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About the Author. Craig Smith (craig@theialabs.com) runs Theia Labs, a security research firm that focuses on security auditing and building hardware and software prototypes. He is also one of the founders of the Hive13 Hackerspace and Open Garages (@OpenGarages). He has worked for several auto manufacturers, where he provided public research on vehicle security and tools.

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where \mathbf{v} is a velocity vector for the bodies involved, \mathbf{J} is a "Jacobian" matrix with one row for every degree of freedom the joint removes from the system, and \mathbf{c} is a right hand side vector. At the next time step, a vector λ is calculated (of the same size as \mathbf{c}) such that the forces applied to the bodies to preserve the joint constraint are

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