

Common_Task_02

quarkgluonClassification

In [1]:	<pre>pip install torch-geometric Downloading torch-geometric-2.6.1-py3-none-any.whl.metadata (63 kB) Collecting torch-geometric Downloading torch-geometric-2.6.1-py3-none-any.whl.metadata (63 kB) Requirement already satisfied: aiohttp in /usr/local/lib/python3.10/dist-packages (from torch-geometric) (3.11.12) Requirement already satisfied: fsspec in /usr/local/lib/python3.10/dist-packages (from torch-geometric) (2024.12.0) Requirement already satisfied: Jinja2 in /usr/local/lib/python3.10/dist-packages (from torch-geometric) (3.1.4) Requirement already satisfied: tqdm in /usr/local/lib/python3.10/dist-packages (from torch-geometric) (4.67.1) Requirement already satisfied: puzil>=5.8.0 in /usr/local/lib/python3.10/dist-packages (from torch-geometric) (5.9.5) Requirement already satisfied: pytorch in /usr/local/lib/python3.10/dist-packages (from torch-geometric) (3.2.0) Requirement already satisfied: requests in /usr/local/lib/python3.10/dist-packages (from torch-geometric) (2.32.3) Requirement already satisfied: scikit-learn in /usr/local/lib/python3.10/dist-packages (from torch-geometric) (1.6.2) Requirement already satisfied: aiohappyhbb[>=2.3.0] in /usr/local/lib/python3.10/dist-packages (from aiohttp->torch-geometric) (2.4.0) Requirement already satisfied: aiohttp[>=4.0.0] in /usr/local/lib/python3.10/dist-packages (from aiohttp->torch-geometric) (4.0.1) Requirement already satisfied: attrs>=17.3.0 in /usr/local/lib/python3.10/dist-packages (from aiohttp->torch-geometric) (25.1.0) Requirement already satisfied: frozenlist>=1.1.1 in /usr/local/lib/python3.10/dist-packages (from aiohttp->torch-geometric) (1.5.0) Requirement already satisfied: multidict<7.0,>=4.5 in /usr/local/lib/python3.10/dist-packages (from aiohttp->torch-geometric) (6.1.0) Requirement already satisfied: propcache>=0.2.0 in /usr/local/lib/python3.10/dist-packages (from aiohttp->torch-geometric) (0.2.1) Requirement already satisfied: yarl<2.0,>=1.17.0 in /usr/local/lib/python3.10/dist-packages (from aiohttp->torch-geometric) (1.18.3) Requirement already satisfied: MarkupSafe>=2.0 in /usr/local/lib/python3.10/dist-packages (from Jinja2->torch-geometric) (3.0.2) Requirement already satisfied: mkl_fft in /usr/local/lib/python3.10/dist-packages (from numpy->torch-geometric) (1.3.8) Requirement already satisfied: mkl_random in /usr/local/lib/python3.10/dist-packages (from numpy->torch-geometric) (1.2.4) Requirement already satisfied: mkl_umath in /usr/local/lib/python3.10/dist-packages (from numpy->torch-geometric) (0.1.1) Requirement already satisfied: mkl in /usr/local/lib/python3.10/dist-packages (from numpy->torch-geometric) (2025.0.2) Requirement already satisfied: tbb4py in /usr/local/lib/python3.10/dist-packages (from numpy->torch-geometric) (2022.0.0) Requirement already satisfied: mkl-service in /usr/local/lib/python3.10/dist-packages (from numpy->torch-geometric) (2.4.1) Requirement already satisfied: charset-normalizer<4,>=2 in /usr/local/lib/python3.10/dist-packages (from requests->torch-geometric) (3.4.1) Requirement already satisfied: idna<4,>=2.5 in /usr/local/lib/python3.10/dist-packages (from requests->torch-geometric) (3.10) Requirement already satisfied: urllib3<3,>=1.21.1 in /usr/local/lib/python3.10/dist-packages (from requests->torch-geometric) (2.3.0) Requirement already satisfied: certifi>=2017.4.17 in /usr/local/lib/python3.10/dist-packages (from requests->torch-geometric) (2025.1.31) Requirement already satisfied: typing-extensions>=4.1.0 in /usr/local/lib/python3.10/dist-packages (from multidict<7.0,>=4.5->aiohttp->torch-geometric) (4.12.2) Requirement already satisfied: intel-openmp>=2024 in /usr/local/lib/python3.10/dist-packages (from mkl->numpy->torch-geometric) (2024.2.0) Downloading torch-geometric-2.6.1-py3-none-any.whl (11.1 MB) 1.1/1.1 MB 19.8 MB/s eta 0:00:00 Installing collected packages: torch-geometric Successfully installed torch-geometric-2.6.1 Note: you may need to restart the kernel to use updated packages.</pre>
In [2]:	<pre>import h5py import numpy as np import torch import torch.nn as nn import torch.nn as nn import matplotlib.pyplot as plt import networkx as nx from sklearn.metrics import roc_curve, auc from sklearn.model_selection import train_test_split from torch_geometric.data import Data, Batch from torch_geometric.loader import DataLoader from torch.optim import Adam import pytorch_lightning as pl import torch.nn.functional as F from torch.nn import Linear</pre>
In [3]:	<pre>device = torch.device("cuda" if torch.cuda.is_available() else "cpu") file_path = "/kaggle/input/autocoder-data/quark-gluon_data-set_n139306.hdf5"</pre>
In [4]:	<pre>print(device) cuda</pre>
In [5]:	<pre>def explore_hdf5(file): with h5py.File(file, 'r') as f: print("Keys in dataset:", f.keys()) for key in f.keys(): print(f"Shape of {key}: {f[key].shape}") explore_hdf5(file_path)</pre> <p>Keys in dataset: ['X_jets', 'm0', 'pt', 'y'] Shape of X_jets: (139306, 125, 125, 3) Shape of m0: (139306,) Shape of pt: (139306,) Shape of y: (139306,)</p>
In [6]:	<pre>def load_data(file_name, sample_size): with h5py.File(file_name, 'r') as f: print("Dataset keys:", f.keys()) print("Total images:", len(f['X_jets'])) print("Image dimensions:", f['X_jets'].shape[1:]) return np.array(f['X_jets'][:sample_size]), np.array(f['y'][:sample_size]) X, y = load_data(file_path, 10000)</pre> <p>Dataset keys: ['X_jets', 'm0', 'pt', 'y'] Total images: 139306 Image dimensions: (125, 125, 3)</p>
In [7]:	<pre>def count_labels(labels): label_counts = np.bincount(labels.astype(np.int64)) return (str(i): count for i, count in enumerate(label_counts)) print(count_labels(y)) {'0': 4994, '1': 5006}</pre>
In [8]:	<pre>def preprocess_images(images): from skimage.transform import resize # Resize to 128x128 and normalize processed = np.array([resize(img, (128, 128), anti_aliasing=True) for img in images], dtype=np.float32) mean, std = np.mean(processed), np.std(processed) return np.clip((processed - mean) / std, 0, None) X = preprocess_images(X)</pre>
In [9]:	<pre>import numpy as np import matplotlib.pyplot as plt from mpl_toolkits.mplot3d import Axes3D def heatmap_with_projection(images, num_samples=3): fig = plt.figure(figsize=(15, 6 * num_samples)) for idx in range(num_samples): # 2D Heatmap ax1 = fig.add_subplot(num_samples, 2, 2*idx + 1) combined_data = np.sum(images[idx], axis=-1) heatmap = ax1.imshow(combined_data, cmap='hot', interpolation='nearest') plt.colorbar(heatmap, ax=ax1) ax1.set_title(f"2D Heatmap - Sample {idx}") # 3D Projection ax2 = fig.add_subplot(num_samples, 2, 2*idx + 2, projection='3d') X, Y = np.meshgrid(combined_data.shape[1:], np.arange(combined_data.shape[0])) ax2.plot_surface(X, Y, combined_data, cmap='viridis') ax2.set_title(f"3D Projection - Sample {idx}") plt.tight_layout() plt.show() heatmap_with_projection(X)</pre>
In [10]:	<pre>from matplotlib.animation import FuncAnimation from IPython.display import HTML def animate_3d_rotation(images, sample_idx=0): fig = plt.figure(figsize=(8, 6)) ax = fig.add_subplot(111, projection='3d') combined_data = np.sum(images[sample_idx], axis=-1) X, Y = np.meshgrid(combined_data.shape[1:], np.arange(combined_data.shape[0])) surf = ax.plot_surface(X, Y, combined_data, cmap='viridis') def update(frame): ax.view_init(elev=20, azim=frame) return fig anim = FuncAnimation(fig, update, frames=np.arange(0, 360, 2), interval=50) plt.close() HTML(anim.to_html5_video()) animate_3d_rotation(X, sample_idx=0)</pre>
Out[10]:	
In [11]:	<pre>def extract_nonzero_mask(images): reshaped = images.reshape((-1, images.shape[1] * images.shape[2], 3)) return np.any(reshaped != [0., 0., 0.], axis=-1).reshape(images.shape[3]) mask = extract_nonzero_mask(X)</pre>
In [12]:	<pre>def create_graph_features(masked_data): indices, features = [], [] for img_idx, mask in enumerate(masked_data): coords = np.column_stack(np.where(mask)) features.append(X[img_idx, coords[:, 0], coords[:, 1], :]) return indices, features indices_list, features_list = create_graph_features(mask)</pre>
In [13]:	<pre>def build_graph_structure(coords, k=4): from scipy.spatial import cKDTree from scipy.sparse import coo_matrix tree = cKDTree(coords) dist, indices = tree.query(coords, k=k) sigma2 = np.mean(dist[:, 1:]**2) weights = np.exp(-dist**2 / sigma2) row, col = np.arange(len(coords)).repeat(k), indices.flatten() return coo_matrix((weights.flatten(), (row, col)), shape=(len(coords), len(coords)))</pre>
In [14]:	<pre>def create_graph_dataset(indices_list, labels, neighbors=8): dataset = [] for i, points in enumerate(indices_list): adjacency = build_graph_structure(points, neighbors) edge_idx = torch.from_numpy(np.vstack((adjacency.row, adjacency.col))).long() edge_weights = torch.from_numpy(adjacency.data).float().view(-1, 1) label = torch.tensor(int(labels[i])).dtype=torch.long graph = Data(x=torch.from_numpy(features_list[i]), edge_index=edge_idx, edge_attr=edge_weights, y=label) dataset.append(graph) return dataset</pre>
In [15]:	<pre>graph_dataset = create_graph_dataset(indices_list, y, neighbors=8)</pre>
In [16]:	<pre>G = nx.Graph() data = graph_dataset[0] edge_tensor = data.edge_index edge_list = [(edge_tensor[0, i].item(), edge_tensor[1, i].item()) for i in range(edge_tensor.shape[1])] G.add_edges_from(edge_list) pos = nx.spring_layout(G, iterations=15, seed=1721) fig, ax = plt.subplots(figsize=(15, 9)) ax.axis("off") nx.draw_networkx(G, pos=pos, ax=ax, node_size=10, with_labels=False, width=0.05) plt.show()</pre> <p>print(f'Number of graphs to work upon : {len(graph_dataset)}') print(f'For the FIRST graph in the graph dataset :') print(f'Type of each graph entity data object : {type(data)}') print(f'Number of nodes : {data.num_nodes}') print(f'Number of edges : {data.num_edges}') print(f'Number of node features : {data.num_node_features}') print(f'Number of edge features : {data.num_edge_features}')</p>
In [17]:	<pre>train_data, test_data = train_test_split(graph_dataset, test_size=0.2, random_state=14) train_loader = DataLoader(train_data, batch_size=16, random_state=14) test_loader = DataLoader(test_data, batch_size=16, shuffle=False) val_loader = DataLoader(val_data, batch_size=16, shuffle=False)</pre>
In [18]:	<pre>from torch.nn import GCNConv, global_mean_pool class GNN(torch.nn.Module): def __init__(self, in_features, hidden_dim, num_classes): super().__init__() self.layers = nn.ModuleList([GCNConv(in_features, hidden_dim), GCNConv(hidden_dim, 2 * hidden_dim), GCNConv(2 * hidden_dim, hidden_dim)]) self.linear = nn.Sequential(nn.Linear(hidden_dim, hidden_dim // 4), nn.ReLU(), nn.Linear(hidden_dim // 4, num_classes)) self.loss_fn = nn.CrossEntropyLoss() def forward(self, x, edge_index, batch): for layer in self.layers: x = F.relu(layer(x, edge_index)) x = global_mean_pool(x, batch) return self.linear(x)</pre>
In [19]:	<pre>def train(model, loader, optimizer, criterion): model.train() total_loss = 0 num_batches = 0 for data in loader: data = data.to(device) optimizer.zero_grad() loss = criterion(model(data.x, data.edge_index, data.batch), data.y) loss.backward() optimizer.step() total_loss += loss.item() return total_loss def evaluate(model, loader): model.eval() correct = 0 for data in loader: data = data.to(device) pred = model(data.x, data.edge_index, data.batch).argmax(dim=-1) correct += int(pred == data.y).sum() return correct / len(loader.dataset) model = GNN(4, 4, 2).to(device) optimizer = Adam(model.parameters(), lr=0.001) criterion = nn.CrossEntropyLoss()</pre>
In [20]:	<pre>def compute_roc_auc(model, loader): model.eval() y_true, y_scores = [], [] for data in loader: data = data.to(device) outputs = model(data.x, data.edge_index, data.batch) probs = F.softmax(outputs, dim=-1, cpu_device=-1).numpy() y_scores.extend(probs) y_true = torch.tensor(y_true, y_scores) return auc(fpr, tpr, fpr, tpr) train_losses = [] train_accuracies = [] test_accuracies = [] roc_auc_scores = [] best_test_acc = 0 for epoch in range(40): train_loss = train(model, train_loader, optimizer, criterion) train_acc = evaluate(model, train_loader) test_acc = evaluate(model, test_loader) roc_auc, fpr, tpr = compute_roc_auc(model, test_loader) train_losses.append(train_loss) train_accuracies.append(train_acc) test_accuracies.append(test_acc) roc_auc_scores.append(roc_auc) # Update best test accuracy if test_acc > best_test_acc: best_test_acc = test_acc print(f'Epoch {epoch}, Train Loss: {train_loss:.4f}, Train Acc: {train_acc:.4f}, Test Acc: {test_acc:.4f}, ROC AUC: {roc_auc:.4f}') print(f'Best Test Accuracy: {best_test_acc:.4f}')</pre> <p>Epoch 0, Train Loss: 38.9843, Train Acc: 0.6038, Test Acc: 0.5970, ROC AUC: 0.7097 Epoch 1, Train Loss: 37.5590, Train Acc: 0.6646, Test Acc: 0.6626, ROC AUC: 0.7231 Epoch 2, Train Loss: 36.8468, Train Acc: 0.6848, Test Acc: 0.6760, ROC AUC: 0.7370 Epoch 3, Train Loss: 35.1756, Train Acc: 0.6914, Test Acc: 0.6880, ROC AUC: 0.7467 Epoch 4, Train Loss: 34.4349, Train Acc: 0.6939, Test Acc: 0.6895, ROC AUC: 0.7529 Epoch 5, Train Loss: 34.2439, Train Acc: 0.6954, Test Acc: 0.6880, ROC AUC: 0.7572 Epoch 6, Train Loss: 34.3309, Train Acc: 0.6915, Test Acc: 0.6915, ROC AUC: 0.7600 Epoch 7, Train Loss: 33.9701, Train Acc: 0.6963, Test Acc: 0.6960, ROC AUC: 0.7630 Epoch 8, Train Loss: 33.7831, Train Acc: 0.7014, Test Acc: 0.6995, ROC AUC: 0.7656 Epoch 9, Train Loss: 33.7409, Train Acc: 0.7013, Test Acc: 0.7035, ROC AUC: 0.7675 Epoch 10, Train Loss: 33.6558, Train Acc: 0.7024, Test Acc: 0.7065, ROC AUC: 0.7700 Epoch 11, Train Loss: 33.4167, Train Acc: 0.7054, Test Acc: 0.7065, ROC AUC: 0.7718 Epoch 12, Train Loss: 33.4624, Train Acc: 0.7053, Test Acc: 0.7090, ROC AUC: 0.7725 Epoch 13, Train Loss: 33.4183, Train Acc: 0.7051, Test Acc: 0.7115, ROC AUC: 0.7742 Epoch 14, Train Loss: 33.0292, Train Acc: 0.7037, Test Acc: 0.6995, ROC AUC: 0.7750 Epoch 15, Train Loss: 32.8394, Train Acc: 0.7179, Test Acc: 0.7165, ROC AUC: 0.7773 Epoch 16, Train Loss: 32.8237, Train Acc: 0.7126, Test Acc: 0.7075, ROC AUC: 0.7770 Epoch 17, Train Loss: 32.6460, Train Acc: 0.7135, Test Acc: 0.7165, ROC AUC: 0.7781 Epoch 18, Train Loss: 32.5271, Train Acc: 0.7119, Test Acc: 0.7060, ROC AUC: 0.7804 Epoch 19, Train Loss: 32.4482, Train Acc: 0.7129, Test Acc: 0.7130, ROC AUC: 0.7804 Epoch 20, Train Loss: 32.2802, Train Acc: 0.7167, Test Acc: 0.7135, ROC AUC: 0.7807 Epoch 21, Train Loss: 32.4910, Train Acc: 0.7171, Test Acc: 0.7165, ROC AUC: 0.7798 Epoch 22, Train Loss: 32.4442, Train Acc: 0.7163, Test Acc: 0.7145, ROC AUC: 0.7807 Epoch 23, Train Loss: 32.4394, Train Acc: 0.7179, Test Acc: 0.7165, ROC AUC: 0.7810 Epoch 24, Train Loss: 32.3283, Train Acc: 0.7149, Test Acc: 0.7100, ROC AUC: 0.7807 Epoch 25, Train Loss: 32.4701, Train Acc: 0.7163, Test Acc: 0.7110, ROC AUC: 0.7811 Epoch 26, Train Loss: 32.3670, Train Acc: 0.7142, Test Acc: 0.7120, ROC AUC: 0.7809 Epoch 27, Train Loss: 32.5638, Train Acc: 0.7154, Test Acc: 0.6995, ROC AUC: 0.7808 Epoch 28, Train Loss: 32.2082, Train Acc: 0.7156, Test Acc: 0.7025, ROC AUC: 0.7814 Epoch 29, Train Loss: 32.1189, Train Acc: 0.7160, Test Acc: 0.7115, ROC AUC: 0.7817 Epoch 30, Train Loss: 32.3968, Train Acc: 0.7136, Test Acc: 0.7145, ROC AUC: 0.7808 Epoch 31, Train Loss: 32.2169, Train Acc: 0.7164, Test Acc: 0.7115, ROC AUC: 0.7817 Epoch 32, Train Loss: 32.3957, Train Acc: 0.7159, Test Acc: 0.7115, ROC AUC: 0.7820 Epoch 33, Train Loss: 32.2124, Train Acc: 0.7169, Test Acc: 0.7100, ROC AUC: 0.7823 Epoch 34, Train Loss: 32.4755, Train Acc: 0.7193, Test Acc: 0.7130, ROC AUC: 0.7820 Epoch 35, Train Loss: 32.1599, Train Acc: 0.7185, Test Acc: 0.7090, ROC AUC: 0.7825 Epoch 36, Train Loss: 32.2576, Train Acc: 0.7137, Test Acc: 0.7110, ROC AUC: 0.7827 Epoch 37, Train Loss: 32.1784, Train Acc: 0.7163, Test Acc: 0.7115, ROC AUC: 0.7832 Epoch 38, Train Loss: 32.0975, Train Acc: 0.7194, Test Acc: 0.7130, ROC AUC: 0.7826 Epoch 39, Train Loss: 32.4635, Train Acc: 0.7178, Test Acc: 0.7100, ROC AUC: 0.7819 Best Test Accuracy: 0.7185</p>
In [21]:	<pre>plt.figure(figsize=(15, 8)) plt.plot(train_accuracies, marker='o', linestyle='--', label='Training Accuracy', color='violet') plt.plot(test_accuracies, marker='x', linestyle='--', label='Validation Accuracy', color='blue') plt.xlabel('Epochs') plt.ylabel('Accuracy') plt.grid(True, linestyle='--', alpha=0.6) plt.legend() plt.show()</pre> <p>Training vs Validation Accuracy</p>
In [22]:	<pre>plt.figure(figsize=(15, 8)) plt.plot(train_losses, marker='o', linestyle='--', label='Training Loss', color='blue') plt.xlabel('Epochs') plt.ylabel('Loss') plt.title('Training Loss') plt.grid(True, linestyle='--', alpha=0.6) plt.legend() plt.show()</pre> <p>Training Loss</p>
In [23]:	<pre>roc_auc, fpr, tpr = compute_roc_auc(model, test_loader) # Plot the ROC curve plt.figure(figsize=(8, 6)) plt.plot(fpr, tpr, label=f'ROC Curve (AUC = {roc_auc:.4f})', color='blue') plt.plot([0, 1], [0, 1], linestyle='--', color='gray') # Random guess line plt.xlabel('False Positive Rate') plt.ylabel('True Positive Rate') plt.title('Receiver Operating Characteristic (ROC) Curve') plt.legend() plt.grid() plt.show()</pre> <p>Receiver Operating Characteristic (ROC) Curve</p>
In []:	