

Geometric transformations
Similarity | Isometry

Geometric Transformation

A **geometric transformation T** is a correspondence that associates with each point P of the plane one and a single point P' of the plane, under the following conditions:

- a) if P and Q are two distinct points, then the corresponding points P' and Q' are also distinct,
- b) if R is any point of the plane, then there is a point S in the plane such that its correspondent by geometric transformation T is R.

Similarity

A geometric transformation S is a **similarity** if it preserves the ratios between lengths of segments, that is, given any three points A, B, and C, the equality $\overline{AB}/\overline{BC} = \overline{A'B'}/\overline{B'C'}$ is verified in which $A'=S(A)$, $B'=S(B)$, $C'=S(C)$.

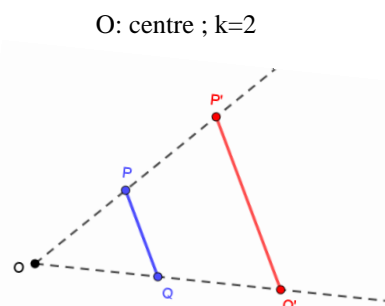
In a similarity, the distances between each two points are multiplied by a constant ($r = \overline{A'B'}/\overline{AB} = \overline{B'C'}/\overline{BC}$), called scale factor, usually represented by r.

Dilation of centre O and scale factor k

Dilation D of centre O and scale factor k does correspond to each point P of the plane the point P'=D(P) of the plane, under the following conditions:

- a) $D(O)=O$, that is, the centre O is a fixed point for dilation,
- b) If $P \neq O$, P' is on the OP line and
 - $\overline{OP'}/\overline{OP} = |k|$,
 - P and P' are on the same side or on opposite sides, relative to O, as k is positive or negative.

[P'Q'] is the image of [PQ]



$|k| > 1$, dilation image is larger than original figure – enlargement
 $|k| = 1$, dilation image is the same size than original figure – (isometry)
 $0 < |k| < 1$, dilation image is smaller than original figure – reduction

Dilation involves “resizing” the figure, resulting in an enlargement or a reduction.

Isometry (Isometric Transformation)

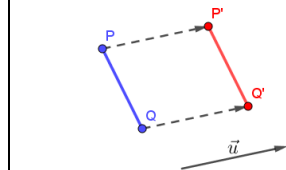
A geometric transformation I is an **isometry** (isometric transformation) if, for any two points P and Q , it has $\text{dist}(P', Q') = \text{dist}(P, Q)$, where $P' = I(P)$ and $Q' = I(Q)$.

An isometry preserves the distances, and the figures are transformed into congruent figures.

Translation associated to vector \vec{u}

Translation associated to vector \vec{u} is a geometric transformation in which each P point of the plane is transformed into another point P' (image of P), with $P' = P + \vec{u}$.

$[P'Q']$ is the image of $[PQ]$



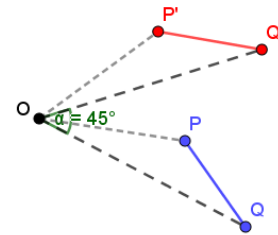
Translation involves “sliding” the figure from one position to another.

Rotation of centre O and amplitude α

Rotation of centre O and amplitude α is a geometric transformation such that:

- whatever the point P of the plane, the distance from O to P is equal to the distance from O to the image of P (P'),
- the amplitude of the oriented angle defined by P , O and P' is equal to α .

$[P'Q']$ is the image of $[PQ]$



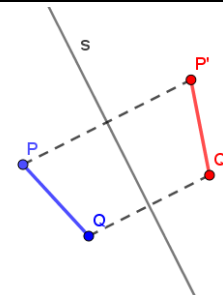
Rotation involves “turning” the figure around a point (centre of rotation).

Reflection associated to line s

Reflection associated to line s is the geometric transformation that does correspond to each point P of the plane the point P' (image of P), in such a way that:

- the line s is perpendicular to $[PP']$ and passes through the midpoint of $[PP']$ (or s is the mediator of $[PP']$),
- if P belongs to s , its image coincides with P .

$[P'Q']$ is the image of $[PQ]$

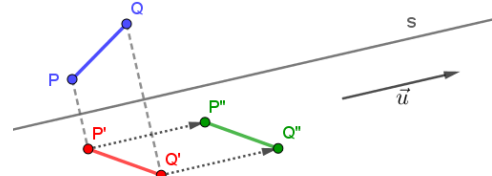


Reflection involves “flipping” the figure over a line (line of reflection).

Glide Reflection associated to line s and vector \vec{u}

Glide reflection is the geometric transformation that results from the sequence of a reflection associated to line s with a translation whose vector \vec{u} has the same direction as s .

$[P''Q'']$ is the image of $[PQ]$



Glide reflection involves “flipping” the figure over a line and “sliding” it, maintaining the direction of the line.