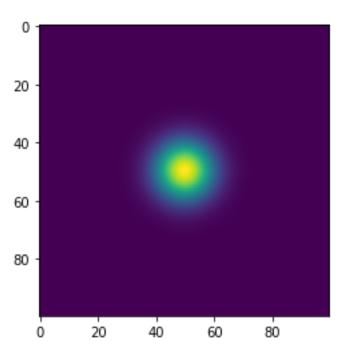
Step 1:

gkern(100,100,20)



gkern(100,100,30)

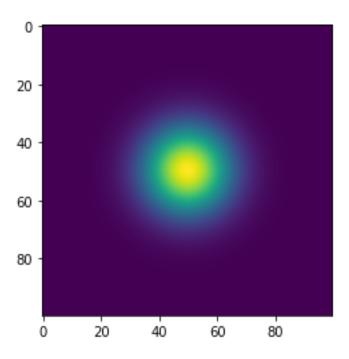
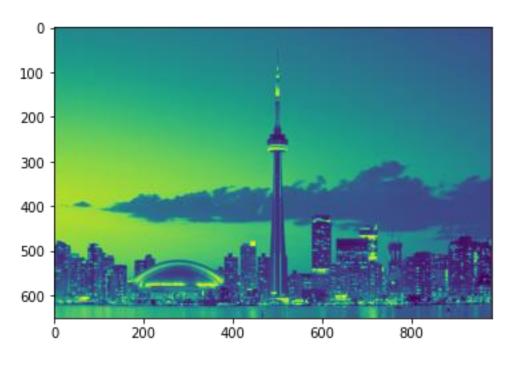
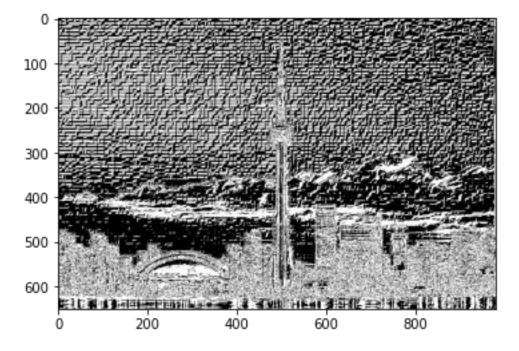


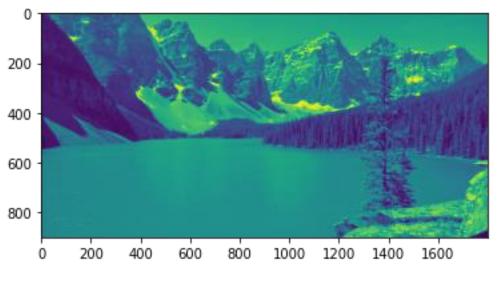
Image 1(convert to grayscale)



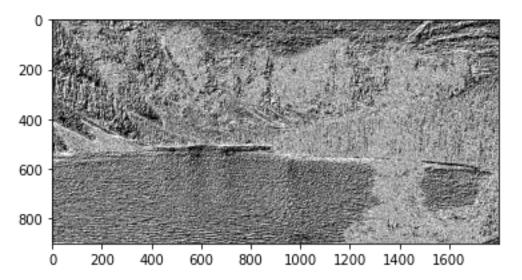
Edge detection image1



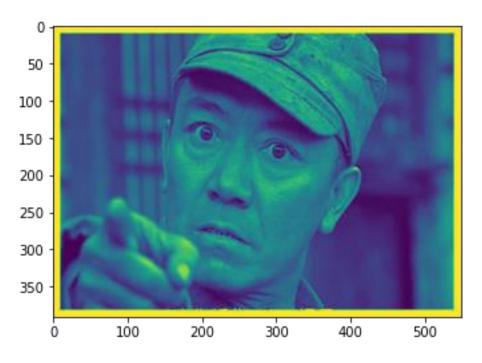
# Image 2(convert to grayscale)



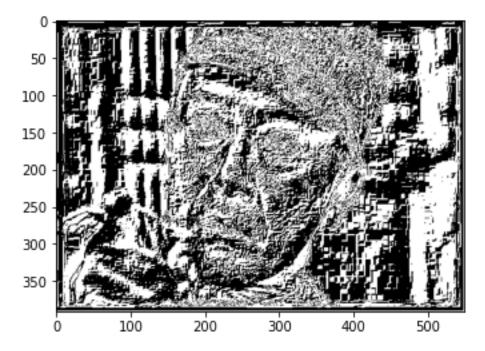
Edge detection image2



## Image 3(grayscale)



Edge detection image3



#### Discussion

#### Weakness:

- 1. When the color contrast in the specific area is not high enough, in such a case, the edge detection output becomes blurred. The edges cannot be shown clearly. For example, in the bottom area of image1, edges of the building are not clear to separate the building since the original image does not have high contrast. For image2, the upper area, the edges of the sky and mountain does not separate clearly.
- 2. The time consuming, it would spend some time to do the iterations in the algorithm and every pixel needs to have comparisons, so it takes long.

### Strength:

- 1. When the color contrast is high enough, the edges are very clear, for example the CN tower in the image1.
- 2. The threshold algorithm would not change the original image and just operated on the original image to find the edge detection output
- 3. The threshold value is found automatically so we don't need to determine by ourselves.