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Due Apr 18, 2:59 PM CST

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coursera

Deep Convolutional Models Coursera	

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Deep Convolutional Models

Graded Quiz • 30 min

Deep Cotivolutional Models

Ouiz • 30 min **Deep Convolutional Models**

Eterbrithmissipmonate 85% **Due** Apr 18, 2:59 PM CST **Attempts** 3 every 8 hours

1. Which of the following do you typically see in a ConvNet? (Check all that apply.) Try again FC layers in the last few layers

Receive grade **⊘** Correct To Pass 80% Left, Highly-connected layers are often used after flattening a volume to output a set of classes in classification.

You radeltiple CONV layers followed by a POOL layer

85% True, as seen in the case studies.

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Multiple POOL layers followed by a CONV layer FC layers in the first few layers Like

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2. LeNet - 5 made extensive use of padding to create valid convolutions, to avoid increasing the number of channels after every convolutional layer. True/False? True False

Correct Yes, back in 1998 when the corresponding paper of LeNet - 5 was written padding wasn't used.

3. The motivation of Residual Networks is that very deep networks are so good at fitting complex functions that when training them we almost always overfit the training data. True/False? False

True Correct Correct, very deep neural networks are hard to train and a deeper network does not always imply lower training error. Residual Networks allow us to train very deep neural networks.

4. The following equation captures the computation in a ResNet block. What goes into the two blanks above? $a^{[l+2]} = g(W^{[l+2]}g(W^{[l+1]}a^{[l]} + b^{[l+1]}) + b^{l+2} + \underline{\qquad}) + \underline{\qquad}$ $igcup z^{[l]}$ and $a^{[l]}$, respectively

 $lackbox{0}$ $a^{[l]}$ and 0, respectively \bigcirc 0 and $z^{[l+1]}$, respectively igcup 0 and $a^{[l]}$, respectively Correct Correct

5. Which ones of the following statements on Residual Networks are true? (Check all that apply.) Correct This is true. $oxedsymbol{\sqcap}$ A ResNet with L layers would have on the order of L^2 skip connections in total.

The skip-connection makes it easy for the network to learn an identity mapping between the input and the output within the ResNet block. Correct This is true. The skip-connections compute a complex non-linear function of the input to pass to a deeper layer in the network.

6. Suppose you have an input volume of dimension $n_H \times n_W \times n_C$. Which of the following statements do you agree with? (Assume that the "1x1 convolutional layer" below always uses a stride of 1 and no padding.) You can use a 2D pooling layer to reduce n_H , n_W , but not n_C .

Correct

Correct

 n_W

other.

volume.

✓ Correct

✓ Correct

Correct

This should not be selected

block, suppose we don't use bias?

No, this is what the pointwise convolution does.

the inception network.

activations resulting from each type of layer.

This is correct.

You can use a 1x1 convolutional layer to reduce n_C but not n_H and n_W .

You can use a 1x1 convolutional layer to reduce n_H , n_W , and n_C .

Making an inception network deeper won't hurt the training set performance.

One problem with simply stacking up several layers is the computational cost of it.

may also help you save a great number of computational resources and data.

Which of the following are true about Depthwise-separable convolutions? (Choose all that apply)

Depthwise-separable convolutions are composed of two different types of convolutions.

Yes, it is composed of a depthwise convolution followed by a pointwise convolution.

The pointwise convolution convolves the input volume with 1×1 filters.

parameters, and the projection part $30 \times 20 = 600$ parameters.

The depthwise convolution convolves each channel in the input volume with a separate filter.

The depthwise convolution convolves the input volume with 1×1 filters over the depth dimension.

depthwise convolutions we use 3 imes3 filters, and 20 filters for the projection. How many parameters are used in the complete

Yes, the expansion filters use 5 imes 30 = 150 parameters, the depthwise convolutions need 3 imes 3 imes 30 = 270

You can use a 2D pooling layer to reduce n_H , n_W , and n_C .

Yes, a 1x1 convolutional layer with a small number of filters is going to reduce n_C but will keep the dimensions n_H and

Inception blocks allow the use of a combination of 1x1, 3x3, 5x5 convolutions, and pooling by applying one layer after the

Incorrect. An inception block stacks up the result of applying the different size convolutions and the pooling in a single

Correct. The use of several different types of layers and stacking up the results to get a single volume is at the heart of

Yes, this is a good way to take advantage of open-source models trained more or less for the task you want to do. This

Inception blocks allow the use of a combination of 1x1, 3x3, 5x5 convolutions and pooling by stacking up all the

7. Which of the following are true about the inception Network? (Check all that apply)

8. Parameters trained for one computer vision task can't be used directly in another task. In most cases, we must change the softmax layer, or the last layers of the model and re-train for the new task. True/False? False True

9.

8250

1101

80

1020

(✓**)** Correct

10. Suppose that in a MobileNet v2 Bottleneck block we have an n imes n imes 5 input volume, we use 30 filters for the expansion, in the

https://www.coursera.org/learn/convolutional-neural-networks/exam/WSTY7/deep-convolutional-models/attempt?redirectToCover=true.pdf.