

Winning Space Race with Data Science

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Outline

- Executive Summary
- Introduction
- Methodology
- Results
- Conclusion
- Appendix

Executive Summary

- Summary of methodologies
- 1. from problem to approach
- 2. working with the data
- 3. Deriving the answer
- Summary of all results

Introduction

- Project background and context
- The commercial space age is here, companies are making space travel affordable for everyone. The most successful is SpaceX. Now SpaceY want to compete with it.
- Problems you want to find answers
- You will also determine if SpaceX will reuse the first stage.
- Instead of using rocket science to determine if the first stage will land successfully,
- you will train a machine learning model and use public information to predict if SpaceX
- will reuse the first stage.



Methodology

Executive Summary

- Data collection methodology:
 - Make a get request to SpaceX API
- Perform data wrangling
 - Using Mean value of PayloadMass to replace it's the missing value
- Perform exploratory data analysis (EDA) using visualization and SQL
- Perform interactive visual analytics using Folium and Plotly Dash
- Perform predictive analysis using classification models
 - How to build, tune, evaluate classification models

Data Collection

- Describe how data sets were collected.
- 1. Request and parse the SpaceX launch data using the GET request
- 2. Filter the DataFrame to only include Falcon 9 launches
- 3. Dealing with missing value (using mean value to replace the missing)

Data Collection - SpaceX API

- Present your data collection with SpaceX REST calls using key phrases and flowcharts
- Add the GitHub URL of the completed SpaceX API calls notebook, as an external reference and peer-review purpose
- https://github.com/tanglily08/IBM-data-science-finalproject/blob/c8eb934d06a503b6ea7fb050e491a887669f15bd/spacexcollecting-date-ds-final1%20(2).ipynb



b"[["fairings":{"reused":false,"recovery attempt":false,"recovered ":false,"ships":[]],"links":{"patch":{"small":"https://images2.ingbox.com/94/f2/NNGPM5Fv.o.png","lange":"https://images2.ingbox.com/54/02/QcHMb5Vv.o.png"},"reddit":{"campaign":null,"launch":null, "media":nul 1, "recovery: :mull], "flicko": "small": [], original": [], "preskit": mull, "mebcast": "https://www.youtube.com/watch?v=00 0001 7000", "youtube id": "00 00001 7000", "article": "https://www.space.com/2196-spacev-inaugural-falcon-1-rocket-lost-launch.html", "wikipedia": ia.org/miki/DemoSat"), "static fire date utc": "2006-03-17700-00:00.0002", "static fire date univ":1142555000, "net":false, "minbow":0, "rocket": "Seddo05edo609557700dleb", "success":false, "fallures":[("time":33, "altitude":mull, "reason"."merlin engine failure")], "details": "Engine failure at 33 seconds and loss of vehicle', "crew': |], 'ships': |], 'capsules': |], 'payloads': "Sebe-disb6cobb0006eeble!'], 'launchpad': "Seive-Si02E5909995de566786', "Flight number':1, "name": FaiconSat", 'date utc': '2006-03-24722:30:00.0002', 'date uniu': 1143239400, 'date local': '2006-03-15710:30:00+11:00", "date precision: "hour", "upcoming 'sfalse, "cores":[["core":"Sepe209df5951003535325", "flight":1, "gridfins' sfalse, "leays-false, "reused":false, "landing attempt":false, "landing success":mull, "landing type":mull, "landpad":mull], "auto update":true, "tbd":fa lse, 'launch library id' :null, 'id': 'Sebārodsffd66600000452a''], ('fairings': 'reused' :false, 'recovery attempt' :false, 'recovered' :false, 'ships': '[]}, 'links': '{"patch': ("small': 'https://images2.imgbox.com/f09/4a/lbb0xfl2a''), 'fairings': 'reused' :false, 'recovery attempt' :fals png", "reddit": "campaign":null, "launch":null, "media ":null, "recovery":null, "flicko": ("snall":[], "original":[]), "presskit":null, "nebasst": "https://naw.youtube.com/natch?v=kkat@AP-Nc", "article": "https://naw.space.com/3590-spacer-fa ils-reach-orbit.html", "nakipedia": "https://en.wikipedia.org/wiki/DemoSat"), "static fire date_wit": "mull, "static fire date_win": "wull, "net": false, "window": 0, "rocket": "5e000095e060099557000dieb", "success": false, "failures": [("time": 301, "altitude": 200, "reason": on leading to premature engine shutdown")], "details": "Successful first stage burn and transition to second stage, maximum altitude 200 km, Premature engine shutdown at TAT min 30 s, Failed to reach orbit, Failed to recover first stage", "creu":[], "ships":[], "capsules":[], "pa yloads':["Seb040blocibb0006eeble2"], "launchpad':"5e94502f5090995de566f06", 'flight number':2, "name":"DemoSat', "date utc':"2007-03-21710:10:00.0002", "date univ':1174439400, "date local":"2007-03-21713:10:000+12:00", "date precision":"hour", "upcoming":false, "cores':"["core":"Se 9e209e759918416a3b2624","filght":1,"griffins":false,"legs":false,"reused":false,"landing attempt":false, landing success":wull, 'landing type":wull, 'landing type":will, 'landing type":will, 'landing type":will, 'landing bybe":filley, 'landing with the state of the d':false, "recovery attempt':false, "recovery":false, "recovery:false, "recovery:f km":["small":[],"original":[]],"presskit":null, "mekcast":"https://mmw.youtube.com/metch?w=0009300860", "youtube id":"00090008600", "article":"http://mm.spacew.com/meus/2013/02/11/falcon-1-flight-3-mission-summary", "idkipedia":"https://en.wikipedia.org/ndki/Trailblater (sate llite)", "static fire date utc: "null, "static fire date unix: "null, "net" ifalse, "hindon":0, "nocket", "Sed0055ed60955f70001eb", "success" ifalse, "failures":[{"time":140,"altitude":35, "reason": "residual stage-1 thrust led to collision between stage 1 and stage 2"}], "details": "Ne sidual stage 1 thrust led to collision between stage 1 and stage 2", "cren": [], "ships": [], "capsules": [], "payLoads": ["Seb0e46b66;3b0006eeble3", "Seb0e46b66;3b0006eeble4"], "launchood": "Se8e450275909995de566766", "Flight number": 3, "name": "Trailblazer", "date utc": "2000-00-03703: 34:00.0002", "date unix":1217734440, "date local": "2000-00-00715:34:00+12:00", "date precision": "hour", "upcoming sfalse, "cores": [6" cores": [6" cores": "Sept200ef359101407302612", "flight": 1," "gridfins": false, "legs": false, "reused": false, "landing attempt": false, "landing success": null, "landing to the precision of ype":mull,"landpad":mull]]["auto update":true,"tbd":false,"launch library.id":mull,"id":"SebtTcdbffd86e000040312"],"fairings":["reused":false, "recovery attempt":false, "recovered":false, "recovered":false, "ships":[]], "links":["patch":["small":"https://images.Linghou.com/95/39/98q0frsv o.po g", "large": "https://inages2.ingbox.com/a3/99/gswM768 o.png"), "reddit": "Campaigm": mull, "launch": mull, "nedda": mull, "recovery": mull), "flicko"; "Small": [], "original": []), "pressicit": mull, "webcast": "https://www.youtube.com/work-duptit109600", "portube id": "duptit196600", "articl

Data Collection - Scraping

- Present your web scraping process using key phrases and flowcharts
- Add the GitHub URL of the completed web scraping notebook, as an external reference and peer-review purpose
- https://github.com/tanglily08/IBM-data-science-finalproject/blob/c8eb934d06a503b6ea7fb050e491a887669f15b d/webscraping-datascience-final2.ipynb

| TASK 1: Request the Falcon9 Launch Wiki page from its URL |
|--|
| First, let's perform an HTTP GET method to request the Falcon® Launch HTML page, as an HTTP response. |
| <pre># use requests.get() method with the provided static_url # assign the response to a object data = requests.get(static_url)</pre> |
| Create a BeautifulSoup object from the HTML response |
| # Use BeautifulSoup() to create a BeautifulSoup object from a response text content soup = data.BeautifulSoup() |
| AttributeFrror Traceback (most recent call last) /tmp/lapkernel_27/955580057.py in cmodule> 1 # Use BeautfulSomp() to create a BeautfulSomp object from a response text content > 2 soup = data BeautfulSoup() AttributeFrror: "Response" object has no attribute "BeautfulSoup" |
| Print the page title to verify if the BeautifulSoup, object was created properly |
| # Use soup.title attribute print(soup.title) |
| TASK 2: Extract all column/variable names from the HTML table header |

Data Wrangling

- Describe how data were processed
- You need to present your data wrangling process using key phrases and flowcharts
- Add the GitHub URL of your completed data wrangling related notebooks, as an external reference and peer-review purpose
- https://github.com/tanglily08/IBM-data-science-final-project/blob/c8eb934d06a503b6ea7fb050e491a887669f15bd/labs-jupyter-spacex-Data%20wrangling.ipynb

EDA with Data Visualization

- Summarize what charts were plotted and why you used those charts
- 1. <u>Catplot</u>
- 2. Barplot
- 3. Scatterplot
- 4. <u>Lineplot</u>
- Add the GitHub URL of your completed EDA with data visualization notebook, as an external reference and peer-review purpose
- https://github.com/tanglily08/IBM-data-science-final-project/blob/c8eb934d06a503b6ea7fb050e491a887669f15bd/spacex-explor-prepare-data-datascience-final4.ipynb

EDA with SQL

- Using bullet point format, summarize the SQL queries you performed
- 1. <u>selectQuery = "select launchsite from spacex"</u>
- 2. selectQuery2 = "select launchsite from spacex where launchsite='CCA%' limit 5"
- 3. <u>selectQuery3 = "select sum(PAYLOAD_MASS_KG_)</u> as sum_of_payload_mass from spacex_new "
- 4. <u>selectQuery4 = "select avg(payload mass kg) as a verage payload mass by F9v1 1 from spacex new where booster version = 'F9 v1.1'"</u>
- 5. <u>selectQuery5 = "select min(date) as first_success_landing from spacex_new where landingoutcome='Success'"</u>
- 6. selectQuery6 = "select booster_version from spacex_new where landingoutcome='Success (drone ship)' and (payload_mass_kg_>4000 and payload_mass_kg_<6000)"
- 7. <u>selectQuery7 = "select mission_outcome, count(mission_outcome) from spacex_new group by mission_outcome"</u>
- 8. selectQuery8 = "select booster version from spacex new where payload mass kg = (select max(payload mass kg) from spacex new)."
- 9. <u>selectQuery9 = "select booster_version,launch_site from spacex_new where YEAR(date) = 2015 and landing outcome = 'Failure (drone ship)'"</u>
- 10. <u>selectQuery10 = "select landingoutcome as landing_outcome, count(landingoutcome) as count_landing_outcome from spacex_new where date between '2010-06-04' and '2017-03-20' group by landingoutcome order by count(landingoutcome) desc"</u>
- Add the GitHub URL of your completed EDA with SQL notebook, as an external reference and peer-review purpose
- https://github.com/tanglily08/IBM-data-science-final-project/blob/c8eb934d06a503b6ea7fb050e491a887669f15bd/sql-notebook-datascience-final.ipynb

Build an Interactive Map with Folium

- Summarize what map objects such as markers, circles, lines, etc. you created and added to a folium map
- · I added markers and cirlcels.
- Explain why you added those objects
- Add the GitHub URL of your completed interactive map with Folium map, as an external reference and peer-review purpose
- https://github.com/tanglily08/IBM-data-science-final-project/blob/c8eb934d06a503b6ea7fb050e491a887669f15bd/interactive-visual-analytics-datascience-final5.ipynb

Build a Dashboard with Plotly Dash

- Summarize what plots/graphs and interactions you have added to a dashboard
- Explain why you added those plots and interactions
- Add the GitHub URL of your completed Plotly Dash lab, as an external reference and peer-review purpose
- https://github.com/tanglily08/IBM-data-science-final-project/blob/c8eb934d06a503b6ea7fb050e491a887669f15bd/spacex_dash_app.py

Predictive Analysis (Classification)

- Summarize how you built, evaluated, improved, and found the best performing classification model
- KNN Regression performs best
- You need present your model development process using key phrases and flowchart
- Add the GitHub URL of your completed predictive analysis lab, as an external reference and peer-review purpose
- https://github.com/tanglily08/IBM-data-science-final-project/blob/040bb1c94f9eb0da532011ded55c65da144a573f/spacex-ml-prediction-datascience-final7.ipynb

Results

- Exploratory data analysis results
- Logistic Regression performs best, because it got highest score, 1.
- Interactive analytics demo in screenshots

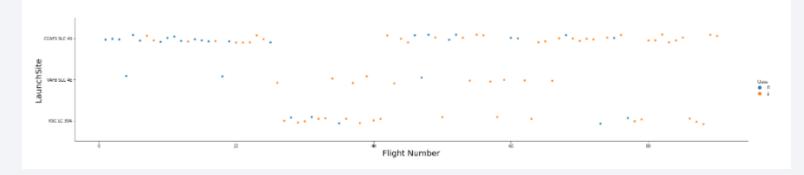


• Predictive analysis results



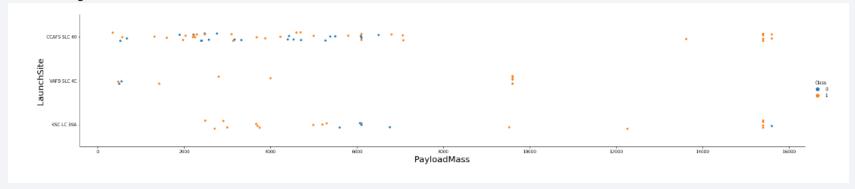
Flight Number vs. Launch Site

 Show a scatter plot of Flight Number vs. Launch Site



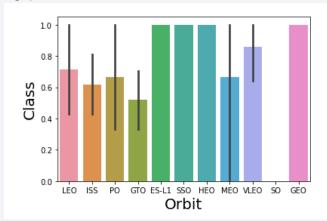
Payload vs. Launch Site

 Show a scatter plot of Payload vs. Launch Site



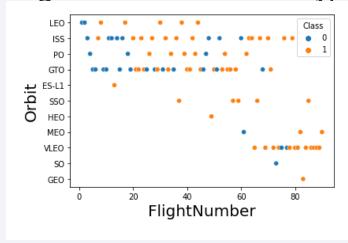
Success Rate vs. Orbit Type

 Show a bar chart for the success rate of each orbit type



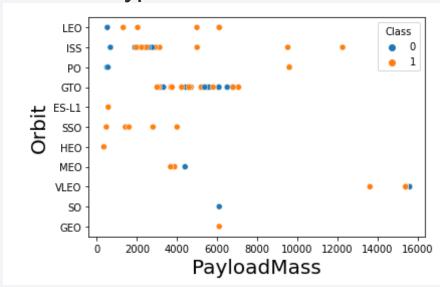
Flight Number vs. Orbit Type

 Show a scatter point of Flight number vs. Orbit type



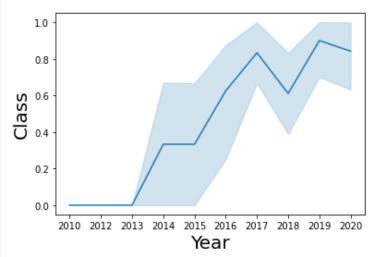
Payload vs. Orbit Type

 Show a scatter point of payload vs. orbit type



Launch Success Yearly Trend

 Show a line chart of yearly average success rate



All Launch Site Names

• Find the names of the unique launch sites



Launch Site Names Begin with 'CCA'

Find 5 records where launch sites begin with `CCA`

| [17]: | DATE | TIME_UTC_ | BOOSTER_VERSION | LAUNCH_SITE | PAYLOAD | PAYLOAD_MASSKG_ | ORBIT | CUSTOMER | MISSION_OUTCOME | LANDINGOUTCOME |
|-------|---------------------|-----------|-----------------|-------------|--|-----------------|-----------|-----------------|-----------------|---------------------|
| | 0 1974-04-02 | 18:45:00 | F9 v1.0 B0003 | CCAFS LC-40 | Dragon Spacecraft Qualification Unit | 0 | LEO | SpaceX | Success | Failure (parachute) |
| | 1 2002-04-04 | 15:43:00 | F9 v1.0 B0004 | CCAFS LC-40 | Dragon demo flight C1, two CubeSats, barrel of | 0 | LEO (ISS) | NASA (COTS) NRO | Success | Failure (parachute) |
| | 2 2012-05-22 | 7:44:00 | F9 v1.0 B0005 | CCAFS LC-40 | Dragon demo flight C2 | 525 | LEO (ISS) | NASA (COTS) | Success | No attempt |
| | 3 1931-04-11 | 0:35:00 | F9 v1.0 B0006 | CCAFS LC-40 | SpaceX CRS-1 | 500 | LEO (ISS) | NASA (CRS) | Success | No attempt |
| | 4 1977-04-12 | 15:10:00 | F9 v1.0 B0007 | CCAFS LC-40 | SpaceX CRS-2 | 677 | LEO (ISS) | NASA (CRS) | Success | No attempt |
| | | | | | | | | | | |

Total Payload Mass

Calculate the total payload carried by boosters from NASA

SUM_OF_PAYLOAD_MASS 619967

Average Payload Mass by F9 v1.1

Calculate the average payload mass carried by booster version F9 v1.1

AVERAGE_PAYLOAD_MASS_BY_F9V1_1
2928

First Successful Ground Landing Date

• Find the dates of the first successful landing outcome on ground pad

FIRST_SUCCESS_LANDING 2018-03-12

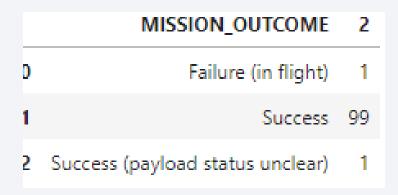
Successful Drone Ship Landing with Payload between 4000 and 6000

 List the names of boosters which have successfully landed on drone ship and had payload mass greater than 4000 but less than 6000

| | BOOSTER_VERSION | | | |
|---|-----------------|--|--|--|
| 0 | F9 FT B1022 | | | |
| 1 | F9 FT B1026 | | | |
| 2 | F9 FT B1021.2 | | | |
| 3 | F9 FT B1031.2 | | | |

Total Number of Successful and Failure Mission Outcomes

Calculate the total number of successful and failure mission outcomes



Boosters Carried Maximum Payload

• List the names of the booster which have carried the maximum payload mass

| | BOOSTER_VERSION |
|----|-----------------|
| 0 | F9 B5 B1048.4 |
| 1 | F9 B5 B1049.4 |
| 2 | F9 B5 B1051.3 |
| 3 | F9 B5 B1056.4 |
| 4 | F9 B5 B1048.5 |
| 5 | F9 B5 B1051.4 |
| 6 | F9 B5 B1049.5 |
| 7 | F9 B5 B1060.2 |
| 8 | F9 B5 B1058.3 |
| 9 | F9 B5 B1051.6 |
| 10 | F9 B5 B1060.3 |
| 11 | F9 B5 B1049.7 |
| | |

2015 Launch Records

• List the failed landing_outcomes in drone ship, their booster versions, and launch site names for in year 2015

BOOSTER_VERSION LAUNCH_SITE

F9 v1.1 B1015 CCAFS LC-40

Rank Landing Outcomes Between 2010-06-04 and 2017-03-20

 Rank the count of landing outcomes (such as Failure (drone ship) or Success (ground pad)) between the date 2010-06-04 and 2017-03-20, in descending order

| | LANDING_OUTCOME | COUNT_LANDING_OUTCOME |
|---|------------------------|-----------------------|
| 0 | Failure (drone ship) | 3 |
| 1 | No attempt | 3 |
| 2 | Success (drone ship) | 3 |
| 3 | Success (ground pad) | 3 |
| 4 | Controlled (ocean) | 2 |
| 5 | Uncontrolled (ocean) | 2 |
| 6 | Precluded (drone ship) | 1 |



<All US Launchsite>

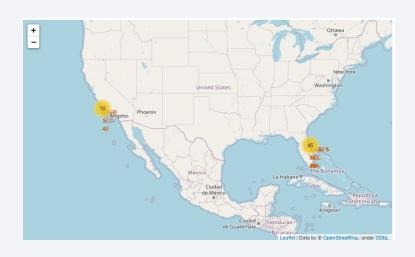
• Explore the generated folium map and make a proper screenshot to include all launch sites' location markers on a global map

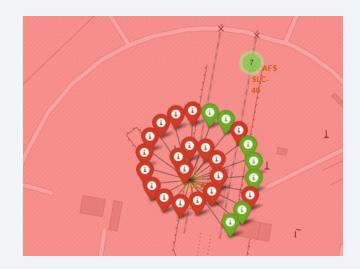


- Explain the important elements and findings on the screenshot
- All launch sites are close to ocean.

<Launch sites with success marker>

• Explore the folium map and make a proper screenshot to show the colorlabeled launch outcomes on the map

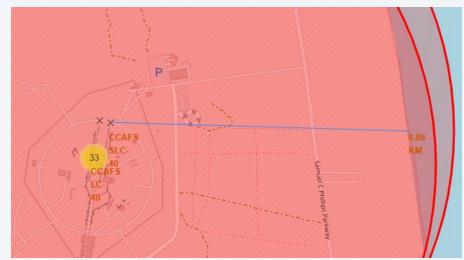




- Explain the important elements and findings on the screenshot
- KCFS-39 site has the most success rate

<Launch site distance from ocean>

 Explore the generated folium map and show the screenshot of a selected launch site to its proximities such as railway, highway, coastline, with distance calculated and displayed

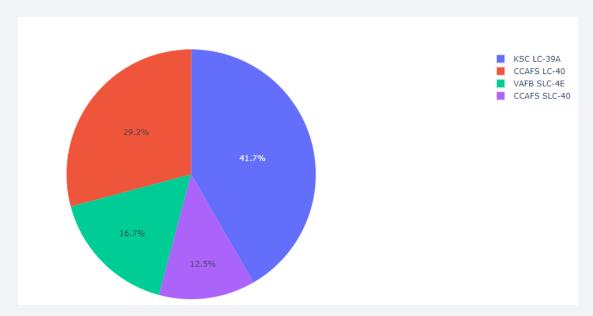


- Explain the important elements and findings on the screenshot
- All launch sites are close to ocean, railway and highway. I think it is for safety and easy to transport.



<Launch success count for all sites>

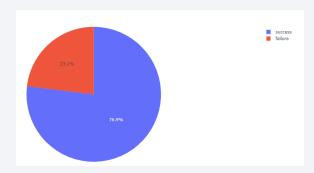
• Show the screenshot of launch success count for all sites, in a piechart



- Explain the important elements and findings on the screenshot
- KSC LX-39A got the most success rate.

<success rate for KSC LC-39A>

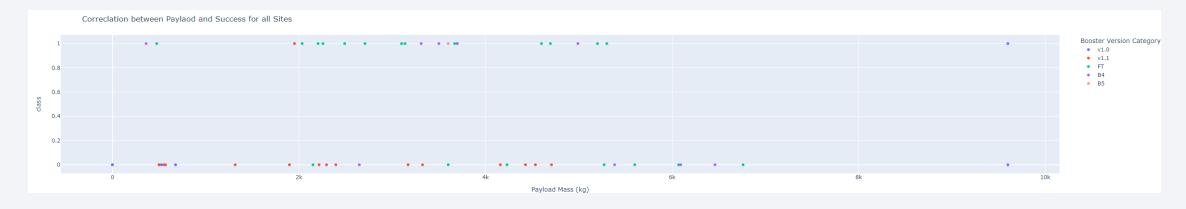
• Show the screenshot of the piechart for the launch site with highest launch success ratio



• Explain the important elements and findings on the screenshot

<Payload vs launch Outcome>

• Show screenshots of Payload vs. Launch Outcome scatter plot for all sites, with different payload selected in the range slider



- Explain the important elements and findings on the screenshot, such as which payload range or booster version have the largest success rate, etc.
- Between 2K-5K payload, FT have the most success rate.



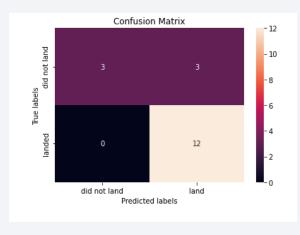
Classification Accuracy

• Visualize the built model accuracy for all built classification models, in a bar chart

• Find which model has the highest classification accuracy

Confusion Matrix

- Show the confusion matrix of the best performing model with an explanation
- K Means Clustering is the best model.



Conclusions

- 1. ES-L1, SSO, HEO, GEO orbits have the most success rate.
- 2. All launch sites are close to ocean. KCFS-39 has the most success rate.
- 3. Between 2K-5K payload mass, Booster version FT has the most success rate
- 4. K means clustering provide the best accuracy.

• ...

Appendix

• Include any relevant assets like Python code snippets, SQL queries, charts, Notebook outputs, or data sets that you may have created during this project

