

02/03/2022

## DFS( $s$ )

Mark  $s$  as "seen"

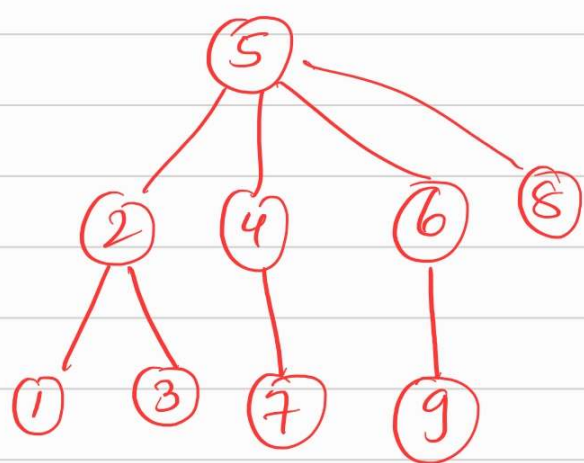
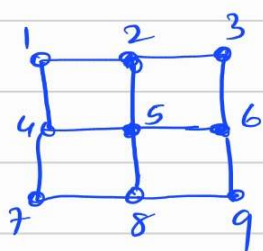
For each edge  $(s, v)$  incident on  $s$

if  $v$  is not marked "seen" then

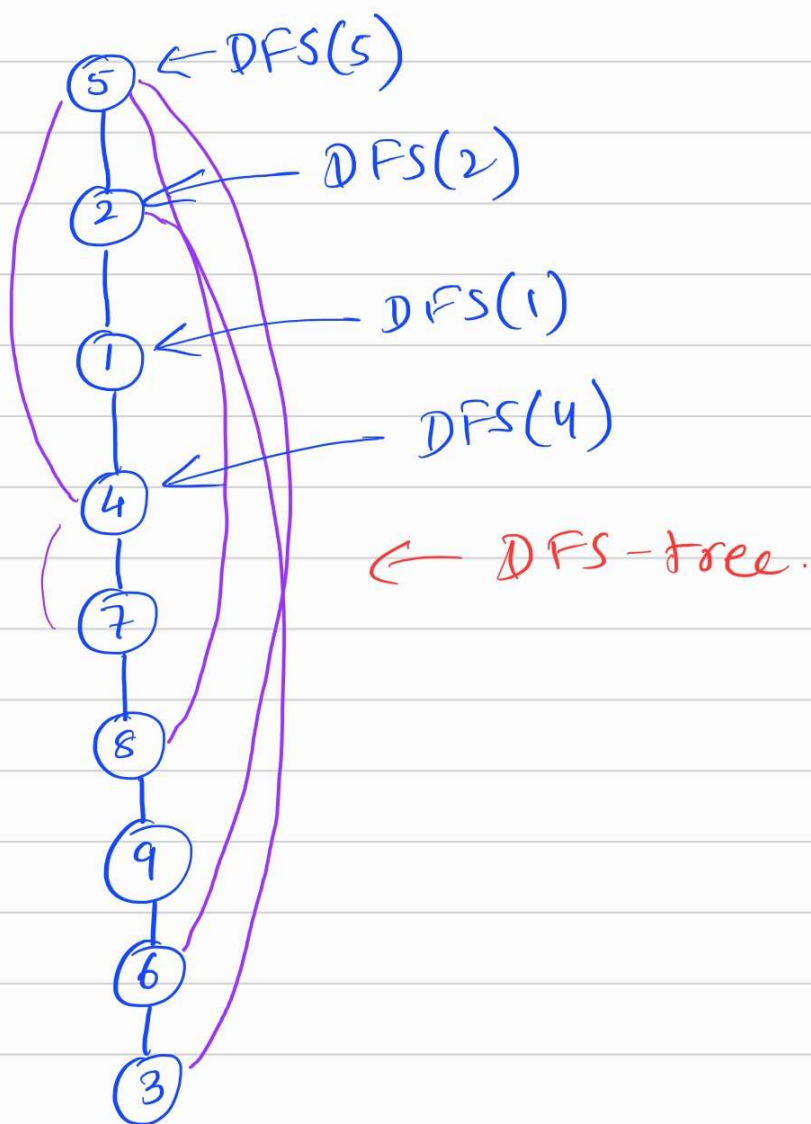
recursively call  $\text{DFS}(v)$

End if

End for.



↑  
BFS-tree



Fact:- Let  $T$  be a DFS-tree and  $(x, y)$  be an edge in  $G$  that doesn't belong to  $T$ . Then either  $x$  is an ancestor of  $y$ .

or  $y$  is an ancestor of  $x$ .

Proof: - WLOG,  $\text{DFS}(x)$  was executed before  $\text{DFS}(y)$ .



At the invocation of  $\text{DFS}(x)$   $y$  is not marked as "seen".

Also  $\text{DFS}(y)$  is not called just after  $\text{DFS}(x)$ .

Then  $(x, y)$  will be considered after you invoke  $\text{DFS}(y)$ .

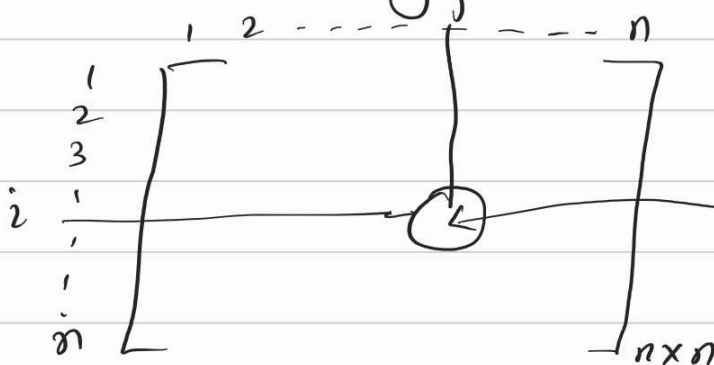
Furthermore this invocation is before the end of the recursive call  $\text{DFS}(x)$ .

□

Runtime:

Representing a graph:

(1) Adjacency Matrix (2) Adjacency List.



this entry  $(i, j)$  is 0 or 1 depending on whether  $(i, j)$  is present or not

Adjacency matrix is implemented as an Array.

Q: Is Adjacency matrix a symmetric matrix? Yes.

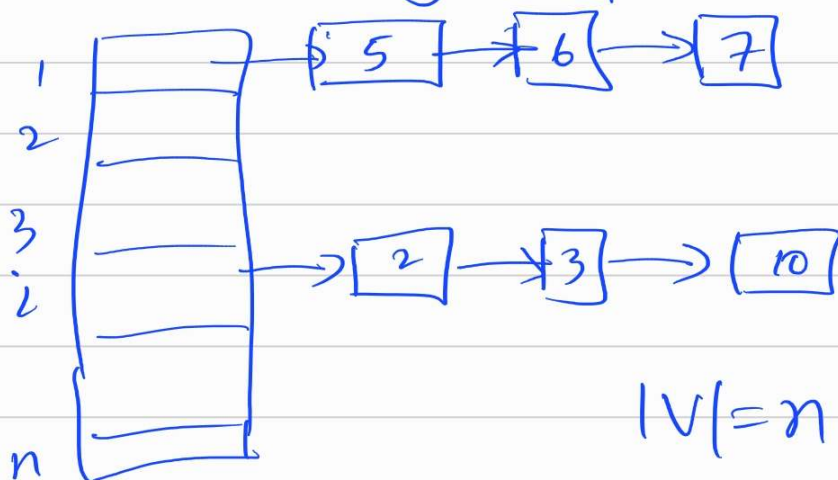
Q: How much space does it take?  
 $O(n^2)$

Q: How much time does it take to figure out if an edge  $(i,j)$  is present?  $O(1)$  time.

Q: How much time does it take to find all neighbors of a given node  $i$ ?  $O(n)$  time.

2) Adjacency list.

→ Array of lists.



$$|V|=n, |E|=m$$

Q: How much space does it take?



each edge is represented twice.

$$(i, j) \quad 2m = O(m)$$

Q: How much time does it take to figure out if an edge is present?  
 $O(\text{deg of that vertex})$

degree of a vertex = # of neighbors of that vertex

Q: How much time does it take to find all neighbours of a given vertex?

$$O(\text{degree})$$

Standard input representation of a graph  
:= Adjacency list.

Queue (FIFO)  $\rightarrow$  BFS

Stacks (LIFO)  $\rightarrow$  DFS.



Implementing BFS :  $O(m+n)$  time.  
Linear-time.

BFS( $s$ ):

Discovered( $s$ ) = True and Discovered( $v$ ) = False  
 $\forall v \neq s$ .

Initialize  $L(0) = \{s\}$ .

Set the layer count  $i$  to 0.

Set the BFS tree  $T = \emptyset$ .

while  $L(i)$  is not empty.

Initialize  $L(i+1) = \emptyset$ .

for each node  $u \in L(i)$

consider edge  $(u, v)$  incident on  $u$ .

If Discovered( $v$ ) = False then

Discovered( $v$ ) = True.

Add  $v$  to  $L(i+1)$

Add  $(u, v)$  to  $T$ .

End if

End for.

Increment the layer count  $i$  to  $i+1$

EndWhile.

Fact:- The above algorithm takes  $O(m+n)$ .

Implementing DFS: Define Array  $\text{Parent}[1..n]$

DFS( $s$ ):

Initialize  $R = \emptyset$ .

Initialize a stack  $S$  with <sup>vertex</sup>  $s$  in it

While  $S$  is not empty.

Take a node  $u$  from  $S$ .

If  $\text{Explored}[u] = \text{false}$  then

Set  $\text{Explored}(u) = \text{True}$ .

$R = R \cup \{u\}$

For each edge  $(u, v)$  incident on  $u$

Add  $v$  to  $S$ ; Set  $\text{Parent}[v] = u$

End for

when  $v \neq s$ .

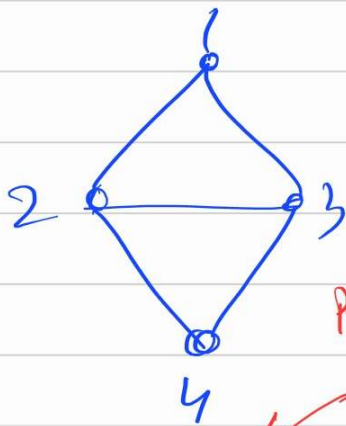
and  $\text{Explored}[v] = \text{false}$ .

End if

End while.

Output  $R$ .

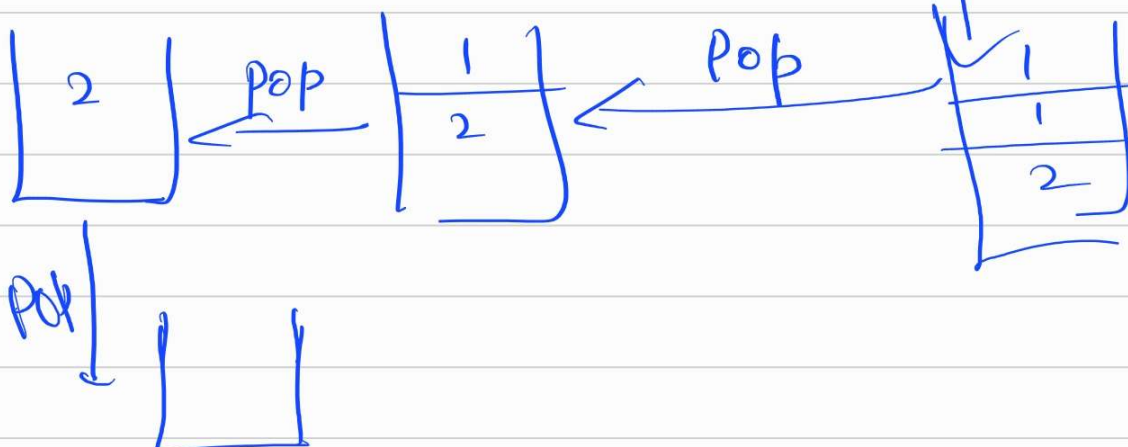
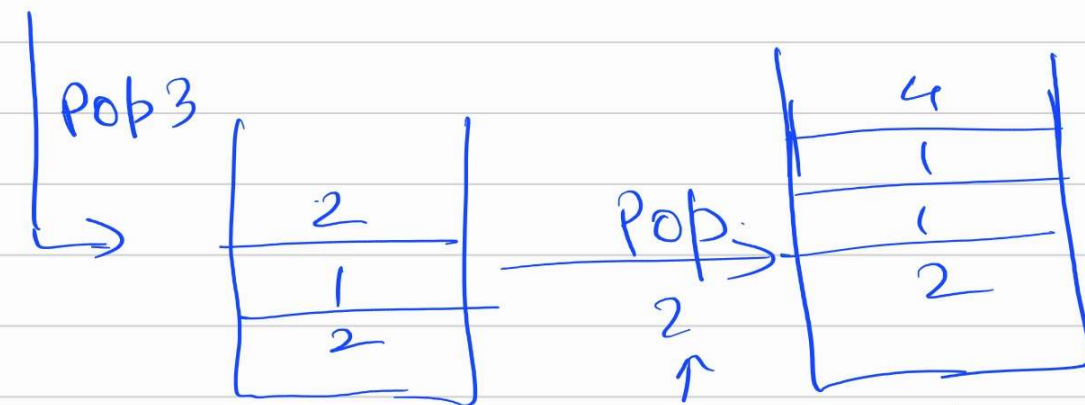
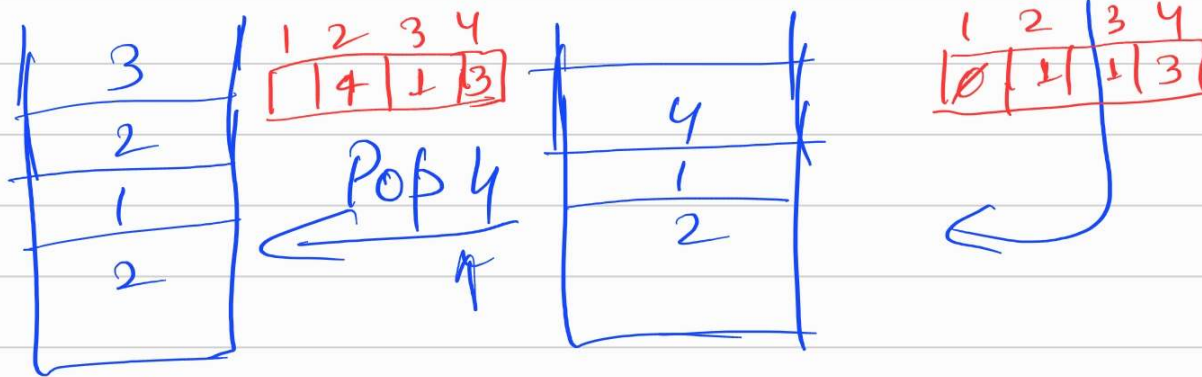
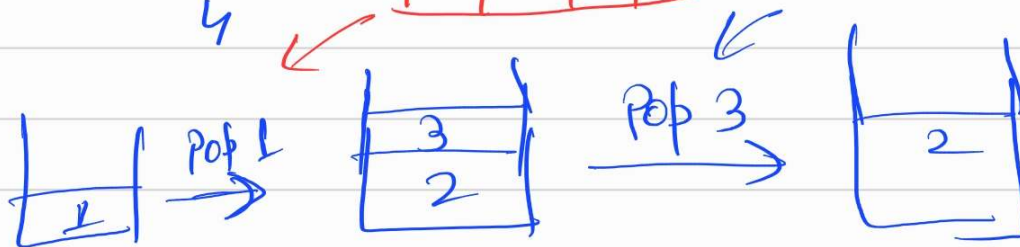




3
2
1

Parent

1	2	3	4
	1	1	



$$O^a \xrightarrow{+1} O^b \xrightarrow{+1} O^c$$