several week images taken using the images of roads downlo	front-facing camera	of your car.	g data:		1 / 1 poi
$ullet$ Each image's lab example, $y^{(i)}=$	pels precisely indicate the $\begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}$ means the image $\begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix}$	e presence of any sp contains a stop sign	pecific road signs a	nd traffic signals c	or combinations of them. For	
When using a non	fully labeled image such in as a multi-task learnii	n as $y^{(i)} = egin{bmatrix} 0 \ ? \ 1 \ ? \ 1 \end{bmatrix}$, whi	ch of the following	strategies is most	appropriate to calculate the	
Make the miss	sing entries equal to 0. $\sum \mathcal{L}(\hat{y}_j^{(i)}, y_j^{(i)})$ w		over all the know o	omponents of $y^{(i)}$		
O It is not possib	sing entries equal to 1. ble to use non fully label	ed images if we trair	n as a multi-task le	arning problem.		
Correct Correct. We model.	can't use the componen	its of the labels that	are missing but we	e can use the ones	we have to train the	
distribution than the train/dev/test sets? Choose the train	ne images you were able ? aining set to be the 900,0	e to find and downlo	ad off the internet	. How should you th 20,000 images fi	comes from a different split the dataset into	1 / 1 poi
camera. The 8 Mix all the 100 dataset into 98	0,000 remaining images 0,000 images with the 90 80,000 for the training s	will be split equally 00,000 images you fo et, 10,000 for the de	in dev and test set ound online. Shuffl v set and 10,000 fo	e everything. Split or the test set.		
camera. The 2 Mix all the 100 dataset into 60	aining set to be the 900, 0,000 remaining images 0,000 images with the 90 00,000 for the training s	s will be split equally 00,000 images you fo	in dev and test set	e everything. Split		
	in the lecture, it is impo ortant for the training s				distribution to "real" data. iismatch problem.	
	ally chosen the following	રુ split between the d	ata:		Error of the	1 / 1 poi
Training Training- Dev	Contains: 940,000 images random front-facing camera ima 20,000 images randomly front-facing camera ima 20,000 images from you	ges) y picked from (900,0 nges)	00 internet images		algorithm: 1% 5.1% 5.6%	
Test	20,000 images from you 20,000 images from the t human-level error on t	car's front-facing ca	mera	cation task is arour	6.8%	
The size of the	ge data-mismatch proble e train-dev set is too high gh variance problem.					
You have a hig	· · · · · · · · · · · · · · · · · · ·	en the training-device	rror and the train	ng error is high		
	ally chosen the following			· ·		1 / 1 poi
Training Training-	Contains: 940,000 images random front-facing camera ima 20,000 images randomly front-facing camera ima	ges) y picked from (900,0			Error of the algorithm: 2% 2.3%	
Dev Test You also know that	front-facing camera ima 20,000 images from you 20,000 images from the t human-level error on t	ir car's front-facing c car's front-facing ca he road sign and tra	mera ffic signals classifio		1.3% 1.1% and 0.5%. Based on the	
True/False? True True True	you conclude that the B	ayes error for the de	ev/test distribution	is nigner than for	tne train distribution.	
⊘ Correct	ice that the test and dev	errors are lower tha	an the train and tra	ain-dev errors.		
Since there is a training set.	a high number of incorr	ectly labeled data in			to decide if the team	
⊘ Correct	+ 2.0 + 1.0, the priority should consider the tra		re images with pa	nould prioritize fixi rtially occluded ele	ng the labels on the whole ments.	
Correct Correct. You trained on th	should consider the tra nis additional data.	deoff between the d	re images with par	nould prioritize fixi rtially occluded ele	ng the labels on the whole ments.	1/1 poi
Correct Correct. You trained on the Service of the Correct. You decide to focus of the Correct o	should consider the trans additional data. s on the dev set and cheeror correctly labeled data	deoff between the d	re images with par	nould prioritize fixi rtially occluded ele	ng the labels on the whole ments.	1/1 poi
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