

Ex:

$$W = \{(v, w, x, y, z) \mid v+s, w-x-z=0\}, \quad y=z$$

$$V = \{(v, w, x, y, z) \mid v+u-3y+z=0\}$$

Find basis of $W \cap V$.

$$A = \begin{bmatrix} 0 & -1 & 0 & -1 \\ 1 & 0 & 0 & -1 \\ 1 & 0 & 1 & -3 \end{bmatrix} \begin{bmatrix} v \\ w \\ x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

\downarrow

A

Ex:

$$A = \begin{bmatrix} 1 & 0 & 0 & -1 & 0 \\ 0 & 1 & -1 & 0 & -1 \\ 1 & 0 & 1 & -3 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 & -1 & 0 \\ 0 & 1 & -1 & 0 & -1 \\ 0 & 0 & 1 & -2 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & -2 & 0 \\ 0 & 0 & 1 & -2 & 1 \end{bmatrix}$$

$$B = \{(1, 0, 1, 2, 1), (0, 1, 0, 0, 1)\}$$

$$B = \{(1, 0, 1, 0, 1), (0, 1, 2, 0, -2), (0, 0, 1, 0, 1)\}$$

$$\sqrt{-y}=0 \quad u=y$$

$$w-2y=0 \quad w=2y$$

$$x-2y+2=0 \quad x=2y$$

$$z+2=y \quad z=y$$

$$= y \begin{pmatrix} 1 & 2 \\ 2 & 1 \\ 0 & 0 \end{pmatrix} + z \begin{pmatrix} 0 & 1 \\ 0 & -1 \\ 1 & 0 \end{pmatrix}$$

Ex: $V = \{(x, y, z) / x+y-z = 0\}$

$$z = x+y$$

$$(x, y, z) = (x, y, x+y)$$

$$= x \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + y \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$$

$$\text{Basis} = \{(1, 0, 1), (0, 1, 1)\}$$

$$\mathbb{R}^n = \{(x_1, x_2, \dots, x_n) / x_i \in \mathbb{R}\}$$

$$e_1 = (1, 0, 0, \dots, 0)$$

$$e_2 = (0, 1, 0, \dots, 0)$$

$$e_n = (0, 0, 0, \dots, 1)$$

$$x \in \mathbb{R}^n = x_1 e_1 + x_2 e_2 + \dots + x_n e_n$$

e_1, \dots, e_n are lin. independent.

$\text{span}(e_1, \dots, e_n)$ at Ex... is?

form basis of \mathbb{R}^n .

$$\begin{bmatrix} 1 & 2 & -1 \\ -1 & 0 & 3 \end{bmatrix}_{m \times n}^{2 \times 3}$$

Row sp. = span $\{ (1, 2, -1), (-1, 0, 3) \}$
 $=$ subsp. of \mathbb{R}^3 (\mathbb{R}^n)

Col. sp. = span $\{ (1, -1), (2, 0), (-1, 3) \}$
 $=$ subsp. of \mathbb{R}^2 (\mathbb{R}^m)

* H.W.

If P is invertible then show that
rows of P form basis of \mathbb{F}^n where \mathbb{F}^n is space
of all row vectors (a_1, a_2, \dots, a_n)

P is invertible $n \times n \rightarrow$ rows of P } basis of \mathbb{F}^n
columns of P

Thm: let V be a vector space which is spanned
by vectors $\{\beta_1, \beta_2, \dots, \beta_m\}$ then any
lin. indep. subset of V cannot have more
than m vectors.

PS: ~~any~~ set of vectors $\{\alpha_1, \dots, \alpha_n\}$ where
 $n \geq m$, is lin. dep.

det of $\alpha_1, \dots, \alpha_n$ be det of n vectors of V

$$x_1\alpha_1 + x_2\alpha_2 + \dots + x_n\alpha_n = \sum_{j=1}^n x_j\alpha_j \quad \text{--- (1)}$$

We know $\{\beta_1, \dots, \beta_m\}$ spans V

$$\Rightarrow \alpha_j = \sum_{i=1}^m a_{ij}\beta_i \quad \text{--- (2)}$$

$$\alpha_1 = a_{11}\beta_1 + a_{21}\beta_2 + \dots + a_{m1}\beta_m$$

for all other α_i we have $a_{ij} \neq 0$ for some j

$$\alpha_n = a_{1n}\beta_1 + a_{2n}\beta_2 + \dots + a_{mn}\beta_m$$

from ① & ②,

$$\alpha_1, \alpha_2, \dots, \alpha_n \text{ are linearly independent} \iff \sum_{i=1}^n x_i \alpha_i = 0 \iff \sum_{i=1}^n x_i A_{ij} \beta_j = 0 \quad i=1 \dots m$$

$$\sum_{i=1}^n x_i A_{ij} \beta_j = 0 \iff \sum_{i=1}^n (A_{ij} x_i) \beta_i = 0 \quad i=[1, m]$$

Now look at $Ax = \sum A_{ij} x_j = 0 \quad i=[1, m]$

$n > m$ therefore there are $m - n$ eq's & n variables ($n < m$)

\Rightarrow There are free variables.

$\Rightarrow Ax=0$ has non-trivial solns.

Let us denote it as (c_1, \dots, c_n)

$$c_1 \alpha_1 + c_2 \alpha_2 + \dots + c_n \alpha_n = \sum_{i=1}^n (A_{ij} c_j) \beta_i$$

$$= 0\beta_1 + 0\beta_2 + \dots + 0\beta_m$$

$c_1, c_2, \dots, c_n \in \mathbb{R}$

$\Rightarrow \alpha_1, \alpha_2, \dots, \alpha_n$ are linearly dependent.

using $\alpha = (c_1, \dots, c_n)$

$\alpha = (c_1, \dots, c_n)$ is a linear combination of β_1, \dots, β_m

Thm: If V vector sp. of dimension n then any 2 basis of V have same no. of elements.

Pf: Let B_1 & B_2 are basis of V containing $m \leq n$ elements resp.
W.l.o.g. let $m \geq n$.

$$B_1 = \{u_1, u_2, \dots, u_m\} \quad m \geq n$$

$$B_2 = \{v_1, v_2, \dots, v_n\} \quad \text{both are basis}$$

By prev. result, $\{v_1, v_2, \dots, v_n\}$ span V

\therefore Any set containing more than n vectors are linearly dependent.

$\therefore \{u_1, u_2, \dots, u_m\}$ are not linearly & indep.

$\therefore B_1$ with $m (\geq n)$ elements will not be basis.

\therefore By contradiction, no. of elements (B_1) = no. of elements (B_2)

* No. of elements in basis is called DIMENSION.

* Corollaries:

① If $\dim(V) = n$, any set containing $\geq n$ elements is lin. dep. set.

② If $\dim(V) = n$ then no set containing $< n$ elements can span V .

dim. (V) = n

$\{v_1, v_2\}$ lin. indep. set

$v_3 \notin \text{span} \{v_1, v_2\} \rightarrow$ You cannot write v_3 as lin. combination of v_1, v_2

$\Rightarrow \{v_1, v_2, v_3\}$ is lin. indep. set

likewise $\{v_1, v_2, v_3, v_4\}, \dots$

$\{v_1, v_2, v_3, \dots, v_n\}, \dots$

dim = n then any $(n+1)$ vectors are lin. dep.

In other words, if dim. (V) = n, then any linearly independent set containing n vectors forms basis of V.

Computation with basis.

B_1, B_2 two sets of basis. If

How are they connected?

Ordered Basis :

$$B_1 = \{(0, 1), (1, 0)\}$$

$$B_2 = \{(0), (0, 1)\}$$

$$B = \{v_1, v_2\}$$

$$B_1 \neq B_2$$

* Co-ordinate :

$$V = \mathbb{R}^3$$

$$B = \left\{ \underbrace{(1, 1, 1)}_{v_1}, \underbrace{(1, 0, 0)}_{v_2}, \underbrace{(0, 0, 1)}_{v_3} \right\}$$

$$v = (4, -3, 2) \in V$$

as B spans V , $v = v_1x_1 + v_2x_2 + v_3x_3$

$$\Rightarrow (4, -3, 2) = x_1(1, 1, 1) + x_2(0, 1, 0) + x_3(1, 0, 0)$$

$$\Rightarrow 4 = x_1 + x_2 + x_3$$

$$\Rightarrow -3 = x_2 + x_3$$

$$\Rightarrow 2 = x_3$$

$$\Rightarrow x_3 = 2, x_2 = -5, x_1 = 7$$

$\begin{bmatrix} 7 \\ -5 \\ 2 \end{bmatrix}$ is called co-ordinate of v w.r.t B

$$v = x_1v_1 + x_2v_2 + \dots + x_nv_n$$

then $\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$

is called co-ordinate vector of v w.r.t $\{v_1, v_2, \dots, v_n\}$

x_1 is called 1st component

x_n is called n th component.

$$(v_1, v_2, v_3) \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = v_1 x_1 + v_2 x_2 + v_3 x_3$$

B

$$x_1 = \text{?} \quad \checkmark$$

* $P_2(\mathbb{R})$ = Vector sp. of all poly. of degree ≤ 2 over \mathbb{R}

$$B = \{ (1-x, 1+x, x^2) \}$$

$$a_0 + a_1 x + a_2 x^2 =$$

$$\alpha - \alpha x + \beta + \beta x$$

$$\alpha + \beta = a_0$$

$$\beta - \alpha = a_1$$

$$\beta = \frac{a_1 + a_0}{2}$$

$$\therefore \alpha = \frac{a_0 - a_1}{2}$$

$$x = \begin{pmatrix} a_0 - a_1 \\ 2 \\ a_0 + a_1 \\ 2 \\ a_1 \end{pmatrix}$$

* $\{v_1, v_2, v_3\}$ of vector sp. V of dim n .

when $w_1, w_2 \in \text{span} \{v_1, v_2, v_3\}$

$$w_1 = Bx_1$$

$$w_2 = Bx_2$$

$$[v_1, v_2, v_3] [x_1, x_2] = (w_1, w_2)$$

$$\begin{bmatrix} v_1 & v_2 & v_3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} v_1 x_1 + v_2 x_2 + v_3 x_3 \\ v_1 y_1 + v_2 y_2 + v_3 y_3 \end{bmatrix}$$

↓
Row matrix

$$B = X_{3 \times 2} = (w_1, w_2)$$

* $\{(1, 0, 0), (0, 1, 0), (1, 0, 0)\} = B$

$$w_1 = (4, -3, 2) \quad w_2 = (1, -1, 0)$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 4 & -3 & 1 \\ -3 & -1 & 0 \\ 2 & 0 & 0 \end{bmatrix} = (w_1, w_2)$$

* $B_1 = \{u_1, u_2, \dots, u_m\}$

$B_2 = \{v_1, v_2, \dots, v_n\}$

$$B_1 \cdot []_{n \times n} = B_2$$

$$Bx = y$$

y is vector of V

If B is invertible, $x = B^{-1}y$.

$\text{Basis}(B) = \{v_1, \dots, v_n\}$

Co-ordinate of v w.r.t B = $[v]_B$

$$\star v_1 = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \quad v_2 = \begin{bmatrix} 3 \\ 5 \end{bmatrix} \text{ basis of } \mathbb{R}^2$$

$$B = [v_1 \ v_2] = \begin{bmatrix} 1 & 3 \\ 2 & 5 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 3 \\ 2 & 5 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} x_1 + 3x_2 \\ 2x_1 + 5x_2 \end{bmatrix}$$

$$\text{Let } x_1 = x_2 = 1 ; \quad = \begin{bmatrix} 4 \\ 7 \end{bmatrix}$$

$$\begin{bmatrix} 4 \\ 7 \end{bmatrix}_B = \text{Span} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\begin{pmatrix} 4 \\ 7 \end{pmatrix} \in \text{Span}(v_1, v_2)$$

~~* $v \rightarrow \text{dim}(B)$, $B = \{v_1, \dots, v_n\}$~~

~~then $v \in \text{Span}$~~

~~* $V = \mathbb{R}^n$~~

~~$[v_1, \dots, v_n]$, $y \in V$ arbitrary vector~~

~~we say $y \in \text{Span}(v_1, \dots, v_n)$ if \exists column~~

~~vector x s.t. $(v_1, \dots, v_n)x = \begin{bmatrix} y_1 \\ y_n \end{bmatrix}$~~

"y"

We say $y_1, y_2 \in \text{span}(v_1, \dots, v_m)$,

if $\exists x_1, x_2$ s.t. $Bx_1 = y_1$, $Bx_2 = y_2$

In other words, if we can opt. matrix

i.e., $A = \begin{bmatrix} x_1 & x_2 \end{bmatrix}$, s.t.

$$BA = Y, \quad Y = \text{span}(y_1, y_2)$$

Eg. $\begin{bmatrix} 1 & 3 \\ 2 & 5 \end{bmatrix}$ vectors of \mathbb{R}^2

Thm

$$\begin{bmatrix} 1 & 3 \\ 2 & 5 \end{bmatrix} \begin{bmatrix} 1 & 2 & 5 \\ -1 & -3 & 1 \end{bmatrix} = \begin{bmatrix} -2 & 7 & 26 \\ -3 & -11 & 45 \end{bmatrix}$$

$w_1 \quad w_2 \quad w_3$

P.S.

$$[w_1] = \begin{bmatrix} -2 \\ -3 \end{bmatrix} \quad [w_2] = \begin{bmatrix} -7 \\ -11 \end{bmatrix} \quad [w_3] = \begin{bmatrix} 26 \\ 45 \end{bmatrix}$$

Thm: V be vector space of dim n & let $\{v_1, \dots, v_m\}$ be any subset of V : $\{w_1, \dots, w_n\}$ is in $\text{span}(v_1, \dots, v_m)$ if $\exists A$ s.t. $[v_1 \dots v_m]A = (w_1, w_2, \dots, w_n)$

$\parallel V = \mathbb{R}^n$

Eg: $\begin{bmatrix} 1 & 3 \\ 2 & 5 \end{bmatrix}$ is invertible matrix

$$B^{-1} = \begin{bmatrix} 3 & -1 \\ -5 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 1 \\ 2 & 3 & 1 \end{bmatrix}$$

$$Y = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$



$$x = B^{-1} y$$

$$= \begin{bmatrix} -5 & 3 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 4 \end{bmatrix}$$

$$= \begin{bmatrix} -7 \\ -2 \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ 4 \end{bmatrix}_B = \begin{bmatrix} -7 \\ -2 \end{bmatrix}$$

Two. Let A be $n \times n$ matrix with entries in \mathbb{F} .
The columns of A forms basis of \mathbb{F}^n iff A is invertible.

Pf: Dim of \mathbb{F}^n is n over \mathbb{F}

A is $n \times n$ matrix so:

Case 1: Suppose columns of A form basis of \mathbb{F}^n , then they are lin. indep. They are lin. of them so $A x = 0$ has only trivial sol $\Rightarrow A$ is inv.

Conversely: suppose A is invertible.

\Rightarrow columns of A are lin. indep. They are lin. of them which is dim of \mathbb{F}^n .

\Rightarrow Columns of A form basis of \mathbb{F}^n .

map between them which is injective & surjective.

papergrid

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Thm: If V is vector space of dimension n , then V is isomorphic to \mathbb{F}^n .

Rmk: All

Pf: $\dim(V) = n \dots$ fix some basis
 $\left[\begin{array}{c} v_1 \\ v_2 \\ \vdots \\ v_n \end{array} \right]$ space of all column vectors

$B = (v_1, v_2, \dots, v_n)$ if V . Then any vector $v \in V$ will have unique representation $v = x_1 v_1 + x_2 v_2 + \dots + x_n v_n$.

Define function $\Psi: \mathbb{F}^n \rightarrow V$ s.t.

$$\Psi \left[\begin{array}{c} x_1 \\ x_2 \\ \vdots \\ x_n \end{array} \right] \rightarrow x_1 v_1 + x_2 v_2 + \dots + x_n v_n$$

Ψ is surjective: Because for every $v \in V$ we have unique $\left[\begin{array}{c} x_1 \\ x_2 \\ \vdots \\ x_n \end{array} \right]$

Ψ is surjective: Because for every $v \in V$ we have

$$\Psi \left(\begin{array}{c} x_1 \\ x_2 \\ \vdots \\ x_n \end{array} \right) = v$$

∴ Ψ is surjective.

Ψ is injective: Let $\Psi(x_1) = \Psi(x_2)$

$$x_1 = \left[\begin{array}{c} \alpha_1 \\ \vdots \\ \alpha_n \end{array} \right] \quad x_2 = \left[\begin{array}{c} \beta_1 \\ \vdots \\ \beta_n \end{array} \right]$$

$$\Rightarrow \alpha_1 v_1 + \dots + \alpha_n v_n = \beta_1 v_1 + \dots + \beta_n v_n$$

$\Rightarrow \alpha_i = \beta_i \quad i = 1 \text{ to } n \rightarrow$ every element has unique representation.

$$\Rightarrow x_1 = x_2$$

Rmk: All finite dimensional vector spaces are classified.

If $\dim(V) = n$ then $V \cong \mathbb{R}^n$,
isomorphism.

Change of Basis:

Let V be finite diml vector space of $\dim n$.

Let $B = (v_1, v_2, \dots, v_n)$

$B' = (w_1, w_2, \dots, w_n)$ are 2 basis of V .

As w_1, w_2, \dots, w_n are basis of V we can write each v_i as linear comb.

of w_1, w_2, \dots, w_n .

In other words, $(v_1, v_2, \dots, v_n) \in \text{span}(w_1, \dots, w_n)$

$\Rightarrow \exists$ matrix P s.t. $[v_i]$

$$(w_1, w_2, \dots, w_n) P = (v_1, v_2, \dots, v_n)$$

$$(w_1, w_2, \dots, w_n) [x_1 \dots x_n] = [v_1, \dots, v_n]$$

$$B' \times P = B$$

$$x_i = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

$$[v_i]_{B'} = x_i$$

$$\text{Hence } [v_i]_{B'} = x_i \quad i = 1 \text{ to } n$$

Matrix P is called matrix of change of basis from B' to B .

Claim: P is invertible.

Pf: Now we can (w_1, \dots, w_n) in terms of (v_1, \dots, v_n) because (v_1, \dots, v_n) are also basis.

$$\Rightarrow \exists P' \text{ s.t.}$$

$$BP' = B'$$

$$\text{Also, } B'P = B$$

~~$$\therefore P^{-1} = P'$$~~

$$\therefore B'PP' = B' \quad \Rightarrow \quad B'P = I$$

$$\Rightarrow PP' = I$$

~~$$\therefore P^{-1} = P'$$~~

Because B' is basis (every element has unique representation)

Rmk: For any vector $v \in V$,

$$[v]_B = x \quad \& \quad [v]_{B'} = x'$$

Connection between x & x' ?

$$\Rightarrow BX = v \quad \Rightarrow B'x' = v$$

$$\Rightarrow B'P^{-1}x = v \quad \Rightarrow B'x' = v$$

~~$$\Rightarrow BX = B'x'$$~~

~~$$\Rightarrow B'P^{-1}x = B'x'$$~~

~~$$\Rightarrow P^{-1}x = x'$$~~

$P^{-1}x$ & x' are 2 coordinate vectors of v wrt B' .

$$\Rightarrow P^{-1}x = x'$$

$$\dim(V) = n$$

$$B = (v_1, v_2, \dots, v_n) \text{ basis of } V$$

Let (w_1, w_2, \dots, w_n) be ANY n vectors of V s.t. $(w_1, w_2, \dots, w_n) \in \text{Span}(B)$
i.e. each $w_i = \text{lin. combination of } (v_1, \dots, v_n)$

Not necessary

$$\exists \text{ matrix } A \text{ s.t. } BA = (w_1, \dots, w_n)$$

claim: (w_1, \dots, w_n) forms basis of V iff
 A is invertible.

$$A = [x_1, \dots, x_n]$$

$$x_i = [w_i]_B$$

Pf: Let $B' = [w_1, \dots, w_n]$.

Suppose B' is basis of V , then,

$BA = B' \Rightarrow A$ is matrix of change
of basis
 $\Rightarrow A$ is invertible.

Suppose A is invertible. \Rightarrow ~~iff~~

$$\Rightarrow B = B' A^{-1} \text{ as } BA = B'$$

$$\Rightarrow B \subseteq \text{span of } B'$$

$$\Rightarrow V = \text{Span}(B) \subseteq \text{Span}(B')$$

$$\Rightarrow V \subseteq \text{span}(B')$$

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Date: / /

B' has n vectors $\Rightarrow \dim(V) = n$,

\therefore All vectors in B' are lin. indep.

$\therefore B'$ is basis of V .

B_{Basis}

Rmk:

If we start with some basis $B = (v_1, \dots, v_n)$,
then all other basis can be obtained
by multiplying any invertible matrix P to B .

BP is new basis.

Assignment 3

A1 -

$$A = \begin{bmatrix} 5 & 1 & 1 & 9 \\ 1 & 5 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{bmatrix}$$

A2 - $a u_1 + b u_2 + c u_3 = w$

$$a + 4b + 1c = 12 \quad (1)$$

$$a + 2c = 1 \quad (2)$$

$$2b + c = 5 \quad (3)$$

$$2a + b + 3c = 10 \quad (4)$$

$$2a + b + 3c = 10 \quad (4)$$

$$2a + b + 3c = 10 \quad (4)$$

$$c - b = 2$$

$$3b = 3$$

$$b = 1$$

$$c = 3$$

$$a = -5$$

$$w = -5u_1 + 4u_2 + 3u_3$$

A3 - $a + b + c = 9$

$$2a + 3b + c = 9$$

$$2a + 3b = 8$$

$$a + 2b + 3c = 8$$

$$a + 2b = 5$$

$$a + b + 2c = 5$$

$$a + b = 3$$

$$\Rightarrow c = 1$$

$$b = 2$$

$$a = 1$$

Yes

$$\begin{bmatrix} 1 & 1 & 1 & 9 \\ 2 & 3 & 1 & 9 \\ 1 & 2 & 3 & 8 \\ 1 & 1 & 2 & 5 \end{bmatrix}$$

A4- $f(x) = ax^3 + bx^2 + cx + d$

$$f(0) = d$$

$$f(1) = a+b+c+d$$

$$\boxed{a+b+c=0}$$

$$S = \{ ax^3 + bx^2 + cx + d \mid a, b, c, d \in \mathbb{R}; a+b+c=0 \}$$

$$v_1 = (a, b, -(a+b), d)$$

$$v_2 = (a', b', -(a'+b'), d')$$

$$\begin{aligned} \alpha v_1 + \beta v_2 &= (\alpha a + a')x^3 + (\alpha b + b')x^2 + (\alpha(-a-b) + c)x + d \\ &= \alpha(a+b+c) + \beta(a'+b'+c') + d + d' \end{aligned}$$

$$v_1 + v_2 = 0 + 0 + -d+d' \in S$$

\therefore It is subspace of P_3 .

A5- (a) $\alpha A = \alpha A^T$

$$\beta B = \beta B^T$$

$$\begin{aligned} (\alpha A + \beta B)^T &= \alpha A^T + \beta B^T \\ &= \alpha A + \beta B \end{aligned}$$

(b) $A = I$

$$B = -I$$

$$A+B = 0 \text{ is not invertible}$$

(c) \checkmark

(d) $\alpha A = -\alpha A^T$

$$\beta B = -\beta B^T$$

$$(\alpha A + \beta B)^T = -\alpha A^T - \beta B^T$$

(a) \times

$$\alpha a_1 + \beta a_2 = a_3$$

$$\alpha(a_1, a_2, a_3) = \alpha(a_1^*, a_2^*, a_3)$$

$$(\alpha a_1 + \beta a_2), (\alpha a_2 + \beta a_3), (\alpha a_3 + \beta a_1)$$

$$\alpha(a_1 + \beta a_2) = \alpha a_3 + \beta a_1$$

 \checkmark

$$(c) a_2 = a_1^*$$

$$\alpha(a_1, a_1^*, \dots) \\ + \beta(a_2, a_2^*, \dots)$$

$$\alpha(a_1 + \beta a_2, a_1^* + \beta a_2^*, \dots)$$

 \times

$$(d) a_1, a_2 = 0$$

$$\alpha(a_1, a_2, \dots) \\ + \beta(a_1^*, a_2^*, \dots)$$

$$(a_1 + \beta a_1^*) \cdot (a_2 + \beta a_2^*) = \cancel{\alpha^2 a_1 a_2} - \cancel{\beta^2 a_1^* a_2^*} \\ - \cancel{\alpha \beta a_1 a_2^*} - \cancel{\beta \alpha a_1^* a_2}$$

 \times \approx

$$(e) \checkmark$$

A7 - $\begin{pmatrix} 0 \\ a \end{pmatrix}$ ✓

A8 - $\begin{pmatrix} 0 \\ 0 \end{pmatrix}$ ✓

$$\begin{pmatrix} 9 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 \\ b \end{pmatrix}$$

$$\begin{pmatrix} 9 \\ b \end{pmatrix}$$

A9 - $\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$ ✓ $\begin{pmatrix} 0 \\ b \\ 0 \end{pmatrix}$ ✓ $\begin{pmatrix} 9 \\ b \\ 0 \end{pmatrix}$ ✓

$$\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \checkmark \quad \begin{pmatrix} 0 \\ 0 \\ c \end{pmatrix} \checkmark \quad \begin{pmatrix} 9 \\ 0 \\ c \end{pmatrix} \checkmark$$

$$\begin{pmatrix} 9 \\ b \\ c \end{pmatrix} \checkmark \quad \begin{pmatrix} 0 \\ b \\ c \end{pmatrix} \checkmark$$

A10 - a) $w_1 = u + v$

$$= \begin{bmatrix} 3 \\ 1 \\ -1 \end{bmatrix}$$

b) $w_2 = \begin{bmatrix} 3 \\ 0 \\ 0 \end{bmatrix}$

$$\text{Ex: } B = \{(1,1,1), (1,-1,1), (1,1,0)\}$$

$$B' = \{(1,0,0), (1,1,0), (1,1,1)\}$$

$$V = \mathbb{R}^3$$

$$B'P = B$$

matrix of
change of basis

$$\begin{aligned} [v]_B &= x \\ [v]_{B'} &= x' \end{aligned} \quad \left. \begin{array}{l} \\ \end{array} \right\} Px = x'$$

$$\text{Def: } (1,1,1) = a_1(1,0,0) + a_2(1,1,0) + a_3(1,1,1)$$

$$[(1,1,1)]_{B'} = [0 \ 0 \ 1]^T$$

$$\begin{aligned} (1, -1, 1) &= " \\ 1 &= a_1 + a_2 + a_3 \\ -1 &= a_2 + a_3 \\ 1 &= a_3 \\ a_2 &= -2 \end{aligned}$$

$$a_1 = 2$$

$$[(1,-1,1)]_{B'} = (2 \ -2 \ 1)^T$$

$$\text{likewise } [v]_{B'} = [0 \ 1 \ 0]^T$$

$$\therefore P = \begin{bmatrix} 0 & 2 & 0 \\ 0 & -2 & 1 \\ 1 & 1 & 0 \end{bmatrix}$$

$$(x \ y \ z)_B = a_1(100) + a_2(110) + a_3(111)$$

$$x = a_1 + a_2 + a_3$$

$$y = a_2 + a_3$$

$$z = a_3$$

$$a_3 = z, \quad a_2 = y - z, \quad a_1 = x - y$$

$$x^1 = [(x, y, z)_B] = \begin{bmatrix} x-y \\ y-z \\ z \end{bmatrix}$$

$$(x, y, z)_B = a_1(1, 1, 1) + a_2(1, -1, 1) + a_3(1, 1, 0)$$

$$x = a_1 + a_2 + a_3 \quad \quad \quad \frac{x-y}{2} = a_2$$

$$y = a_1 - a_2 + a_3$$

$$z = a_1 + a_2$$

$$a_1 = z - \frac{x-y}{2}$$

$$a_1 = \frac{2z - x + y}{2}$$

$$\cancel{a_1 0} - a_3 = x - z$$

$$x = [(x, y, z)_B]_8 = \begin{bmatrix} 2z - x + y \\ \frac{x-y}{2} \\ x-z \end{bmatrix}$$

$$Px = \begin{bmatrix} 0 & 2 & 0 \\ 0 & -2 & 1 \\ 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} (2z - x+y)/2 \\ (x-y)/2 \\ x-z \end{bmatrix}$$

$$= \begin{bmatrix} x-y \\ y-x+z-z \\ z \end{bmatrix}$$

$$Px = x'$$

Linear Transformation

Let V & W are 2 vector spaces over \mathbb{F}

A map $T: V \rightarrow W$ is called linear transformation, If it satisfies following:

- ① $\forall u, v \in V \quad T(u+v) = T(u) + T(v)$
- ② $\forall c \in \mathbb{F} \quad T(cu) = cT(u)$

Rmk: ① $T(0_V) = 0_W$ $0_V = 0_V + 0_V$
 $T(0_V) = T(0_V) + T(0_V)$
 $\Rightarrow T(0_V) = 0_W$

Ex: ① $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$
 $T(x, y) = (x+1, y+3) \rightarrow$ not linear trans
 $T(0, 0) = (1, 3) \neq (0, 0)$

② $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$
 $T(V) = V$ Id map
 It's linear trans.

③ $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$
 $T(x, y, z) \rightarrow (x, y, 0) \quad (\checkmark)$

④ Let A an $n \times n$ matrix, then A gives linear trans.

$$T: \mathbb{F}^n \rightarrow \mathbb{F}^m$$

$$T: V \rightarrow AV$$

$$\mathbb{F}^n = \left\{ \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \mid x_i \in \mathbb{F} \right\}$$

$$V = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}, \quad A = \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \dots & a_{mn} \end{bmatrix}$$

$x_i \in \mathbb{F}$

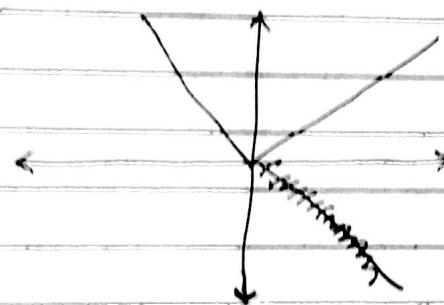
Av

$$\left[\begin{array}{c} \vec{a}_1, \vec{x}_1 \\ \vdots \\ \vec{a}_m, \vec{x}_j \end{array} \right] \quad \left[\begin{array}{c} \beta_1 \\ \vdots \\ \beta_m \end{array} \right] \quad C H''$$

Ex: $A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$

$A: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

$$\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \rightarrow \begin{bmatrix} -y \\ x \end{bmatrix}$$



Ex: $A = \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix}$

$x = (r, \alpha) \rightarrow$ polar co ordinates

$$v = \begin{bmatrix} r\cos\alpha \\ r\sin\alpha \end{bmatrix}$$

$$Av = \begin{bmatrix} r\cos\theta\cos\alpha - r\sin\theta\sin\alpha \\ r\sin\theta\cos\alpha + r\cos\theta\sin\alpha \end{bmatrix}$$

A gives rotation by angle θ .

$$(r, \alpha) \rightarrow (r, \theta + \alpha)$$

$f: X \rightarrow Y$

set of all all $x \in X$ s.t. $f(x) = 0$
is called kernel of f .

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Date: / /

$V, W \rightarrow 2$ vector spaces

$T: V \rightarrow W$ be lin. trans (LT)

$Ax=0$ $R(T) = \{T(x) / x \in V\} = \text{Im } T$ image space

$Ax=0$ $N(T) = \{x \in V / T(x) = 0\} = \ker T$ null space
kernel

$N(T) \subseteq V$

$R(T) \subseteq W$

Thm: $T: V \rightarrow W$ be a LT.

Suppose $\{v_1, v_2, \dots, v_n\}$ have property that

$\{T(v_1), T(v_2), \dots, T(v_n)\}$ are lin. indep,
then $\{v_1, v_2, \dots, v_n\}$ are lin. indep.

Pf: We have to show $\{v_1, \dots, v_n\}$ are lin. indep.

Let $c_1 v_1 + c_2 v_2 + \dots + c_n v_n = 0$

$T(c_1 v_1 + c_2 v_2 + \dots + c_n v_n) = T(0) = 0$

$c_1 T(v_1) + c_2 T(v_2) + \dots + c_n T(v_n) = 0$

But, $\{T(v_1), \dots, T(v_n)\}$ are lin. indep.

$\Rightarrow c_i = 0 \quad \forall i \in [1, n]$

$\Rightarrow \{v_1, \dots, v_n\}$ are lin. indep.

Def: $T: V \rightarrow W$

$\{v_1, v_2, \dots, v_m\}$ are basis of V .

It is enough ~~of~~ to know how T acts on $\{v_1, \dots, v_m\}$

$$\begin{aligned} v &= a_1 v_1 + \dots + a_m v_m \\ T(v) &= a_1 T(v_1) + \dots + a_m T(v_m) \end{aligned}$$

Thm: $T: V \rightarrow W$ be a LT, then,

- ① T is one-one iff $\ker T = \{0\}$
- ② " " onto " $\text{Im } T = W$
- ③ T is bijective $\Leftrightarrow \text{Im } T = W \wedge \ker T = \{0\}$

Pf: ① T is one-one $\Leftrightarrow T(x_1) = T(x_2) \Leftrightarrow x_1 = x_2$

Let T be one-one. we know $T(0) = 0$.

Let $v \in \ker T$ be any arbitrary vector of $\ker T$

$$\Rightarrow T(v) = 0$$

" T is one-one $\Rightarrow v = 0 \Rightarrow \ker T = \{0\}$

Conversely, let $\ker T = \{0\}$. Show T is one-one.

$$\begin{aligned} T(x_1) &= T(x_2) \\ \Rightarrow T(x_1) - T(x_2) &= 0 \\ \Rightarrow T(x_1 - x_2) &= 0 \\ \Rightarrow x_1 - x_2 &\in \ker(T) \\ \Rightarrow x_1 - x_2 &= 0 \\ \Rightarrow x_1 &= x_2 \end{aligned}$$

$\therefore T$ is one-one.

- ② Directly defⁿ
- ③ from ① & ④

Thm: $T: V \rightarrow W$ form LT, V, W ~~are~~ vector sp.

Let $\{v_1, v_2, \dots, v_n\}$ be a basis of V , then

① If $\{T(v_1), T(v_2), \dots, T(v_n)\}$ are lin. indep.
 $\Rightarrow T$ is one-one. (3)

② If $T(v_1), \dots, T(v_n)$ span W , then
 T is onto

③ If $\{T(v_1), \dots, T(v_n)\}$ is basis of W , then
 T is bijective.

Pf: ① Any $v \in \ker(T)$
 $\Rightarrow v \in V$ s.t. $T(v) = 0$

$$v = a_1 v_1 + \dots + a_n v_n \quad \text{--- (1)}$$

and

$$0 = a_1 T(v_1) + \dots + a_n T(v_n) \rightarrow \text{lin. indep.} \\ \Rightarrow a_i = 0 \quad \forall i \in [1, n] \quad \text{--- (2)}$$

$$\Rightarrow v = 0 \quad \text{from (1) \& (2)}$$

② We need to show $\text{Im}(T) = W$

$$\text{We have } \text{Im} \subseteq W \quad \text{--- (1)}$$

Let $w \in W$,

but $(T(v_1) + T(v_2) + \dots + T(v_n))$ spans W .

$$\begin{aligned} w &= a_1 T(v_1) + \dots + a_n T(v_n) \\ &= T(a_1 v_1 + \dots + a_n v_n) \\ &= T(v) \\ \Rightarrow w &\in \text{Im}(T) \\ \Rightarrow w &\subseteq \text{Im}(T) \quad \text{--- (2)} \end{aligned}$$

From ① & ②, $\text{Im}(T) = W$
 \therefore onto

③ T is one-one \rightarrow ~~that~~ $T(v_i)$ are lin. indep.

T is onto \rightarrow ~~that~~ $T(v_i)$ are onto

T is bijective \rightarrow ① + ②
 \rightarrow ~~that~~ $T(v_i)$ are basis
 $i \in [1, n]$

Thm: $T: V \rightarrow W$ be a linear transformation.
Suppose $\{v_1, \dots, v_n\}$ are basis of V

(a)

① $R(T)$ is subspace of W .

② $R(T) = \text{span } \{T(v_1), \dots, T(v_n)\}$

③ $\dim(R(T)) \leq \dim W$

(b) ① $N(T)$ is subsp. of V

② $\dim(N(T)) \leq \dim V$

(c) T is one-one $\Leftrightarrow N(T) = \{0\}$

$\Leftrightarrow \{T(v_i)\}_{i=1}^n$ form basis of $R(T)$

(d) $\dim(R(T)) = \dim V$ iff $N(T) = \{0\}$

Pf, ① $\forall v_1, v_2 \in R(T)$

$$T(v_1) + T(v_2) = T(v_1 + v_2)$$

$$\in R(T) \because v_1 + v_2 \in V$$

$$\forall t \in R(T)$$

$$t = T(\alpha v_1) \in R(T)$$

$$\because \alpha v_1 \in V$$

(c) T is one-one $\Rightarrow T(v_1), \dots, T(v_n)$ are lin. - indep.

By (i) (ii) $T(v_1), \dots, T(v_n)$ span W

$$w = \text{span} \{ T(v_i) \} \quad \text{by (ii)}$$

from (i) & (ii), $T(v_1), \dots, T(v_n)$ form basis of w

(d) $\dim \text{span } v = n$

By (c), if $\ker = \{0\} \Rightarrow T(v_1), \dots, T(v_n)$ is a basis of w

$$\Rightarrow \text{Dim. } V = \text{Dim}(R(T))$$

★ Rank nullity theorem :

Let V & W be 2 vector spaces &

let $T: V \rightarrow W$ be a LT then,

$$\begin{aligned} \dim(V) &= \dim(R(T)) + \dim(N(T)) \\ &= \text{rank} + \text{nullity} \end{aligned}$$