Detection Algorithms | Coursera

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Due Apr 25, 2:59 PM CST

இர்ட்றை இரு atulations! You passed! **Grade received** 80% **To pass** 80% or higher

Detection Algorithms

Quiz • 30 min **Detection Algorithms**

Due Apr 25, 2:59 PM CST **Attempts** 3 every 8 hours

Detection Algorithms

Graded Quiz • 30 min

1. You are building a 3-class object classification and localization algorithm. The classes are: pedestrian (c=1), car (c=2), motorcycle **Try-agaiv** hat should y be for the image below? Remember that "?" means "don't care", which means that the neural network loss

Aterbrity Aussis and ade 80%

function won't care what the neural network gives for that component of the output. Recall $y=[p_c,b_x,b_y,b_h,b_w,c_1,c_2,c_3]$.

https://www.pexels.com/es-es/foto/mujer-vestida-con-falda-azul-y-blanca-caminando-cerca-de-la-hierba-verde-durante-el-dia-144474/ $\bigcirc \ y = [1, ?, ?, ?, ?, 1, ?, ?]$

 $\bigcirc \ y = [1, 0.66, 0.5, 0.16, 0.75, 1, 0, 0]$

 $\bigcirc \ y = [1, 0.66, 0.5, 0.75, 0.16, 0, 0, 0]$

⊘ Correct Correct. $p_c=1$ since there is a pedestrian in the picture. We can see that b_x,b_y as percentages of the image are approximately correct as well b_h, b_w , and the value of $c_1=1$ for a pedestrian.

want it to take a picture and decide whether (i) there is a soft-drink can in the image, and if so (ii) its bounding box. Since the soft-drink can is round, the bounding box is always square, and the soft drink can always appear the same size in the image. There is at most one soft drink can in each image. Here are some typical images in your training set:

O Logistic unit, b_x , b_y , b_h (since $b_w = b_h$) lacksquare Logistic unit, b_x and b_y

Logistic unit (for classifying if there is a soft-drink can in the image)

What are the most appropriate (lowest number of) output units for your neural network?

2. You are working on a factory automation task. Your system will see a can of soft-drink coming down a conveyor belt, and you

3. If you build a neural network that inputs a picture of a person's face and outputs N landmarks on the face (assume the input image always contains exactly one face), how many output units will the network have?

Correct Correct!

 \bigcirc Logistic unit, b_x , b_y , b_h , b_w

2N ✓ Correct Correct

3N

 \bigcirc N

bounding box. True/False? False True

(X) Incorrect

must have several bounding boxes.

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1x1.

Correct Correct. This is a problem of semantic segmentation since we need to classify each pixel from the image.

True False

⟨√⟩ Correct Correct! False True

✓ Correct patient.

7. If we use anchor boxes in YOLO we no longer need the coordinates of the bounding box b_x, b_y, b_h, b_w since they are given by the cell position of the grid and the anchor box selection. True/False?

car 0.26 pedestrian 0.98

tree 0.74

None of the above

%

4. When training one of the object detection systems described in the lectures, each image must have zero or exactly one

Incorrect. In a single image, there might be more than only one instance of the object we are trying to localize, so it

5. What is the IoU between these two boxes? The upper-left box is 2x2, and the lower-right box is 2x3. The overlapping region is

⊘ Correct Correct. The left box's area is 4 while the right box 's is 6. Their intersection's area is 1. So their union's area is 4 + 6 - 1 = 9 which leads to an intersection over union of 1/9.

6. Suppose you run non-max suppression on the predicted boxes below. The parameters you use for non-max suppression are that boxes with probability \leq 0.4 are discarded, and the IoU threshold for deciding if two boxes overlap is 0.5. How many boxes will remain after non-max suppression?

motorcycle 0.58

Correct. We use the grid and anchor boxes to improve the capabilities of the algorithm to localize and detect objects, for example, two different objects that intersect, but we still use the bounding box coordinates. 8. We are trying to build a system that assigns a value of 1 to each pixel that is part of a tumor from a medical image taken from a

This is a problem of localization? True/False

https://www.coursera.org/learn/convolutional-neural-networks/exam/laJVI/detection-algorithms/attempt?redirect To Cover=true the sum of the convolution of the convo

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