

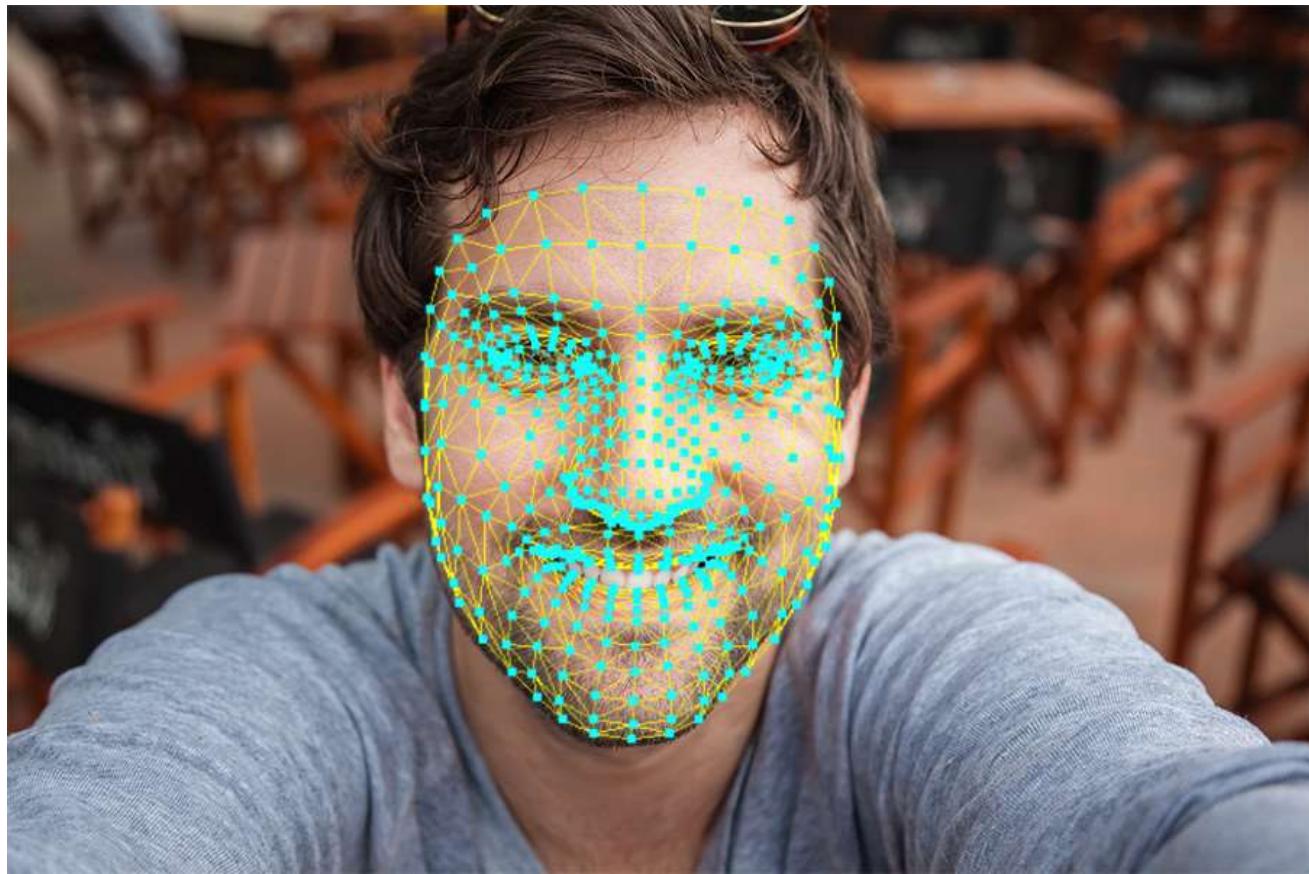
Dataintelliage

Body language decoder

Real time action recognition using Mediapipe for single person

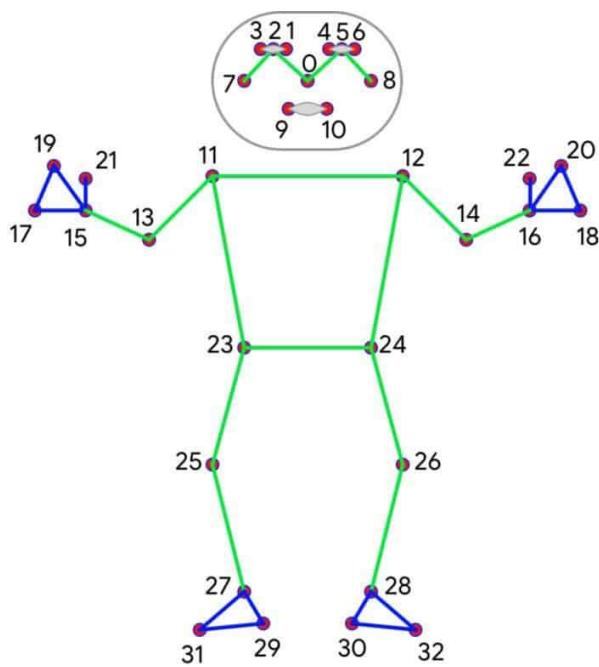
1. What is Mediapipe?

MediaPipe is an open-source framework for building pipelines to perform computer vision inference over arbitrary sensory data such as video or audio. Using MediaPipe, such a perception pipeline can be built as a graph of modular components. MediaPipe is currently in alpha at v0.7, and there may still be breaking API changes. Stable APIs are expected by v1.0.



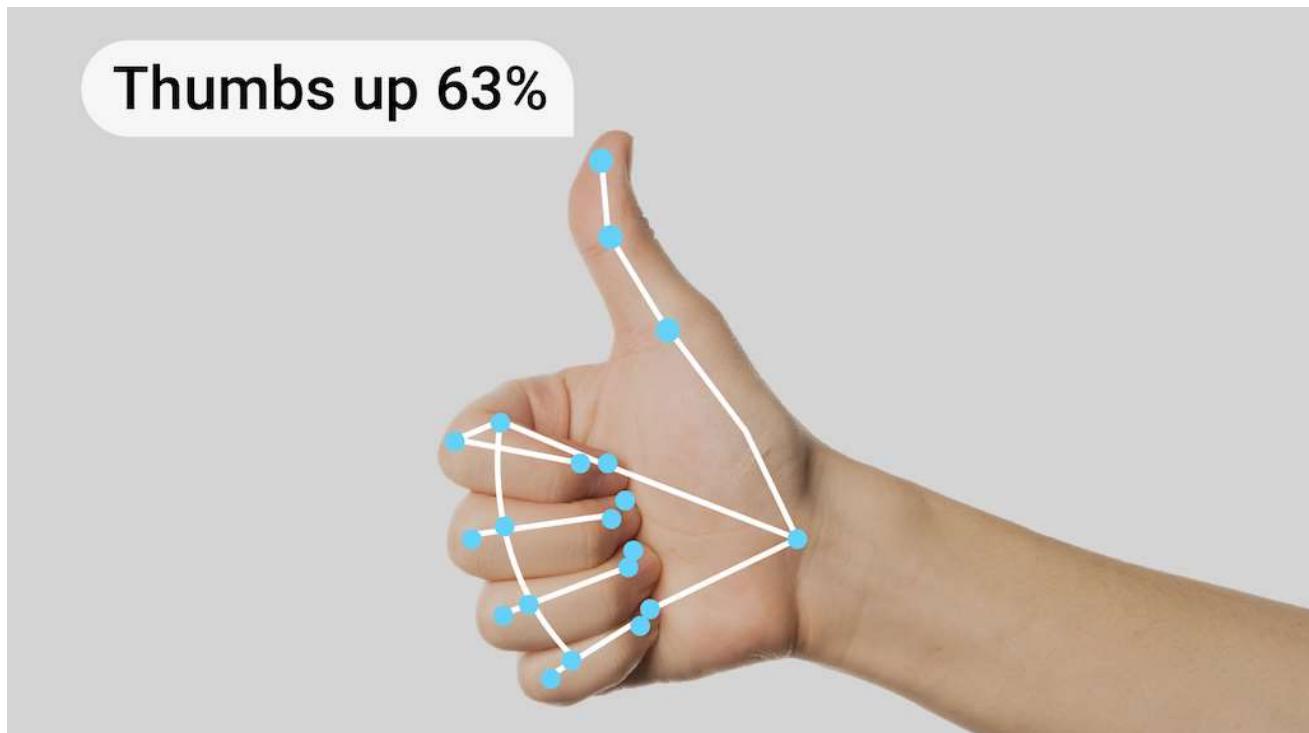
2. Pose landmarker

The pose landmarker model tracks 33 body landmark locations, representing the approximate location of the following body parts:



- 0. nose
- 1. right eye inner
- 2. right eye
- 3. right eye outer
- 4. left eye inner
- 5. left eye
- 6. left eye outer
- 7. right ear
- 8. left ear
- 9. mouth right
- 10. mouth left
- 11. right shoulder
- 12. left shoulder
- 13. right elbow
- 14. left elbow
- 15. right wrist
- 16. left wrist
- 17. right pinky knuckle #1
- 18. left pinky knuckle #1
- 19. right index knuckle #1
- 20. left index knuckle #1
- 21. right thumb knuckle #2
- 22. left thumb knuckle #2
- 23. right hip
- 24. left hip
- 25. right knee
- 26. left knee
- 27. right ankle
- 28. left ankle
- 29. right heel
- 30. left heel
- 31. right foot index
- 32. left foot index

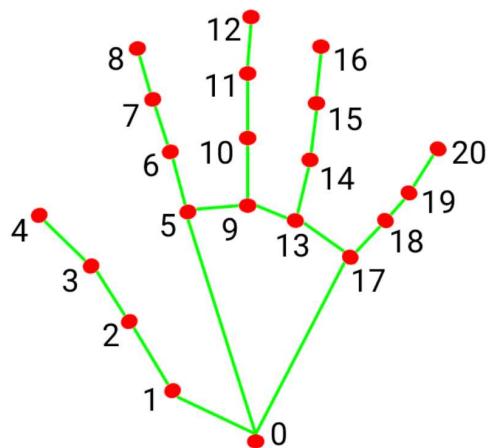
3. Application of mediapipe



-Object detection

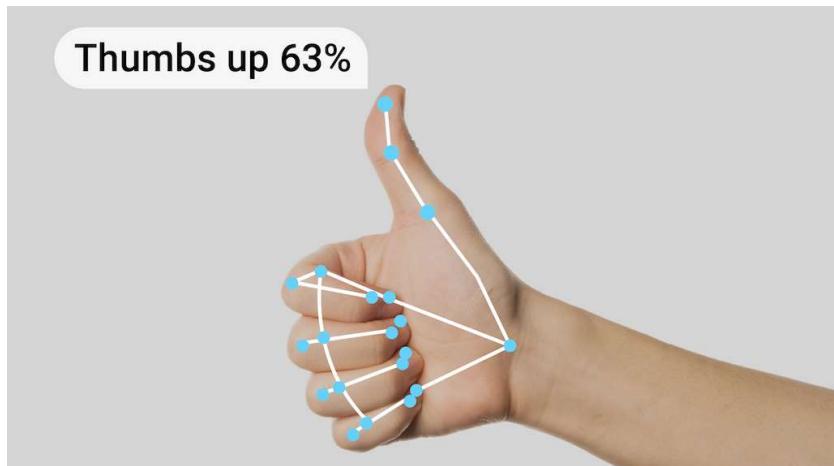
-Face detection

-Hand landmark detection



- | | |
|-----------------------|-----------------------|
| 0. WRIST | 11. MIDDLE_FINGER_DIP |
| 1. THUMB_CMC | 12. MIDDLE_FINGER_TIP |
| 2. THUMB_MCP | 13. RING_FINGER_MCP |
| 3. THUMB_IP | 14. RING_FINGER_PIP |
| 4. THUMB_TIP | 15. RING_FINGER_DIP |
| 5. INDEX_FINGER_MCP | 16. RING_FINGER_TIP |
| 6. INDEX_FINGER_PIP | 17. PINKY_MCP |
| 7. INDEX_FINGER_DIP | 18. PINKY_PIP |
| 8. INDEX_FINGER_TIP | 19. PINKY_DIP |
| 9. MIDDLE_FINGER_MCP | 20. PINKY_TIP |
| 10. MIDDLE_FINGER_PIP | |

-Gesture control



-Emotion recognition

-Single body action recognition

4. Procedure

-creating separate environment

- installing dependencies
- extracting landmarks (coordinates)
- saving all coordinates in csv file with different class (standing ,seating , happy , etc)
- training our models on the coordinates
- then predicting actions , emotions

Install and import dependencies

```
In [1]: !pip install mediapipe opencv-python pandas scikit-learn
```

```
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```

```
In [1]: import mediapipe as mp # Import mediapipe
import cv2
```

```
In [2]: mp_drawing = mp.solutions.drawing_utils # Drawing helpers
mp_holistic = mp.solutions.holistic
```

make detection

```
In [6]: cap = cv2.VideoCapture(0)
# Initiate holistic model
with mp_holistic.Holistic(min_detection_confidence=0.5, min_tracking_confidence=0.5) as mp_holistic:

    while cap.isOpened():
        ret, frame = cap.read()

        # Recolor Feed
        image = cv2.cvtColor(frame, cv2.COLOR_BGR2RGB)
        image.flags.writeable = False

        # Make Detections
        results = holistic.process(image)
        # print(results.face_landmarks)

        # face_Landmarks, pose_Landmarks, left_hand_Landmarks, right_hand_Landmarks

        # Recolor image back to BGR for rendering
        image.flags.writeable = True
        image = cv2.cvtColor(image, cv2.COLOR_RGB2BGR)

        # 1. Draw face Landmarks
        mp_drawing.draw_landmarks(image, results.face_landmarks, mp_holistic.FACEMESH_FACE_OVAL,
                                  mp_drawing.DrawingSpec(color=(80,110,10), thickness=1),
                                  mp_drawing.DrawingSpec(color=(80,256,121), thickness=1))

        # 2. Right hand
        mp_drawing.draw_landmarks(image, results.right_hand_landmarks, mp_holistic.HAND_CONNECTIONS,
                                  mp_drawing.DrawingSpec(color=(80,22,10), thickness=2),
                                  mp_drawing.DrawingSpec(color=(80,44,121), thickness=2))

        # 3. Left Hand
        mp_drawing.draw_landmarks(image, results.left_hand_landmarks, mp_holistic.HAND_CONNECTIONS,
                                  mp_drawing.DrawingSpec(color=(121,22,76), thickness=2),
                                  mp_drawing.DrawingSpec(color=(121,44,250), thickness=2))

        # 4. Pose Detections
        mp_drawing.draw_landmarks(image, results.pose_landmarks, mp_holistic.POSE_CONNECTIONS,
                                  mp_drawing.DrawingSpec(color=(245,117,66), thickness=2),
                                  mp_drawing.DrawingSpec(color=(245,66,230), thickness=2))

        cv2.imshow('Raw Webcam Feed', image)

        if cv2.waitKey(10) & 0xFF == ord('q'):
            break

cap.release()
cv2.destroyAllWindows()
```

```
In [4]: results.face_landmarks.landmark[0].visibility
```

```
Out[4]: 0.0
```

capture landmarks

```
In [17]: import csv  
import os  
import numpy as np
```

```
In [18]: num_coords = len(results.pose_landmarks.landmark)+len(results.face_landmarks.landmark)  
num_coords
```

```
NameError Traceback (most recent call last)  
Cell In[18], line 1  
----> 1 num_coords = len(results.pose_landmarks.landmark)+len(results.face_landmarks.  
landmark)  
      2 num_coords  
  
NameError: name 'results' is not defined
```

```
In [17]: landmarks = ['class']  
for val in range(1, num_coords+1):  
    landmarks += ['x{}'.format(val), 'y{}'.format(val), 'z{}'.format(val), 'v{}'.format(val)]
```

```
In [18]: landmarks
```

```
Out[18]: ['class',  
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```

```
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'x241',
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'z241',
've241',
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'z248',
've248',
'x249',
'y249',
'z249',
've249',
'x250',
'y250',
'z250',
...]
```

In [28]:

```
with open('coord.csv', mode='w', newline='') as f:
    csv_writer = csv.writer(f, delimiter=',', quotechar='"', quoting=csv.QUOTE_MINIMAL)
    csv_writer.writerow(landmarks)
```

In [59]:

```
class_name = "standing"
```

In [60]:

```
cap = cv2.VideoCapture(0)
# Initiate holistic model
with mp_holistic.Holistic(min_detection_confidence=0.5, min_tracking_confidence=0.5) as holistic:

    while cap.isOpened():
        ret, frame = cap.read()

        # Recolor Feed
        image = cv2.cvtColor(frame, cv2.COLOR_BGR2RGB)
        image.flags.writeable = False
```

```

# Make Detections
results = holistic.process(image)
# print(results.face_landmarks)

# face_landmarks, pose_landmarks, left_hand_landmarks, right_hand_landmarks

# Recolor image back to BGR for rendering
image.flags.writeable = True
image = cv2.cvtColor(image, cv2.COLOR_RGB2BGR)

# 1. Draw face Landmarks
mp_drawing.draw_landmarks(image, results.face_landmarks, mp_holistic.FACEMESH_
                           mp_drawing.DrawingSpec(color=(80,110,10), thickness=1
                           mp_drawing.DrawingSpec(color=(80,256,121), thickness=1
                           )

# 2. Right hand
mp_drawing.draw_landmarks(image, results.right_hand_landmarks, mp_holistic.HAND_
                           mp_drawing.DrawingSpec(color=(80,22,10), thickness=2,
                           mp_drawing.DrawingSpec(color=(80,44,121), thickness=2
                           )

# 3. Left Hand
mp_drawing.draw_landmarks(image, results.left_hand_landmarks, mp_holistic.HAND_
                           mp_drawing.DrawingSpec(color=(121,22,76), thickness=2
                           mp_drawing.DrawingSpec(color=(121,44,250), thickness=2
                           )

# 4. Pose Detections
mp_drawing.draw_landmarks(image, results.pose_landmarks, mp_holistic.POSE_CONN_
                           mp_drawing.DrawingSpec(color=(245,117,66), thickness=1
                           mp_drawing.DrawingSpec(color=(245,66,230), thickness=1
                           )

# Export coordinates
try:
    # Extract Pose Landmarks
    pose = results.pose_landmarks.landmark
    pose_row = list(np.array([[landmark.x, landmark.y, landmark.z, landmark.visibility]]))

    # Extract Face Landmarks
    face = results.face_landmarks.landmark
    face_row = list(np.array([[landmark.x, landmark.y, landmark.z, landmark.visibility]]))

    # Concat rows
    row = pose_row+face_row

    # Append class name
    row.insert(0, class_name)

    # Export to CSV
    with open('coord.csv', mode='a', newline='') as f:
        csv_writer = csv.writer(f, delimiter=',', quotechar='"', quoting=csv.QUOTE_MINIMAL)
        csv_writer.writerow(row)

except:
    pass

cv2.imshow('Raw Webcam Feed', image)

if cv2.waitKey(10) & 0xFF == ord('q'):

```

break

```
cap.release()
cv2.destroyAllWindows()
```

In [1]: `import pandas as pd
from sklearn.model_selection import train_test_split`

In [2]: `df = pd.read_csv('coord.csv')`

In [3]: `df.head()`

Out[3]:

	class	x1	y1	z1	v1	x2	y2	z2	v2	x3
0	working	0.452353	0.278074	-0.483196	0.999997	0.470504	0.234207	-0.449846	0.999994	0.481901
1	working	0.454130	0.276581	-0.543517	0.999996	0.470552	0.233398	-0.492786	0.999993	0.481845
2	working	0.454202	0.275508	-0.542326	0.999995	0.470423	0.232785	-0.493952	0.999993	0.481429
3	working	0.458049	0.270778	-0.489343	0.999994	0.471127	0.229890	-0.432510	0.999992	0.481477
4	working	0.457954	0.270314	-0.481695	0.999994	0.470534	0.229904	-0.423149	0.999992	0.479913

5 rows × 2005 columns

In [4]: `df.tail()`

Out[4]:

	class	x1	y1	z1	v1	x2	y2	z2	v2	
627	standing	0.442585	0.288592	-0.405592	0.999865	0.449690	0.273587	-0.382563	0.999829	0.4530
628	standing	0.504412	0.291029	-0.243900	0.999705	0.500397	0.272937	-0.213305	0.999541	0.5010
629	standing	0.382215	0.317442	-0.340185	0.999013	0.389706	0.299102	-0.337546	0.998961	0.3935
630	standing	0.384418	0.312225	-0.317954	0.999196	0.392302	0.292905	-0.303286	0.999143	0.3966
631	standing	0.379089	0.292984	-0.433839	0.999272	0.388350	0.273902	-0.414130	0.999213	0.3938

5 rows × 2005 columns

In [5]: `df[df['class']=='working']`

Out[5]:

	class	x1	y1	z1	v1	x2	y2	z2	v2	...
0	working	0.452353	0.278074	-0.483196	0.999997	0.470504	0.234207	-0.449846	0.999994	0.48190
1	working	0.454130	0.276581	-0.543517	0.999996	0.470552	0.233398	-0.492786	0.999993	0.48184
2	working	0.454202	0.275508	-0.542326	0.999995	0.470423	0.232785	-0.493952	0.999993	0.48145
3	working	0.458049	0.270778	-0.489343	0.999994	0.471127	0.229890	-0.432510	0.999992	0.48145
4	working	0.457954	0.270314	-0.481695	0.999994	0.470534	0.229904	-0.423149	0.999992	0.47994
...
115	working	0.395265	0.248851	-0.508753	0.999328	0.413086	0.197402	-0.484638	0.998845	0.42731
116	working	0.404025	0.235304	-0.520985	0.999140	0.422906	0.182646	-0.500296	0.998510	0.43670
117	working	0.426504	0.189636	-0.527140	0.999161	0.447941	0.138167	-0.505648	0.998507	0.46248
118	working	0.484437	0.113024	-0.565920	0.998896	0.511246	0.062458	-0.538478	0.997820	0.52687
119	working	0.513042	0.110527	-0.575804	0.998516	0.539975	0.058484	-0.557212	0.996654	0.55434

120 rows × 2005 columns



```
In [6]: X = df.drop('class', axis=1) # features
y = df['class'] # target value
```

```
In [7]: X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.3, random_state=42)
```

```
In [8]: y_test
```

```
Out[8]: 558      standing
234    talking on phone
430      sleeping
326      seating
389      walking
...
555      standing
454      sleeping
511      sleeping
285      seating
390      walking
Name: class, Length: 190, dtype: object
```

```
In [ ]:
```

```
In [9]: from sklearn.pipeline import make_pipeline
from sklearn.preprocessing import StandardScaler

from sklearn.linear_model import RidgeClassifier
from sklearn.ensemble import RandomForestClassifier, GradientBoostingClassifier
```

```
In [10]: pipelines = {
    'lr':make_pipeline(StandardScaler(), LogisticRegression()),
    'rc':make_pipeline(StandardScaler(), RidgeClassifier()),
    'rf':make_pipeline(StandardScaler(), RandomForestClassifier()),
```

```
'gb':make_pipeline(StandardScaler(), GradientBoostingClassifier()),  
}
```

```
In [14]: fit_models = {}  
for algo, pipeline in pipelines.items():  
    model = pipeline.fit(X_train, y_train)  
    fit_models[algo] = model
```

```
In [15]: fit_models
```

```
Out[15]: {'rc': Pipeline(steps=[('standardscaler', StandardScaler()),  
                               ('ridgeclassifier', RidgeClassifier())]),  
          'rf': Pipeline(steps=[('standardscaler', StandardScaler()),  
                               ('randomforestclassifier', RandomForestClassifier())]),  
          'gb': Pipeline(steps=[('standardscaler', StandardScaler()),  
                               ('gradientboostingclassifier', GradientBoostingClassifier())])}
```

```
In [31]: fit_models['rc'].predict(X_test)
```

```
Out[31]: array(['standing', 'talking on phone', 'sleeping', 'seating', 'walking',
   'talking on phone', 'sleeping', 'standing', 'talking on phone',
   'talking on phone', 'seating', 'walking', 'working', 'sleeping',
   'talking on phone', 'working', 'standing', 'standing', 'standing',
   'talking on phone', 'talking on phone', 'standing', 'walking',
   'sleeping', 'sleeping', 'standing', 'seating', 'standing',
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   'seating', 'working', 'sleeping', 'seating', 'seating', 'working',
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   'talking on phone', 'talking on phone', 'talking on phone',
   'talking on phone', 'sleeping', 'talking on phone', 'working',
   'walking', 'standing', 'standing', 'talking on phone',
   'walking', 'talking on phone', 'talking on phone',
   'talking on phone', 'seating', 'walking', 'talking on phone',
   'seating', 'talking on phone', 'sleeping', 'standing', 'standing',
   'working', 'seating', 'sleeping', 'working', 'seating',
   'talking on phone', 'talking on phone', 'talking on phone',
   'working', 'walking', 'walking', 'talking on phone', 'walking',
   'standing', 'working', 'walking', 'walking', 'sleeping', 'working',
   'sleeping', 'working', 'seating', 'talking on phone',
   'talking on phone', 'standing', 'talking on phone', 'seating',
   'seating', 'sleeping', 'walking', 'sleeping', 'working',
   'working', 'talking on phone', 'talking on phone', 'sleeping',
   'talking on phone', 'sleeping', 'sleeping', 'talking on phone',
   'sleeping', 'seating', 'standing', 'walking', 'sleeping',
   'talking on phone', 'seating', 'standing', 'seating',
   'talking on phone', 'working', 'working', 'working', 'sleeping',
   'seating', 'seating', 'standing', 'working', 'working',
   'talking on phone', 'seating', 'seating', 'working', 'sleeping',
   'talking on phone', 'walking', 'talking on phone', 'working',
   'working', 'sleeping', 'sleeping', 'working', 'seating',
   'talking on phone', 'sleeping', 'seating', 'sleeping', 'walking',
   'standing', 'seating', 'working', 'sleeping', 'seating',
   'talking on phone', 'working', 'seating', 'sleeping', 'sleeping',
   'talking on phone', 'working', 'walking', 'working', 'walking',
   'sleeping', 'standing', 'seating', 'talking on phone', 'sleeping',
   'sleeping', 'standing', 'working', 'standing', 'sleeping',
   'sleeping', 'seating', 'walking'], dtype='<U16')
```

```
In [17]: from sklearn.metrics import accuracy_score # Accuracy metrics
import pickle
```

```
In [18]: for algo, model in fit_models.items():
    yhat = model.predict(X_test)
    print(algo, accuracy_score(y_test, yhat))
```

```
rc 1.0
rf 1.0
gb 0.9947368421052631
```

```
In [32]: fit_models['rc'].predict(X_test)
```

```
Out[32]: array(['standing', 'talking on phone', 'sleeping', 'seating', 'walking',
   'talking on phone', 'sleeping', 'standing', 'talking on phone',
   'talking on phone', 'seating', 'walking', 'working', 'sleeping',
   'talking on phone', 'working', 'standing', 'standing', 'standing',
   'talking on phone', 'talking on phone', 'standing', 'walking',
   'sleeping', 'sleeping', 'standing', 'seating', 'standing',
   'seating', 'sleeping', 'standing', 'sleeping', 'standing',
   'standing', 'talking on phone', 'seating', 'sleeping', 'seating',
   'sleeping', 'talking on phone', 'standing', 'standing', 'sleeping',
   'seating', 'working', 'sleeping', 'seating', 'seating', 'working',
   'standing', 'seating', 'walking', 'seating', 'talking on phone',
   'sleeping', 'working', 'talking on phone', 'seating',
   'talking on phone', 'talking on phone', 'talking on phone',
   'talking on phone', 'sleeping', 'talking on phone', 'working',
   'walking', 'standing', 'standing', 'talking on phone',
   'walking', 'talking on phone', 'talking on phone',
   'talking on phone', 'seating', 'walking', 'talking on phone',
   'seating', 'talking on phone', 'sleeping', 'standing', 'standing',
   'working', 'seating', 'sleeping', 'working', 'seating',
   'talking on phone', 'talking on phone', 'talking on phone',
   'working', 'walking', 'walking', 'talking on phone', 'walking',
   'standing', 'working', 'walking', 'walking', 'sleeping', 'working',
   'sleeping', 'working', 'seating', 'talking on phone',
   'talking on phone', 'standing', 'talking on phone', 'seating',
   'seating', 'sleeping', 'walking', 'sleeping',
   'talking on phone', 'seating', 'standing', 'seating',
   'talking on phone', 'working', 'working', 'working', 'sleeping',
   'seating', 'seating', 'standing', 'working', 'working',
   'talking on phone', 'seating', 'seating', 'working', 'sleeping',
   'talking on phone', 'walking', 'talking on phone', 'working',
   'working', 'sleeping', 'sleeping', 'working', 'seating',
   'talking on phone', 'sleeping', 'seating', 'sleeping', 'walking',
   'standing', 'seating', 'working', 'sleeping', 'seating',
   'talking on phone', 'working', 'seating', 'sleeping', 'sleeping',
   'talking on phone', 'working', 'walking', 'working', 'walking',
   'sleeping', 'standing', 'seating', 'talking on phone', 'sleeping',
   'sleeping', 'standing', 'working', 'standing', 'sleeping',
   'sleeping', 'seating', 'walking'], dtype='<U16')
```

In [33]: `y_test`

```
Out[33]: 558      standing
234    talking on phone
430      sleeping
326      seating
389      walking
...
555      standing
454      sleeping
511      sleeping
285      seating
390      walking
Name: class, Length: 190, dtype: object
```

In [34]: `with open('body_language_pose_rf.pkl', 'wb') as f:`
 `pickle.dump(fit_models['rc'], f)`

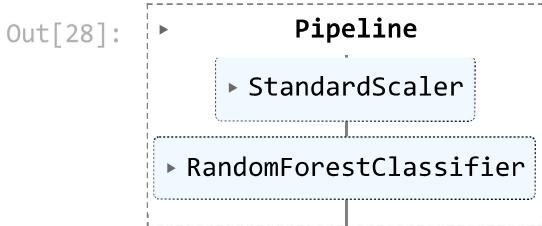
4. Make Detections with Model

```
In [25]: with open('body_language_pose.pkl', 'rb') as f:
    model = pickle.load(f)
```

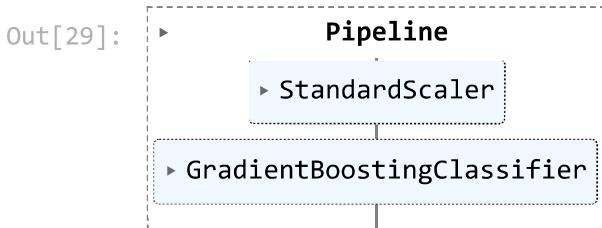
```
In [26]: with open('body_language_pose.pkl1', 'rb') as f:
    model1 = pickle.load(f)
```

```
In [35]: with open('body_language_pose_rf.pkl', 'rb') as f:
    model2 = pickle.load(f)
```

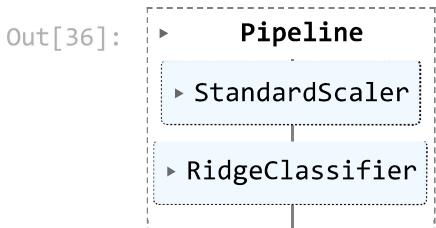
```
In [28]: model
```



```
In [29]: model1
```



```
In [36]: model2
```



```
In [ ]:
```

```
In [1]: cap = cv2.VideoCapture(0)
# Initiate holistic model
with mp_holistic.Holistic(min_detection_confidence=0.5, min_tracking_confidence=0.5) as mp_holistic:

    while cap.isOpened():
        ret, frame = cap.read()

        # Recolor Feed
        image = cv2.cvtColor(frame, cv2.COLOR_BGR2RGB)
        image.flags.writeable = False
```

```

# Make Detections
results = holistic.process(image)
print(results.face_landmarks)

# face_Landmarks, pose_Landmarks, left_hand_Landmarks, right_hand_Landmarks

# Recolor image back to BGR for rendering
image.flags.writeable = True
image = cv2.cvtColor(image, cv2.COLOR_RGB2BGR)

# 1. Draw face Landmarks
mp_drawing.draw_landmarks(image, results.face_landmarks, mp_holistic.FACEMESH_
                           mp_drawing.DrawingSpec(color=(80,110,10), thickness=1
                           mp_drawing.DrawingSpec(color=(80,256,121), thickness=1
                           )

# 2. Right hand
mp_drawing.draw_landmarks(image, results.right_hand_landmarks, mp_holistic.HAND_
                           mp_drawing.DrawingSpec(color=(80,22,10), thickness=2,
                           mp_drawing.DrawingSpec(color=(80,44,121), thickness=2
                           )

# 3. Left Hand
mp_drawing.draw_landmarks(image, results.left_hand_landmarks, mp_holistic.HAND_
                           mp_drawing.DrawingSpec(color=(121,22,76), thickness=2
                           mp_drawing.DrawingSpec(color=(121,44,250), thickness=2
                           )

# 4. Pose Detections
mp_drawing.draw_landmarks(image, results.pose_landmarks, mp_holistic.POSE_CONN_
                           mp_drawing.DrawingSpec(color=(245,117,66), thickness=1
                           mp_drawing.DrawingSpec(color=(245,66,230), thickness=1
                           )

# Export coordinates
try:
    # Extract Pose Landmarks
    pose = results.pose_landmarks.landmark
    pose_row = list(np.array([[landmark.x, landmark.y, landmark.z, landmark.visibility]]))

    # Extract Face Landmarks
    face = results.face_landmarks.landmark
    face_row = list(np.array([[landmark.x, landmark.y, landmark.z, landmark.visibility]]))

    # Concat rows
    row = pose_row+face_row

    # Append class name
    row.insert(0, class_name)

    # Export to CSV
    with open('body_language.csv', mode='a', newline='') as f:
        csv_writer = csv.writer(f, delimiter=',', quotechar='"', quoting=csv.QUOTE_MINIMAL)
        csv_writer.writerow(row)

    # Make Detections
    X = pd.DataFrame([row])
    body_language_class = model.predict(X)[0]
    body_language_prob = model.predict_proba(X)[0]
    print(body_language_class, body_language_prob)

```

```

# Grab ear coords
coords = tuple(np.multiply(
    np.array(
        (results.pose_landmarks.landmark[mp_holistic.PoseLandmark.LEFT_EAR].x,
         results.pose_landmarks.landmark[mp_holistic.PoseLandmark.LEFT_EAR].y),
        [640,480]).astype(int))

cv2.rectangle(image,
              (coords[0], coords[1]+5),
              (coords[0]+len(body_language_class)*20, coords[1]-30),
              (245, 117, 16), -1)
cv2.putText(image, body_language_class, coords,
            cv2.FONT_HERSHEY_SIMPLEX, 1, (255, 255, 255), 2, cv2.LINE_AA)

# Get status box
cv2.rectangle(image, (0,0), (250, 60), (245, 117, 16), -1)

# Display Class
cv2.putText(image, 'CLASS'
            , (95,12), cv2.FONT_HERSHEY_SIMPLEX, 0.5, (0, 0, 0), 1, cv2.LINE_AA)
cv2.putText(image, body_language_class.split(' ')[0]
            , (90,40), cv2.FONT_HERSHEY_SIMPLEX, 1, (255, 255, 255), 2, cv2.LINE_AA)

# Export to CSV
with open('body_language.csv', mode='a', newline='') as f:
    csv_writer = csv.writer(f, delimiter=',', quotechar='"', quoting=csv.QUOTE_MINIMAL)
    csv_writer.writerow(row)

# Display Probability
cv2.putText(image, 'PROB'
            , (15,12), cv2.FONT_HERSHEY_SIMPLEX, 0.5, (0, 0, 0), 1, cv2.LINE_AA)
cv2.putText(image, str(round(body_language_prob[np.argmax(body_language_prob)]*100))
            , (10,40), cv2.FONT_HERSHEY_SIMPLEX, 1, (255, 255, 255), 2, cv2.LINE_AA)

except:
    pass

cv2.imshow('Raw Webcam Feed', image)

if cv2.waitKey(10) & 0xFF == ord('q'):
    break

cap.release()
cv2.destroyAllWindows()

```

Cell In[1], line 59
`row.insert(0, class_name)`
`^`

IndentationError: unexpected indent

In [26]: `tuple(np.multiply(np.array((results.pose_landmarks.landmark[mp_holistic.PoseLandmark.LEFT_EAR].x,`
`results.pose_landmarks.landmark[mp_holistic.PoseLandmark.LEFT_EAR].y)), [640,480]).ast`

```
NameError
Cell In[26], line 1
----> 1 tuple(np.multiply(np.array((results.pose_landmarks.landmark[mp_holistic.PoseLandmark.LEFT_EAR].x,
                                     2 results.pose_landmarks.landmark[mp_holistic.PoseLandmark.LEFT_EAR].y)), [640, 480]).astype(int))

NameError: name 'np' is not defined
```

In []:

In []:

In []:

In []:

```
In [1]: import csv
import os
import numpy as np
import pandas as pd
```

```
In [2]: import pickle
```

```
In [3]: import mediapipe as mp # Import mediapipe
import cv2
```

```
In [4]: mp_drawing = mp.solutions.drawing_utils # Drawing helpers
mp_holistic = mp.solutions.holistic
```

```
In [5]: with open('body_language_pose.pkl', 'rb') as f:
    model = pickle.load(f)
```

```
In [6]: model
```

Out[6]:

```
▶ Pipeline
  ▶ StandardScaler
  ▶ RandomForestClassifier
```

```
In [10]: cap = cv2.VideoCapture(0)
# Initiate holistic model
with mp_holistic.Holistic(min_detection_confidence=0.5, min_tracking_confidence=0.5) as holistic:

    while cap.isOpened():
        ret, frame = cap.read()

        # Recolor Feed
        image = cv2.cvtColor(frame, cv2.COLOR_BGR2RGB)
        image.flags.writeable = False

        # Make Detections
        results = holistic.process(image)
        # print(results.face_landmarks)

        # face_Landmarks, pose_Landmarks, left_hand_landmarks, right_hand_landmarks

        # Recolor image back to BGR for rendering
        image.flags.writeable = True
        image = cv2.cvtColor(image, cv2.COLOR_RGB2BGR)

        # 1. Draw face Landmarks
        mp_drawing.draw_landmarks(image, results.face_landmarks, mp_holistic.FACEMESH_FACE_OVAL,
                                  mp_drawing.DrawingSpec(color=(80,110,10), thickness=1),
                                  mp_drawing.DrawingSpec(color=(80,256,121), thickness=1))

        # 2. Right hand
        mp_drawing.draw_landmarks(image, results.right_hand_landmarks, mp_holistic.HAND_CONNECTIONS,
                                  mp_drawing.DrawingSpec(color=(80,22,10), thickness=2),
```

```

        mp_drawing.DrawingSpec(color=(80,44,121), thickness=2
    )

# 3. Left Hand
mp_drawing.draw_landmarks(image, results.left_hand_landmarks, mp_holistic.HAND
    mp_drawing.DrawingSpec(color=(121,22,76), thickness=2
    mp_drawing.DrawingSpec(color=(121,44,250), thickness=
) )

# 4. Pose Detections
mp_drawing.draw_landmarks(image, results.pose_landmarks, mp_holistic.POSE_CONN
    mp_drawing.DrawingSpec(color=(245,117,66), thickness=2
    mp_drawing.DrawingSpec(color=(245,66,230), thickness=
) )

# Export coordinates
try:
    # Extract Pose Landmarks
    pose = results.pose_landmarks.landmark
    pose_row = list(np.array([[landmark.x, landmark.y, landmark.z, landmark.vi

    # Extract Face Landmarks
    face = results.face_landmarks.landmark
    face_row = list(np.array([[landmark.x, landmark.y, landmark.z, landmark.vi

    # Concat rows
    row = pose_row+face_row

    #
    # Append class name
    # row.insert(0, class_name)

    #
    # Export to CSV
    # with open('coord.csv', mode='a', newline='') as f:
    #     csv_writer = csv.writer(f, delimiter=',', quotechar='"', quoting=csv
    #     csv_writer.writerow(row)

    # Make Detections
    X = pd.DataFrame([row])
    body_language_class = model.predict(X)[0]
    body_language_prob = model.predict_proba(X)[0]
    print(body_language_class, body_language_prob)

    # Grab ear coords
    coord = tuple(np.multiply(
        np.array(
            (results.pose_landmarks.landmark[mp_holistic.PoseLandm
            results.pose_landmarks.landmark[mp_holistic.PoseLandm
        , [640,480]].astype(int))

    cv2.rectangle(image,
        (coord[0], coord[1]+5),
        (coord[0]+len(body_language_class)*20, coord[1]-30),
        (245, 117, 16), -1)
    cv2.putText(image, body_language_class, coord,
        cv2.FONT_HERSHEY_SIMPLEX, 1, (255, 255, 255), 2, cv2.LINE_AA)

    # Get status box
    cv2.rectangle(image, (0,0), (250, 60), (245, 117, 16), -1)

    # Display Class
    cv2.putText(image, 'CLASS'

```

```

        , (95,12), cv2.FONT_HERSHEY_SIMPLEX, 0.5, (0, 0, 0), 1, cv2.LINE_AA)
cv2.putText(image, body_language_class.split(' ')[0]
            , (90,40), cv2.FONT_HERSHEY_SIMPLEX, 1, (255, 255, 255), 2, cv2.LINE_AA)

# Display Probability
cv2.putText(image, 'PROB'
            , (15,12), cv2.FONT_HERSHEY_SIMPLEX, 0.5, (0, 0, 0), 1, cv2.LINE_AA)
cv2.putText(image, str(round(body_language_prob[np.argmax(body_language_prob)]*100))
            , (10,40), cv2.FONT_HERSHEY_SIMPLEX, 1, (255, 255, 255), 2, cv2.LINE_AA)

except:
    pass

cv2.imshow('Raw Webcam Feed', image)

if cv2.waitKey(10) & 0xFF == ord('q'):
    break

cap.release()
cv2.destroyAllWindows()

```

```

C:\Users\Asus\anaconda3\Lib\site-packages\sklearn\base.py:464: UserWarning: X does not have valid feature names, but StandardScaler was fitted with feature names
  warnings.warn(
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  warnings.warn(
talking on phone [0.  0.43 0.  0.5  0.  0.07]
sleeping [0.  0.45 0.  0.4  0.  0.15]

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  warnings.warn(
sleeping [0.  0.67 0.  0.07 0.  0.26]
sleeping [0.  0.74 0.  0.04 0.  0.22]

```

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sleeping [0.  0.74 0.  0.04 0.  0.22]
sleeping [0.  0.73 0.  0.04 0.  0.23]

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t have valid feature names, but StandardScaler was fitted with feature names
    warnings.warn(
sleeping [0.  0.68 0.  0.04 0.  0.28]
sleeping [0.  0.69 0.  0.04 0.  0.27]

C:\Users\Asus\anaconda3\Lib\site-packages\sklearn\base.py:464: UserWarning: X does no
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sleeping [0.  0.71 0.  0.04 0.  0.25]
sleeping [0.  0.69 0.  0.04 0.  0.27]

C:\Users\Asus\anaconda3\Lib\site-packages\sklearn\base.py:464: UserWarning: X does no
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sleeping [0.  0.69 0.  0.04 0.  0.27]
sleeping [0.  0.68 0.  0.03 0.  0.29]
sleeping [0.  0.69 0.  0.03 0.  0.28]
```