

THAI CANNABIS PLANTS

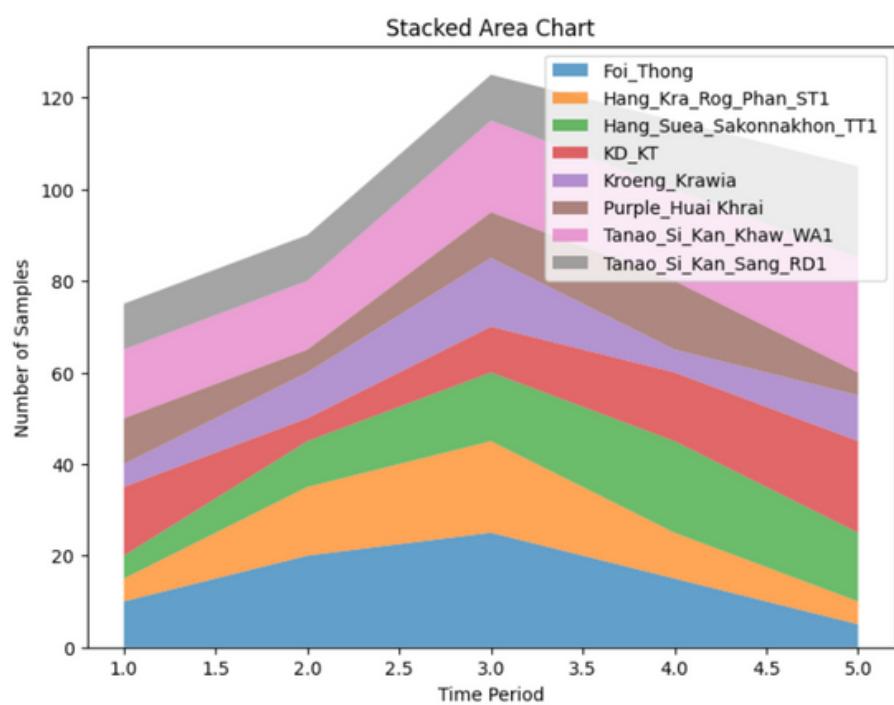
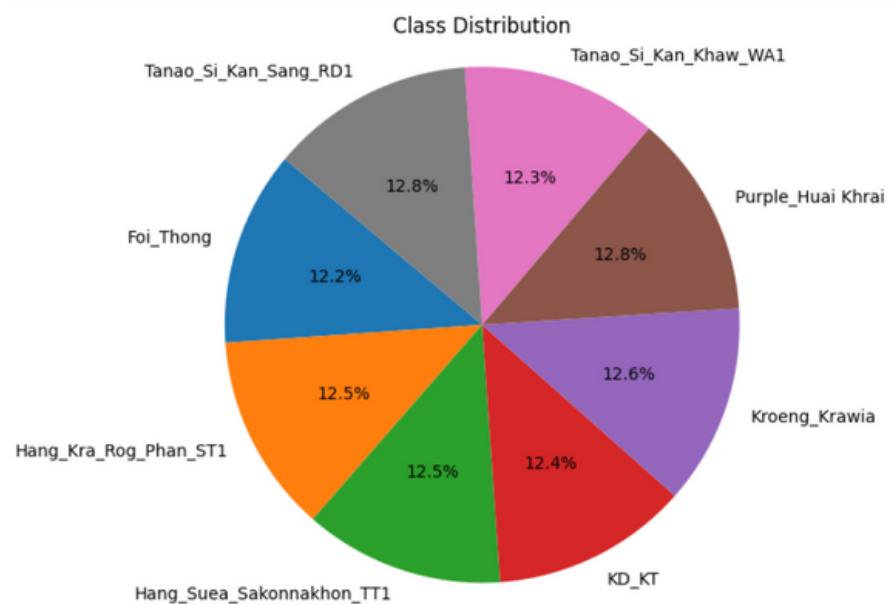


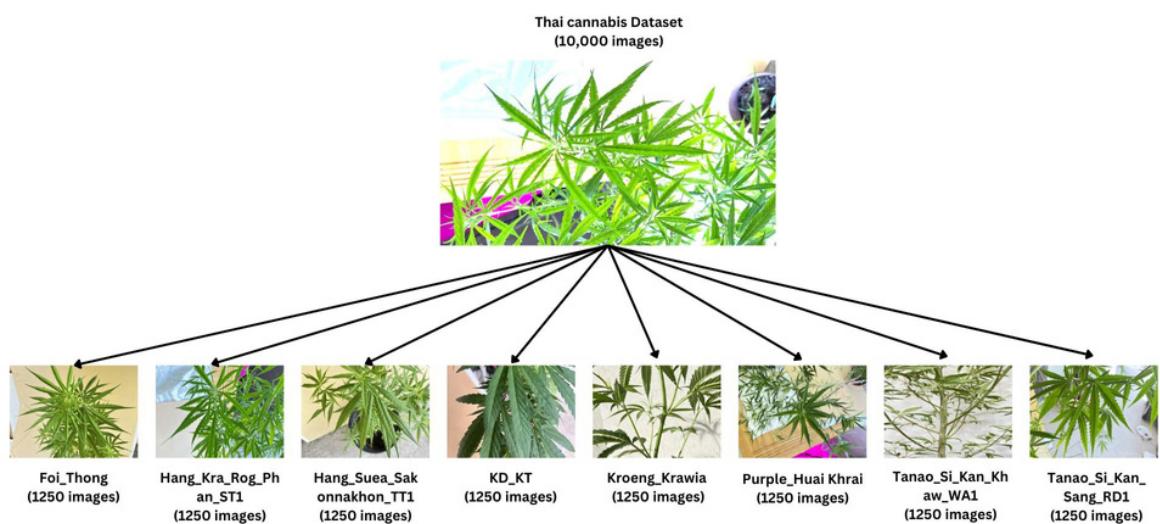
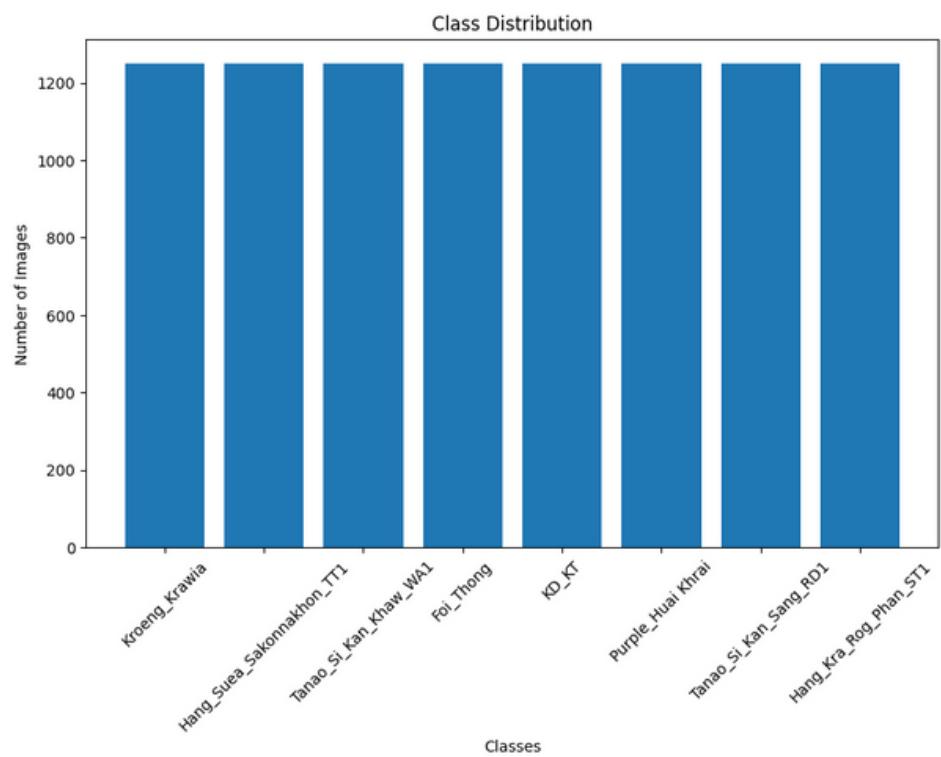
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DATA AND INFORMATION VISUALIZATION





COMPARISON

Model	Accuracy	Val_Accuracy	Recall	F1-Score	ROC Curve	Loss	Val_Loss
VGG16	0.9833	0.9382	0.9378	0.9394	0.9965	0.1452	0.5889
ResNet50	0.9866	0.9791	0.9792	0.9791	0.9986	0.0609	0.1438
MobileNetV2	0.9645	0.9636	0.9628	0.9635	0.9977	0.1192	0.1415

VGG-16

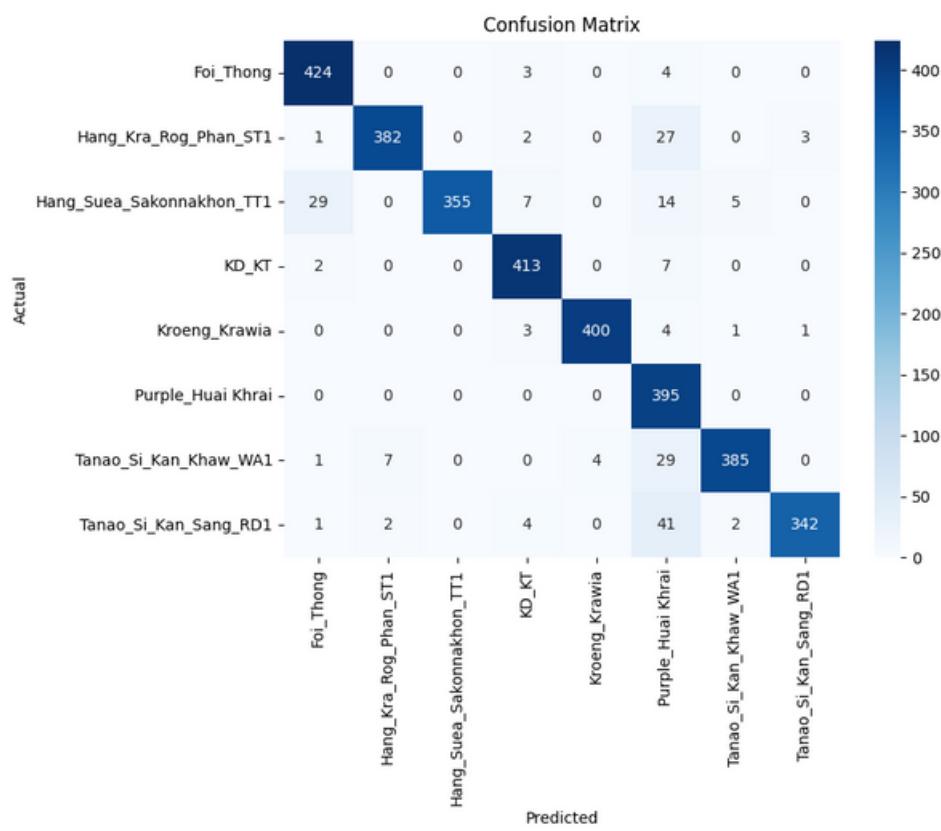
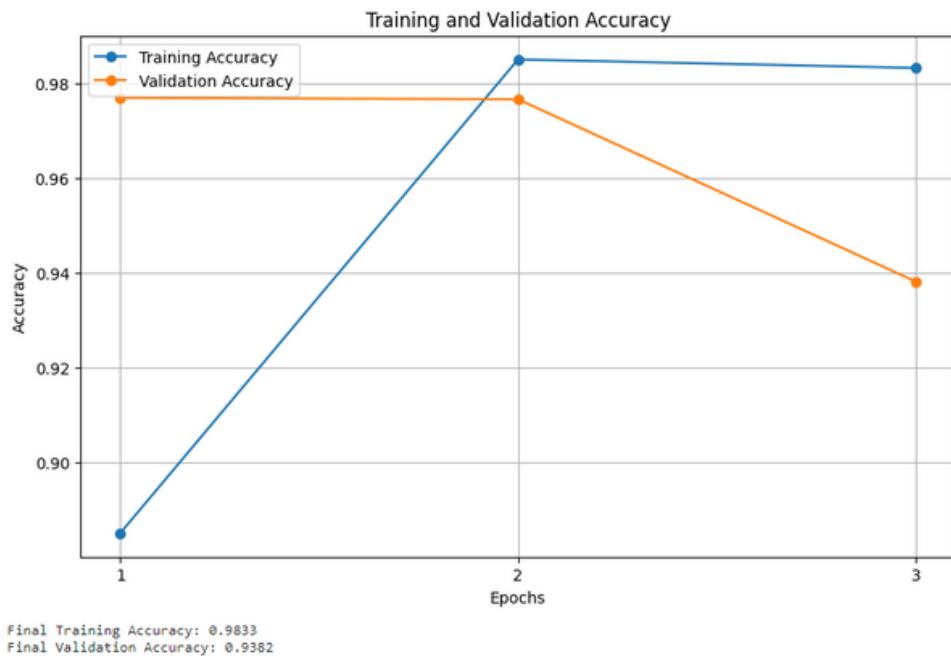
VGG-16, short for Visual Geometry Group 16, is a convolutional neural network (CNN) architecture widely recognized for its exceptional performance in image classification and object recognition tasks. Developed by the Visual Geometry Group at the University of Oxford, VGG-16 is a key milestone in the evolution of deep learning models for computer vision.

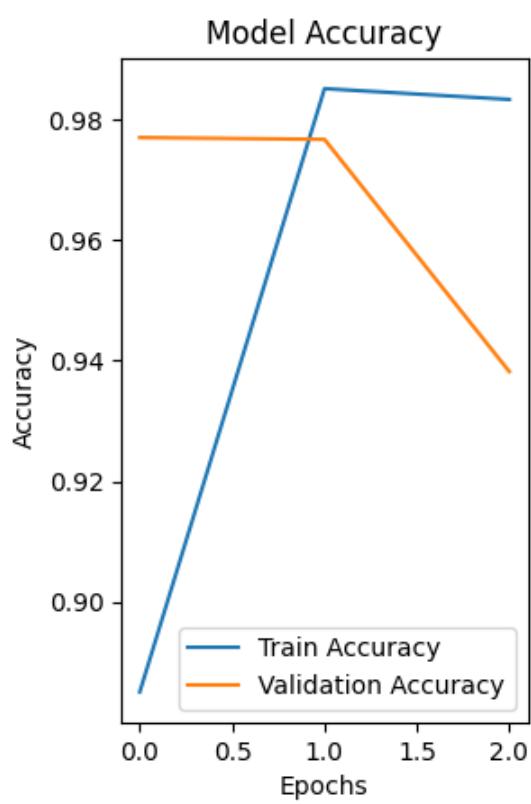
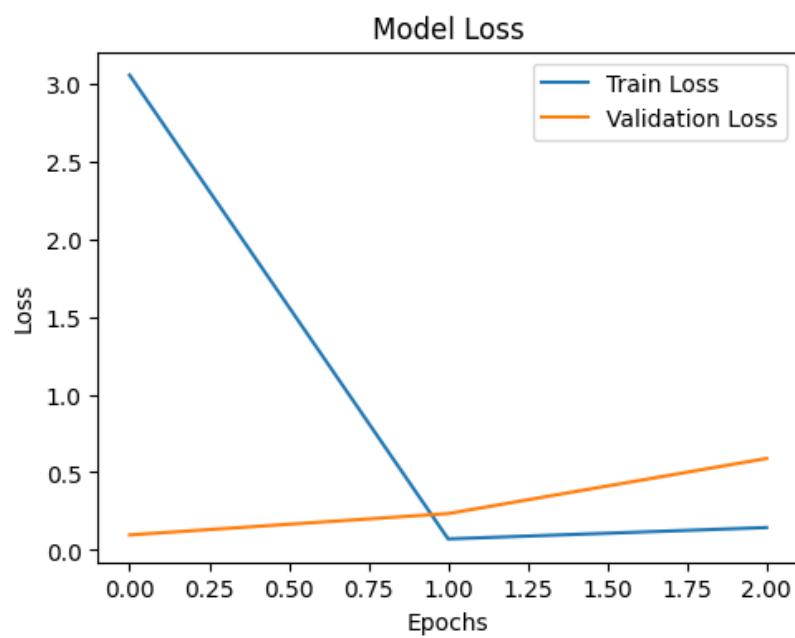
The VGG-16 architecture consists of 16 weight layers, which include 13 convolutional layers and 3 fully connected layers. The simplicity and uniformity of this architecture are notable, with small 3x3 convolutional filters used throughout the network. This design choice allows the model to learn intricate features and patterns in images, making it highly effective in recognizing objects of varying complexities.

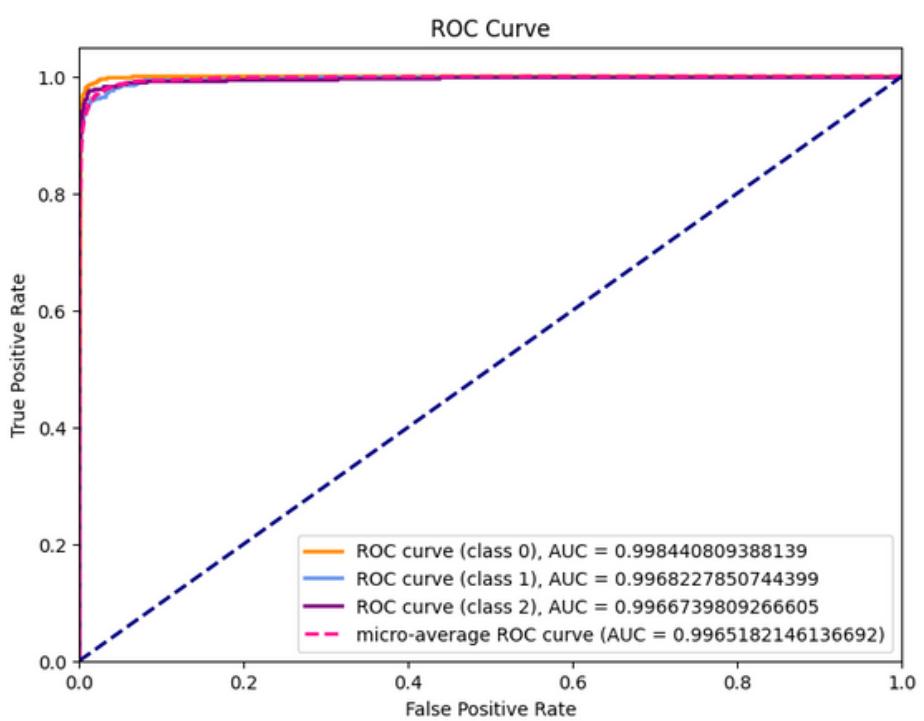
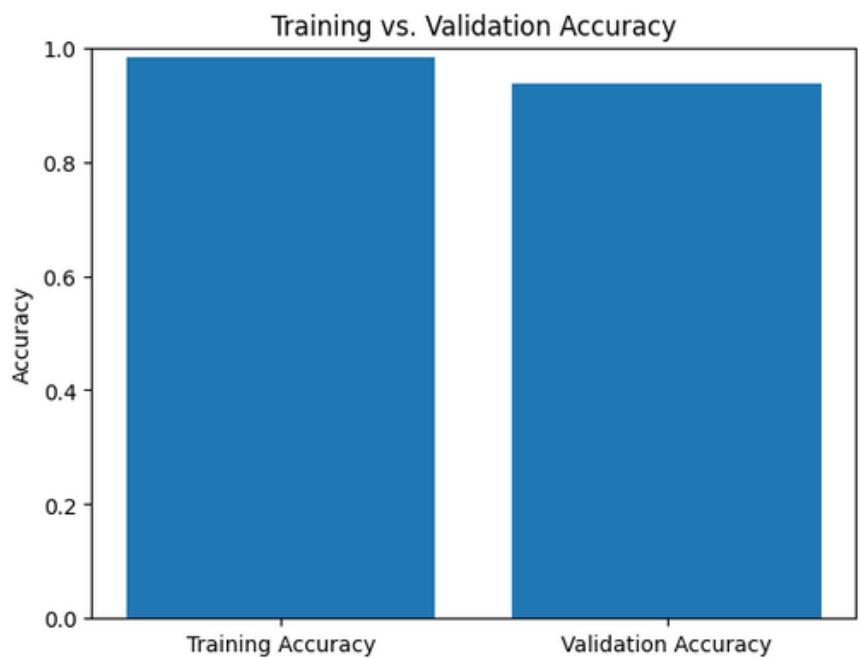
VGG-16 achieved its prominence by winning the 2014 ImageNet Large Scale Visual Recognition Challenge (ILSVRC) competition. It demonstrated remarkable accuracy in classifying a diverse range of objects in images, solidifying its reputation as a benchmark in the field of deep learning. Researchers and practitioners often use VGG-16 as a base architecture for transfer learning in various computer vision applications, thanks to its strong generalization capabilities.

Despite its impressive performance, VGG-16 has certain drawbacks. Its architecture is relatively deep and computationally expensive, making it less suitable for real-time applications on resource-constrained devices. Also, VGG-16 does not incorporate recent advancements like residual connections or attention mechanisms, which are present in more recent models like ResNet and Transformer-based networks.

In summary, VGG-16 is a groundbreaking CNN architecture that set a standard for image classification. While it may not be the most efficient model in terms of computational resources, its simplicity and effectiveness continue to make it a valuable tool in the deep learning community, serving as a reference point for researchers and engineers working on computer vision tasks.







RESNET-50

ResNet-50, short for "Residual Network with 50 layers," is a deep convolutional neural network architecture designed for image classification tasks. It's a variant of the ResNet family, which was introduced by Kaiming He and his colleagues in 2015 and is known for its remarkable performance in various computer vision tasks.

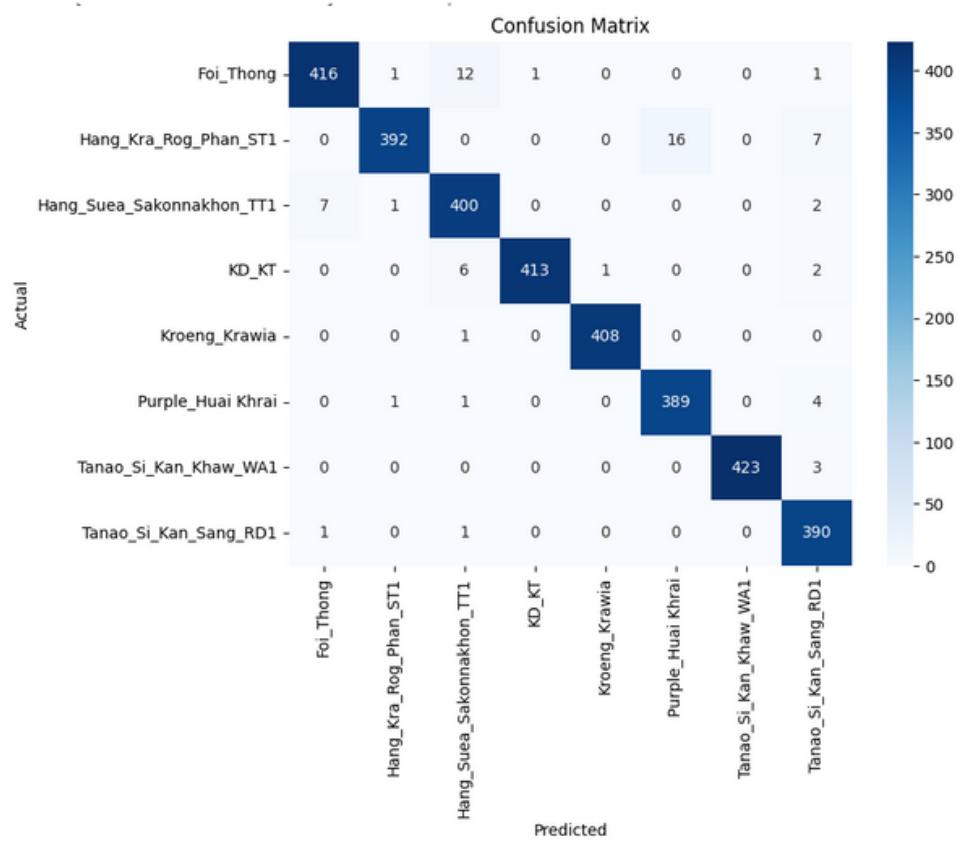
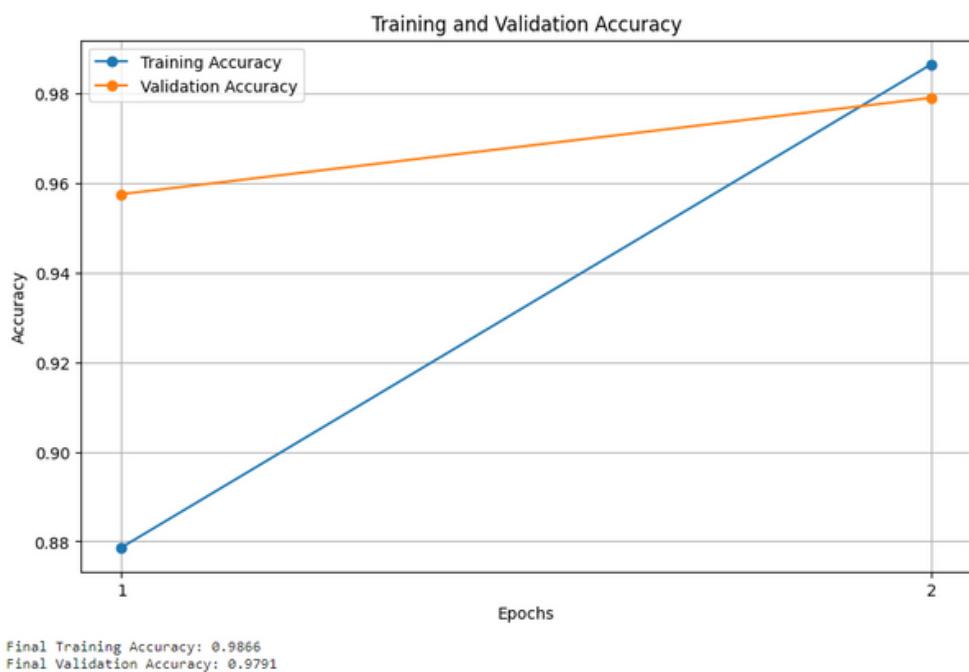
ResNet-50's key innovation is the introduction of residual blocks, which allow for the training of extremely deep neural networks. Each residual block contains skip connections, or "shortcut connections," that skip one or more layers. This enables the network to learn residual functions, making it easier to train and mitigating the vanishing gradient problem.

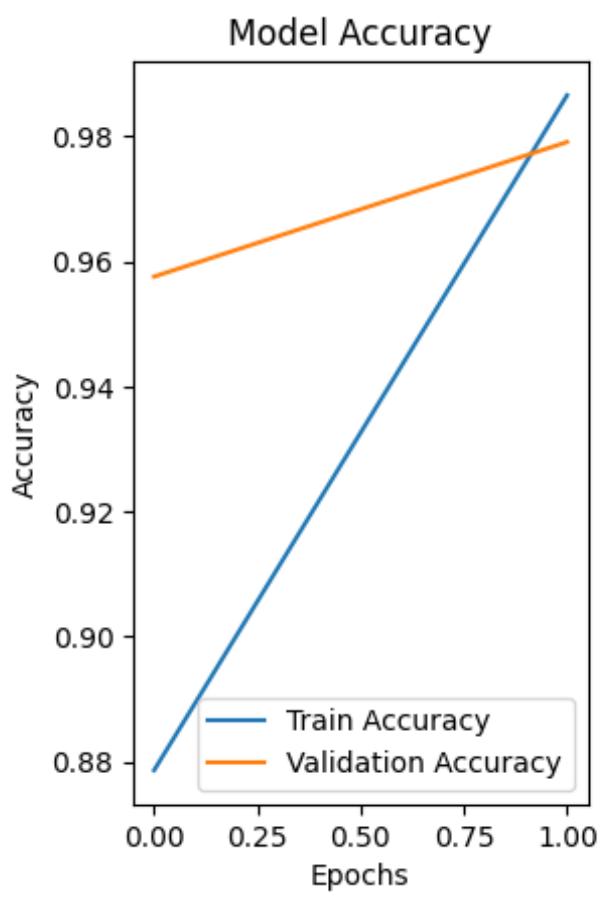
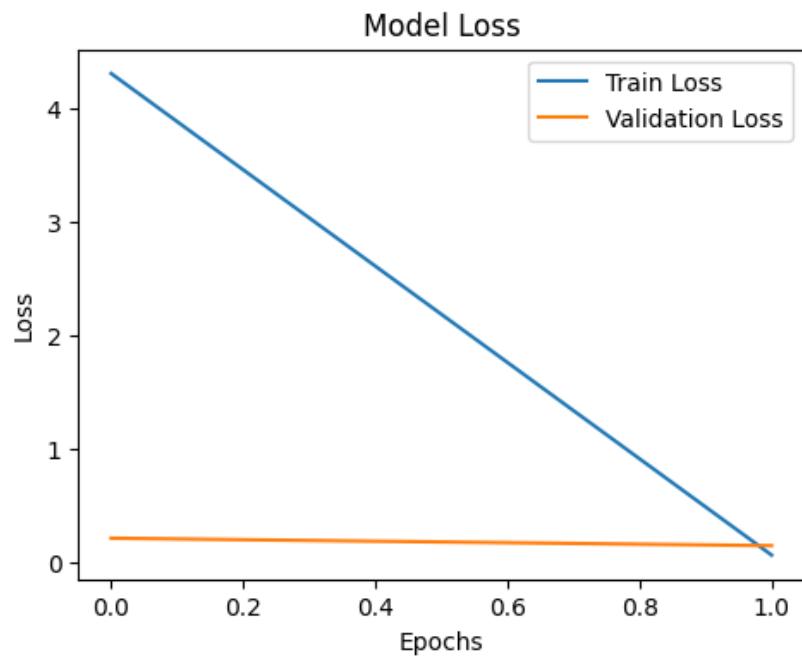
ResNet-50 comprises 50 layers, including convolutional, batch normalization, activation, and fully connected layers. It is pre-trained on large-scale image datasets such as ImageNet, where it learns to recognize a wide range of objects and features.

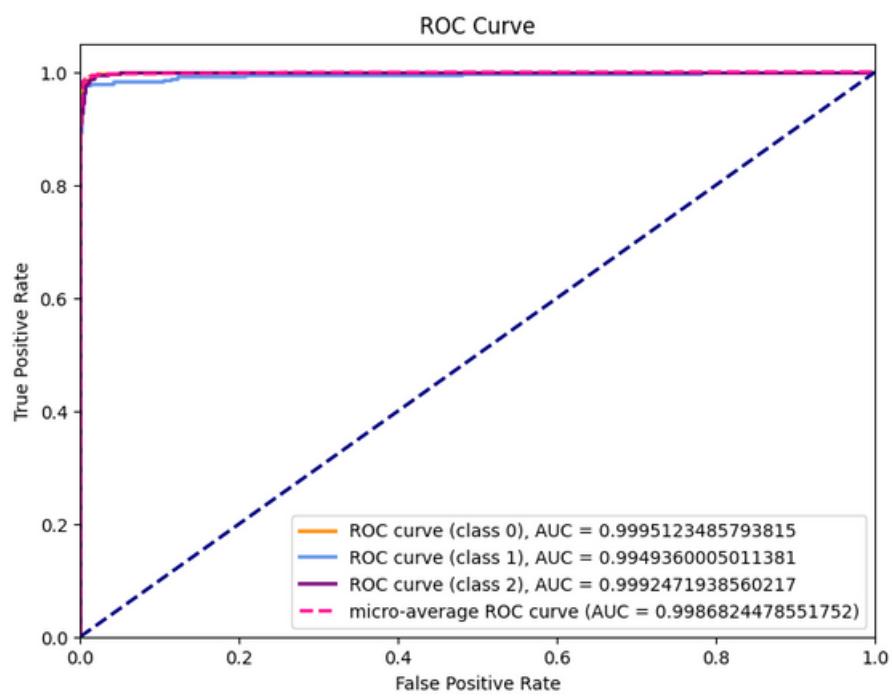
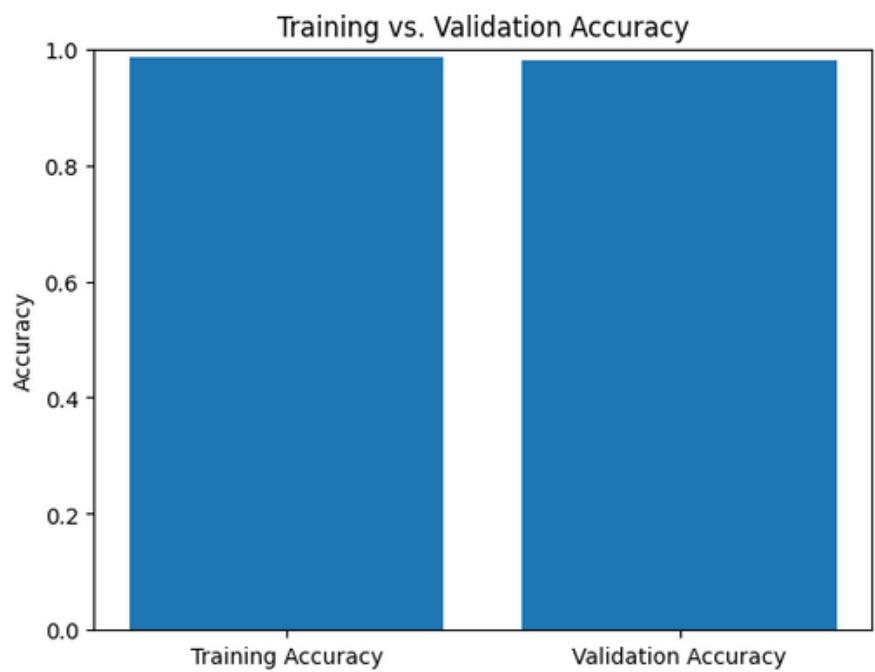
The architecture of ResNet-50 can be summarized as follows:

1. Input Layer: Accepts images of a fixed size (typically 224x224 pixels with three color channels).
2. Convolutional Layers: Multiple layers of 3x3 convolution operations.
3. Residual Blocks: Comprising a series of convolutional and batch normalization layers, with skip connections.
4. Global Average Pooling Layer: Reduces the spatial dimensions of the feature maps.
5. Fully Connected Layer: The output layer for classifying images into specific categories.

ResNet-50 has become a popular choice for various computer vision tasks due to its deep architecture, excellent accuracy, and the availability of pre-trained models. Researchers and practitioners often fine-tune it for specific tasks or use it as a feature extractor by removing the fully connected layers. Its ability to handle complex visual data has made it an essential tool in the field of deep learning and image recognition.







MOBILENETV2

MobileNetV2 is a deep learning neural network architecture developed by Google as an evolution of the original MobileNet. It is designed for efficient on-device computer vision tasks, particularly on mobile and embedded devices with limited computational resources.

MobileNetV2 introduces several key features to improve its performance and efficiency. One of the most notable innovations is the use of inverted residual blocks, which consist of a lightweight bottleneck layer followed by an expansion layer. This structure reduces the overall computational cost while maintaining model accuracy. Additionally, MobileNetV2 utilizes depthwise separable convolutions, which separate the convolutional operation into depthwise and pointwise convolutions, further reducing computation and model size.

The architecture also incorporates a feature called linear bottlenecks, which prevents information loss during the transformations, and skip connections that enable better gradient flow during training. MobileNetV2 uses a set of hyperparameters to control model size and computational efficiency, allowing for customization to suit specific hardware and deployment constraints.

MobileNetV2 has proven to be highly efficient and effective for various computer vision tasks, including image classification, object detection, and semantic segmentation. Its lightweight design and compatibility with mobile and embedded devices make it a popular choice for real-time applications, such as mobile photography, augmented reality, and autonomous vehicles.

In summary, MobileNetV2 is a state-of-the-art neural network architecture optimized for mobile and embedded devices. Its innovative features, including inverted residual blocks and depthwise separable convolutions, enable efficient and accurate computer vision tasks, making it a valuable tool for applications requiring low-power and real-time processing.

