




# Peerannot: learning from crowdsourced image datasets with Python

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## Abstract

Crowdsourcing is a fast and easy way to collect labels for large datasets. However, it is common for workers to disagree with each other. The sources of errors might come from the workers' abilities, but also from the task's intrinsic difficulty. We introduce *peerannot*: a Python library to handle crowdsourced labels and learn from them. Our library allows users to aggregate labels from common noise models or train a deep-learning based classifier directly from crowdsourced labels. Moreover, we provide an identification module to explore both the datasets' tasks difficulty and workers abilities easily.

*Keywords:* crowdsourcing, label noise, task difficulty, worker ability

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## 1 Introduction: crowdsourcing in image classification

Image datasets widely use crowdsourcing to collect labels. This allows workers to annotate images for a small cost and faster than using expert labeling. Many classical datasets using machine learning have been created with human intervention to create labels, such as CIFAR-10, (Krizhevsky and Hinton 2009), ImageNet (Deng et al. 2009) or (Garcin et al. 2021) in image classification, but also COCO (Lin et al. 2014), solar photovoltaic arrays (Kasmi et al. 2023) or even macro litter (Chagneux et al. 2023) in image segmentation and object counting.

Crowdsourced datasets induce at least three entangled problems to which we contribute with `peerannot`:

- *How to aggregate multiple labels into a single label from crowdsourced tasks?* This problem occurs for example when dealing with a single dataset that has been labeled by multiple workers where there are disagreements. But it is also encountered with polls, reviewing, *etc.* This is treated with the `aggregate` command.
- *How to learn a classifier from crowdsourced datasets?* Where the first question is bound by aggregating multiple labels into a single one, this considers the case where we don't need a label to train on, but we need to train a classifier with the crowdsourced data that performs well on a testing set. This end-to-end vision, is the most common case in machine learning, however, this means that we need the actual tasks to train on – and in crowdsourced datasets, they are not always available. This is treated with the `aggregate-deep` command.
- *How to score workers in a crowdsourcing experiment?* Beyond learning a classifier or inferring the true label, one could wish to find a ranking between workers. For example, it is relevant for the gamification of crowdsourcing experiments (Servajean et al. 2016) This is treated with the `identify` command.

The library `peerannot` addresses these practical questions within a reproducible setting. Indeed, the complexity of experiments often leads to a lack of transparency and reproducible results for simulations and real datasets. We propose standard simulation settings with explicit parameter implementations that can be shared. For real datasets, `peerannot` is compatible with standard neural networks architectures from the `Torchvision` (Marcel and Rodriguez 2010) library and `Pytorch` (Paszke et al. 2019), allowing a flexible framework with easy-to-share scripts to reproduce experiments.

## 2 Notation and package structure

### 2.1 Crowdsourcing notation

Let us consider the classical supervised learning classification framework. A training set  $\mathcal{D} = \{(x_i, y_i^*)\}_{i=1}^{n_{\text{task}}}$  is composed of  $n_{\text{task}}$  tasks  $x_i \in \mathcal{X}$  with ground truth label  $y_i^* \in [K] = 1, \dots, K$  one of the

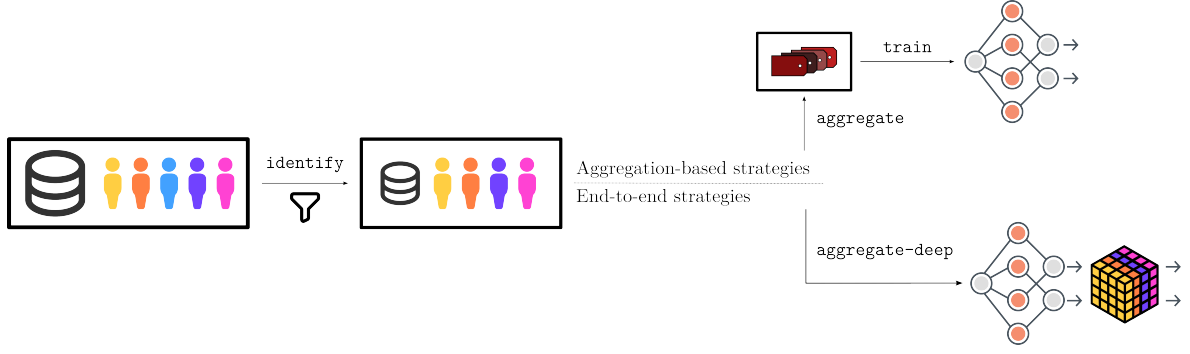


Figure 1: From crowdsourced labels to training a classifier neural network, the full pipeline using the peerannot library.

$K$  possible classes. In the following, the tasks considered are generally RGB images. We use the notation  $\sigma$  for the softmax function.

What differs from the classical setting with crowdsourced data, is that the ground truth  $y_i^*$  is unknown. However, instead for a given task  $x_i$ , a worker  $w_j$  proposes their label denoted  $y_i^{(j)}$ . The set of workers answering the task  $x_i$  is denoted  $\mathcal{A}(x_i) = \{j \in [n_{\text{worker}}] : w_j \text{ answered } x_i\}$ . The cardinal  $|\mathcal{A}(x_i)|$  is called the feedback effort on the task  $x_i$ . The feedback effort can not exceed the total number of workers  $n_{\text{worker}}$ . Mirroring the point of view by considering the workers and not the tasks: the set of tasks answered by a worker  $w_j$  is denoted  $\mathcal{T}(w_j) = \{i \in [n_{\text{task}}] : w_j \text{ answered } x_i\}$ . The cardinal  $|\mathcal{T}(w_j)|$  is called the workerload of  $w_j$ . The final dataset is:

$$\mathcal{D}_{\text{train}} := \bigcup_{i \in [n_{\text{task}}]} \{(x_i, (y_i^{(j)})) \text{ for } j \in \mathcal{A}(x_i)\} = \bigcup_{j \in [n_{\text{worker}}]} \{(x_i, (y_i^{(j)})) \text{ for } i \in \mathcal{T}(w_j)\} .$$

In this article, we do not address the setting where workers report their self-confidence (XXX), nor settings where workers are presented a trapping set – *i.e* a subset of tasks where the ground truth is known to evaluate them with known labels (Khattak 2017).

## 2.2 Storing crowdsourced datasets in peerannot

To store crowdsourcing datasets efficiently and in a standardized fashion, peerannot proposes the following structure:

```
datasetname
  train
    class0
      task0-<vote_index_0>.png
      task1-<vote_index_1>.png
      ...
      taskn0-<vote_index_n0>.png
    class1
      ...
    classK
  val
  test
  metadata.json
  answers.json
```

Each dataset is its folder. If the tasks (images) are available, they must be stored as it is usual to store ImageFolder datasets with pytorch into a train, val and test folder. Each image can have its name followed by its index in the answers.json file.

The answers.json file stores the different votes for each task as described in Figure 2. Finally, a metadata.json file include all relevant information related to the crowdsourcing experiment such as the number of workers, number of tasks, etc.

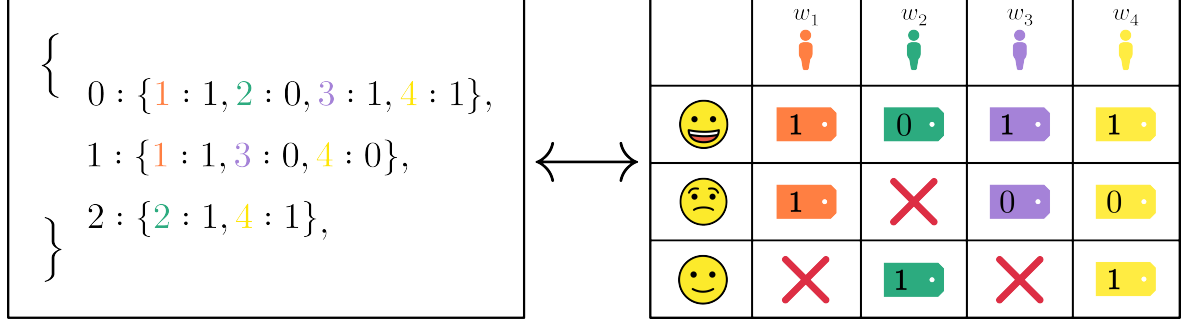


Figure 2: From collected labels to data storage in the answers.json file for a binary classification task on recognising smiling faces.

In this example, there are three tasks,  $n_{worker} = 4$  workers and  $K = 2$  classes. For the first task, the feedback effort is  $|\mathcal{A}(x_1)| = 4$ . The workload of  $w_2$  is  $|\mathcal{T}(w_2)| = 2$ .

### 3 Aggregation strategies in crowdsourcing

The first question we address with peerannot is: *How to aggregate multiple labels into a single label from crowdsourced tasks?* The aggregation step can lead to two types of learnable labels  $\hat{y}_i \in \Delta_K$  defined on the simplex of dimension  $K - 1$  depending on the use case:

- a **hard** label:  $\hat{y}_i$  is a Dirac distribution, this can be encoded as a classical label in  $[K]$ ,
- a **soft** label:  $\hat{y}_i \in \Delta_K$  can be a probability distribution other than Dirac distribution, in that case, each coefficient in  $\hat{y}_i$  represents the probability to belong to the given class.

Learning from soft labels has been shown to improve learning performance and make the classifier learn the task ambiguity. **XXX** However, crowdsourcing is often used as a stepping stone to creating a new dataset and we usually expect a classification dataset to associate a task  $x_i$  to a single label and not a full probability distribution. In this case, we recommend in practice releasing the anonymous answered labels and the aggregation strategy used to reach a consensus on a single label. With peerannot, both soft and hard labels can be produced. Note that when a strategy produces a soft label, a hard label can be induced by taking the class with the maximum probability.

#### 3.1 Classical models

While the most intuitive way to create a label from multiple answers for any type of crowdsourced task would be to take the majority vote (MV), this strategy has many shortcomings (James 1998) – there is no noise model, no worker reliability estimated, no task difficulty involved and especially no way to remove poorly performing workers. This baseline aggregation can be expressed as:

$$\hat{y}_i^{\text{MV}} = \underset{k \in [K]}{\operatorname{argmax}} \sum_{j \in \mathcal{A}(x_i)} 1_{\{y_i^{(j)} = k\}}.$$

One pitfall with the MV is that the label produced is hard, hence the ambiguity is discarded by construction. To remedy this, the Naive Soft (NS) labeling consists in using the empirical frequency distribution as the task label:

$$\hat{y}_i^{\text{NS}} = \left( \frac{1}{|\mathcal{A}(x_i)|} \sum_{j \in \mathcal{A}(x_i)} 1_{\{y_i^{(j)} = k\}} \right)_{k \in [K]}.$$

With the NS label, we keep the ambiguity, but all workers and all tasks are put on the same level. In practice, it is known that each worker comes with their abilities, thus modeling this knowledge can produce better results.

Going further into the aggregation, researchers began creating a noise model to take into account the workers' abilities in the aggregation. These types of models are most often EM-based and one of the most studied (Gao and Zhou 2013) and applied (Servajean et al. 2017; Rodrigues and Pereira 2018) is the Dawid and Skene's (DS) model (Dawid and Skene 1979). Assuming the workers are answering tasks independently, this model boils down to model pairwise confusions between each possible class. Each worker  $w_j$  is assigned a confusion matrix  $\pi^{(j)} \in \mathbb{R}^{K \times K}$  such that  $\pi_{k\ell}^{(j)} = \mathbb{P}(y_i^{(j)} = \ell | y_i^* = k)$ . The model assumes that the probability for a task  $x_i$  to have true label  $y_i^* = k$  follows a multinomial distribution with probabilities  $\pi_{k,\bullet}^{(j)}$  for each worker. Each class has a prevalence  $\rho_k = \mathbb{P}(y_i^* = k)$  to appear in the dataset. Using the independence between workers, we obtain the following likelihood to maximize (using the EM algorithm):

$$\prod_{i \in [n_{\text{task}}]} \prod_{k \in [K]} \left[ \rho_k \prod_{j \in [n_{\text{worker}}]} \prod_{\ell \in [K]} (\pi_{k\ell}^{(j)})^{1_{\{y_i^{(j)} = \ell\}}} \right]^{T_{ik}},$$

with  $T_{i,k} = 1_{\{y_i^* = k\}}$ . The final aggregated soft label is  $\hat{y}_i^{\text{DS}} = T_{i,\cdot}$ .

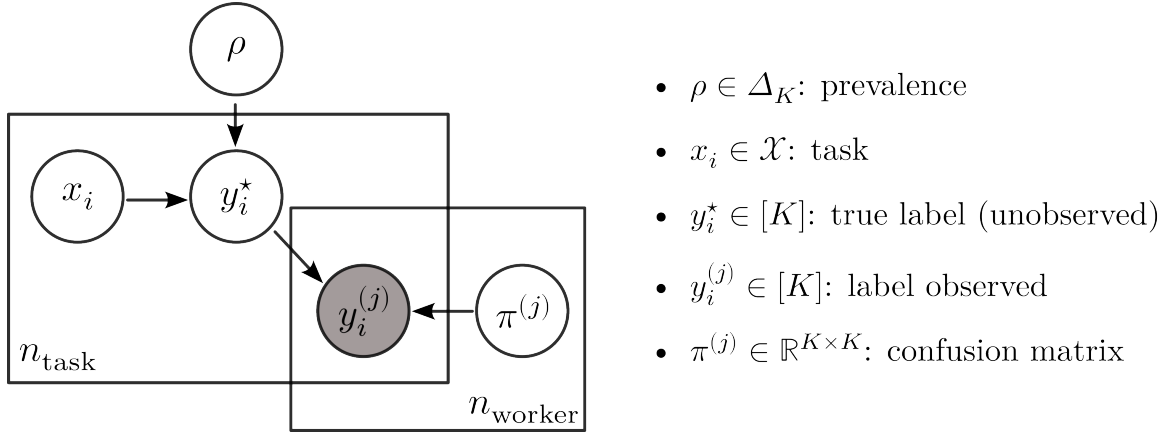


Figure 3: Bayesian plate notation for the DS model

Many variants of the DS model have been proposed in the literature, using Dirichlet priors on the confusion matrices (Passonneau and Carpenter 2014), using  $L$  clusters of workers (Imamura, Sato, and Sugiyama 2018) with  $1 \leq L \leq n_{\text{worker}}$  (DSWC) or even faster implementation that produces only hard labels (Sinha, Rao, and Balasubramanian 2018).

Finally, we present the GLAD model (Whitehill et al. 2009) that not only takes into account the worker's ability, but also the task difficulty in the noise model. Denoting  $\alpha_j \in \mathbb{R}$  the worker ability (the higher the better) and  $\beta_i \in \mathbb{R}_+^+$  the task's difficulty (the higher the easier), the model noise is:

$$\mathbb{P}(y_i^{(j)} = y_i^* | \alpha_j, \beta_i) = \frac{1}{1 + \exp(-\alpha_j \beta_i)} .$$

GLAD’s model also assumes that the errors are uniform across wrong labels, thus:

$$\forall k \in [K], \mathbb{P}(y_i^{(j)} = k | y_i^* \neq k, \alpha_j, \beta_i) = \frac{1}{K-1} \left( 1 - \frac{1}{1 + \exp(-\alpha_j \beta_i)} \right) .$$

The likelihood can then be optimized using an EM algorithm to recover the soft label  $\hat{y}_i^{\text{GLAD}}$ .

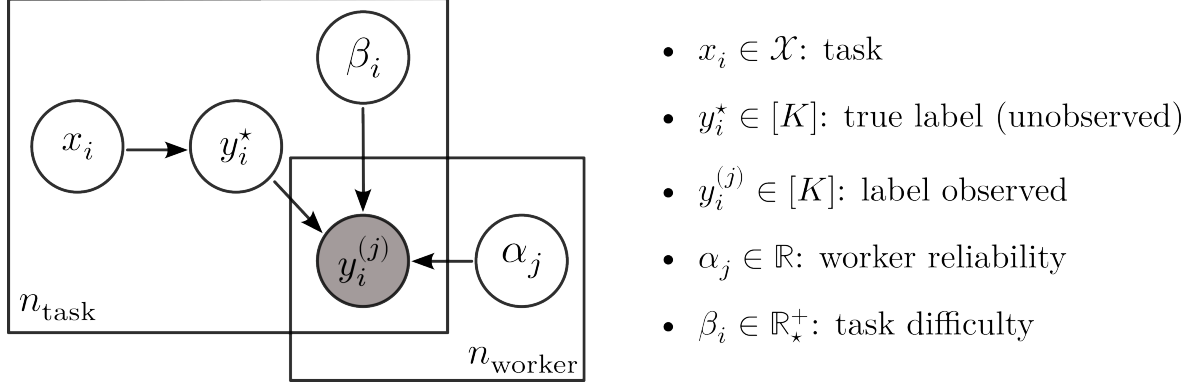


Figure 4: Bayesian [plate notation](#) for the GLAD model

All of these aggregation strategies – and more – are available in the `peerannot` library from the `peerannot.models` module. Each model is a class object in its own Python file. It inherits from the `CrowdModel` template class and is defined with at least two methods: - `run`: includes the optimization procedure to obtain needed weights (*e.g.* the EM algorithm for the DS model), - `get_probas`: returns the soft labels output for each task.

### 3.2 Experiments and evaluation of label aggregation strategies

One way to evaluate the label aggregation strategies is to measure their accuracy. This means that the underlying ground truth must be known – or at least for a representative subset. As the set of  $n_{\text{task}}$  can be seen as a training set for a future classifier, we denote this metric `AccTrain` on a dataset  $\mathcal{D}$  for a given aggregated label  $(\hat{y}_i)_i$  as:

$$\text{AccTrain}(\mathcal{D}) = \frac{1}{|\mathcal{D}|} \sum_{i=1}^{|\mathcal{D}|} 1_{\{y_i^* = \arg\max_{k \in [K]} \hat{y}_i\}} .$$

In the following, we write `AccTrain` for `AccTrain( $\mathcal{D}_{\text{train}}$ )` as we only consider the full training set so there is no ambiguity. While this metric is useful, in practice there are a few arguable issues:

- the `AccTrain` does not consider the ambiguity of the soft label, only the most probable class, whereas in some contexts ambiguity can be informative,
- in supervised learning one objective is to identify difficult or mislabeled tasks (Pleiss et al. 2020; Lefort et al. 2022), pruning those tasks can easily artificially improve the `AccTrain`, but there is no guarantee over the predictive performance of a model based on the newly pruned dataset.

We first consider classical simulation settings in the literature that can easily be created and reproduced using `peerannot`.

### 3.2.1 Simulated independent mistakes

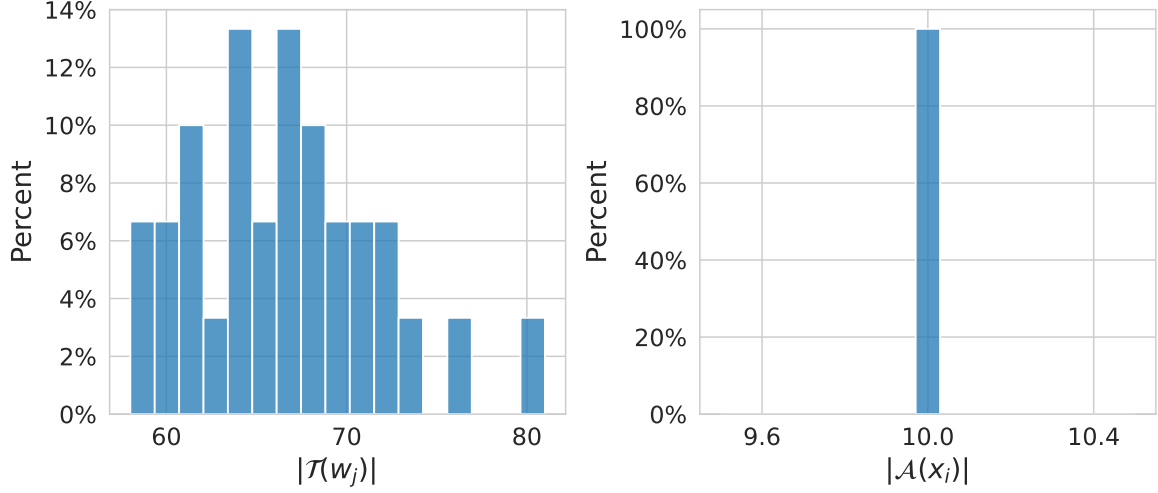
The independent mistakes consider that each worker  $w_j$  answers following a multinomial distribution with weights given at the row  $y_i^*$  of their confusion matrix  $\pi^{(j)} \in \mathbb{R}^{K \times K}$ . Each confusion matrix is generated diagonally dominant. Answers are independent of one another as each matrix is generated independently and each worker answers independently of other workers. In this setting, the DS model is expected to perform the best with enough data as we are simulating data from its assumed noise model.

We simulate  $n_{\text{task}} = 200$  tasks and  $n_{\text{worker}} = 30$  workers with  $K = 5$  possible classes. Each task receives  $|\mathcal{A}(x_i)| = 10$  labels.

```
! peerannot simulate --n-worker=30 --n-task=200 --n-classes=5 \
                    --strategy independent-confusion \
                    --feedback=10 --seed 0 \
                    --folder ./simus/independent

from peerannot.helpers.helpers_visu import feedback_effort, working_load
import seaborn as sns
import matplotlib.pyplot as plt
from matplotlib.ticker import MaxNLocator
from pathlib import Path
import matplotlib.ticker as mtick
sns.set_style("whitegrid")

votes_path = Path.cwd() / "simus" / "independent" / "answers.json"
metadata_path = Path.cwd() / "simus" / "independent" / "metadata.json"
efforts = feedback_effort(votes_path)
workerload = working_load(votes_path, metadata_path)
feedback = feedback_effort(votes_path)
nbins = 17
fig, ax = plt.subplots(1, 2, figsize=(9, 4))
sns.histplot(workerload, stat="percent", bins=nbins, shrink=1, ax=ax[0])
ax[0].yaxis.set_major_formatter(mtick.PercentFormatter(decimals=0))
ax[0].set_xlabel(r"$\text{vert}\mathcal{T}(w_j)\text{vert}$")
sns.histplot(feedback, stat="percent", bins=nbins, shrink=1, ax=ax[1])
ax[1].yaxis.set_major_formatter(mtick.PercentFormatter(decimals=0))
ax[1].set_xlabel(r"$\text{vert}\mathcal{A}(x_i)\text{vert}$")
ax[1].xaxis.set_major_locator(plt.MaxNLocator(3))
for i in range(2):
    ax[i].xaxis.set_major_locator(MaxNLocator(3))
    ax[i].xaxis.label.set_size(15)
    ax[i].yaxis.label.set_size(15)
    ax[i].xaxis.set_tick_params(labelsize=13)
    ax[i].yaxis.set_tick_params(labelsize=13)
    ax[i].title.set_size(18)
plt.tight_layout()
plt.show()
```



With the obtained answers, we can look at the aforementioned aggregation strategies performance:

```
for strat in ["MV", "NaiveSoft", "DS", "GLAD", "DSWC[L=5]", "DSWC[L=10]"]:
    ! peerannot aggregate ./simus/independent/ -s {strat}

import pandas as pd
import numpy as np
from IPython.display import display
simu_indep = Path.cwd() / 'simus' / "independent"
results = {"mv": [], "naivesoft": [], "glad": [], "ds": [], "dswc[l=5]": [], "dswc[l=10]": []}
for strategy in results.keys():
    path_labels = simu_indep / "labels" / f"labels_independent-confusion_{strategy}.npy"
    ground_truth = np.load(simu_indep / "ground_truth.npy")
    labels = np.load(path_labels)
    acc = (
        np.mean(labels == ground_truth)
        if labels.ndim == 1
        else np.mean(
            np.argmax(labels, axis=1)
            == ground_truth
        )
    )
    results[strategy].append(acc)
results = pd.DataFrame(results, index=['AccTrain'])
results.columns = map(str.upper, results.columns)
display(results)
```

Table 1: AccTrain metric on simulated independent mistakes considering classical feature-blind label aggregation strategies

	MV	NAIVESOFT	GLAD	DS	DSWC[L=5]	DSWC[L=10]
AccTrain	0.755	0.76	0.775	0.89	0.775	0.77



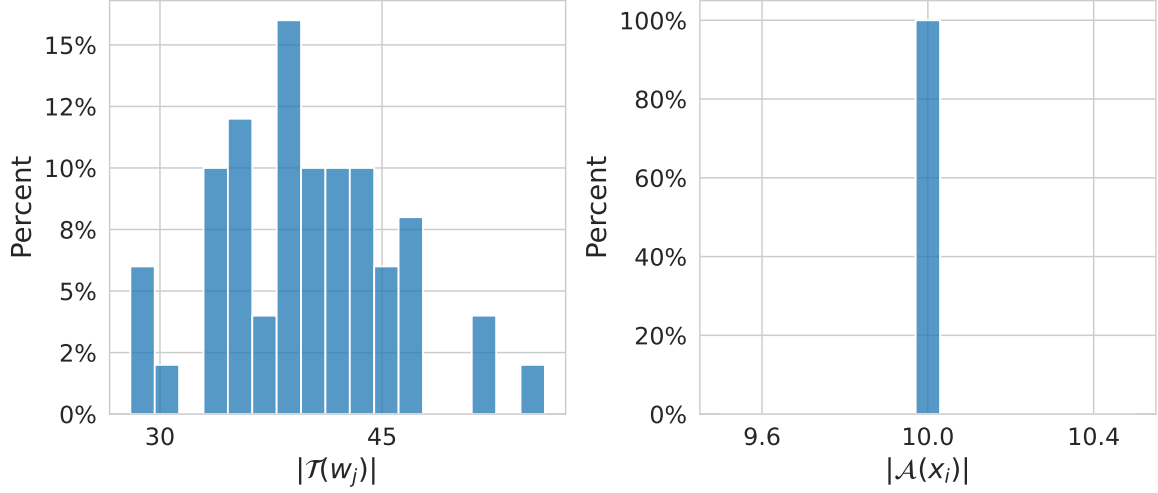
### 3.2.2 Simulated correlated mistakes

The correlated mistakes are also known as the student-teacher setting. Consider that the crowd of workers is divided into two categories: teachers and students such that  $n_{\text{teacher}} + n_{\text{student}} = n_{\text{worker}}$ . Each student is randomly assigned to one teacher at the beginning of the experiment. We generate the (diagonally dominant) confusion matrices of each teacher and the students are associated with their's teacher confusion matrix. Then, they all answer independently, following a multinomial distribution with weights given at the row  $y_i^*$  of their confusion matrix  $\pi^{(j)} \in \mathbb{R}^{K \times K}$ .

We simulate  $n_{\text{task}} = 200$  tasks and  $n_{\text{worker}} = 50$  with 80% of students in the crowd. There are  $K = 5$  possible classes. Each task receives  $|\mathcal{A}(x_i)| = 10$  labels.

```
! peerannot simulate --n-worker=50 --n-task=200 --n-classes=5 \
                    --strategy student-teacher \
                    --ratio 0.8 \
                    --feedback=10 --seed 0 \
                    --folder ./simus/student_teacher

votes_path = Path.cwd() / "simus" / "student_teacher" / "answers.json"
metadata_path = Path.cwd() / "simus" / "student_teacher" / "metadata.json"
efforts = feedback_effort(votes_path)
workerload = working_load(votes_path, metadata_path)
feedback = feedback_effort(votes_path)
nbins = 17
fig, ax = plt.subplots(1, 2, figsize=(9, 4))
sns.histplot(workerload, stat="percent", bins=nbins, shrink=1, ax=ax[0])
ax[0].yaxis.set_major_formatter(mtick.PercentFormatter(decimals=0))
ax[0].set_xlabel(r"$\vert\mathcal{T}\{w_j\}\vert$")
sns.histplot(feedback, stat="percent", bins=nbins, shrink=1, ax=ax[1])
ax[1].yaxis.set_major_formatter(mtick.PercentFormatter(decimals=0))
ax[1].set_xlabel(r"$\vert\mathcal{A}\{x_i\}\vert$")
ax[1].xaxis.set_major_locator(plt.MaxNLocator(3))
for i in range(2):
    ax[i].xaxis.set_major_locator(MaxNLocator(3))
    ax[i].xaxis.label.set_size(15)
    ax[i].yaxis.label.set_size(15)
    ax[i].xaxis.set_tick_params(labelsize=13)
    ax[i].yaxis.set_tick_params(labelsize=13)
    ax[i].title.set_size(18)
plt.tight_layout()
plt.show()
```



With the obtained answers, we can look at the aforementioned aggregation strategies performance:

```
for strat in ["MV", "NaiveSoft", "DS", "GLAD", "DSWC[L=5]", "DSWC[L=10]"]:
    ! peerannot aggregate ./simus/student_teacher/ -s {strat}

simu_corr = Path.cwd() / 'simus' / "student_teacher"
results = {"mv": [], "naivesoft": [], "glad": [], "ds": [], "dswc[l=5]": [], "dswc[l=10]": []}
for strategy in results.keys():
    path_labels = simu_corr / "labels" / f"labels_student-teacher_{strategy}.npy"
    ground_truth = np.load(simu_corr / "ground_truth.npy")
    labels = np.load(path_labels)
    acc = (
        np.mean(labels == ground_truth)
        if labels.ndim == 1
        else np.mean(
            np.argmax(labels, axis=1)
            == ground_truth
        )
    )
    results[strategy].append(acc)
results = pd.DataFrame(results, index=['AccTrain'])
results.columns = map(str.upper, results.columns)
display(results)
```

Table 2: AccTrain metric on simulated correlated mistakes considering classical feature-blind label aggregation strategies

	MV	NAIVESOFT	GLAD	DS	DSWC[L=5]	DSWC[L=10]
AccTrain	0.745	0.72	0.68	0.765	0.725	0.695

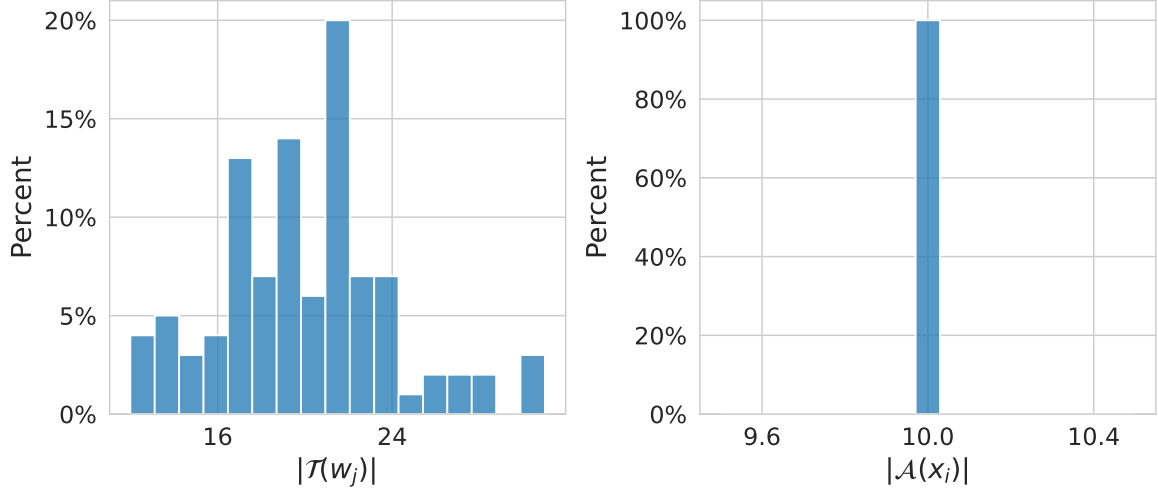
### 3.2.3 Simulated mistakes with discrete difficulty levels on tasks

For the final simulation setting, we consider the discrete difficulty presented in Whitehill et al. (2009). Contrary to other simulations, we here consider that each worker is either good or bad and each task is either easy or hard. Easy tasks are answered without mistakes by involved workers. However, hard tasks are answered following the worker's confusion matrix. The confusion matrix  $\pi^{(j)}$  is diagonally dominant for good workers while each row is drawn uniformly in the simplex  $\Delta_K$  for bad workers. Each worker then answers independently to the presented tasks.

We simulate  $n_{\text{task}} = 500$  tasks and  $n_{\text{worker}} = 100$  with 30% of good workers in the crowd and 50% of easy tasks. There are  $K = 5$  possible classes. Each task receives  $|\mathcal{A}(x_i)| = 10$  labels.

```
! peerannot simulate --n-worker=100 --n-task=200 --n-classes=5 \
    --strategy discrete-difficulty \
    --ratio 0.35 --ratio-diff 1 \
    --feedback 10 --seed 0 \
    --folder ./simus/discrete_difficulty

votes_path = Path.cwd() / "simus" / "discrete_difficulty" / "answers.json"
metadata_path = Path.cwd() / "simus" / "discrete_difficulty" / "metadata.json"
efforts = feedback_effort(votes_path)
workerload = working_load(votes_path, metadata_path)
feedback = feedback_effort(votes_path)
nbins = 17
fig, ax = plt.subplots(1, 2, figsize=(9, 4))
sns.histplot(workerload, stat="percent", bins=nbins, shrink=1, ax=ax[0])
ax[0].yaxis.set_major_formatter(mtick.PercentFormatter(decimals=0))
ax[0].set_xlabel(r"$\text{vert}\mathcal{T}(w_j)\text{vert}$")
sns.histplot(feedback, stat="percent", bins=nbins, shrink=1, ax=ax[1])
ax[1].yaxis.set_major_formatter(mtick.PercentFormatter(decimals=0))
ax[1].set_xlabel(r"$\text{vert}\mathcal{A}(x_i)\text{vert}$")
for i in range(2):
    ax[i].xaxis.set_major_locator(MaxNLocator(3))
    ax[i].xaxis.label.set_size(15)
    ax[i].yaxis.label.set_size(15)
    ax[i].xaxis.set_tick_params(labelsize=13)
    ax[i].yaxis.set_tick_params(labelsize=13)
    ax[i].title.set_size(18)
plt.tight_layout()
plt.show()
```



With the obtained answers, we can look at the aforementioned aggregation strategies performance:

```
for strat in ["MV", "NaiveSoft", "DS", "GLAD", "DSWC[L=2]", "DSWC[L=5]"]:
    ! peerannot aggregate ./simus/discrete_difficulty/ -s {strat}

simu_corr = Path.cwd() / 'simus' / "discrete_difficulty"
results = {"mv": [], "naivesoft": [], "glad": [], "ds": [], "dswc[l=2]": [], "dswc[l=5]": []}
for strategy in results.keys():
    path_labels = simu_corr / "labels" / f"labels_discrete-difficulty_{strategy}.npy"
    ground_truth = np.load(simu_corr / "ground_truth.npy")
    labels = np.load(path_labels)
    acc = (
        np.mean(labels == ground_truth)
        if labels.ndim == 1
        else np.mean(
            np.argmax(labels, axis=1)
            == ground_truth
        )
    )
    results[strategy].append(acc)
results = pd.DataFrame(results, index=['AccTrain'])
results.columns = map(str.upper, results.columns)
display(results)
```

Table 3: AccTrain metric on simulated mistakes when tasks are associated a difficulty level considering classical feature-blind label aggregation strategies

	MV	NAIVESOFT	GLAD	DS	DSWC[L=2]	DSWC[L=5]
AccTrain	0.79	0.79	0.845	0.81	0.6	0.66

## 4 Learning from crowdsourced tasks

Most often, tasks are crowdsourced to create a large training set as modern machine learning models require more and more data. The aggregation step then simply becomes the first step in the complete learning pipeline. However, instead of aggregating labels, modern neural networks let us directly train a classifier from multiple noisy labels.

### 4.1 Classical models

In recent years, directly learning a classifier from noisy labels was introduced. Two of the most used models: CrowdLayer (Rodrigues and Pereira 2018) and CoNAL (Chu, Ma, and Wang 2021), are directly available in peerannot. These two learning strategies directly incorporate a DS-based noise model in the neural network’s architecture.

CrowdLayer trains a classifier with noisy labels as follows. Let the scores (logits) output of a given classifier neural network  $\mathcal{C}$  be  $z_i = \mathcal{C}(x_i)$ . Then CrowdLayer adds a new layer  $\pi \in \mathbb{R}^{n_{\text{worker}} \times K \times K}$ , the tensor of all  $\pi^{(j)}$ s such that the crossentropy loss (CE) is adapted to the crowdsourcing setting into  $\mathcal{L}_{CE}^{\text{CrowdLayer}}$  and computed as:

$$\mathcal{L}_{CE}^{\text{CrowdLayer}}(x_i) = \sum_{j \in \mathcal{A}(x_i)} \text{CE}(\sigma(\pi^{(j)} \sigma(z_i)), y_i^{(j)}) .$$

The confusion matrices are incorporated as is into the network architecture as a new layer to transform the output probabilities to match each worker’s answer. However, for some datasets, it was noticed that global confusion occurs between the proposed classes. It is the case for example in the LabelMe dataset (Rodrigues et al. 2017) where classes overlap. In this case, Chu, Ma, and Wang (2021) proposed to extend the CrowdLayer model by not only modeling the worker confusion matrices; but also a global confusion matrix  $\pi^g \in \mathbb{R}^{K \times K}$ .

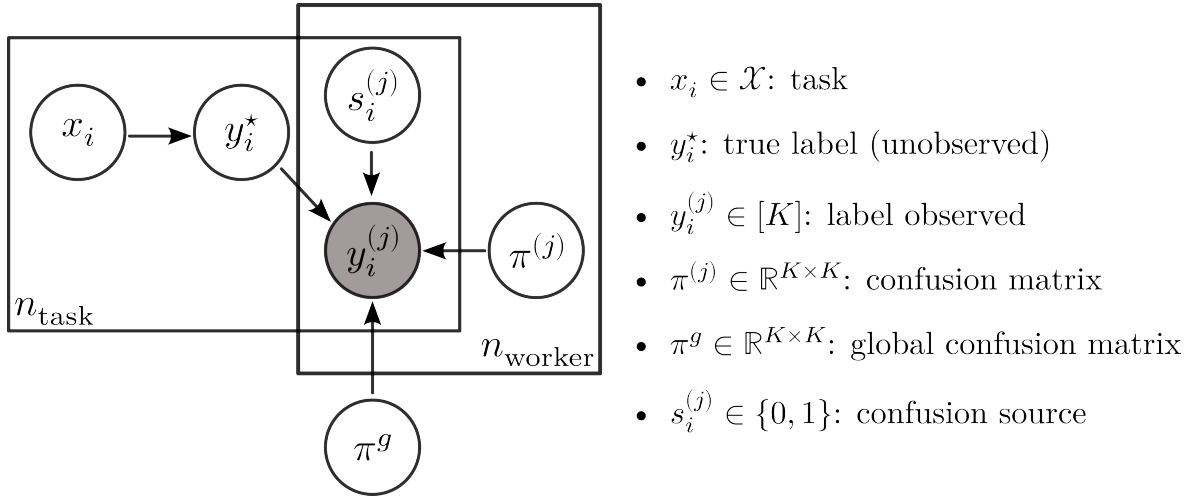


Figure 5: Bayesian plate notation for CoNAL model. Each worker is assigned a confusion matrix  $\pi^{(j)}$ . A global confusion matrix  $\pi^g$  is shared between workers. A tradeoff between the global confusion and the local one is applied.

Given the output  $z_i = \mathcal{C}(x_i) \in \mathbb{R}^K$  of a given classifier and task, CoNAL interpolates between the

local confusion  $\pi^{(j)}\sigma(z_i)$  and the global one  $\pi^g\sigma(z_i)$ . The loss function is computed as follows:

$$\begin{aligned}\mathcal{L}_{CE}^{\text{CoNAL}}(x_i) &= \sum_{j \in \mathcal{A}(x_i)} \text{CE}(h_i^{(j)}, y_i^{(j)}) , \\ \text{with } h_i^{(j)} &= \sigma\left((\omega_i^{(j)}\pi^g + (1 - \omega_i^{(j)})\pi^{(j)})z_i\right) .\end{aligned}$$

The interpolation weight is defined as  $s_i^{(j)} \sim \mathcal{B}(w_i^{(j)})$  and is unobservable in practice. So, to compute  $h_i^{(j)}$ , the weight is obtained through an auxiliary network that projects the task  $x_i$  onto  $v_i$  and the worker  $w_j$  onto  $u_j$ , two vectors in an embedding space of dimension  $d \geq 1$ . Finally,  $w_i^{(j)} = (1 + \exp(-u_j^\top v_i))^{-1}$ .

Both CrowdLayer and CoNAL model worker confusions directly in the classifier’s weights to learn from the noisy collected labels and are available in peerannot as we will see in the following.

## 4.2 Prediction error when learning from crowdsourced tasks

The AccTrain metric presented in Section 3.2 might no longer be of interest when training a classifier. Classical error measurements involve a test dataset to estimate the generalization error. To do so, we present hereafter two error metrics. Assuming we trained our classifier  $f_\theta$  on a training set: - the test accuracy is computed as  $\frac{1}{n_{\text{test}}} \sum_{i=1}^{n_{\text{test}}} 1_{\{y_i^* = \widehat{f_\theta(x_i)}\}}$  - the expected calibration error (Guo et al. 2017), computed as: XXX

Where the accuracy represents how well the classifier generalizes, the expected calibration error (ECE) quantifies the deviation between the accuracy and the confidence of the classifier. Modern neural networks are known to often be overconfident in their predictions XXX. However, it has also been remarked that training on crowdsourced data, depending on the strategy, mitigates this confidence issue. That is why we propose to compare them both in our coming experiments. Note that the ECE error estimator is known to be biased (Gruber and Buettner 2022). Smaller training sets are known to have a higher ECE estimation error. And in the crowdsourcing setting, openly available datasets are often quite small.

## 4.3 Use case with peerannot on real datasets

Few real crowdsourcing experiments have been released publicly. Among the available ones, CIFAR-10H (Peterson et al. 2019) is one of the largest with 10000 tasks labeled by workers (the testing set of CIFAR-10). The issue with CIFAR-10H is that there are little to no disagreements and a simple majority voting leads to a near-perfect AccTrain error. While with this dataset comparing the impact of aggregation and end-to-end strategies might not be relevant, it is a good benchmark for task difficulty identification and worker evaluation scoring XXX

The LabelMe dataset was extracted from crowdsourcing segmentation experimentation and a subset of  $K = 8$  classes was released in Rodrigues et al. (2017).

To install these datasets, we run the `install` command from peerannot:

```
! peerannot install ./datasets/labelme/labelme.py
! peerannot install ./datasets/cifar10H/cifar10h.py
```

Let us use peerannot to train a Resnet34 on the LabelMe dataset for:

- aggregation strategies: MV, NS, DS, GLAD,
- end-to-end strategies: CrowdLayer and CoNAL.

As we can see, CoNAL strategy performs best. In this case, it is expected behavior as CoNAL was created for the LabelMe dataset. However, using peerannot we can look into **why** modeling common confusion returns better results with this dataset. To do so, we can explore the datasets from two points of view: worker-wise or task-wise.

## 5 Exploring crowdsourced datasets

If a dataset requires citizen knowledge to be labeled, it is because expert knowledge is long and costly to obtain. In the era of big data, where datasets are built using web scraping XXX and other techniques, citizen science is popular as it is an easy way to produce many labels.

However, mistakes and confusions happen during these experiments. Sometimes involuntarily (e.g. because the task is too hard or the worker is unable to differentiate between two classes) and sometimes not (e.g. the worker is a spammer).

Underlying all the learning models and aggregation strategies, the cornerstone of crowdsourcing is evaluating the trust we put in each worker depending on the presented task. And with the gamification of crowdsourcing XXX, it has become essential to find scoring metrics both for workers and tasks to keep citizens in the loop so to speak. This is the purpose of the identification module in peerannot

### 5.1 Exploring tasks' difficulty

To explore the tasks' intrinsic difficulty, we propose to compare three scoring metrics:

- the entropy of the NS distribution: reliable with a big enough and not adversarial crowd, the entropy measures the inherent uncertainty of the distribution to the possible outcomes.
- GLAD's scoring: by construction, Whitehill et al. (2009) introduced a scalar coefficient to score the difficulty of a task  $\beta_i > 0$ .
- the WAUM: introduced in XXX, this weighted area under the margins indicates how difficult it is for a model to classify the task given the crowdsourced labels and the trust we have in each worker.

Note that each of these statistics is useful in its context. The entropy can not be used in a setting with  $|\mathcal{A}(x_i)|$  low (few labels per task), in particular for the LabelMe dataset it is not informative. The WAUM can work with any number of labels, but the larger the better. However, as it uses a deep learning classifier, the WAUM needs the tasks  $(x_i)_i$  in addition to the proposed labels while the other strategies are feature-blind.

#### 5.1.1 CIFAR-10H dataset

First, let us consider a dataset with a large number of tasks, annotations and workers: the CIFAR-10H dataset by Peterson et al. (2019).

```
import torch
import matplotlib.pyplot as plt
from PIL import Image
from pathlib import Path
nrow = 5
ncol = 5
fig, axs = plt.subplots(
    nrow,
```

```

        ncol,
        sharey="row",
        sharex="col",
        figsize=(12,8)
    )
    match_ = {0: "bird", 1: "car", 2: "cat", 3: "deer", 4: "dog", 5: "frog", 6: "horse", 7: "plane",
    path = Path.cwd() / "datasets" / "cifar10H" / "train"
    for i in range(nrow):
        img_folder = path / f"{match_[i]}"
        all_imgs = list(img_folder.glob("*"))[:ncol]
        for j in range(ncol):
            image = np.asarray(Image.open(path / all_imgs[j]))
            axs[i,j].imshow(image, aspect="equal")
            axs[i,j].axis("off")
            axs[i,j].set_yticklabels([])
    plt.subplots_adjust(left=0.05, bottom=0.05, right=0.95, top=0.95, wspace=0.05, hspace=0.05)
    plt.show()

```

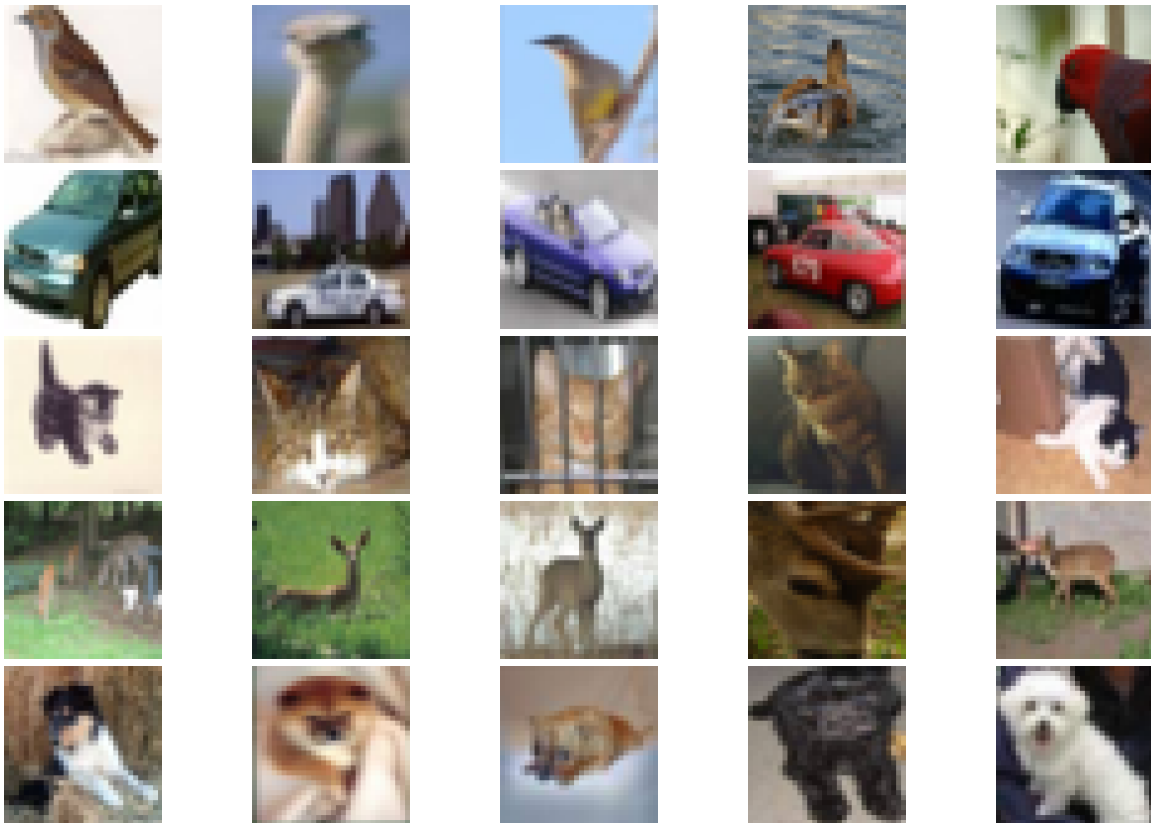


Figure 6: Example of images to label from the CIFAR-10H dataset with label bird, car, cat, deer and dog (top to bottom) by row.

```

! peerannot identify ./datasets/cifar10H -s entropy -K 10 --labels ./datasets/cifar10H/answers.
! peerannot aggregate ./datasets/cifar10H/ -s GLAD

```



```

from scipy.stats import pearsonr
def corrfunc(x, y, ax=None, **kws):
    r, _ = pearsonr(x, y)
    ax = ax or plt.gca()
    ax.annotate(rf'$\rho$ = {r:.2f}', xy=(.1, .9), xycoords=ax.transAxes)
results = {'glad': [], "entropy": []}
path = Path.cwd() / "datasets" / "cifar10H" / "identification"
results["entropy"] = np.load(path / 'entropies.npy')
results["glad"] = np.exp(np.load(path / "glad" / "difficulties.npy")[:, 1])
# results["waum"] = pd.read_csv(path / "resnet34" / "waum_0.01_yang" / 'waum.csv')['waum'].values
results = pd.DataFrame(results)
g = sns.pairplot(results, corner=True, diag_kind="kde")
g.map_lower(corrfunc)

# axes = g.axes.flatten()
# for i, ax in enumerate(axes):
#     if i % len(results) == 0:

plt.show()

```

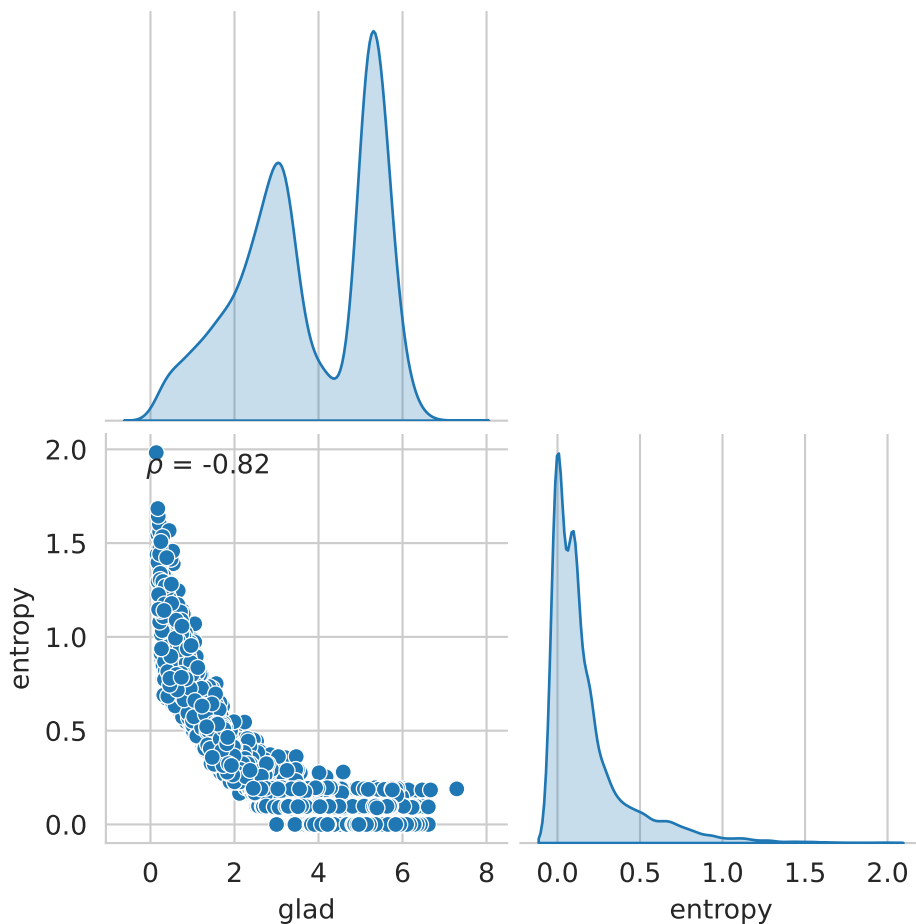


Figure 7: Comparison of metrics scoring the task's intrinsic difficulty.

### 5.1.2 LabelMe dataset

```
! peerannot identify ./datasets/labelme/ -s entropy -K 10 --labels ./datasets/labelme/answers.js
! peerannot aggregate ./datasets/labelme/ -s GLAD
```

```
from scipy.stats import pearsonr
def corrfunc(x, y, ax=None, **kws):
    r, _ = pearsonr(x, y)
    ax = ax or plt.gca()
    ax.annotate(rf'$\rho$ = {r:.2f}', xy=(.1, .9), xycoords=ax.transAxes)
results = {'glad': [], 'entropy': []}
path = Path.cwd() / "datasets" / "labelme" / "identification"
results["entropy"] = np.load(path / 'entropies.npy')
results["glad"] = np.exp(np.load(path / "glad" / "difficulties.npy")[:, 1])
results = pd.DataFrame(results)
g = sns.pairplot(results, corner=True, diag_kind="kde")
g.map_lower(corrfunc)
plt.show()
```

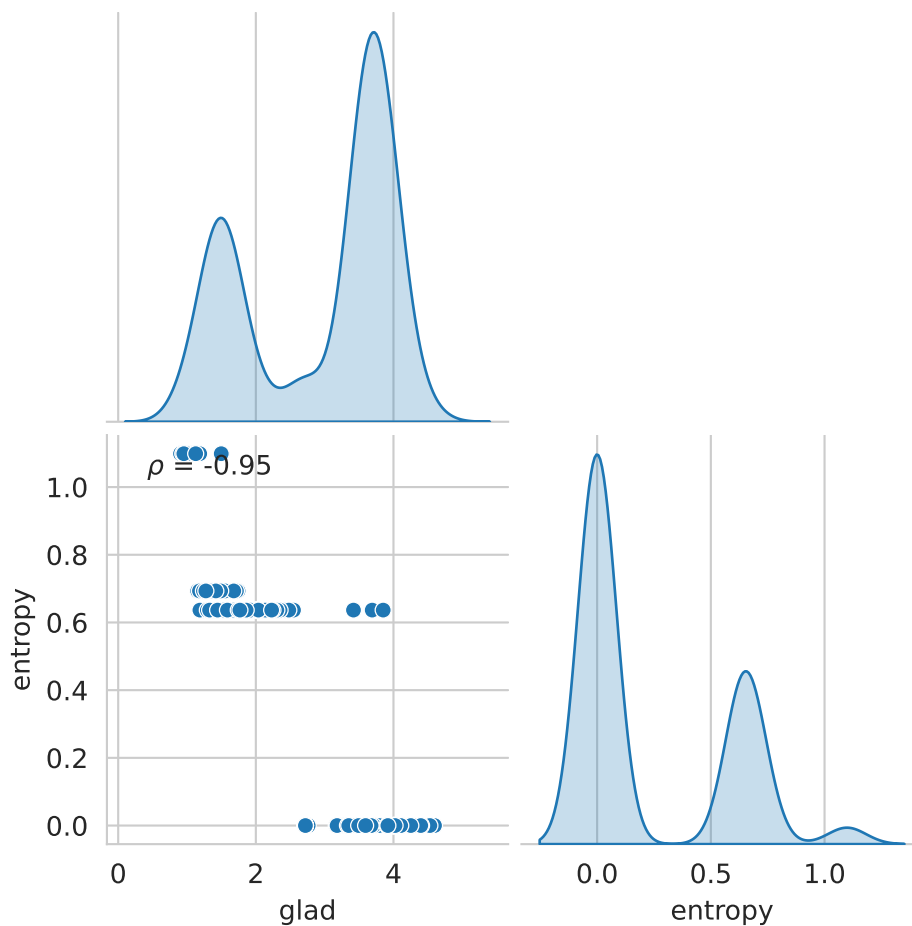


Figure 8: Comparison of metrics scoring the task's intrinsic difficulty.

## 5.2 Exploring workers' reliability

From the labels, we can explore different worker evaluation scores. GLAD's strategy estimates a reliability scalar coefficient  $\alpha_j$  per worker. With strategies looking to estimate confusion matrices, we investigate two scoring rules for workers:

- the trace of the confusion matrix: the closer to K the better the worker,
- the spammer score (Raykar and Yu 2011) that is the Frobenius norm between the estimated confusion matrix  $\hat{\pi}^{(j)}$  and the closest rank-1 matrix. The further to zero the better the worker.

When the tasks are available, confusion-matrix-based deep learning models can also be of use. We thus add to the comparison the trace of the confusion matrices with CrowdLayer and CoNAL on the datasets. For CoNAL, we only consider the trace of the confusion matrix  $\pi^{(j)}$  in the pairwise comparison, and provide the common confusion matrix  $\pi^g$  as separate.

### 5.2.1 CIFAR-10H

The Cifar-10H dataset has few disagreements among workers. From XXX, we can see that

```
! peerannot aggregate ./datasets/cifar10H/ -s GLAD
for method in ["trace_confusion", "spam_score"]:
    ! peerannot identify ./datasets/cifar10H/ --n-classes=10 \
        -s {method} --labels ./datasets/cifar10H/answers.json
```

```
path_ = Path.cwd() / "datasets" / "cifar10H"
results_identif = {"trace_confusion": [], "spam_score": [], "glad": []}
results_identif["trace_confusion"].extend(np.load(path_ / 'identification' / "traces_confusion.npy"))
results_identif["spam_score"].extend(np.load(path_ / 'identification' / "spam_score.npy"))
results_identif["glad"].extend(np.load(path_ / 'identification' / "glad" / "abilities.npy")[:, 1])
results_identif = pd.DataFrame(results_identif)
g = sns.pairplot(results_identif, corner=True, diag_kind="kde")
g.map_lower(corrfunc)
plt.show()
```

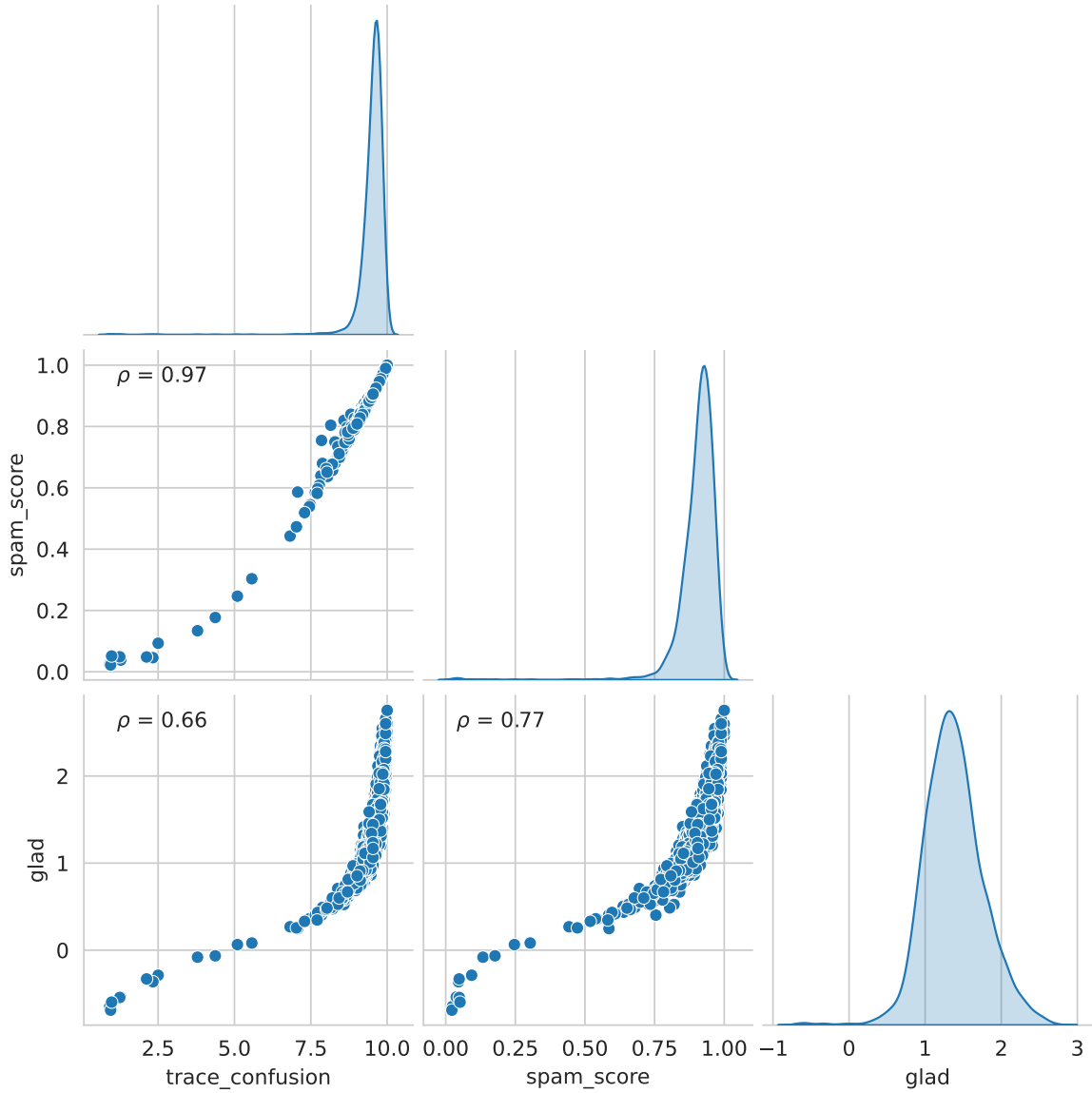


Figure 9: Comparison of ability scores by workers for the CIFAR-10H dataset.

### 5.2.2 LabelMe

```
! peerannot aggregate ./datasets/labelme/ -s GLAD
for method in ["trace_confusion", "spam_score"]:
    ! peerannot identify ./datasets/labelme/ --n-classes=10 \
        -s {method} --labels ./datasets/labelme/answers.json
```

```
path_ = Path.cwd() / "datasets" / "labelme"
results_identif = {"trace_confusion": [], "spam_score": [], "glad": []}
results_identif["trace_confusion"].extend(np.load(path_ / 'identification' / "traces_confusion.npy"))
results_identif["spam_score"].extend(np.load(path_ / 'identification' / "spam_score.npy"))
results_identif["glad"].extend(np.load(path_ / 'identification' / "glad" / "abilities.npy")[:, 1])
results_identif = pd.DataFrame(results_identif)
```

```
g = sns.pairplot(results_identif, corner=True, diag_kind="kde")
g.map_lower(corrfunc)
plt.show()
```

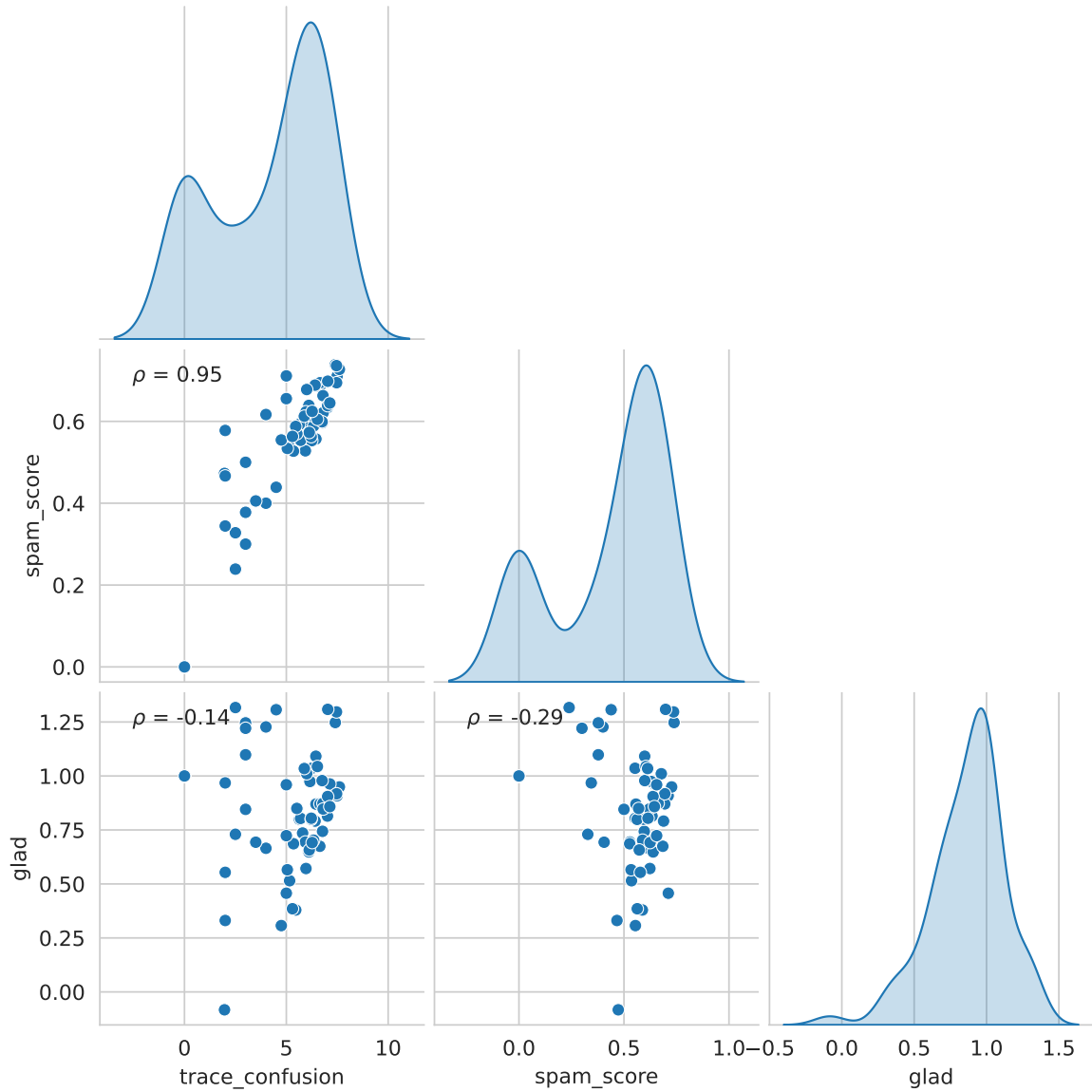


Figure 10: Comparison of ability scores by workers for the CIFAR-10H dataset.

## 6 Conclusion

We introduced peerannot, a library to handle crowdsourced datasets. This library enables both easy label aggregation and direct training strategies with classical state-of-the-art classifiers. The identification module of the library allows exploring the collected data from both the tasks and the workers' point of view for better scorings and data cleaning procedures. Our library also comes with templated datasets to better share crowdsourced datasets and have strategies more uniform to test on.

We hope that this library helps reproducibility in the crowdsourcing community and also standardizes

training from crowdsourced datasets. New strategies can easily be incorporated into the open-source code [available on github](#). Finally, as peerannot is mostly directed to handle classification datasets, one of our future works would be to consider other peerannot modules to handle crowdsourcing for object detection, segmentation and even worker evaluation in other contexts like peer-grading.

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