Graph algorithms - Bellman-Ford algorithm

Problem

Given a graph with no negative costs cycles and two vertices s and t, find a minimum cost walk from s to t.

Idea

The algorithm keeps two mappings:

- dist[x] = the cost of the minimum cost walk from s to x known so far
- prev[x] = the vertex just before x on the walk above.

Initially, dist[s]=0 and $dist[x]=\infty$ for $x \neq s$; this reflects the fact that we only know a zero-length walk from s to itself.

Then, we repeatedly performs a relaxation operation defined as follows: if (x,y) is an edge such that dist[y] > dist[x] + c(x,y), then we set:

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    dist[y] = dist[x] + c(x,y)
    prev[y] = x
```

The idea of the relaxation operation is that, if we realize that we have a better walk leading to y by using (x,y) as its last edge, compared to what we know so far, we update our knowledge.

The algorithm

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Input:
    G : directed graph with costs
    s, t : two vertices
Output:
    dist: a map that associates, to each accessible vertex, the cost of the minimum
            cost walk from s to it
    prev : a map that maps each accessible vertex to its predecessor on a path from s to it
Algorithm:
    for x in X do
        dist[x] = \infty
    end for
    dist[s] = 0
    changed = true
    while changed do
        changed = false
        for (x,y) in E do
            if dist[y] > dist[x] + c(x,y) then
                dist[y] = dist[x] + c(x, y)
                prev[y] = x
                changed = true
            end if
        end for
    end while
```

Proof of correctness

The proof is in three parts:

- at each stage, dist and prev correspond to existing walks (this comes immediately from how the relaxation operation works;
- the algorithm finishes;
- when the algorithm finishes, dist[x] = d(s,x) for all vertices x.

For the last two parts, we notice that, at iteration k, we have that $dist[x] \le w_{k,x}$ (see the <u>Bellman's dynamic programming algorithm</u>). This makes the Bellman-Ford finish in at most n-l iterations and end with the correct distances.