

Classical Mechanics Tutorial IV

Engineering Physics

Indian Institute of Information Technology, Allahabad

Writing Down a Hamiltonian

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- ▶ We shall first obtain the Lagrangian of the system.
- ▶ We will then find the generalized momenta and express \dot{q} in terms of p
- ▶ Finally we shall use $H = \sum p\dot{q} - L$ to obtain the Hamiltonian

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Lastly, since $p = \partial L / \partial \dot{x} = m\dot{x} \implies \dot{x} = p/m$, We get

$$T = \frac{p^2}{2m} \quad (3)$$

So using these equations

$$H = \sum p\dot{x} - L \quad (4)$$

$$= p\frac{p}{m} - \frac{p^2}{2m} + \frac{1}{2}kx^2 + \frac{1}{4}bx^4 \quad (5)$$

where

$$L = \frac{1}{2}m\dot{x}^2 - \frac{1}{2}kx^2 - \frac{1}{4}bx^4 \quad (6)$$

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After doing the simple algebra, we get

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We can now figure out the equations of motion.

Finding out the Equations of Motion

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Now we can differentiate 10 and use 11 to write

$$m\ddot{x} = \dot{p} \implies m\ddot{x} + kx + bx^3 = 0$$

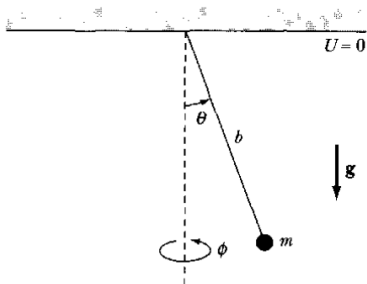
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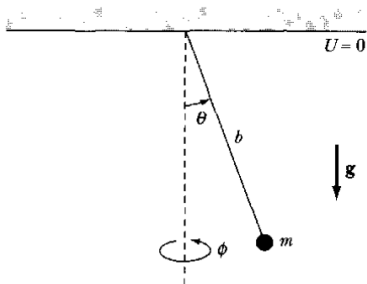
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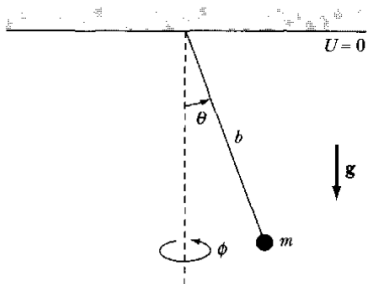
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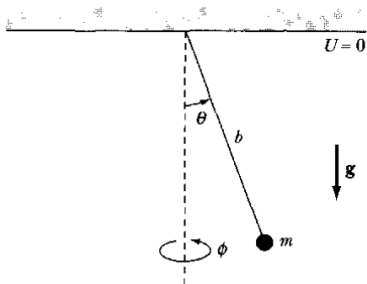
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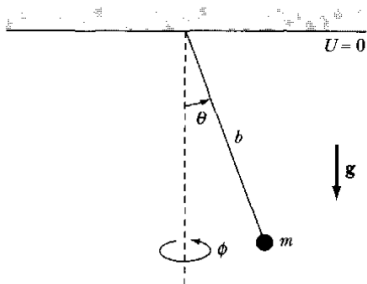
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The kinetic energy is $T = \frac{1}{2}mb^2\dot{\theta}^2 + \frac{1}{2}mb^2\sin^2\theta\dot{\phi}^2$

Finding out the Equations of Motion

The generalized coordinates are θ and ϕ .



The kinetic energy is $T = \frac{1}{2}mb^2\dot{\theta}^2 + \frac{1}{2}mb^2\sin^2\theta\dot{\phi}^2$ and the potential energy is $U = -mgb\cos\theta$

Finding out the Equations of Motion

We can now write the Lagrangian as

$$L = \frac{1}{2}mb^2\dot{\theta}^2 + \frac{1}{2}mb^2\sin^2\theta\dot{\phi}^2 + mgb\cos\theta \quad (12)$$

and calculate the generalized momenta as

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$$p_{\theta} = \frac{\partial L}{\partial \dot{\theta}} = mb^2\dot{\theta} \quad (13)$$

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We then calculate the Hamiltonian using $H = p_\theta\dot{\theta} + p_\phi\dot{\phi} - L$

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$$\begin{aligned} H &= p_\theta \frac{p_\theta}{mb^2} + p_\phi \frac{p_\phi}{mb^2 \sin^2 \theta} - \frac{1}{2}mb^2 \left(\frac{p_\theta}{mb^2} \right)^2 \\ &\quad - \frac{1}{2}mb^2 \sin^2 \theta \left(\frac{p_\phi}{mb^2 \sin^2 \theta} \right)^2 - mgb \cos \theta \end{aligned}$$

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$$H = p_\theta \frac{p_\theta}{mb^2} + p_\phi \frac{p_\phi}{mb^2 \sin^2 \theta} - \frac{1}{2}mb^2 \left(\frac{p_\theta}{mb^2} \right)^2 \\ - \frac{1}{2}mb^2 \sin^2 \theta \left(\frac{p_\phi}{mb^2 \sin^2 \theta} \right)^2 - mgb \cos \theta$$

$$H = \frac{p_\theta^2}{2mb^2} + \frac{p_\phi^2}{2mb^2 \sin^2 \theta} - mgb \cos \theta \quad (15)$$

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$$\text{Since, } H = \frac{p_{\theta}^2}{2mb^2} + \frac{p_{\phi}^2}{2mb^2 \sin^2 \theta} - mgb \cos \theta$$

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$$\dot{p}_\phi = -\frac{\partial H}{\partial \phi} = 0 \quad (19)$$

Because ϕ is a cyclic coordinate, the momentum p_ϕ about the symmetry axis is constant