

## Internet of things

### Unit 4

From Nov-Des question paper

\*Q1) What is an IOT Device? List different IOT Devices. Explain any 2 devices.

#### ➔IoT Devices: A Brief Overview

IoT (Internet of Things) devices are physical objects that are embedded with sensors, software, and network connectivity, allowing them to collect and exchange data. These devices can interact with each other and with the surrounding environment, providing real-time information and automated control.

#### Types of IoT Devices

- \* **Wearable Devices:** These devices are worn on the body and collect data about the wearer's health, fitness, or other personal metrics. Examples include smartwatches, fitness trackers, and heartrate monitors.
- \* **Home Automation Devices:** These devices control various aspects of a home, such as lighting, temperature, security, and entertainment. Examples include smart thermostats, smart locks, and smart speakers.
- \* **Industrial IoT (IIoT) Devices:** These devices are used in manufacturing, logistics, and other industrial settings to monitor and control equipment, optimize processes, and improve efficiency. Examples include sensors for temperature, pressure, and vibration, as well as robotic systems.
- \* **Agricultural IoT Devices:** These devices are used in agriculture to monitor crop health, soil conditions, and weather patterns. Examples include soil moisture sensors, drone-based imaging systems, and livestock monitoring devices.
- \* **Automotive IoT Devices:** These devices are used in vehicles to collect data about driving behavior, vehicle performance, and location. Examples include in-car entertainment systems, telematics devices, and autonomous driving systems.

#### Examples of IoT Devices:

- \* **Smart Thermostat:** A smart thermostat is a programmable thermostat that can be controlled remotely using a smartphone or other device. It uses sensors to monitor indoor

and outdoor temperatures and adjusts the heating or cooling system accordingly. This can help to save energy and improve comfort.

- \* **Fitness Tracker:** A fitness tracker is a wearable device that monitors physical activity, heart rate, sleep, and other health metrics. It can provide users with detailed information about their fitness levels and help them to set and achieve health goals. Some fitness trackers also have GPS capabilities, allowing users to track their routes and distance.

These are just a few examples of the many types of IoT devices that are available today. As technology continues to advance, we can expect to see even more innovative and useful IoT applications in the future.

\*Q2) Why python is important in IoT? Why the python is the first choice for the Raspberry Pi language than C or C++?

➔ Python's combination of readability, community support, rapid development capabilities, platform independence, hardware integration, and data analysis tools make it an ideal choice for IoT development. Its versatility and ease of use allow developers to create innovative and efficient IoT solutions.

### Python's Popularity on Raspberry Pi: A Comparative Analysis

Python has become the language of choice for many Raspberry Pi projects, surpassing traditional languages like C and C++. Here's why:

#### 1. Readability and Simplicity:

- \* **Pythonic Syntax:** Python's syntax is clean, concise, and easy to read, making it more accessible to beginners and experienced programmers alike.

- \* **Reduced Boilerplate Code:** Python eliminates the need for much of the boilerplate code required in C and C++, leading to faster development time.

#### 2. Large and Active Community:

- \* **Extensive Libraries and Frameworks:** Python boasts a vast ecosystem of libraries and frameworks, such as TensorFlow, OpenCV, and NumPy, that can be leveraged for various tasks, from machine learning to image processing.

- \* **Community Support:** The large Python community provides abundant resources, tutorials, and forums, making it easier to find solutions and learn from others.

#### 3. Rapid Development and Prototyping:

- \* **Interactive Shell:** Python's interactive shell allows for quick experimentation and testing, making it ideal for prototyping and iterating on ideas.

- \* **Dynamic Typing:** Python's dynamic typing eliminates the need for explicit type declarations, further simplifying development and reducing the likelihood of errors.

#### 4. Memory Efficiency:

- \* **Garbage Collection:** Python's automatic memory management (garbage collection) frees developers from the burden of manual memory allocation and deallocation, reducing the risk of memory leaks.

- \* **Optimized for Embedded Systems:** While Python is generally less memory-efficient than C or C++, recent optimizations and implementations like MicroPython have made it suitable for embedded systems like the Raspberry Pi.

#### 5. Cross-Platform Compatibility:

- \* **Python Everywhere:** Python code is highly portable and can run on a wide range of platforms, including Windows, macOS, Linux, and embedded systems like the Raspberry Pi.

While C and C++ offer performance advantages, Python's combination of readability, ease of use, and a vast ecosystem makes it a compelling choice for many Raspberry Pi projects, especially those that prioritize rapid development, prototyping, and accessibility.

In summary, Python's strengths in readability, community support, rapid development, memory efficiency, and cross-platform compatibility make it an excellent choice for Raspberry Pi projects.

Q3) Explain in detail Interfaces (Serial, SPI, I2C).

#### ➔ Serial, SPI, and I2C Interfaces

These three interfaces are commonly used for communication between electronic components, particularly in embedded systems and IoT devices.

##### Serial Interface

- \* **Basic Principle:** Data is transmitted one bit at a time, sequentially.

- \* **Data Transmission:** A single wire (or pair of wires for bidirectional communication) is used to transmit data.

- \* Clock Signal: A separate clock signal is required to synchronize the data transmission.

- \* Common Types:

- \* RS-232: A standard serial interface for short-distance communication, typically used for connecting computers to modems or peripherals.

- \* RS-485: A balanced serial interface for longer distances and multi-point communication.

- \* USB: A high-speed serial interface for connecting devices to computers.

### SPI (Serial Peripheral Interface)

- \* Basic Principle: A synchronous serial interface, where the clock signal is generated by the master device.

- \* Data Transmission: Four wires are typically used:

- \* MOSI (Master Out Slave In): Data from the master to the slave.

- \* MISO (Master In Slave Out): Data from the slave to the master.

- \* SCK (Serial Clock): Clock signal generated by the master.

- \* SS (Slave Select): A chip select signal used to select the specific slave device.

- \* Common Applications: Connecting microcontrollers to sensors, memory devices, and other peripherals.

### I2C (Inter-Integrated Circuit)

- \* Basic Principle: A synchronous serial interface that uses a multi-master architecture, allowing multiple devices to communicate on the same bus.

- \* Data Transmission: Two wires are used:

- \* SDA (Serial Data): Bidirectional data bus.

- \* SCL (Serial Clock): Clock signal generated by the master.

- \* Address Bus: Each device on the bus has a unique address.

- \* Common Applications: Connecting microcontrollers to sensors, memory devices, and other peripherals, especially those that require low power consumption.

### Comparison of the Three Interfaces

| Feature | Serial | SPI | I2C |

|---|---|---|---|

| Number of wires | 1-2 | 4 | 2 |

| Clock signal | External | Generated by master | Generated by master |

| Master-slave architecture | Yes | Yes | Yes (multi-master) |

| Addressing | Not required | Not required | Required (unique address for each device) |

| Typical applications | Connecting computers to peripherals, long-distance communication | Connecting microcontrollers to peripherals | Connecting microcontrollers to peripherals, low-power applications |

The choice of interface depends on factors such as the distance between devices, the number of devices to be connected, the required data transfer rate, and the power consumption requirements.

Q4) Draw and explain interfacing of input device (LED) using Arduino Uno with program.

➔ Interfacing an LED with Arduino Uno

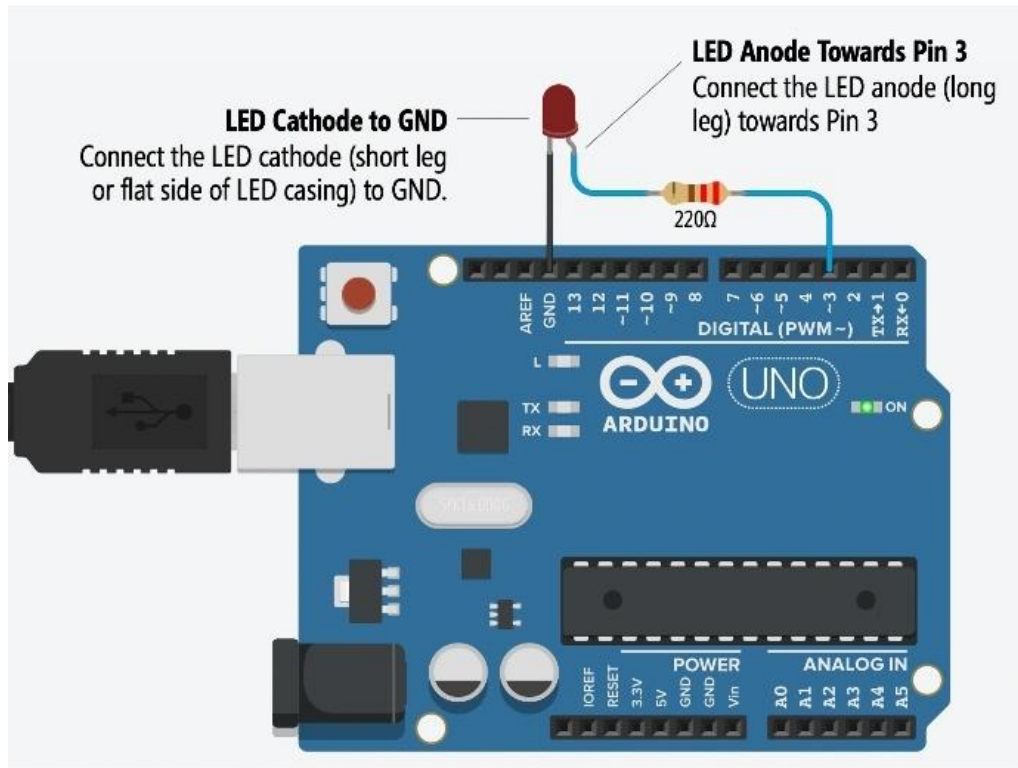
Understanding the Components:

\* Arduino Uno: A microcontroller board that serves as the brain of the circuit.

\* LED (Light-Emitting Diode): A semiconductor device that emits light when a current flows through it.

\* Resistor: A passive component that limits the current flowing through the LED to prevent it from burning out.

Circuit Diagram:



In this circuit:

- \* LED: Connected to digital pin 13 of the Arduino Uno.

- \* Resistor: Connected in series with the LED to limit the current. The value of the resistor depends on the LED's specifications and the desired brightness. A common value is 220 ohms.

Arduino Code:

```
const int ledPin = 13;
```

```
void setup() {
```

```
    pinMode(ledPin, OUTPUT);
```

```
}
```

```
void loop() {
```

```
digitalWrite(ledPin, HIGH); // Turn LED on
delay(1000);           // Wait for 1 second
digitalWrite(ledPin, LOW); // Turn LED off
delay(1000);           // Wait for 1 second
}
```

#### Explanation:

- \* Include necessary libraries: This code doesn't require any external libraries.
- \* Define pin: The ledPin constant is defined to represent the digital pin number where the LED is connected (13 in this case).
- \* Setup function:
  - \* pinMode(ledPin, OUTPUT): Sets the ledPin as an output pin, which means the Arduino can control the voltage on this pin.
- \* Loop function:
  - \* digitalWrite(ledPin, HIGH): Sets the voltage on ledPin to HIGH, turning the LED on.
  - \* delay(1000): Pauses the program for 1000 milliseconds (1 second).
  - \* digitalWrite(ledPin, LOW): Sets the voltage on ledPin to LOW, turning the LED off.
  - \* delay(1000): Pauses the program for another 1 second.

#### Functionality:

This code will continuously blink the LED connected to pin 13. It turns the LED on for 1 second, then off for 1 second, and repeats this cycle indefinitely.

Note: To ensure proper operation, make sure the LED and resistor are connected correctly, and the resistor value is appropriate for the LED. Also, consider using a breadboard for easier prototyping and testing.

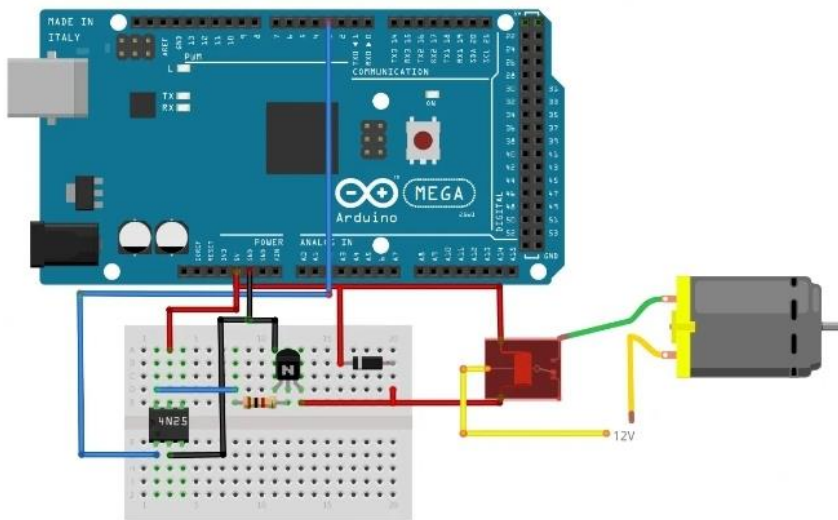
Q5) Draw and explain interfacing of output device (Relay) using Arduino Uno with program.

## ➔ Interfacing a Relay with Arduino Uno

### Understanding the Components:

- \* Arduino Uno: A microcontroller board that controls the relay.
- \* Relay: An electromechanical switch that can control a high-current or high-voltage circuit using a low-current control signal.
- \* Resistor: Used to limit the current flowing through the relay's coil.

### Circuit Diagram:



### In this circuit:

- \* Arduino Uno: Provides a control signal to the relay's coil.
- \* Relay: Switches the high-current or high-voltage load on or off based on the control signal.
- \* Resistor: Limits the current flowing through the relay's coil to prevent it from burning out.

### Arduino Code:



```
const int relayPin = 9; // Replace with your relay's pin  
const int loadPin = 13; // Replace with the pin connected to the load
```

```
void setup() {  
  pinMode(relayPin, OUTPUT);  
  pinMode(loadPin, OUTPUT);  
}
```

```
void loop() {  
  // Turn on the relay  
  digitalWrite(relayPin, HIGH);  
  digitalWrite(loadPin, HIGH);  
  delay(1000);  
  
  // Turn off the relay  
  digitalWrite(relayPin, LOW);  
  digitalWrite(loadPin, LOW);  
  delay(1000);  
}
```

#### Explanation:

- \* Include necessary libraries: This code doesn't require any external libraries.
- \* Define pins:
  - \* relayPin: The digital pin number connected to the relay's coil.
  - \* loadPin: The digital pin number connected to the load (the device being controlled by the relay).

\* Setup function:

\* `pinMode(relayPin, OUTPUT)`: Sets the `relayPin` as an output pin, allowing the Arduino to control the voltage on it.

\* `pinMode(loadPin, OUTPUT)`: Sets the `loadPin` as an output pin, allowing the Arduino to control the voltage on the load.

\* Loop function:

\* Turn on the relay:

\* `digitalWrite(relayPin, HIGH)`: Activates the relay's coil, closing the contacts and connecting the load to the power source.

\* `digitalWrite(loadPin, HIGH)`: Turns on the load.

\* Turn off the relay:

\* `digitalWrite(relayPin, LOW)`: Deactivates the relay's coil, opening the contacts and disconnecting the load from the power source.

\* `digitalWrite(loadPin, LOW)`: Turns off the load.

Functionality:

This code will continuously turn the relay on and off, controlling the load connected to it. The `delay()` function is used to introduce a pause between each state change.

Note:

\* Replace 9 and 13 with the actual pin numbers connected to your relay and load.

\* The relay's specifications may require a specific resistor value to limit the current flowing through its coil.

\* The load's power requirements should be taken into account when selecting the relay's ratings.

\* For more complex applications, you can use multiple relays and control them independently or in combination.

