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The graph representation of n-ary ordered state space and 2D state space used in CJupiter and
XJupiter, respectively.
{\tt EXTENDS}\ JupiterCtx,\ GraphsUtil
IsSS(G) \stackrel{\Delta}{=} A state space is a digraph with labeled edges.
       \wedge IsGraph(G) It is a digraph (represented by a record).
      \land G.node \subseteq (SUBSET\ Oid) Each node represents a document state, i.e., a set of Oid.
      \land G.edge \subseteq [from: G.node, to: G.node, cop: Cop] Labeled with a Cop operation.
EmptySS \stackrel{\triangle}{=} EmptyGraph
Locate(cop, ss) \stackrel{\Delta}{=} Locate the node in state space ss that matches the context of cop.
     CHOOSE n \in ss.node : n = cop.ctx
xForm(NextEdge(\_,\_,\_), r, cop, ss) \stackrel{\triangle}{=} Transform cop with an operation sequence
     LET u \triangleq Locate(cop, ss)
                                                        in state space ss at replica r.
           v \triangleq u \cup \{cop.oid\}
           RECURSIVE xFormHelper(\_, \_, \_, \_)
            xFormHelper(uh, vh, coph, xss) \stackrel{\triangle}{=}
                 IF uh = ds[r]
                  THEN [xcop \mapsto coph,
                            xss \mapsto xss, xss: eXtra ss created during transformation
                            lss \mapsto [node \mapsto \{vh\},
                                      edge \mapsto \{[from \mapsto uh, to \mapsto vh, cop \mapsto coph]\}]
                  ELSE LET e \stackrel{\triangle}{=} NextEdge(r, uh, ss)
                                 copprime \triangleq e.cop
                                  uprime \stackrel{\triangle}{=} e.to
                                  vprime \triangleq vh \cup \{copprime.oid\}
                                   coph2copprime \stackrel{\triangle}{=} COT(coph, copprime)
copprime2coph \stackrel{\triangle}{=} COT(copprime, coph)
                                  xFormHelper(uprime, vprime, coph2copprime,
                                      xss \oplus [node \mapsto \{vprime\},
                                               edge \mapsto \{[from \mapsto vh, to \mapsto vprime,
                                                              cop \mapsto copprime2coph,
                                                            [from \mapsto uprime, to \mapsto vprime,
                                                              cop \mapsto coph2copprime[]])
            xFormHelper(u, v, cop, [node \mapsto \{v\},
    IN
                                              edge \mapsto \{[from \mapsto u, to \mapsto v, cop \mapsto cop]\}])
xFormCopCops(cop, cops) \stackrel{\triangle}{=} Transform cop against cops on state space.
     LET RECURSIVE xFormCopCopsSSHelper(_, _, _)
            xFormCopCopsSSHelper(coph, copsh, xss) \stackrel{\triangle}{=}
                 LET u \triangleq coph.ctx

v \triangleq u \cup \{coph.oid\}
                   uvSS \stackrel{\Delta}{=} [node \mapsto \{u, v\},
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- Module GraphStateSpace -

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edge \mapsto \{[from \mapsto u, to \mapsto v, cop \mapsto coph]\}]
                         IF copsh = \langle \rangle THEN [xcop \mapsto coph,
                                                           xss \mapsto xss \oplus uvSS, lss \mapsto uvSS
                            ELSE LET copprimeh \stackrel{\triangle}{=} Head(copsh)

uprime \stackrel{\triangle}{=} u \cup \{copprimeh.oid\}
                                                \begin{array}{ll} uprime & \stackrel{\triangle}{=} & u \in \{corp....,\\ vprime & \stackrel{\triangle}{=} & u \cup \{coph.oid, copprimeh.oid\} \end{array}
                                            coph2copprimeh \stackrel{\triangle}{=} COT(coph, copprimeh)
                                             copprimeh2coph \triangleq COT(copprimeh, coph)
                                            xFormCopCopsSSHelper(coph2copprimeh,
                                                  Tail(copsh),
                                                 xss \oplus [node \mapsto \{u, v\},\]
                                                           edge \mapsto \{[from \mapsto u, \ to \mapsto v, \ cop \mapsto coph],\
                                                                         [from \mapsto u, to \mapsto uprime,
                                                                           cop \mapsto copprimeh],
                                                                         [from \mapsto v, to \mapsto vprime,
                                                                           cop \mapsto copprimeh2coph[\}]
             xFormCopCopsSSHelper(cop, cops, EmptySS)
     IN
xFormCopCopsShift(cop, cops, shift) \triangleq
                                  shifting the first shift elements out of cops
     xFormCopCops(cop, SubSeq(cops, shift + 1, Len(cops)))
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<sup>\ \*</sup> Modification History

<sup>\*</sup> Last modified Sat Jan 19 16:32:38 CST 2019 by anonymous

<sup>\*</sup> Created Wed Dec 19 18:15:25 CST 2018 by anonymous