```
/home/rosi5/workspaces
/emd_ws/src/easy_manipulation
_deployment/grasp_execution
/include/grasp_execution/utils.hpp
```

```
/home/rosi5/workspaces
/emd_ws/src/easy_manipulation
_deployment/grasp_execution
/include/grasp_execution/dynamic
_safety/dynamic_safety.hpp
```

```
/home/rosi5/workspaces
/emd_ws/src/easy_manipulation
_deployment/grasp_execution
/include/grasp_execution/grasp
_execution.hpp
```

```
/home/rosi5/workspaces
/emd_ws/src/easy_manipulation
_deployment/grasp_execution
/include/grasp_execution/moveit2
/moveit_cpp_if.hpp
```