



Towards Embodied Speech Recognition

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Introduction



- Area of improvements on current speech recognitions
- Expanding my technical skills and learn Python
- Increase the accessibility of speech recognition when encountering corrupted instructions and handle different accents



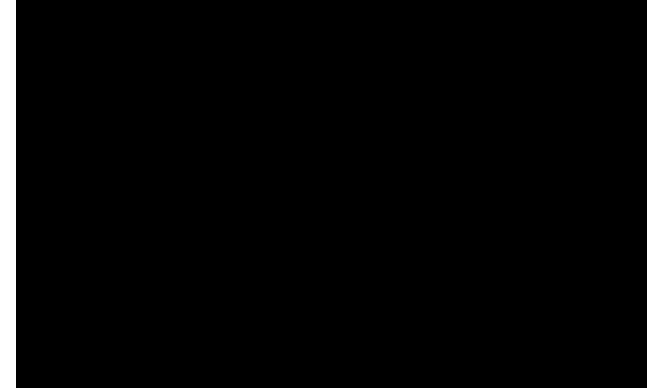
Literature Review



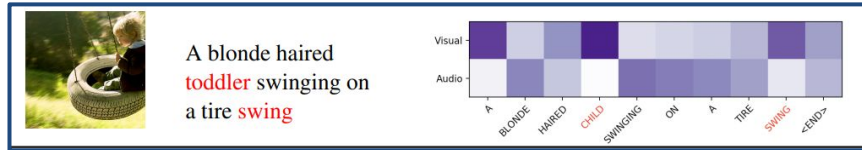
- MacDonald, J., and McGurk, H. (1978). Visual influences on speech perception processes. *Percept. Psychophys.* 24, 253–257. doi: 10.3758/BF03206096



- Kolve, Eric, et al. "Ai2-thor: An interactive 3d environment for visual ai." *arXiv preprint arXiv:1712.05474* (2017).



- Srinivasan, Tejas, et al. "Multimodal speech recognition with unstructured audio masking." *arXiv preprint arXiv:2010.08642* (2020).



Pick up the spoon on the table



Pick up the soon on the table

- Krol, Jacob. Amazon's Astro Home Robot Puts Alexa on Wheels — but Is It Worth \$1,000?, *Cnn Underscored*, 28 Sep. 2021, <https://www.cnn.com/cnn-underscored/electronics/astro-amazon-robot-hands-on>.



Research Questions

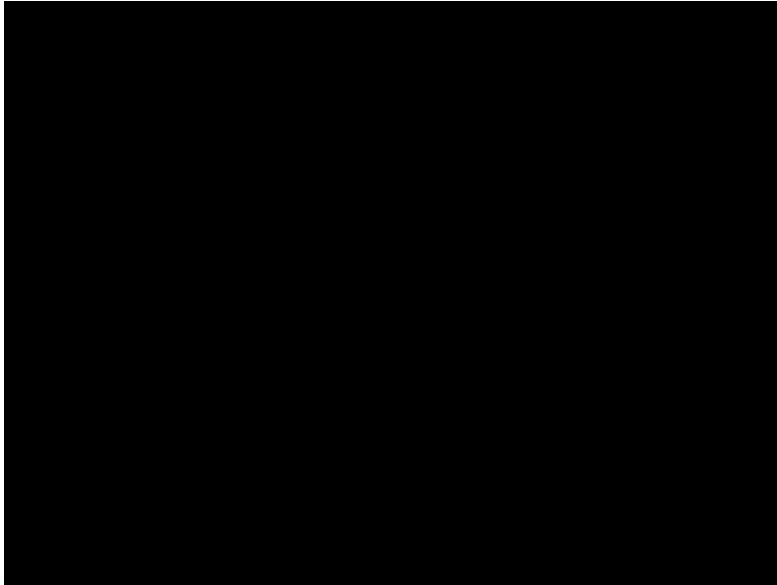


- What information do robots need to perform tasks effectively?
- What are some aspects that at-home-robots can improve?
- If a speech signal is corrupted, what kind of information can be utilized to compensate?
- Will the combination of speech signal and visual scene information increase the accuracy of automatic speech recognition?

Research Methods



- AI2-THOR (virtual environment)
- ALFRED (text-based language directives)



Goal: "Rinse off a mug and place it in the coffee maker"

Step	Instruction	Timestamp	Category
1	"walk to the coffee maker on the right"	$t=0$	visual navigation
2	"pick up the dirty mug from the coffee maker"	$t=10$	object interaction
3	"turn and walk to the sink"	$t=21$	visual navigation
4	"wash the mug in the sink"	$t=27$	object interaction state changes
5	"pick up the mug and go back to the coffee maker"	$t=36$	visual navigation memory
6	"put the clean mug in the coffee maker"	$t=50$	object interaction

Findings/ Data

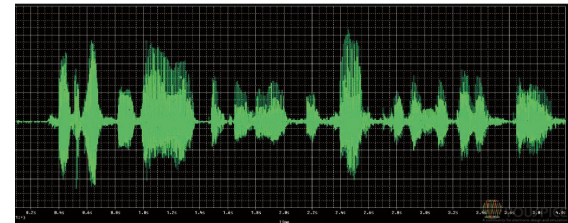


```
"turk_annotations": {  
  "anns": [  
    {  
      "assignment_id": "ALKQPW009C98N_3LQ8PUHQF09B1YF0Q32EVNW2MSCIHQ",  
      "high_descs": [  
        "Turn right and go to the clock to the left of the plant",  
        "Pick the clock up",  
        "Turn right, walk around the bed to the table with the lamp on it",  
        "Hold the clock and turn the light on"  
      ]  
    }  
  ]  
}
```

```
Go to the counter in front of you.  
go to the counter in front of bev  
Pick up the bread on the counter.  
pick up the bread on aja counter  
Turn around and move forward, then turn left and go to the fridge.  
turn around and move forward then turn deft and go to the fridge
```



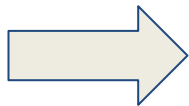
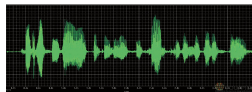
```
Turn right and go to the clock to the left of the plant  
turn right and go to the clock to the left of* the plant  
Pick the clock up  
pick the clock* up  
Turn right, walk around the bed to the table with the lamp on it  
turn right, walk around the bed to the table* with the lamp on it  
Hold the clock and turn the light on  
hold* the clock and turn the light on
```



Findings/ Data

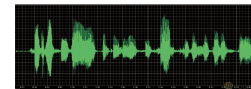


SPOON S P UW1 N

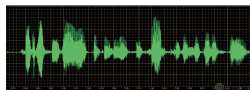


HARPOON HH AA0 R P UW1 N

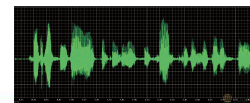
LAMPOON L AE0 M P UW1 N



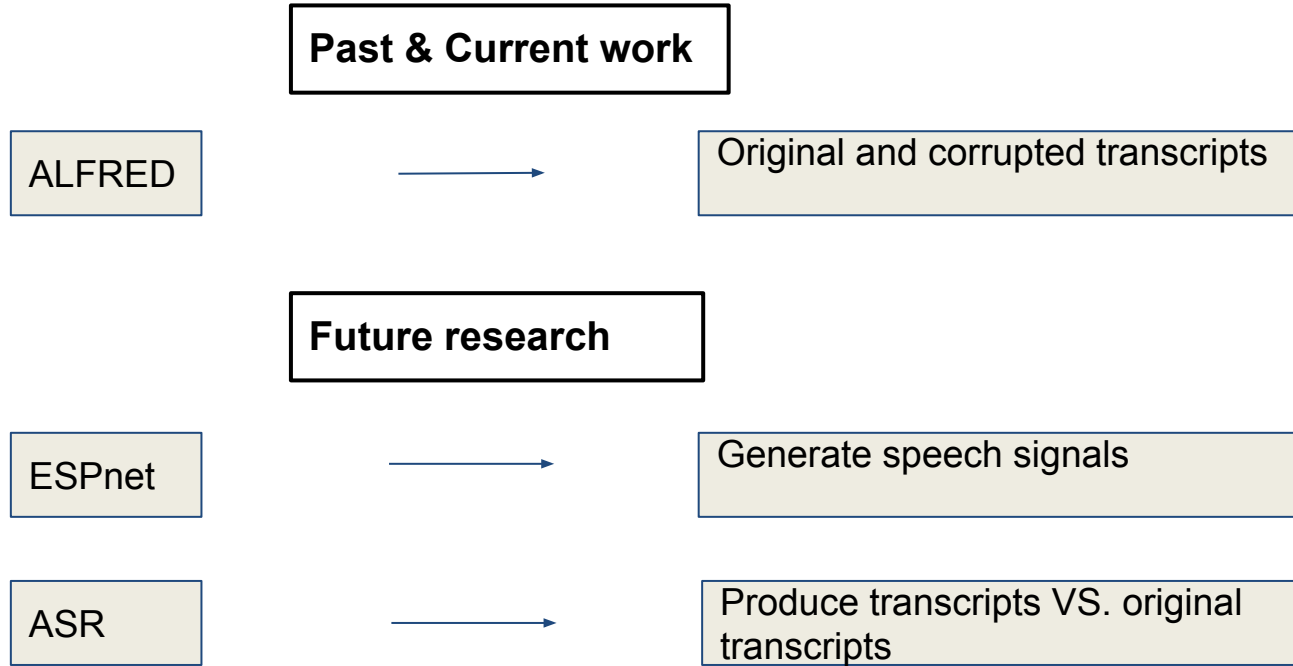
Pick up the spoon on the table



Pick up the soon on the table



Future Research



Discussion/ Conclusion



- Contribution: extracted JSON file & made corruptions on instructions
- Issue: Corrupted instructions can reduce the accuracy of speech recognition
- Goal: Robots/agents recover corrupted instructions
- Approach: Visual information to increase accessibility of speech recognition

References



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- Srinivasan, Tejas, et al. "Multimodal speech recognition with unstructured audio masking." *arXiv preprint arXiv:2010.08642* (2020).
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