

Quiz 2

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Download all latex codes from

<https://github.com/tanmaygoyal258/EE3900-Linear-Systems-and-Signal-processing/blob/main/Quiz2/main.tex>

<https://github.com/tanmaygoyal258/EE3900-Linear-Systems-and-Signal-processing/blob/main/Quiz2/code.py>

1 PROBLEM

(Oppenheim/3.24(a)) Sketch the following sequence and determine their z-transform, including their region of convergence:

$$a[n] = \sum_{k=-\infty}^{\infty} \delta[n - 4k] \quad (1.0.1)$$

2 SOLUTION

Lemma 2.1.

$$x(t) \times \delta(t - t_1) = x(t_1) \times \delta(t - t_1) \quad (2.0.1)$$

Proof.

$$\delta(t - t_1) = \begin{cases} 0 & t \neq t_1 \\ \infty & t = t_1 \end{cases} \quad (2.0.2)$$

$$\Rightarrow x(t) \times \delta(t - t_1) = \begin{cases} 0 & t \neq t_1 \\ x(t_1) \times \infty & t = t_1 \end{cases} \quad (2.0.3)$$

$$= x(t_1) \times \begin{cases} 0 & t \neq t_1 \\ \infty & t = t_1 \end{cases} \quad (2.0.4)$$

$$= x(t_1) \times \delta(t - t_1) \quad (2.0.5)$$

□

The Z-transform of a signal $x[n]$ is given by:

$$x[n] \xrightarrow{Z} X(z) = \sum_{n=-\infty}^{\infty} x[n]z^{-n} \quad (2.0.6)$$

Thus, the z-transform of $a[n]$ is given by:

$$A(z) = \sum_{n=-\infty}^{\infty} a[n]z^{-n} \quad (2.0.7)$$

$$= \sum_{n=-\infty}^{\infty} \sum_{k=-\infty}^{\infty} \delta[n - 4k]z^{-n} \quad (2.0.8)$$

$$= \sum_{k=-\infty}^{\infty} \sum_{n=-\infty}^{\infty} \delta[n - 4k]z^{-n} \quad (2.0.9)$$

$$= \sum_{k=-\infty}^{\infty} \sum_{n=-\infty}^{\infty} \delta[n - 4k]z^{-4k} \quad (2.0.10)$$

using (2.0.1). Thus, we get:

$$A(z) = \sum_{k=-\infty}^{\infty} z^{-4k} \sum_{n=-\infty}^{\infty} \delta[n - 4k] \quad (2.0.11)$$

$$= \sum_{k=-\infty}^{\infty} z^{-4k} \quad (2.0.12)$$

using the fact that:

$$\sum_{n=-\infty}^{\infty} \delta[n - m] = 1 \quad (2.0.13)$$

When $k > 0$, the term z^{-4k} becomes undefined for $z = 0$, and similarly when $k < 0$, the term z^{-4k} is undefined when $z = \pm\infty$. Thus, the region of convergence is:

$$ROC = z \in \mathbb{R} \setminus \{0, \pm\infty\} \quad (2.0.14)$$

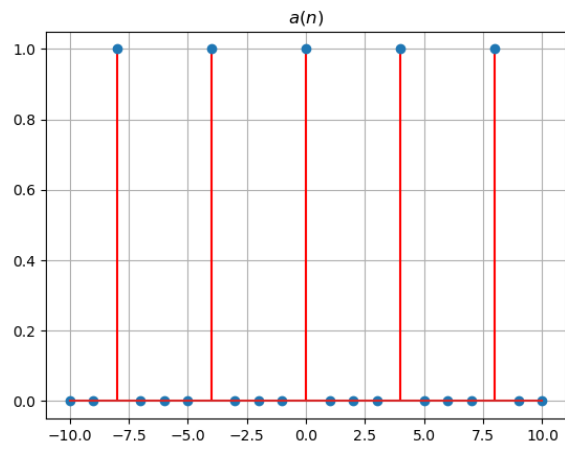


Fig. 0: $a[n]$

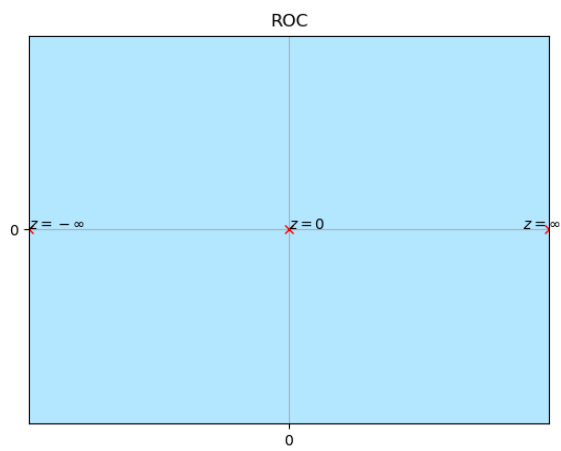


Fig. 0: ROC