Common_Task_02

quark/gluon Classification

In [1]:
```
pip install torch-geometric
```

```
Collecting torch-geometric
  Downloading torch_geometric-2.6.1-py3-none-any.whl.metadata (63 kB)
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Requirement already satisfied: idna<4,>=2.5 in /usr/local/lib/python3.10/dist-packages (from requests->torch-geometric) (3.10)
Requirement already satisfied: urllib3<3,>=1.21.1 in /usr/local/lib/python3.10/dist-packages (from requests->torch-geometric) (2.3.0)
Requirement already satisfied: certifi>=2017.4.17 in /usr/local/lib/python3.10/dist-packages (from requests->torch-geometric) (2025.1.31)
Requirement already satisfied: typing-extensions>=4.1.0 in /usr/local/lib/python3.10/dist-packages (from multidict<7.0,>=4.5->aiohttp->torch-geometric) (4.12.2)
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Downloading torch_geometric-2.6.1-py3-none-any.whl (1.1 MB)
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Installing collected packages: torch-geometric
Successfully installed torch-geometric-2.6.1
Note: you may need to restart the kernel to use updated packages.
```

In [2]:
```python
# Import necessary libraries

import h5py
import numpy as np
import torch
import torch.nn as nn
import torch.optim as optim
import matplotlib.pyplot as plt
import networkx as nx
from mpl_toolkits.mplot3d import Axes3D
from sklearn.model_selection import train_test_split
from sklearn.metrics import roc_curve, auc
from torch_geometric.data import Data, Batch
from torch_geometric.loader import DataLoader
from torch.optim import Adam
import pytorch_lightning as pl
import torch.nn.functional as F
from torch.nn import Linear
```

In [3]:
```python
# Check if CUDA (GPU) is available; otherwise, default to CPU
device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
file_path = "/kaggle/input/autoencoder-data/quark-gluon_data-set_n139306.hdf5"
```

In [4]:
```python
print(device)
```

```
cuda
```

In [5]:
```python
def explore_hdf5(file):
    with h5py.File(file, "r") as f:
        print("Keys in dataset:", list(f.keys()))
        for key in f.keys():
            print(f"Shape of {key}: {f[key].shape}")

explore_hdf5(file_path)
```

```
Keys in dataset: ['X_jets', 'm0', 'pt', 'y']
Shape of X_jets: (139306, 125, 125, 3)
Shape of m0: (139306,)
Shape of pt: (139306,)
Shape of y: (139306,)
```

In [6]:
```python
def load_data(file_name, sample_size):
    with h5py.File(file_name, 'r') as f:
        print("Dataset keys:", list(f.keys()))
        print("Total images:", len(f['X_jets']))
        print("Image dimensions:", f['X_jets'].shape[1:])
        return np.array(f['X_jets'][:sample_size]), np.array(f['y'][:sample_size])

# Load 10,000 samples from the dataset
X, y = load_data(file_path, 10000)
```

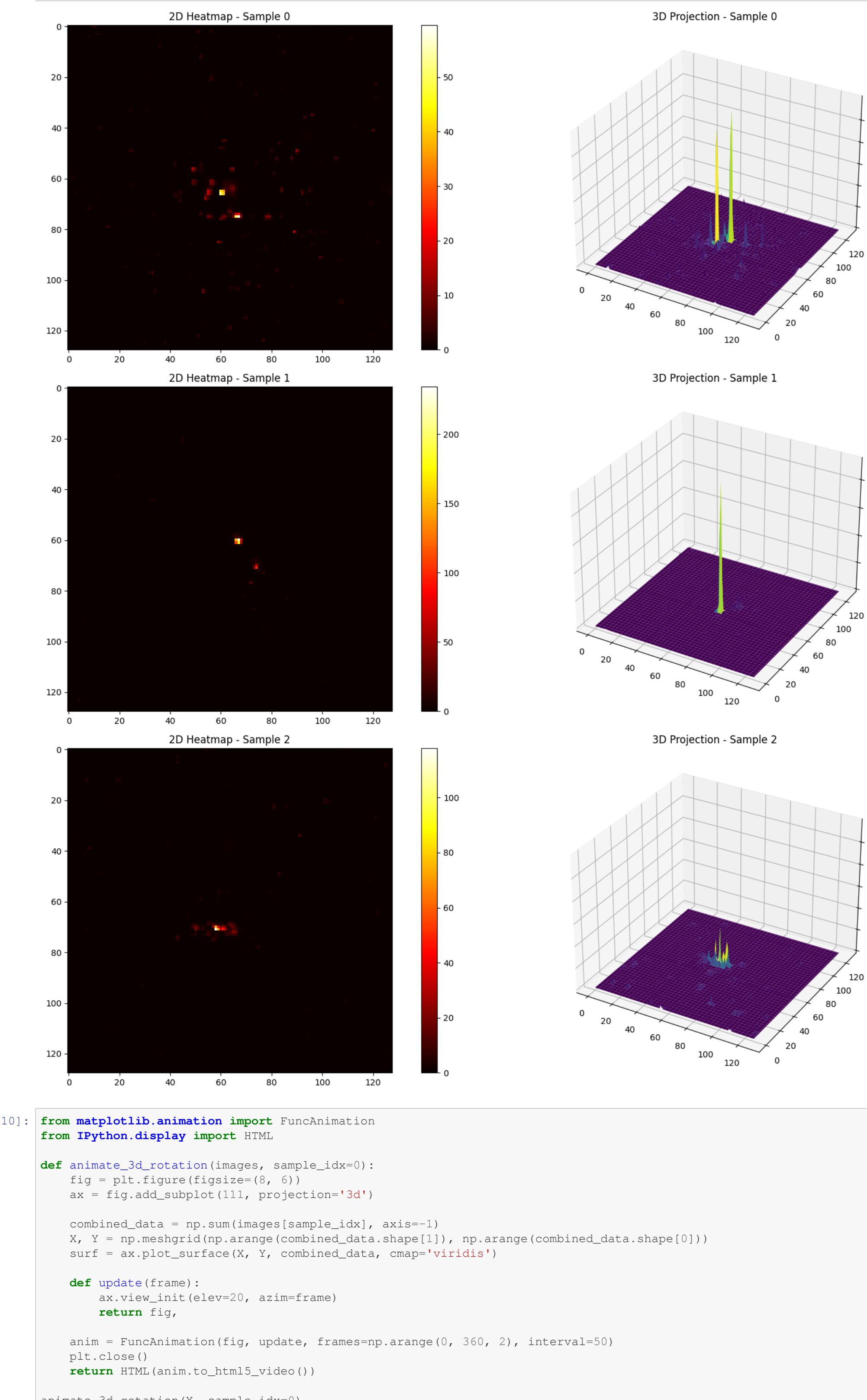
```
Dataset keys: ['X_jets', 'm0', 'pt', 'y']
Total images: 139306
Image dimensions: (125, 125, 3)
```

In [7]:
```python
def count_labels(labels):
    label_counts = np.bincount(labels.astype(np.int64))
    return {str(i): count for i, count in enumerate(label_counts)}

print(count_labels(y))
```

```
{'0': 4994, '1': 5006}
```

In [8]:
```python
def preprocess_images(images):
    from skimage.transform import resize
    # Resize to 128x128 and normalize
    processed = np.array([resize(img, (128, 128), anti_aliasing=True) for img in images], dtype=np.float32)
    # Compute mean and standard deviation for normalization
    mean, std = np.mean(processed), np.std(processed)
    # Normalize: (X - mean) / std, and clip negative values to 0
    return np.clip((processed - mean) / std, 0, None)

X = preprocess_images(X)
```

In [9]:
```python
import numpy as np
import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d import Axes3D

def heatmap_with_projection(images, num_samples=3):
    fig = plt.figure(figsize=(18, 6 * num_samples))

    for idx in range(num_samples):
        # 2D Heatmap
        ax1 = fig.add_subplot(num_samples, 2, 2*idx + 1)
        combined_data = np.sum(images[idx], axis=-1)
        heatmap = ax1.imshow(combined_data, cmap='hot', interpolation='nearest')
        plt.colorbar(heatmap, ax=ax1)
        ax1.set_title(f'2D Heatmap - Sample {idx}')

        # 3D Projection
        ax2 = fig.add_subplot(num_samples, 2, 2*idx + 2, projection='3d')
        X, Y = np.meshgrid(np.arange(combined_data.shape[1]), np.arange(combined_data.shape[0]))
        ax2.plot_surface(X, Y, combined_data, cmap='viridis')
        ax2.set_title(f'3D Projection - Sample {idx}')

    plt.tight_layout()
    plt.show()

heatmap_with_projection(X)
```



In [10]:
```python
from matplotlib.animation import FuncAnimation
from IPython.display import HTML

def animate_3d_rotation(images, sample_idx=0):
    fig = plt.figure(figsize=(8, 6))
    ax = fig.add_subplot(111, projection='3d')

    combined_data = np.sum(images[sample_idx], axis=-1)
    X, Y = np.meshgrid(np.arange(combined_data.shape[1]), np.arange(combined_data.shape[0]))
    surf = ax.plot_surface(X, Y, combined_data, cmap='viridis')

    def update(frame):
        ax.view_init(elev=20, azim=frame)
        return fig,

    anim = FuncAnimation(fig, update, frames=np.arange(0, 360, 2), interval=50)
    plt.close()
    return HTML(anim.to_html5_video())

animate_3d_rotation(X, sample_idx=0)
```

Out[10]:

In [11]:
```python
def extract_nonzero_mask(images):
    # Reshape the images array to combine height and width dimensions while keeping the 3 channels (Track, ECAL, HCAL)
    reshaped = images.reshape((-1, images.shape[1] * images.shape[2], 3))
    # Check if any channel in each pixel has nonzero values (i.e., meaningful data) and create a binary mask
    # axis=-1 ensures the check is applied along the 3 channels (Track, ECAL, HCAL)
    return np.any(reshaped != [0., 0., 0.], axis=-1).reshape(images.shape[:3])# Restore the original shape

mask = extract_nonzero_mask(X)
```

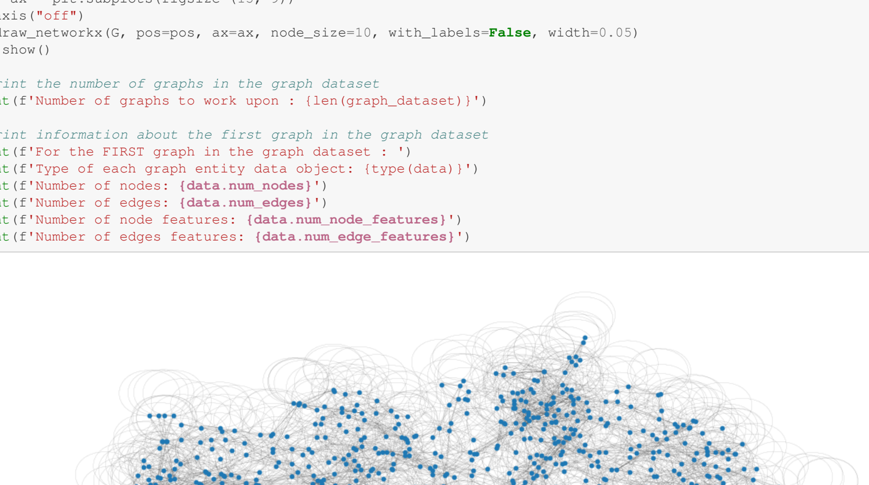
In [12]:
```python
def create_graph_features(masked_data):
    indices, features = [], [] # Initialize lists to store the indices (coordinates) and features (pixel values)
    # Iterate through each image and its corresponding mask
    for img_idx, mask in enumerate(masked_data):
        # Get the coordinates (row, column) of non-zero pixels (True pixels in the mask)
        coords = np.column_stack(np.where(mask))

        # Extract the feature (pixel values) for the corresponding coordinates in the image
        # `coords[:, 0]` gives the row indices, and `coords[:, 1]` gives the column indices
        features.append(X[img_idx, coords[:, 0], coords[:, 1], :])# Collect feature values (Track, ECAL, HCAL)
        # Store the coordinates of the non-zero pixels as graph nodes
        indices.append(coords)

    return indices, features

indices_list, features_list = create_graph_features(mask)
```

In [13]:
```python
def build_graph_structure(coords, k=4):
    from scipy.spatial import cKDTree
    from scipy.sparse import coo_matrix
    # Create a k-d tree from the coordinates to efficiently find the k nearest neighbors
    tree = cKDTree(coords)

    # Query the k nearest neighbors for each point (coordinates)
    # dist contains the distances to the k nearest neighbors, indices contains their indices
    dist, indices = tree.query(coords, k=k)

    # Compute the variance of the distance of the k-th nearest neighbor (to use as a scaling factor for the kernel)
    sigma2 = np.mean(dist[:, -1])**2

    # Compute the weights for the edges based on the Gaussian kernel (exponent of negative squared distance / sigma^2)
    weights = np.exp(-dist**2 / sigma2)

    # Create the row and column indices for the sparse adjacency matrix
    # Repeat the index for each neighbor and flatten the indices array for the coo_matrix
    row, col = np.arange(len(coords)).repeat(k), indices.flatten()

    # Return the sparse adjacency matrix in COO format
    return coo_matrix((weights.flatten(), (row, col)), shape=(len(coords), len(coords)))
```

In [14]:
```python
def create_graph_dataset(indices_list, labels, neighbors=8):
    dataset = []
    # Loop over each sample in the indices list
    for i, points in enumerate(indices_list):
        # Build the graph structure using k-nearest neighbors (k=neighbors)
        adjacency = build_graph_structure(points, k=neighbors)

        # Convert the adjacency matrix row and column indices to a PyTorch tensor
        # These represent the edges of the graph
        edge_idx = torch.from_numpy(np.vstack((adjacency.row, adjacency.col))).long()

        # Convert the edge weights to a PyTorch tensor
        edge_weights = torch.from_numpy(adjacency.data).float().view(-1, 1)

        # Convert the label for the current graph to a PyTorch tensor
        label = torch.tensor([int(labels[i])], dtype=torch.long)

        # Create a PyTorch Geometric graph object containing:
        # - x: Node features (features corresponding to each point in the graph)
        # - edge_index: The indices of the edges (which nodes are connected)
        # - edge_attr: The weights of the edges
        # - y: The label of the graph
        graph = Data(x=torch.from_numpy(features_list[i]), edge_index=edge_idx, edge_attr=edge_weights, y=label)
        # Add the created graph object to the dataset
        dataset.append(graph)
    return dataset
```

In [15]:
```python
# Create the graph dataset by calling the create_graph_dataset function
# The function takes in:
# - indices_list: List of indices representing the coordinates of the non-zero points in the images
# - y: The labels corresponding to each image in the dataset
# - neighbors: The number of nearest neighbors (k) to consider when building the graph structure (set to 8)
graph_dataset = create_graph_dataset(indices_list, y, neighbors=8)
```

In [16]:
```python
# Initialize an empty NetworkX graph
G = nx.Graph()

# Extract the first graph from the graph dataset
data = graph_dataset[0]

# Get the edge index tensor from the data object, which contains information about the graph edges
edge_tensor = data.edge_index

# Convert the edge index tensor into a list of edge tuples (node1, node2) for NetworkX
edge_list = [(edge_tensor[0, i].item(), edge_tensor[1, i].item()) for i in range(edge_tensor.shape[1])]

# Add the edges to the NetworkX graph G
G.add_edges_from(edge_list)

# Create a layout for the nodes of the graph using the spring layout (force-directed layout)
pos = nx.spring_layout(G, iterations=15, seed=1721)

# Plot the graph
fig, ax = plt.subplots(figsize=(15, 9))
ax.axis("off")
nx.draw_networkx(G, pos=pos, ax=ax, node_size=10, with_labels=False, width=0.05)
plt.show()

# Print the number of graphs in the graph dataset
print(f'Number of graphs to work upon : {len(graph_dataset)}')

# Print information about the first graph in the graph dataset
print(f'For the FIRST graph in the graph dataset : ')
print(f'Type of each graph entity data object: {type(data)}')
print(f'Number of nodes: {data.num_nodes}')
print(f'Number of edges: {data.num_edges}')
print(f'Number of node features: {data.num_node_features}')
print(f'Number of edges features: {data.num_edge_features}')
```



```
Number of graphs to work upon : 10000
For the FIRST graph in the graph dataset :
Type of each graph entity data object: <class 'torch_geometric.data.data.Data'>
Number of nodes: 1530
Number of edges: 12240
Number of node features: 3
Number of edges features: 1
```

In [17]:
```python
# Split the graph dataset into training (80%), validation (10%), and testing (10%) sets
train_data, test_data = train_test_split(graph_dataset, test_size=0.2, random_state=14)
train_data, val_data = train_test_split(train_data, test_size=0.1, random_state=14)

# Create DataLoader instances for the train, validation, and test sets with batch size of 128
train_loader = DataLoader(train_data, batch_size=128, shuffle=True)
test_loader = DataLoader(test_data, batch_size=128, shuffle=False)
val_loader = DataLoader(val_data, batch_size=128, shuffle=False)
```

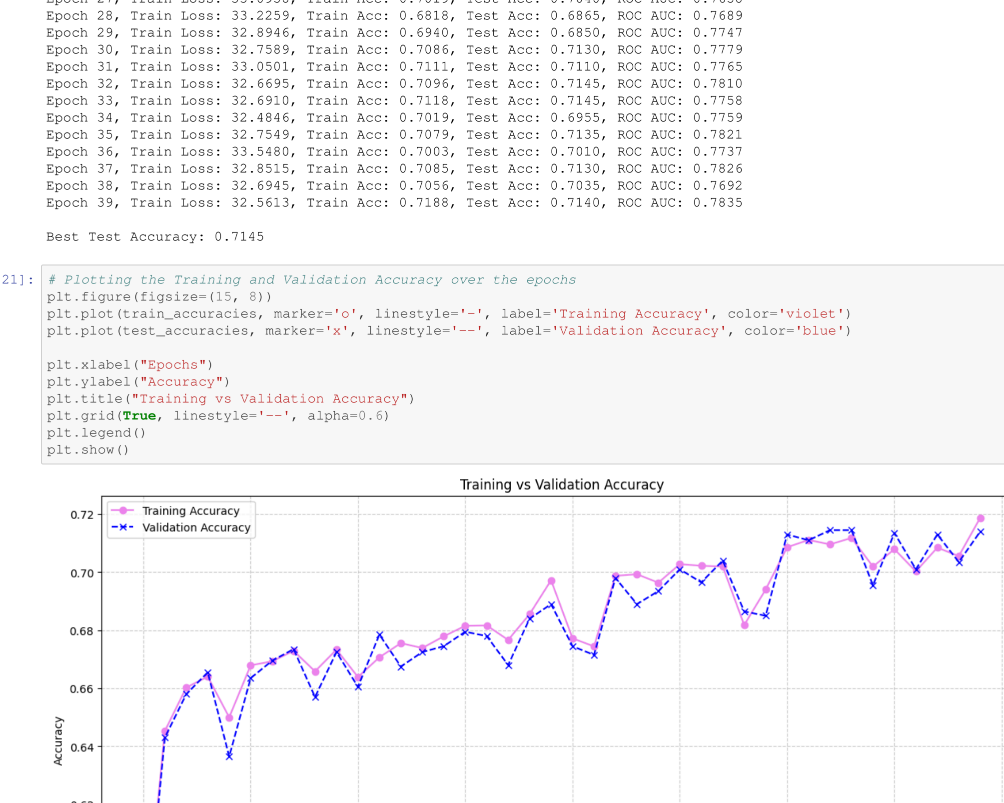
In [18]:
```python
from torch_geometric.nn import GATConv,global_mean_pool
class GNN(torch.nn.Module):
    def __init__(self, in_features, hidden_dim, num_classes):
        super().__init__()

         # Defining the layers of the GCN
        # First GCN layer transforms input features to hidden_dim
        self.layers = nn.ModuleList([
            GATConv(in_features, hidden_dim),
            GATConv(hidden_dim, 2 * hidden_dim),
            GATConv(2 * hidden_dim, hidden_dim)
        ])

        # Fully connected layers to map the hidden feature vector to the output classes
        self.linear = nn.Sequential(
            nn.Linear(hidden_dim, hidden_dim // 4),
            nn.ReLU(),
            nn.Linear(hidden_dim // 4, num_classes)
        )
        self.loss_fn = nn.CrossEntropyLoss()

    def forward(self, x, edge_index, batch):
         # Apply each GCN layer followed by ReLU activation
        for layer in self.layers:
            x = F.relu(layer(x, edge_index))

        # Global mean pooling to aggregate node-level features to graph-level features
        x = global_mean_pool(x, batch)# Pooling the node features for graph classification

        # Pass the pooled graph-level features through the fully connected layers
        return self.linear(x)# Return the output from the linear layers (final classification)
```

In [19]:
```python
def train(model, loader, optimizer, criterion):
    """
    Function to train the model for one epoch.
    Arguments:
        model: The neural network model to train.
        loader: DataLoader instance containing the training dataset.
        optimizer: The optimizer to update the model's weights.
        criterion: The loss function used to compute the error.
    Returns:
        total_loss: Total loss accumulated over all batches in the epoch.
    """
    model.train()
    total_loss = 0
    num_batches = 0
    # Iterate through batches in the DataLoader
    for data in loader:
        data = data.to(device)
        optimizer.zero_grad()
        # Forward pass: Compute predicted outputs by passing the data through the model
        loss = criterion(model(data.x, data.edge_index, data.batch), data.y)
        loss.backward()
        optimizer.step()
        total_loss += loss.item()

    return total_loss

def evaluate(model, loader):
    """
    Function to evaluate the model's performance.
    Arguments:
        model: The trained model to evaluate.
        loader: DataLoader instance containing the validation or test dataset.
    Returns:
        accuracy: The model's accuracy on the given dataset.
    """
    model.eval()
    correct = 0
    # Iterate through batches in the DataLoader
    for data in loader:
        data = data.to(device)
        # Forward pass: Compute predictions and find the class with the highest probability
        pred = model(data.x, data.edge_index, data.batch).argmax(dim=1)
        correct += int((pred == data.y).sum())
    return correct / len(loader.dataset)

# Model initialization: Input features = 3, hidden dim = 64, number of output classes = 2
model = GNN(3, 64, 2).to(device)
# Optimizer: Adam with learning rate of 0.001
optimizer = Adam(model.parameters(), lr=0.001)
# Loss function: CrossEntropyLoss for classification tasks
criterion = nn.CrossEntropyLoss()
```

In [20]:
```python
def compute_roc_auc(model, loader):
    """
    Function to compute ROC AUC score for the model on a given data loader.
    Arguments:
        model: The trained model.
        loader: DataLoader instance containing the validation or test dataset.
    Returns:
        auc_score: The AUC score for the model.
        fpr: False Positive Rate values for ROC curve.
        tpr: True Positive Rate values for ROC curve.
    """
    model.eval()
    y_true, y_scores = [], []
    # Iterate through batches in the DataLoader
    for data in loader:
        data = data.to(device)
        outputs = model(data.x, data.edge_index, data.batch)
        probs = F.softmax(outputs, dim=1)[:, 1].cpu().detach().numpy()
        y_true.extend(data.y.cpu().numpy())
        y_scores.extend(probs)

    # Compute the ROC curve and AUC score
    fpr, tpr, _ = roc_curve(y_true, y_scores)
    return auc(fpr, tpr), fpr, tpr # Return the AUC score, and the FPR and TPR for plotting

train_losses = []
train_accuracies = []
test_accuracies = []
roc_auc_scores = []
best_test_acc = 0

# Training loop for 40 epochs
for epoch in range(40):
    train_loss = train(model, train_loader, optimizer, criterion)
    train_acc = evaluate(model, train_loader)
    test_acc = evaluate(model, test_loader)
    roc_auc, fpr, tpr = compute_roc_auc(model, test_loader)

    train_losses.append(train_loss)
    train_accuracies.append(train_acc)
    test_accuracies.append(test_acc)
    roc_auc_scores.append(roc_auc)

    # Update best test accuracy
    if test_acc > best_test_acc:
        best_test_acc = test_acc

    # Print metrics for the current epoch
    print(f'Epoch {epoch}, Train Loss: {train_loss:.4f}, Train Acc: {train_acc:.4f}, Test Acc: {test_acc:.4f}, ROC AUC: {roc_auc:.4f}')


# After the loop, print the best test accuracy obtained during training
print(f'\nBest Test Accuracy: {best_test_acc:.4f}')
```

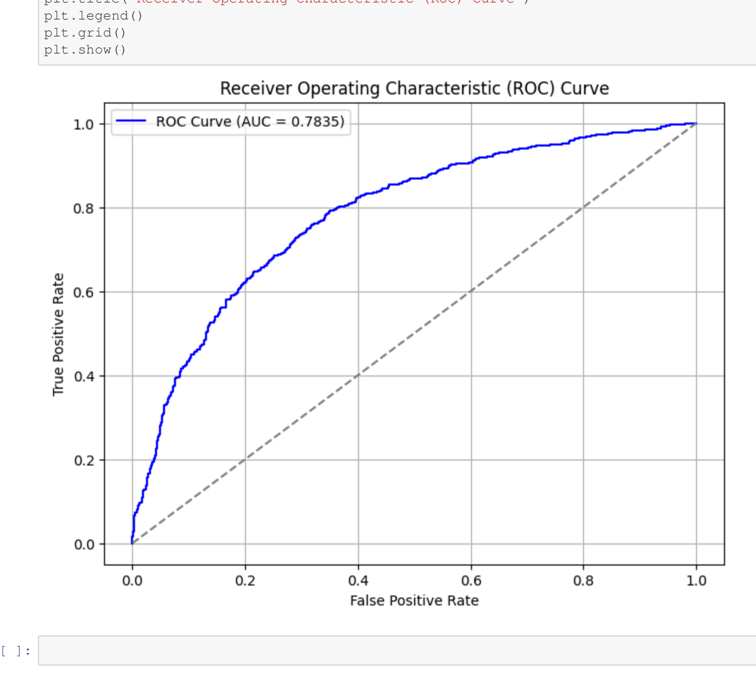
```
Epoch 0, Train Loss: 39.1672, Train Acc: 0.5693, Test Acc: 0.5660, ROC AUC: 0.6248
Epoch 1, Train Loss: 37.7975, Train Acc: 0.6453, Test Acc: 0.6430, ROC AUC: 0.7069
Epoch 2, Train Loss: 36.0635, Train Acc: 0.6603, Test Acc: 0.6580, ROC AUC: 0.7164
Epoch 3, Train Loss: 35.7432, Train Acc: 0.6640, Test Acc: 0.6655, ROC AUC: 0.7202
Epoch 4, Train Loss: 35.3330, Train Acc: 0.6500, Test Acc: 0.6365, ROC AUC: 0.7235
Epoch 5, Train Loss: 35.2203, Train Acc: 0.6679, Test Acc: 0.6635, ROC AUC: 0.7264
Epoch 6, Train Loss: 35.1481, Train Acc: 0.6693, Test Acc: 0.6695, ROC AUC: 0.7274
Epoch 7, Train Loss: 35.0575, Train Acc: 0.6729, Test Acc: 0.6735, ROC AUC: 0.7305
Epoch 8, Train Loss: 35.0719, Train Acc: 0.6658, Test Acc: 0.6570, ROC AUC: 0.7243
Epoch 9, Train Loss: 34.9194, Train Acc: 0.6733, Test Acc: 0.6725, ROC AUC: 0.7354
Epoch 10, Train Loss: 34.9770, Train Acc: 0.6639, Test Acc: 0.6605, ROC AUC: 0.7306
Epoch 11, Train Loss: 34.7864, Train Acc: 0.6707, Test Acc: 0.6785, ROC AUC: 0.7337
Epoch 12, Train Loss: 34.8646, Train Acc: 0.6756, Test Acc: 0.6675, ROC AUC: 0.7318
Epoch 13, Train Loss: 34.7715, Train Acc: 0.6739, Test Acc: 0.6725, ROC AUC: 0.7357
Epoch 14, Train Loss: 34.4670, Train Acc: 0.6779, Test Acc: 0.6745, ROC AUC: 0.7370
Epoch 15, Train Loss: 34.4817, Train Acc: 0.6815, Test Acc: 0.6795, ROC AUC: 0.7431
Epoch 16, Train Loss: 34.3495, Train Acc: 0.6817, Test Acc: 0.6780, ROC AUC: 0.7408
Epoch 17, Train Loss: 34.2530, Train Acc: 0.6767, Test Acc: 0.6680, ROC AUC: 0.7410
Epoch 18, Train Loss: 34.1559, Train Acc: 0.6856, Test Acc: 0.6840, ROC AUC: 0.7452
Epoch 19, Train Loss: 33.8487, Train Acc: 0.6972, Test Acc: 0.6890, ROC AUC: 0.7603
Epoch 20, Train Loss: 33.8468, Train Acc: 0.6772, Test Acc: 0.6745, ROC AUC: 0.7518
Epoch 21, Train Loss: 33.8808, Train Acc: 0.6744, Test Acc: 0.6715, ROC AUC: 0.7442
Epoch 22, Train Loss: 33.6528, Train Acc: 0.6987, Test Acc: 0.6980, ROC AUC: 0.7580
Epoch 23, Train Loss: 33.5755, Train Acc: 0.6993, Test Acc: 0.6890, ROC AUC: 0.7576
Epoch 24, Train Loss: 33.4453, Train Acc: 0.6964, Test Acc: 0.6935, ROC AUC: 0.7575
Epoch 25, Train Loss: 33.4204, Train Acc: 0.7028, Test Acc: 0.7010, ROC AUC: 0.7622
Epoch 26, Train Loss: 33.2922, Train Acc: 0.7022, Test Acc: 0.6965, ROC AUC: 0.7616
Epoch 27, Train Loss: 33.0958, Train Acc: 0.7019, Test Acc: 0.7040, ROC AUC: 0.7658
Epoch 28, Train Loss: 33.2259, Train Acc: 0.6818, Test Acc: 0.6865, ROC AUC: 0.7689
Epoch 29, Train Loss: 32.8946, Train Acc: 0.6940, Test Acc: 0.6850, ROC AUC: 0.7747
Epoch 30, Train Loss: 32.7589, Train Acc: 0.7086, Test Acc: 0.7130, ROC AUC: 0.7779
Epoch 31, Train Loss: 33.0501, Train Acc: 0.7111, Test Acc: 0.7110, ROC AUC: 0.7765
Epoch 32, Train Loss: 32.6695, Train Acc: 0.7096, Test Acc: 0.7145, ROC AUC: 0.7810
Epoch 33, Train Loss: 32.6910, Train Acc: 0.7118, Test Acc: 0.7145, ROC AUC: 0.7758
Epoch 34, Train Loss: 32.4846, Train Acc: 0.7019, Test Acc: 0.6955, ROC AUC: 0.7759
Epoch 35, Train Loss: 32.7549, Train Acc: 0.7079, Test Acc: 0.7135, ROC AUC: 0.7821
Epoch 36, Train Loss: 33.5480, Train Acc: 0.7003, Test Acc: 0.7010, ROC AUC: 0.7737
Epoch 37, Train Loss: 32.8515, Train Acc: 0.7085, Test Acc: 0.7130, ROC AUC: 0.7826
Epoch 38, Train Loss: 32.6945, Train Acc: 0.7056, Test Acc: 0.7035, ROC AUC: 0.7692
Epoch 39, Train Loss: 32.5613, Train Acc: 0.7188, Test Acc: 0.7140, ROC AUC: 0.7835

Best Test Accuracy: 0.7145
```

In [21]:
```python
# Plotting the Training and Validation Accuracy over the epochs
plt.figure(figsize=(15, 8))
plt.plot(train_accuracies, marker='o', linestyle='-', label='Training Accuracy', color='violet')
plt.plot(test_accuracies, marker='x', linestyle='--', label='Validation Accuracy', color='blue')

plt.xlabel("Epochs")
plt.ylabel("Accuracy")
plt.title("Training vs Validation Accuracy")
plt.grid(True, linestyle='--', alpha=0.6)
plt.legend()
plt.show()
```



In [22]:
```python
# Plotting the Training Loss over the epochs
plt.figure(figsize=(15, 8))
plt.plot(train_losses, marker='o', linestyle='-', label='Training Loss', color='blue')

plt.xlabel("Epochs")
plt.ylabel("Loss")
plt.title("Training Loss")
plt.grid(True, linestyle='--', alpha=0.6)
plt.legend()
plt.show()
```

In [23]:
```python
# Compute ROC AUC and False Positive Rate (FPR), True Positive Rate (TPR)
roc_auc, fpr, tpr = compute_roc_auc(model, test_loader)

# Plot the ROC curve
plt.figure(figsize=(8, 6))
plt.plot(fpr, tpr, label=f'ROC Curve (AUC = {roc_auc:.4f})', color='blue')
plt.plot([0, 1], [0, 1], linestyle='--', color='gray')  # Random guess line
plt.xlabel('False Positive Rate')
plt.ylabel('True Positive Rate')
plt.title('Receiver Operating Characteristic (ROC) Curve')
plt.legend()
plt.grid()
plt.show()
```



In [ ]: