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Nonlinear control theory is the area of control theory which deals with systems that are nonlinear, time-variant, or both. Control theory is an interdisciplinary branch of engineering and mathematics that is concerned with the behavior of dynamical systems with inputs, and how to modify the output by changes in the input using feedback, feedforward, or signal filtering.

Nonlinear control - Wikipedia

Model predictive control (MPC) is an advanced method of process control that is used to control a process while satisfying a set of constraints. It has been in use in the process industries in chemical plants and oil refineries since the 1980s. In recent years it has also been used in power system balancing models and in power electronics. Model predictive controllers rely on dynamic models of ...

Model predictive control - Wikipedia

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Aaron Ames. Bren Professor of Mechanical and Civil Engineering and Control and Dynamical Systems Professor Ames' research interests center on robotics, nonlinear control, hybrid systems and cyber-physical systems, with special emphasis on foundational theory and experimental realization on robotic systems; his lab designs, builds and tests novel bipedal robots and prosthesis with the goal of ...

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A Lecture on Model Predictive Control Jay H. Lee School of Chemical and Biomolecular Engineering Center for Process Systems Engineering Georgia Inst. of Technology

A Lecture on Model Predictive Control - CEPAC

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Nonlinear relationship between ER Ca2+ depletion versus ...

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Minimax and Maximin Optimization - APMonitor

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