

Assignment No: 9

Title: System Call

AIM:

Implement a new system call, `swipe()`, in the Linux kernel that transfers the remaining time slice of each process in a specified set to a target process. Demonstrate various uses of the system call.

OBJECTIVE:

To create and integrate the `swipe()` system call into the Linux kernel, and illustrate its effects both beneficially and detrimentally.

THEORY:

Steps to Add a New System Call:

1. Download the Kernel Source:

```
wget https://www.kernel.org/pub/linux/kernel/v4.x/linux-4.17.4.tar.xz
```

Steps to Add a New System Call:

Download the Kernel Source:

```
bash
```

```
Copy code
```

```
wget
```

```
https://www.kernel.org/pub/linux/kernel/v4.x/linux-4.17.4.tar.xz
```

Extract the Kernel Source Code:

```
bash
```

```
Copy code
```

```
sudo tar -xvf linux-4.17.4.tar.xz -C /usr/src/
```

```
cd /usr/src/linux-4.17.4/
```

Create the System Call Implementation:

Create a directory for the new system call:

```
bash
```

Copy code

```
mkdir swipe  
cd swipe
```

○

Create the `swipe.c` file:

bash

Copy code

```
gedit swipe.c
```

○

Implement the `swipe()` function:

c

Copy code

```
#include <linux/kernel.h>  
#include <linux/sched.h>  
#include <linux/syscalls.h>
```

```
asmlinkage long sys_swipe(pid_t target_pid, pid_t *source_pids, int  
num_sources) {
```

```
    struct task_struct *target_task;  
    struct task_struct *source_task;  
    long time_slice;
```

```
    target_task = pid_task(find_vpid(target_pid), PIDTYPE_PID);  
    if (!target_task) return -ESRCH; // Target process not found
```

```
    for (int i = 0; i < num_sources; i++) {  
        source_task = pid_task(find_vpid(source_pids[i]),  
PIDTYPE_PID);  
        if (!source_task) return -ESRCH; // Source process not  
found
```

```
        // Transfer time slice (hypothetical implementation)  
        time_slice = source_task->sched_info.time_slice;  
        source_task->sched_info.time_slice = 0; // Reset source  
time slice  
        target_task->sched_info.time_slice += time_slice; // Add to  
target time slice  
    }
```

```
    return 0; // Success
}
```

○

Create a Makefile:

bash

Copy code

```
gedit Makefile
```

Add the line:

makefile

Copy code

```
obj-y := swipe.o
```

Modify the Kernel Makefile:

Go to the parent directory:

bash

Copy code

```
cd ..
```

```
gedit Makefile
```

○

Find the line with `core-y` and add `swipe/` at the end:

makefile

Copy code

```
core-y += kernel/ mm/ fs/ ipc/ security/ crypto/ block/ swipe/
```

○

Add to System Call Table:

Open the syscall table for 64-bit systems:

bash

Copy code

```
cd arch/x86/entry/syscalls/
```

```
gedit syscall_64.tbl
```

○

Add the new system call at the end:

plaintext

Copy code

```
549
```

```
64
```

```
swipe
sys_swipe
```

○

Add to System Call Header:

Open the system call header:

```
bash
```

Copy code

```
cd ../../../../include/linux/
gedit syscalls.h
```

○

Add the prototype for `swipe()`:

```
asmlinkage long sys_swipe(pid_t target_pid, pid_t *source_pids, int
num_sources);
```

○

Compile the Kernel:

Install necessary packages:

```
sudo apt-get install gcc libncurses5-dev bison flex libssl-dev
libelf-dev
```

Configure the kernel:

```
sudo make menuconfig
```

Compile the kernel:

```
sudo make -j$(nproc)
```

Install/Update Kernel:

```
sudo make modules_install install
```

```
sudo shutdown -r now
```

Test the System Call:

- Create a user space program:

```
cd ~
```

```
gedit userspace.c
```

```
#include <stdio.h>
```

```
#include <unistd.h>
```

```
#include <sys/syscall.h>
```

```
#define SYS_swipe 549 // Update this number accordingly
```

```
int main() {
```

```
    pid_t target_pid = 1234; // Example target PID
```

```
    pid_t source_pids[] = {5678, 91011}; // Example source PIDs
```

```
    int num_sources = 2;
```

```
    long result = syscall(SYS_swipe, target_pid, source_pids,  
num_sources);
```

```
    printf("System call sys_swipe returned %ld\n", result);
```

```
    return 0;
```

```
}
```

Compile and Run the User Space Program:

```
gcc userspace.c -o userspace
```

```
./userspace
```

```
Dmesg
```

```

#include <linux/kernel.h>

asmlinkage long sys_hello(void)
{
    printk(KERN_INFO "Hello world\n");
    return 0;
}

#include <stdio.h>
#include <linux/kernel.h>
#include <sys/syscall.h>
#include <unistd.h>
int main()
{
    long int r = syscall(358);
    printf("System call sys_hello returned %ld\n", r);
    return 0;
}

```

308	common	setns	__x64_sys_setns
309	common	getcpu	__x64_sys_getcpu
310	64	process_vm_readv	__x64_sys_process_vm_readv
311	64	process_vm_writev	__x64_sys_process_vm_writev
312	common	kcmp	__x64_sys_kcmp
313	common	finit_module	__x64_sys_finit_module
314	common	sched_setattr	__x64_sys_sched_setattr
315	common	sched_getattr	__x64_sys_sched_getattr
316	common	renameat2	__x64_sys_renameat2
317	common	seccomp	__x64_sys_seccomp
318	common	getrandom	__x64_sys_getrandom
319	common	memfd_create	__x64_sys_memfd_create
320	common	kexec_file_load	__x64_sys_kexec_file_load
321	common	bpf	__x64_sys_bpf
322	64	execveat	__x64_sys_execveat/ptregs
