In [2]: import h5py import numpy as np import torch import torch.nn as nn import torch.optim as optim import matplotlib.pyplot as plt import networkx as nx from mpl_toolkits.mplot3d import Axes3D from sklearn.model_selection import train_test_split from sklearn.metrics import roc_curve, auc from torch_geometric.data import Data, Batch from torch_geometric.loader import DataLoader from torch.optim import Adam import pytorch_lightning as pl import torch.nn.functional as F from torch.nn import Linear In [3]: device = torch.device("cuda" if torch.cuda.is_available() else "cpu") file_path = "/kaggle/input/autoencoder-data/quark-gluon_data-set_n139306.hdf5" In [4]: print(device) cuda In [5]: def explore_hdf5(file): with h5py.File(file, "r") as f: print("Keys in dataset:", list(f.keys())) for key in f.keys(): print(f"Shape of {key}: {f[key].shape}") explore_hdf5(file_path) Keys in dataset: ['X_jets', 'm0', 'pt', 'y'] Shape of X_jets: (139306, 125, 125, 3) Shape of m0: (139306,) Shape of pt: (139306,) Shape of y: (139306,) In [6]: def load_data(file_name, sample_size): with h5py.File(file_name, 'r') as f: print("Dataset keys:", list(f.keys())) print("Total images:", len(f['X_jets'])) print("Image dimensions:", f['X_jets'].shape[1:]) X = np.array(f['X_jets'][:sample_size]) y = np.array(f['y'][:sample_size], dtype=np.int64) metadata = np.column_stack((f['m0'][:sample_size], f['pt'][:sample_size])) return X, y, metadata X, y, metadata = load_data(file_path, 10000) Dataset keys: ['X_jets', 'm0', 'pt', 'y'] Total images: 139306 Image dimensions: (125, 125, 3) In [7]: def count_labels(labels): label_counts = np.bincount(labels.astype(np.int64)) return {str(i): count for i, count in enumerate(label_counts)} print(count_labels(y)) {'0': 4994, '1': 5006} In [8]: def preprocess_images(images): from skimage.transform import resize # Resize to 128x128 and normalize processed = np.array([resize(img, (128, 128), anti_aliasing=True) for img in images], dtype=np.float32) mean, std = np.mean(processed), np.std(processed) return np.clip((processed - mean) / std, 0, None) X = preprocess_images(X) In [9]: def normalize_metadata(metadata): mean, std = np.mean(metadata, axis=0), np.std(metadata, axis=0) return (metadata - mean) / std metadata = normalize_metadata(metadata) In [10]: def heatmap_with_projection(images, num_samples=3): fig = plt.figure(figsize=(18, 6 * num_samples)) for idx in range(num_samples): # 2D Heatmap $ax1 = fig.add_subplot(num_samples, 2, 2*idx + 1)$ combined_data = np.sum(images[idx], axis=-1) heatmap = ax1.imshow(combined_data, cmap='hot', interpolation='nearest') plt.colorbar(heatmap, ax=ax1) ax1.set_title(f'2D Heatmap - Sample {idx}') # 3D Projection ax2 = fig.add_subplot(num_samples, 2, 2*idx + 2, projection='3d') X, Y = np.meshgrid(np.arange(combined_data.shape[1]), np.arange(combined_data.shape[0])) ax2.plot_surface(X, Y, combined_data, cmap='viridis') ax2.set_title(f'3D Projection - Sample {idx}') plt.tight_layout() plt.show() heatmap_with_projection(X) 2D Heatmap - Sample 0 3D Projection - Sample 0 50 40 30 30 20 - 20 120 100 10 40 60 80 100 120 -120 2D Heatmap - Sample 1 3D Projection - Sample 1 200 150 150 100 50 100 120 100 100 -50 80 40 60 80 100 120 2D Heatmap - Sample 2 3D Projection - Sample 2 100 80 80 60 60 40 100 20 40 20 60 120 -40 0 20 80 100 120 In [11]: from matplotlib.animation import FuncAnimation from IPython.display import HTML def animate_3d_rotation(images, sample_idx=0): fig = plt.figure(figsize=(8, 6)) ax = fig.add_subplot(111, projection='3d') combined_data = np.sum(images[sample_idx], axis=-1) X, Y = np.meshgrid(np.arange(combined_data.shape[1]), np.arange(combined_data.shape[0])) surf = ax.plot_surface(X, Y, combined_data, cmap='viridis') def update(frame): ax.view_init(elev=20, azim=frame) return fig, anim = FuncAnimation(fig, update, frames=np.arange(0, 360, 2), interval=50) return HTML(anim.to_html5_video()) animate_3d_rotation(X, sample_idx=0) Out[11]: 0:00 / 0:09 In [12]: def extract_nonzero_mask(images): reshaped = images.reshape((-1, images.shape[1] * images.shape[2], 3)) return np.any(reshaped != [0., 0., 0.], axis=-1).reshape(images.shape[:3]) mask = extract_nonzero_mask(X) In [13]: def create_graph_features(masked_data): indices, features = [], [] for img_idx, mask in enumerate(masked_data): coords = np.column_stack(np.where(mask)) features.append(X[img_idx, coords[:, 0], coords[:, 1], :]) indices.append(coords) return indices, features indices_list, features_list = create_graph_features(mask) In [14]: def create_graph_features(masked_data): indices, features = [], [] for img_idx, mask in enumerate(masked_data): coords = np.column_stack(np.where(mask)) features.append(X[img_idx, coords[:, 0], coords[:, 1], :]) indices.append(coords) return indices, features indices_list, features_list = create_graph_features(mask) In [15]: def build_graph_structure(coords, k=4): from scipy.spatial import cKDTree from scipy.sparse import coo_matrix tree = cKDTree(coords) dist, indices = tree.query(coords, k=k) sigma2 = np.mean(dist[:, -1])**2weights = np.exp(-dist**2 / sigma2)row, col = np.arange(len(coords)).repeat(k), indices.flatten() return coo_matrix((weights.flatten(), (row, col)), shape=(len(coords), len(coords))) In [16]: def create_graph_dataset(indices_list, features_list, metadata, labels, neighbors=8): dataset = []for i, points in enumerate(indices_list): adjacency = build_graph_structure(points, k=neighbors) edge_idx = torch.from_numpy(np.vstack((adjacency.row, adjacency.col))).long() edge_weights = torch.from_numpy(adjacency.data).float().view(-1, 1) mass, momentum = metadata[i] mass_tensor = torch.full((features_list[i].shape[0], 1), mass, dtype=torch.float32) momentum_tensor = torch.full((features_list[i].shape[0], 1), momentum, dtype=torch.float32) node_features = torch.from_numpy(features_list[i]).float() node_features = torch.cat((node_features, mass_tensor, momentum_tensor), dim=1) label = torch.tensor([int(labels[i])], dtype=torch.long) graph = Data(x=node_features, edge_index=edge_idx, edge_attr=edge_weights, y=label) dataset.append(graph) return dataset In [17]: graph_dataset = create_graph_dataset(indices_list, features_list, metadata, y, neighbors=8) In [18]: G = nx.Graph()data = graph_dataset[0] edge_tensor = data.edge_index edge_list = [(edge_tensor[0, i].item(), edge_tensor[1, i].item()) for i in range(edge_tensor.shape[1])] G.add_edges_from(edge_list) pos = nx.spring_layout(G, iterations=15, seed=1721) fig, ax = plt.subplots(figsize=(15, 9)) ax.axis("off") nx.draw_networkx(G, pos=pos, ax=ax, node_size=10, with_labels=False, width=0.05) print(f'Number of graphs to work upon : {len(graph_dataset)}') print(f'For the FIRST graph in the graph dataset : ') print(f'Type of each graph entity data object: {type(data)}') print(f'Number of nodes: {data.num_nodes}') print(f'Number of edges: {data.num_edges}') print(f'Number of node features: {data.num_node_features}') print(f'Number of edges features: {data.num_edge_features}') Number of graphs to work upon : 10000 For the FIRST graph in the graph dataset : Type of each graph entity data object: <class 'torch_geometric.data.data.Data'> Number of nodes: 1530 Number of edges: 12240 Number of node features: 5 Number of edges features: 1 In [19]: import torch import torch.nn as nn import torch.nn.functional as F from torch_geometric.nn import SAGEConv, global_mean_pool class GraphEncoder(nn.Module): def __init__(self, point_dim=3, metadata_dim=2, hidden_dim=128, out_dim=64): super().__init__() self.point_encoder = nn.Sequential(nn.Linear(point_dim, hidden_dim // 2), nn.ReLU(), self.metadata_encoder = nn.Sequential(nn.Linear(metadata_dim, hidden_dim // 4), nn.ReLU(), nn.Linear(hidden_dim // 4, hidden_dim // 2), self.conv1 = SAGEConv(hidden_dim, hidden_dim) self.conv2 = SAGEConv(hidden_dim, hidden_dim) self.conv3 = SAGEConv(hidden_dim, out_dim) def forward(self, data): point_features = data.x[:, :3] metadata_features = data.x[:, 3:] point_emb = self.point_encoder(point_features) metadata_emb = self.metadata_encoder(metadata_features) x = torch.cat([point_emb, metadata_emb], dim=1) x = F.relu(self.conv1(x, data.edge_index)) x = F.relu(self.conv2(x, data.edge_index)) $x = self.conv3(x, data.edge_index)$ return global_mean_pool(x, data.batch) In [20]: import torch import torch.nn as nn import torch.nn.functional as F class Model (nn.Module): def __init__(self, encoder, projection_dim=32): super().__init__() self.encoder = encoder self.projector = nn.Sequential(nn.Linear(64, 128), nn.ReLU(), nn.Linear(128, projection_dim), def forward(self, graph): embedding = self.encoder(graph) projected = self.projector(embedding) return F.normalize(projected, dim=1) In [21]: import torch import torch.nn as nn import torch.nn.functional as F class Loss(nn.Module): def __init__(self, temperature=0.1, hard_neg_weight=0.5): super().__init__() self.temp = temperature self.hard_neg_weight = hard_neg_weight def forward(self, features, labels): features = F.normalize(features, dim=1) sim_matrix = torch.matmul(features, features.T) / self.temp mask = torch.eq(labels.unsqueeze(1), labels.unsqueeze(0)).float() exp_sim = torch.exp(sim_matrix) hard_neg_mask = (1 - mask) * (sim_matrix > 0.5).float() log_prob = sim_matrix - torch.log(exp_sim.sum(dim=1, keepdim=True)) weighted_log_prob = log_prob * (mask + self.hard_neg_weight * hard_neg_mask) mean_log_prob = weighted_log_prob.sum(1) / (mask.sum(1) + self.hard_neg_weight * hard_neg_mask.sum(1)) return -mean_log_prob.mean() In [22]: import torch import numpy as np from sklearn.neighbors import KNeighborsClassifier def train(model, train_loader, val_loader, optimizer, criterion, schedular, num_epochs=50, device="cuda"): model.to(device) # Initialize KNN once knn = KNeighborsClassifier(n_neighbors=5) train_losses = [] train_accuracies = [] val_accuracies = [] best_val_acc = 0.0 for epoch in range(num_epochs): model.train() $total_loss = 0$ train_embeddings = [] train_labels = [] # Training phase for batch in train_loader: batch = batch.to(device) optimizer.zero_grad() projections = model(batch) loss = criterion(projections, batch.y.view(-1)) loss.backward() optimizer.step() total_loss += loss.item() with torch.no_grad(): emb = model.encoder(batch).cpu() train_embeddings.append(emb) train_labels.append(batch.y.cpu()) scheduler.step() current_lr = scheduler.get_last_lr()[0] train_embeddings = torch.cat(train_embeddings).numpy() train_labels = torch.cat(train_labels).numpy() knn.fit(train_embeddings, train_labels) train_acc = knn.score(train_embeddings, train_labels) val_acc, val_auc, _, _= evaluate(model, val_loader, knn) if val_loader else 0.0 train_losses.append(total_loss / len(train_loader)) train_accuracies.append(train_acc) val_accuracies.append(val_acc) if val_acc > best_val_acc: best_val_acc = val_acc print(f"Epoch {epoch+1}/{num_epochs} | " f"Loss: {total_loss / len(train_loader):.4f} | " f"Train Acc: {train_acc:.4f} | " f"Val Acc: {val_acc:.4f} | " f"Val ROC-AUC: {val_auc:.4f}") # Print best validation accuracy print(f"\n() Best Validation Accuracy: {best_val_acc:.4f}") return train_losses, train_accuracies, val_accuracies In [23]: import torch import numpy as np def evaluate(model, loader, knn, device="cuda"): model.eval() embeddings = [] labels = []with torch.no_grad(): for batch in loader: batch = batch.to(device) emb = model.encoder(batch).cpu() embeddings.append(emb) labels.append(batch.y.view(-1).cpu()) if not embeddings: return 0.0 embeddings = torch.cat(embeddings).numpy() labels = torch.cat(labels).numpy() val_acc = knn.score(embeddings, labels) probs = knn.predict_proba(embeddings)[:, 1] val_auc = roc_auc_score(labels, probs) if len(np.unique(labels)) > 1 else 0.0 fpr, tpr, _ = roc_curve(labels, probs) if len(np.unique(labels)) > 1 else ([], [], []) return val_acc, val_auc, fpr, tpr In [24]: import torch from torch.utils.data import random_split from torch_geometric.loader import DataLoader from sklearn.neighbors import KNeighborsClassifier from sklearn.metrics import roc_auc_score, roc_curve device = torch.device("cuda" if torch.cuda.is_available() else "cpu") if __name__ == "__main__": train_size = int(0.8 * len(graph_dataset)) val_size = len(graph_dataset) - train_size train_set, val_set = random_split(graph_dataset, [train_size, val_size], generator=torch.Generator().manual_seed(4) 2)) train_loader = DataLoader(train_set, batch_size=16, shuffle=True) val_loader = DataLoader(val_set, batch_size=16) encoder = GraphEncoder(point_dim=3, metadata_dim=2).to(device) model = Model(encoder).to(device) optimizer = torch.optim.Adam(model.parameters(), lr=1e-3) scheduler = torch.optim.lr_scheduler.CosineAnnealingLR(optimizer, T_max=50, eta_min=1e-5) criterion = Loss() train_losses, train_accuracies, val_accuracies= train(model, train_loader, val_loader, optimizer, criterion, scheduler, num_epochs=50, device=device knn = KNeighborsClassifier(n_neighbors=5) train_embeddings, train_labels = [], [] model.eval() with torch.no_grad(): for batch in train_loader: batch = batch.to(device) emb = model.encoder(batch).cpu() train_embeddings.append(emb) train_labels.append(batch.y.cpu()) train_embeddings = torch.cat(train_embeddings).numpy() train_labels = torch.cat(train_labels).numpy() knn.fit(train_embeddings, train_labels) test_acc, test_auc, fpr, tpr = evaluate(model, val_loader, knn, device=device) print(f"\nFinal Test Accuracy: {test_acc:.4f}") print(f"Final Test ROC-AUC: {test_auc:.4f}") Epoch 1/50 | Loss: 2.7715 | Train Acc: 0.7590 | Val Acc: 0.6420 | Val ROC-AUC: 0.7018 Epoch 2/50 | Loss: 2.7703 | Train Acc: 0.7629 | Val Acc: 0.6720 | Val ROC-AUC: 0.6988 Epoch 3/50 | Loss: 2.7696 | Train Acc: 0.7628 | Val Acc: 0.6830 | Val ROC-AUC: 0.7177 Epoch 4/50 | Loss: 2.7692 | Train Acc: 0.7664 | Val Acc: 0.6985 | Val ROC-AUC: 0.7367 Epoch 5/50 | Loss: 2.7690 | Train Acc: 0.7766 | Val Acc: 0.6905 | Val ROC-AUC: 0.7325 Epoch 6/50 | Loss: 2.7687 | Train Acc: 0.7780 | Val Acc: 0.6530 | Val ROC-AUC: 0.7000 Epoch 7/50 | Loss: 2.7685 | Train Acc: 0.7789 | Val Acc: 0.6705 | Val ROC-AUC: 0.7205 Epoch 8/50 | Loss: 2.7684 | Train Acc: 0.7722 | Val Acc: 0.6890 | Val ROC-AUC: 0.7383 Epoch 9/50 | Loss: 2.7684 | Train Acc: 0.7721 | Val Acc: 0.6805 | Val ROC-AUC: 0.7287 Epoch 10/50 | Loss: 2.7684 | Train Acc: 0.7825 | Val Acc: 0.6750 | Val ROC-AUC: 0.7265 Epoch 11/50 | Loss: 2.7684 | Train Acc: 0.7752 | Val Acc: 0.6965 | Val ROC-AUC: 0.7373 Epoch 12/50 | Loss: 2.7682 | Train Acc: 0.7785 | Val Acc: 0.6845 | Val ROC-AUC: 0.7235 Epoch 13/50 | Loss: 2.7683 | Train Acc: 0.7794 | Val Acc: 0.6885 | Val ROC-AUC: 0.7246 Epoch 14/50 | Loss: 2.7683 | Train Acc: 0.7811 | Val Acc: 0.6870 | Val ROC-AUC: 0.7303 Epoch 15/50 | Loss: 2.7682 | Train Acc: 0.7732 | Val Acc: 0.6855 | Val ROC-AUC: 0.7320 Epoch 16/50 | Loss: 2.7681 | Train Acc: 0.7729 | Val Acc: 0.6890 | Val ROC-AUC: 0.7286 Epoch 17/50 | Loss: 2.7681 | Train Acc: 0.7821 | Val Acc: 0.6950 | Val ROC-AUC: 0.7411 Epoch 18/50 | Loss: 2.7679 | Train Acc: 0.7814 | Val Acc: 0.6890 | Val ROC-AUC: 0.7346 Epoch 19/50 | Loss: 2.7679 | Train Acc: 0.7895 | Val Acc: 0.6770 | Val ROC-AUC: 0.7267 Epoch 20/50 | Loss: 2.7677 | Train Acc: 0.7770 | Val Acc: 0.7000 | Val ROC-AUC: 0.7411 Epoch 21/50 | Loss: 2.7680 | Train Acc: 0.7849 | Val Acc: 0.6845 | Val ROC-AUC: 0.7274 Epoch 22/50 | Loss: 2.7678 | Train Acc: 0.7804 | Val Acc: 0.7045 | Val ROC-AUC: 0.7492 Epoch 23/50 | Loss: 2.7679 | Train Acc: 0.7804 | Val Acc: 0.6885 | Val ROC-AUC: 0.7311 Epoch 24/50 | Loss: 2.7677 | Train Acc: 0.7830 | Val Acc: 0.6860 | Val ROC-AUC: 0.7370 Epoch 25/50 | Loss: 2.7675 | Train Acc: 0.7867 | Val Acc: 0.6870 | Val ROC-AUC: 0.7328 Epoch 26/50 | Loss: 2.7677 | Train Acc: 0.7785 | Val Acc: 0.7015 | Val ROC-AUC: 0.7480 Epoch 27/50 | Loss: 2.7678 | Train Acc: 0.7759 | Val Acc: 0.6925 | Val ROC-AUC: 0.7363 Epoch 28/50 | Loss: 2.7675 | Train Acc: 0.7804 | Val Acc: 0.7010 | Val ROC-AUC: 0.7474 Epoch 29/50 | Loss: 2.7674 | Train Acc: 0.7820 | Val Acc: 0.6855 | Val ROC-AUC: 0.7349 Epoch 30/50 | Loss: 2.7676 | Train Acc: 0.7929 | Val Acc: 0.6900 | Val ROC-AUC: 0.7318 Epoch 31/50 | Loss: 2.7675 | Train Acc: 0.7849 | Val Acc: 0.6960 | Val ROC-AUC: 0.7465 Epoch 32/50 | Loss: 2.7673 | Train Acc: 0.7816 | Val Acc: 0.6900 | Val ROC-AUC: 0.7369 Epoch 33/50 | Loss: 2.7675 | Train Acc: 0.7809 | Val Acc: 0.6790 | Val ROC-AUC: 0.7252 Epoch 34/50 | Loss: 2.7673 | Train Acc: 0.7802 | Val Acc: 0.6960 | Val ROC-AUC: 0.7336 Epoch 35/50 | Loss: 2.7671 | Train Acc: 0.7785 | Val Acc: 0.6895 | Val ROC-AUC: 0.7390 Epoch 36/50 | Loss: 2.7673 | Train Acc: 0.7856 | Val Acc: 0.6880 | Val ROC-AUC: 0.7301 Epoch 37/50 | Loss: 2.7674 | Train Acc: 0.7885 | Val Acc: 0.7000 | Val ROC-AUC: 0.7384 Epoch 38/50 | Loss: 2.7672 | Train Acc: 0.7843 | Val Acc: 0.6940 | Val ROC-AUC: 0.7502 Epoch 39/50 | Loss: 2.7671 | Train Acc: 0.7874 | Val Acc: 0.6905 | Val ROC-AUC: 0.7389 Epoch 40/50 | Loss: 2.7671 | Train Acc: 0.7919 | Val Acc: 0.6855 | Val ROC-AUC: 0.7333 Epoch 41/50 | Loss: 2.7673 | Train Acc: 0.7814 | Val Acc: 0.6910 | Val ROC-AUC: 0.7368 Epoch 42/50 | Loss: 2.7672 | Train Acc: 0.7896 | Val Acc: 0.6990 | Val ROC-AUC: 0.7395 Epoch 43/50 | Loss: 2.7671 | Train Acc: 0.7869 | Val Acc: 0.6965 | Val ROC-AUC: 0.7414 Epoch 44/50 | Loss: 2.7671 | Train Acc: 0.7893 | Val Acc: 0.6930 | Val ROC-AUC: 0.7505 Epoch 45/50 | Loss: 2.7670 | Train Acc: 0.7876 | Val Acc: 0.6940 | Val ROC-AUC: 0.7364 Epoch 46/50 | Loss: 2.7669 | Train Acc: 0.7866 | Val Acc: 0.6975 | Val ROC-AUC: 0.7472 Epoch 47/50 | Loss: 2.7669 | Train Acc: 0.7887 | Val Acc: 0.7000 | Val ROC-AUC: 0.7390 Epoch 48/50 | Loss: 2.7669 | Train Acc: 0.7849 | Val Acc: 0.6940 | Val ROC-AUC: 0.7349 Epoch 49/50 | Loss: 2.7668 | Train Acc: 0.7874 | Val Acc: 0.7015 | Val ROC-AUC: 0.7419 Epoch 50/50 | Loss: 2.7669 | Train Acc: 0.7897 | Val Acc: 0.6985 | Val ROC-AUC: 0.7377 6 Best Validation Accuracy: 0.7045 Final Test Accuracy: 0.6980 Final Test ROC-AUC: 0.7326 In [25]: plt.figure(figsize=(15, 8)) plt.plot(train_accuracies, marker='o', linestyle='-', label='Training Accuracy', color='violet') plt.plot(val_accuracies, marker='x', linestyle='--', label='Validation Accuracy', color='blue') plt.xlabel("Epochs") plt.ylabel("Accuracy") plt.title("Training vs Validation Accuracy") plt.grid(True, linestyle='--', alpha=0.6) plt.legend() plt.show() Training vs Validation Accuracy 0.80 Training Accuracy -×- Validation Accuracy 0.78 0.76 0.74 Accuracy 22.0 0.70 0.68 0.66 0.64 10 30 **Epochs** In [26]: plt.figure(figsize=(15, 8)) plt.plot(train_losses, marker='o', linestyle='-', label='Training Loss', color='blue') plt.xlabel("Epochs") plt.ylabel("Loss") plt.title("Training Loss") plt.grid(True, linestyle='--', alpha=0.6) plt.legend() plt.show() Training Loss Training Loss 2.771 2.770 2.769 2.768 2.767 10 20 30 Epochs In [27]: plt.figure(figsize=(8, 6)) plt.plot(fpr, tpr, label=f'ROC Curve (AUC = {test_auc:.4f})', color='blue') plt.plot([0, 1], [0, 1], linestyle='--', color='gray') plt.xlabel('False Positive Rate') plt.ylabel('True Positive Rate') plt.title('Receiver Operating Characteristic (ROC) Curve') plt.legend() plt.grid() plt.show() Receiver Operating Characteristic (ROC) Curve ROC Curve (AUC = 0.7326) 1.0 0.8 True Positive Rate 0.6 0.4 0.2 0.0 0.0 0.2 0.4 0.6 0.8 1.0 False Positive Rate

Specific_Task_01

Collecting torch-geometric

In [1]: pip install torch-geometric

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enmp>=2024->mkl->numpy->torch-geometric) (2024.2.0)

Installing collected packages: torch-geometric Successfully installed torch-geometric-2.6.1

Downloading torch_geometric-2.6.1-py3-none-any.whl (1.1 MB)

Note: you may need to restart the kernel to use updated packages.

1.1)

quark/gluon Classification using Contrastive Loss

Downloading torch_geometric-2.6.1-py3-none-any.whl.metadata (63 kB)

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Requirement already satisfied: typing-extensions>=4.1.0 in /usr/local/lib/python3.10/dist-packages (from multidict<7.

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Requirement already satisfied: mkl-service in /usr/local/lib/python3.10/dist-packages (from numpy->torch-geometric)

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