

Tango training

client API - C++



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# outline

remarks

fundamental operations with examples

# C++ client side API

Each Tango device is an instance of a ***DeviceProxy***

- Easy connection building between clients and devices
- Manage re-connection
- Hide some IDL call details
- Hide some memory management issues

```
Tango::DeviceProxy mydev("sys/tg_test/1");
```

```
Tango::DeviceProxy *ptrdev;  
ptrdev = new DeviceProxy("sys/tg_test/1");  
delete ptrdev;
```

# Errors

Errors throw exceptions (clean, standard O.O. style)

Tango exceptions inherit from **DevFailed** class:

- one catch is enough for Tango errors
- 10 exceptions classes derived from DevFailed allow detailed analysis:

ConnectionFailed, CommunicationFailed, WrongNameSyntax,  
NonDbDevice, WrongData, NonSupportedFeature,  
AsyncCall, AsyncReplyNotArrived, EventSystemFailed,  
NamedDevFailedList

see documentation

# reading an attribute

- *DeviceProxy* *read\_attribute* method
- class *DeviceAttribute* is used for the received data
- overloaded operators for extracting data

```
DeviceAttribute DeviceProxy::read_attribute(string&) ;
```

see example: `reading01.cpp`

# reading an attribute

- DeviceAttribute contains **lots** of informations:
  - name of attribute
  - timestamp
  - dim\_x, dim\_y
  - type
  - quality factor
  - setpoint of a r\_w variable    **IMPORTANT !!**

see example: reading02.cpp

# reading vector (spectrum)

- overloaded operators for extracting data into:
- a DevVar\*Array structure:

```
DevVarDoubleDouble *outdvarray;  
da >> outdvarray;
```

- data is consumed, user get ownership, must free data
- `std::vector<>` of element:

```
vector<double> outvect; da >> outvect;
```

- easier to handle, data not consumed

see example: `reading03.cpp` , manual

# writing an attribute

*DeviceProxy* `write_attribute` method

```
void DeviceProxy::write_attribute(DeviceAttribute&) ;
```

object of class `DeviceAttribute` used to name the attribute and send the data. Constructors and insertion operators are defined for all the Tango types.

see example: `writing01.cpp`



# writing vector (spectrum)

DeviceAttribute must be filled with a `std::vector<*>` using overloaded operators (easier, preferred)

It is also possible to use a `DevVar*Array` structure.

In this case the data ownership will be transferred to the ORB  
no need to call delete.

see example: `writing02.cpp`

# executing commands

*DeviceProxy* `command_inout` method sends a command to the device

class `DeviceData` is used for sending and receiving command data to and from the device.

```
DeviceData DeviceProxy::command_inout(const char*,  
DeviceData&) ;
```

data is inserted / extracted in/from `DeviceData` by means of overloaded operators.

Pay attention to types!

see example: `command01.cpp`

# asynch calls

reads, writes, and commands can be executed *asynchronously* by the client.

The call is split in two phases:

- 1) invocation
- 2) result reading

May be useful when the server response is slow, the client can do other things while the server is working.

We present examples of asynch calls for `read_attribute` only, but the same concepts apply to `write_attribute` and `command_inout`.

# asynch call models

The asynch calls follow three distinct models:

- polling model
- callback pull model
- callback push model

# polling model

The client calls `read_read_attribute_async()`, actively polls the server to detect when the response arrives and eventually extracts the data.

```
long request_id = dev->read_attribute_async(attname);
```

```
....
```

```
DeviceAttribute* da;
```

```
da = dev->read_attribute_reply(request_id,wait_time_ms);
```

Simple model , easy to manage. If `wait_time_ms` is 0, the call blocks untill the response arrives.

The key for getting the reply is `request_id`

See example `asynread01.cpp` for more details and exception handling.

# callback poll model

The client prepares a *callback* which will be invoked for extracting and reading the attribute value. The callback is a class derived from `Tango::CallBack`; as a minimum the virtual method `read_attr(AttrReadEvent*)` must be implemented. The `read_attr` method is in charge of extracting the attribute value and passing it to client.

```
ReadCallBack rd_short_cb;  
  
dev->read_attribute_async(attname, rd_short_cb);  
  
....  
  
dev->get_async_replies(wait_time_ms);
```

When `get_async_replies` is called, if data is ready, `ReadCallBack::read_attr()` method is called.

More complicated data handling !

The clients maintains some control on the timing of the callback execution.

See example `asynread02.cpp` for more details and exception handling.

We will use `Tango::CallBack` when dealing with events.

# callback push model

The client prepares a *callback* which will be invoked for extracting and reading the attribute value. The callback is a class derived from `Tango::CallBack`; as a minimum the virtual method `read_attr(AttrReadEvent*)` must be implemented. The `read_attr` method is in charge of extracting the attribute value and passing it to client. The client must also set globally the callback model

```
ReadCallBack rd_short_cb;  
  
ApiUtil::instance()->set_async_cb_sub_model(PUSH_CALLBACK);  
  
dev->read_attribute_async(attname, rd_short_cb);
```

When data is ready, `ReadCallBack::read_attr()` method is called, in a completely asynchronous mode.

The client **has no control** on the timing of the callback execution!  
See example `asynread03.cpp` for more details and exception handling.

# callback push model

Last example of asynch feature is the execution of a command.

In this case the Callback class must implement the `cmd_ended()` method.

```
CmdCallback cmd_short_cb;
```

```
ApiUtil::instance()->set_asynch_cb_sub_model(PUSH_CALLBACK);
```

```
dev->command_inout_asynch(attname, cmd_short_cb);
```

When data is ready, `CmdCallback::cmd_ended()` method is called, in a completely asynchronous mode.

The client **has no control** on the timing of the callback execution!

See example `asyncmd01.cpp` for more details and exception handling.



# asynch pros/cons

## pros:

- client is not bound by slow server response
- client can interact with several devices “in parallel”

## cons:

- more complex logic flow
- time and order of arrival undetermined
- exception handling is duplicated
  - when calling the asynch method
  - when extracting data

# event subscription

Clients do not poll: polling is done in Server : polling thread.

Server must be configured/written to generate events.

Server sends data to interested client when “something” changes.

Clients must *subscribe* to events and handle *asynchronous* data.

# event subscription

Client creates an object derived from `Tango::Callback` implementig the relevant `push_event(...)` method.

`push_event(...)` is exeucted upon arrival of the event.

Upon successful subscrition at least one event is sent by server.

Client calls `unsubscribe_event()` when no more events are needed.

# event subscription

by default Event subscription fails if Server does not support the requested event.

- if *stateless* is set to true subscription succeeds anyway, and events will be received when the server is up and correctly configured!

Heartbeat : client is notified if server is not reachable via event (exception is notified to callback)

Heartbeat automatically re-subscribes event again when server becomes reachable again.

see: event01.cpp

# Group

Provides a single point of control for a group of devices: client performs a ***read/write\_attribute*** or ***command\_inout*** to all the devices with a single call.

Group calls are internally executed asynchronously:  
speed!

Client creates a `Tango::Group`, then adds devices

It is also possible to add a Group object to a Group to create a hierarchical object (advanced feature).

# Group

Devices are added by *name*.

Wildcard \* can be used in any part of the name ( \*/\*/\* : whole control system).

Groups are really useful when:

- Devices have uniform interfaces: use AbstractClasses
- there is a consistent and rational naming convention for device names

-----> Design the control system as a whole, bottom-up AND top-down

Deployment and configuration of Devices is an important and delicate step in the building and maintenance of the control system.

# Group

no exceptions during Group calls

error are reported by GroupReplyList object:

- check `has_failed()` globally
- check `has_failed()` for each list element
  - can enable exceptions and get an exception while extracting a datum:
  - `GroupReply::enable_exceptions(true);`

# Group

Group can contain also other Groups

- hierarchical organization

The reply is not heriarchical!

Actions performed on a Group can be forwarded or not to subgroups

- default: forward
- turn off/on globally with statyc method on Group
- additional parameter for actions



# Group

with a Group a client can:

- excute command
  - without argument
  - with same iput argument to all members
  - with different input arguments for different members
- read one attribute
- write one attribute
  - with same value for all members
  - with different values for different members

see: `group01.cpp`

comprehensive examples on Tango manual

# device locking

A client can lock a device server to gain “exclusive” write access to the device:

```
dev->lock(); .... dev->unlock();
```

A client can verify/check the locking of a device:

```
dev->is_locked(); dev->is_locked_by_me();
```

```
dev->get_locker(LockerInfo&);
```

- the lock is reset if no actions is done by locker for an amount of time, if server is restarted, etc. Destroying DeviceProxy unlocks the device.

- **a client can force the unlocking of a device :**

```
dev->unlock(true);
```

- use locking with utmost restraint and care ...

# pipes

Pipe: new in tango-9 , can contain any combination of Tango types values, including other Pipe objects.

The structure of a Pipe may change at each reading/writing.

Each pipe value is named with a string.

Each pipe value has its type identifier.

- dynamically discovery of the structure

available only in C++ (jan. 2016)

# reading pipes

```
DevicePipe DeviceProxy::read_pipe(string&)
```

reads the named pipe, then clients must extract data from `DevicePipe` object.

In case the Pipe structure is known beforehand you can use directly the extract operator >>

see : `pipe01.cpp`

# reading pipes

If the DevicePipe structure is unknown or changes call-to-call, you have to analyze it in order to extract the values. Methods `get_data_elt_nb()`, `get_data_elt_name(i)`, `get_data_elt_type(i)` together with `>>` operator are the available tools.

see: pipe02.cpp first part

# writing pipes

Use `write_pipe()` method :

```
DeviceProxy::write_pipe(DevicePipe&)
```

You must first build and fill the `DevicePipe` object. You must set:

- pipe name
- number of elements
- names of elements
- element values

`DevicePipe` has methods on operators to do this

see `pipe02.cpp` second part

# special Tango types

`DevVarDoubleStringArray:`

holds together an array of strings and an array of *double*.  
Each array has its own length. N.B.: strings are of type  
`TangoDevString` .

`DevVarLongStringArray:`

holds together an array of strings and an array of *long*.  
Each array has its own length. N.B.: strings are of type  
`TangoDevString` .

see `tangotypes01.cpp`

# TangoDevString

`Tango::DevString` is a `char*`.

Use auxiliary functions from `CORBA` namespace:

`string_alloc()`, `string_dup()`, `string_free()`. Use C `strcpy()` for copying.

```
DevString mystring = CORBA::string_alloc(5);  
strcpy(mystring, "tango");  
DevString tangostring = CORBA::string_dup("pluto");  
CORBA::string_free(tangostring);  
CORBA::string_free(mystring);
```



# Sequences

`Tango::DevVar*Array` are CORBA IDL sequences mapped to C++ classes;

They behave like vectors of variable length

Defined for Tango basic types.

Can allocate and manage their own buffer or use a client supplied buffer for the array values.

There are operators for filling `std::vector<*>` to/from `DevVar*Array` Make life easier at the price of some memory copies.

see `devvar01.cpp`