

# Gate Assignment 1

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Download all python codes from

<https://github.com/tanmaygoyal258/EE3900-Linear-Systems-and-Signal-processing/blob/main/GateAssignment1/code.py>

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<https://github.com/tanmaygoyal258/EE3900-Linear-Systems-and-Signal-processing/blob/main/GateAssignment1/main.tex>

## 1 PROBLEM

(EC 2017- Q.7) The input  $x(t)$  and output  $y(t)$  of a continous time signal are related as:

$$y(t) = \int_{t-T}^t x(u) du \quad (1.0.1)$$

The system is:

- 1) Linear and Time-variant
- 2) Linear and Time-invariant
- 3) Non-Linear and Time-variant
- 4) Non-Linear and Time-invariant

## 2 SOLUTION

**Definition 1.** We say that a system is **linear** if and only if it follows the Principle of Superposition, i.e Law of Additivity and Law of Homogeneity.

**Definition 2.** A system is said to be **time invariant** if the output signal does not depend on the absolute time, i.e a time delay on the input signal directly equates to the delay in the output signal.

**Lemma 2.1.** The system relating the input signal  $x(t)$  and output signal  $y(t)$ , given by

$$y(t) = \int_{t-T}^t x(u) du \quad (2.0.1)$$

is linear and time invariant in nature.

*Proof.* From (1), we can say the system is linear if it follows both the laws of Additivity and Homogeneity.

Law of Additivity:

Let the two input signals be  $x_1(t)$  and  $x_2(t)$ , and their corresponding output signals be  $y_1(t)$  and  $y_2(t)$ , then:

$$y_1(t) = \int_{t-T}^t x_1(u) du \quad (2.0.2)$$

$$y_2(t) = \int_{t-T}^t x_2(u) du \quad (2.0.3)$$

$$y_1(t) + y_2(t) = \int_{t-T}^t [x_1(u) + x_2(u)] du \quad (2.0.4)$$

Now, consider the input signal of  $x_1(t) + x_2(t)$ , then the corresponding output signal is given by  $y'(t)$ :

$$y'(t) = \int_{t-T}^t [x_1(u) + x_2(u)] du \quad (2.0.5)$$

Clearly, from (2.0.4) and (2.0.5):

$$y'(t) = y_1(t) + y_2(t) \quad (2.0.6)$$

Thus, the Law of Additivity holds.

Law of Homogeneity:

Consider an input signal  $kx(t)$ , where  $k$  is any constant. Let the corresponding output be given by  $y'(t)$ , then:

$$y'(t) = \int_{t-T}^t kx(u) du \quad (2.0.7)$$

$$= k \int_{t-T}^t x(u) du \quad (2.0.8)$$

$$= ky(t) \quad (2.0.9)$$

Clearly, from (2.0.9),

$$y'(t) = ky(t) \quad (2.0.10)$$

Thus, the Law of Homogeneity holds.

Since both the Laws hold, the system satisfies the Principle of Superposition, and is thus, a **linear system**.

From (2), to check for time-invariance, we would introduce a delay of  $t_0$  in the output and input

signals.

Delay in output signal:

$$y(t - t_0) = \int_{t-t_0-T}^{t-t_0} x(u) du \quad (2.0.11)$$

Now, we consider an input signal with a delay of  $t_0$ , given by  $x(t - t_0)$ , and let the corresponding output signal be given by  $y'(t)$ , then:

$$y'(t) = \int_{t-T}^t x(u - t_0) du \quad (2.0.12)$$

Substituting  $a = u - t_0$ :

$$y'(t) = \int_{t-t_0-T}^{t-t_0} x(a) da \quad (2.0.13)$$

Clearly, from (2.0.11) and (2.0.13):

$$y'(t) = y(t - t_0) \quad (2.0.14)$$

Thus, the system is **time-invariant**.

The correct option is **2) Linear and Time-invariant**  $\square$

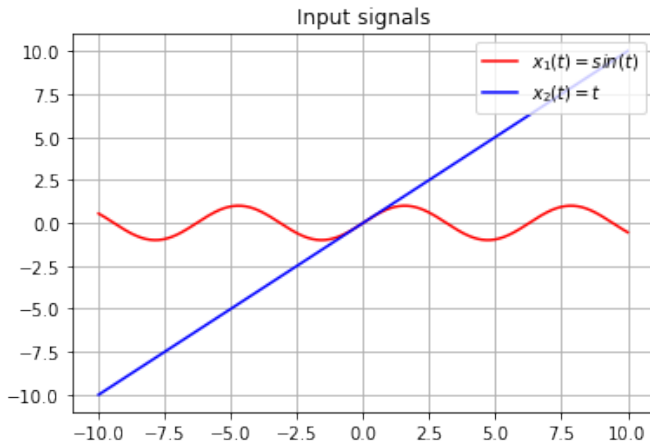


Fig. 4:  $x_1(t) = \sin t$  and  $x_2(t) = t$

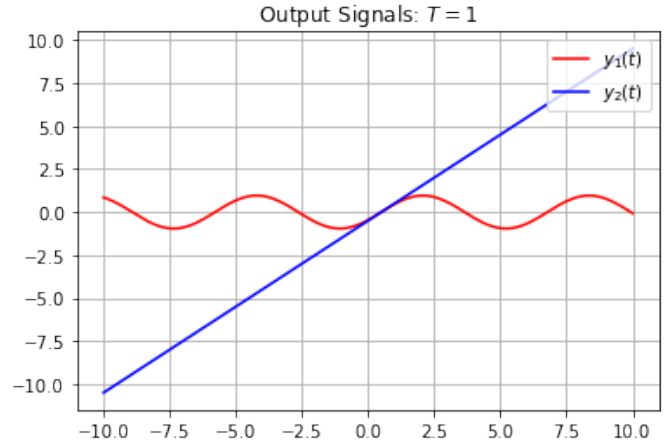


Fig. 4:  $y_1(t)$  and  $y_2(t)$

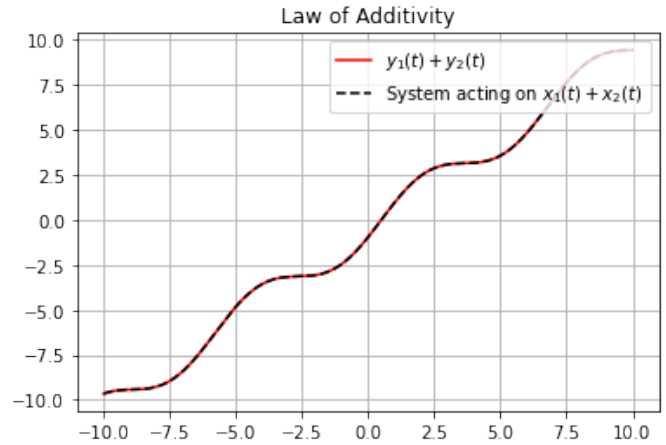


Fig. 4: Law of Additivity

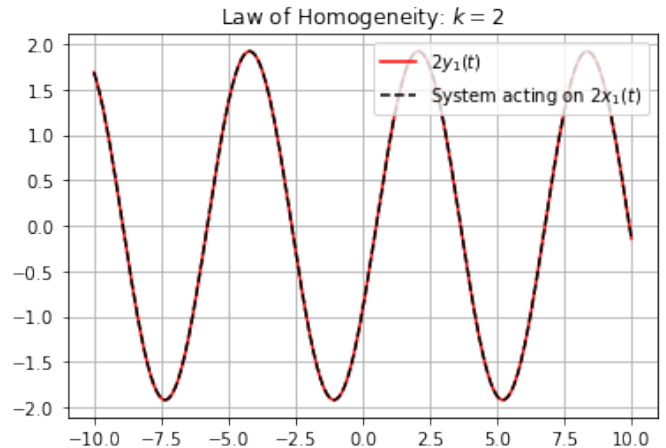


Fig. 4: Law of Homogeneity

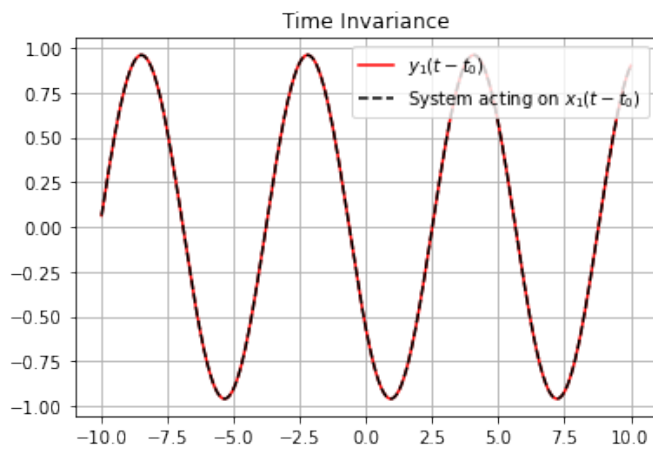


Fig. 4: Time invariance