

## Topological Field Theory WS 2025

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## PROBLEM SET 6

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## 1. Exterior multiplication in phase space

Consider the 2-form

$$\omega^2 = \sum_{i=1}^n p_i \wedge q_i. \quad (1)$$

Evaluate the  $2k$  form

$$\underbrace{\omega^2 \wedge \omega^2 \wedge \dots \wedge \omega^2}_{k \text{ factors}} \quad (2)$$

in terms of the  $p_i$ 's and the  $q_i$ 's.

## 2. Example of a pullback of a differential form

Consider the mapping

$$f : M = \mathbb{R}^3 \rightarrow N = \mathbb{R}^2 : y_1 = x_1 + x_2^2 + x_3^3, y_2 = x_1 x_2 x_3, \quad (3)$$

and the 2-form  $\omega = dy_1 \wedge dy_2$ .Evaluate the form  $f^*\omega$  on  $M$ . Is  $f^*\omega$  a 2-form or a 3-form?

## 3. Derivation of the Jacobian determinant formula

Consider the mapping

$$f : M = \mathbb{R}^k \rightarrow N = \mathbb{R}^k : \mathbf{x} \in D \rightarrow \mathbf{y} \in f(D), \quad (4)$$

where  $D$  is a convex polyhedron in  $M$ .

Use the identity (4.13) from the lectures,

$$\int_D f^* \omega = \int_{f(D)} \omega \quad (5)$$

to derive the Jacobian for a transformation of integration variables from  $dy_1 dy_2 \dots dy_k$  to  $dx_1 dx_2 \dots dx_k$ .Hint: The most general  $k$ -form on  $N$  is

$$\omega^k = \phi(\mathbf{y}) dy_1 \wedge dy_2 \wedge \dots \wedge dy_k. \quad (6)$$

## 4. Exterior differentiation

(a) Show  $d(\omega^k \wedge \omega^l) = d\omega^k \wedge \omega^l + (-1)^k \omega^k \wedge d\omega^l$ .

(b) Show  $dd\omega = 0 \forall \omega$ .

(c) Let  $f : M \rightarrow N$  be a differentiable mapping, and  $\omega^k$  a  $k$ -form on  $N$ .  
Show  $f^*(d\omega) = d(f^*\omega)$ .5. Exterior derivatives in  $\mathbb{R}^3$ 

Recall the following definitions from Sect. 4.3 of the lectures:

$$\omega_A^1(\xi) = (\mathbf{A}, \xi) \equiv \mathbf{A} \cdot \xi, \quad (7)$$

$$\omega_A^2(\xi_1, \xi_2) = (\mathbf{A}, \xi_1, \xi_2) \equiv \mathbf{A} \cdot (\xi_1 \times \xi_2), \quad (8)$$

where  $\xi = (dx_1, dx_2, dx_3)$ , as well as eqs. (4.5a) and (4.5b):

$$\omega_A^1 \wedge \omega_B^1 = \omega_{A \times B}^2 \quad (9)$$

$$\omega_A^1 \wedge \omega_B^2 = (\mathbf{A}, \mathbf{B}) dx_1 \wedge dx_2 \wedge dx_3 \quad (10)$$

Show

(a)  $df = \omega_{\nabla f}^1$ .

(b)  $d\omega_A^1 = \omega_{\nabla \times A}^2$ .

(c)  $d\omega_A^2 = (\nabla \mathbf{A}) dx_1 \wedge dx_2 \wedge dx_3$

6. Vector analysis in  $\mathbb{R}^3$ 

Show

(a)  $\nabla(\mathbf{A} \times \mathbf{B}) = (\nabla \times \mathbf{A})\mathbf{B} - \mathbf{A}(\nabla \times \mathbf{B})$ .

Hint: Use (9), (10), (b), and (c) from Problem 5 above.

(b)  $\nabla \times (a\mathbf{A}) = (\nabla a) \times \mathbf{A} + a(\nabla \times \mathbf{A})$ .

(c)  $\nabla(a\mathbf{A}) = (\nabla a)\mathbf{A} + a(\nabla \mathbf{A})$ .

(d)  $\nabla \times (\nabla f) = 0$ .

(e)  $\nabla(\nabla \times \mathbf{A}) = 0$ .