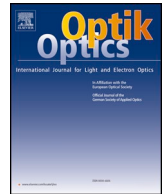




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Original research article

Uneven illumination correction of digital images: A survey of the state-of-the-art

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ABSTRACT

The common image related artifacts during image acquisition are noise caused due to external interference and imbalance in illumination. Uneven illumination correction incorporates a penalty term that performs intensity distribution, and transfer between pre-defined uniformly illuminated and non-uniformly illuminated sub-regions of the input scale image. Many methods exist in the literature to address illumination correction. In this study, an overview of illumination models, estimation, unevenly illuminated image processing, non-uniform illumination correction, background correction techniques, and shadow correction are delivered. Various real-life applications, in the field of remote sensing imaging, automatic medical diagnosis of different diseases, underground imaging, and document imaging depend on image quality and illumination conditions. Some of the related work done by different researchers in solving illumination correction is discussed in a sequel. Assessment of correction quality is difficult because of non-availability of unilluminated images. Some of the objective assessment techniques are also discussed in this survey. This study aims at putting forward an all-inclusive discussion on the application of non-uniform image processing by means of various existing correction models in a wide application domain, and their frequently encountered challenges.

1. Introduction

Significant growth of low-cost digital imaging is noticed in recent times. Devices used in capturing images under uneven lighting, such as smartphones, digital cameras and likewise other personal digital assistants often result in images experiencing non-uniform illumination. The main reason behind unevenly illuminated images are (a) unstable lighting, (b) uneven distribution of light generated due to the presence of large objects, and (c) shadow of other objects makes it difficult to optically isolate the scene [1–3]. Under high illumination variations, in most of the cases, traditional adaptive threshold based segmentation techniques fail to detect small regions or objects and results in over-segmentation. Detection of foreground objects from a non-uniform image background using unsupervised segmentation technique is always vulnerable in the presence of various noise components, shadows (false detections) and reflections from light sources. For uneven background images, the main challenge is to solve the ill-posed inverse problem for correction of background signals without distorting the foreground.

Relatively complex images have an extensive range of varying signal-to-noise ratio. The chance of edge loss in the low-intensity region increases on application of edge detection operators and edge redundancy in the light surface [4].

Captured textures might differ even in conditions where an image of the same surface is taken under varying illumination directions. The extracted features from the same surface are called “illumination-sensitive” texture features. “Illumination-sensitive” texture features affect the performance of traditional classifiers [5]. To improve the overall performance, de-noising [6,7] and

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illumination normalization are required. Illumination normalization is a technique to obtain normalized images from images of unconstrained illumination conditions [8]. An outline of uneven background correction techniques is discussed which needs to be deployed on digital images in various application areas under uneven lighting conditions. Prospective correction is *a priori* correction [9], which is used during image acquisition, whereas retrospective correction is *a posteriori* correction applied after the acquisition. A detailed discussion of the same is provided in Section 4.

This study aims at reporting various techniques of image processing and analyses (e.g.- segmentation [10–15], edge detection [16–21], etc.) and mechanism of texture feature extraction [22–25], which are required for image processing in unconstrained illumination conditions. This survey proposes to provide an accommodating review of existing literature in the domain of uneven image processing and thereby filtering out possible areas having potential for future research.

The schema of the paper is as follows: in Section 2, illumination model and estimation techniques are briefly introduced. Sections 3 and 4 report various uneven illumination image processing and uneven illumination normalization, background correction, and shadow removal techniques. Section 5 is dealing with applications of uneven illumination corrections, while Section 6 deals with objective assessment. Section 7 concludes the proposed ideas of the author and finally discusses the avenues where future research can be directed.

2. Illumination

The appearance of surfaces under various lighting conditions is needed to be simulated in order to produce realistic images.

2.1. Illumination model

Reflected light quantifies illumination incident at a point on a surface.

The lighting impacts are depicted with models that take into account the interaction between light sources and object surfaces. The lighting impacts determining factors include (I) parameters of the light source (electromagnetic spectrum, positions, and shape), (II) parameters of the surface (reflectance properties, position, a position of adjacent surfaces) and (III) parameters of the eye (camera) (sensor spectrum sensitivities, position). The illumination model computes the intensity of the reflected light on a surface at a specified point. Three basic models are proposed based on the standard lighting conditions in a scene. In [26] a detailed discussion of all these 3 different model types is clearly discussed.

2.1.1. Ambient light (Model I)

Illumination of a particular object is due to the presence of ambient light that enters into a room and bounces several times throughout the room. The light's ambient color and the ambient material color contribute to ambient lighting.

The ambient term of a given light is mathematically represented as follows:

$$I_A = L_i L_A M_A \quad (1)$$

where L_i is the illumination, L_A is the light's ambient color and M_A is the ambient material.

The color and intensity of the light are represented by *light's ambient color*, whereas the surface reflection of ambient light (as a whole) is represented by the *ambient material color*.

2.1.2. Diffuse light (Model II)

The influence of *diffuse light* (generated from direct light hitting the surface) is dependent on the incident angle. This influence is directly proportional to the incident angle. The depending factors for *diffuse light* are namely: (I) light colors, (II) material colors, and (III) illuminance (IV) normal vector.

The representation of *the diffuse light* can be expressed as:

$$I_D = L_i \max(0, \hat{L}_{Dir} \cdot \hat{nor}) L_{Diff} M_{Diff} \quad (2)$$

where L_i is the illuminance, L_{Diff} is the light diffuse color, M_{Diff} is the diffuse material, \hat{L}_{Dir} is the light director, and \hat{nor} is the surface normal vector.

2.1.3. Specular light (Model III)

Specular light is observed on smooth, shiny objects as a white highlight reflection. Specular light depends on (I) light direction, (II) surface normal, and (III) viewer location.

Specular light is represented as follows:

$$I_s = \begin{cases} L_i \max(0, (\hat{ref} \cdot \hat{v}))^m L_s M_s, & \text{if } \hat{L}_{Dir} \cdot \hat{nor} > 0 \\ 0, & \text{otherwise} \end{cases} \quad (3)$$

where L_i is the luminance, \hat{ref} is the reflection vector, L_s is the light specular color, M_s is the specular material, and m is the *shininess coefficient*. The *Reflection Vector* is presented as:

$$\hat{ref} = 2(\hat{L}_i \cdot \hat{nor}) \hat{nor} - \hat{L}_i \quad (4)$$

A detailed discussion on the ambient light illumination model is presented in [27]. An illumination model for skin layer bounded by rough surfaces has been stated in [28]. In [29], a discussion of the illumination model inverted from the range and intensity maps was considered.

Parameter estimation for an illumination model using photometric stereo is addressed in [30]. Phong illumination model and infrared sensors are used to measure distances [31]. Illumination models are also used in various application areas like face recognition [32], face alignment [33], soft X-ray transients [34], smart indoor solid-state lighting [35], optical satellite data of rugged terrain [36], visual tracking [37], object tracking [38,39], etc.

2.2. Illumination estimation

For enhancing non-uniform illumination images, retinex [40] algorithm received much attention owing to its simplicity and effectiveness. As per retinex model, an image can be decomposed into two components, namely, (I) illumination (L), and (II) reflectance (R). The observed image (S) is represented by $S = L \times R$. For computational simplicity $S = L \times R$ is converted in logarithmic form $s = l + r$ or $r = s - l$, where $s = \log(S)$, $l = \log(L)$, and $r = \log(R)$. Reflectance (inherent property of an object) can be obtained by taking index form of $r = s - l$. The obtained index form is $R = \exp(s - l)$. Retinex algorithm uses the low-pass filter to estimate the illumination [41,42]. An effective method for estimating L is the key to illumination normalization based on Retinex theory [43].

To realize the photometric consistency, it is important to estimate the illumination of the real world environment. This estimation precision is enough to satisfy human perception. Various illumination estimation techniques are already widely reported in literature, such as:

- (I) using human visual characteristics for AR [44],
- (II) based on red chromaticity [45],
- (III) using shadow borders [46], etc. Estimation techniques are also deployed in multiple application domains, such as:
- (IV) deep outdoor illumination estimation [47],
- (V) lighting virtual object in real scene using a single image [48],
- (VI) urban scenes illumination estimation with the help of color matching [49],
- (VII) real-time estimation techniques from faces for coherent rendering, etc [50],
- (VIII) a real-time system for augmented reality on mobile devices to estimate of illumination direction [51], etc.

For illumination estimation, the Data Driven Estimation Methods (DDEMs) can be used [39]. DDEMs are of two types, namely, (I) unsupervised DDEMs, and (II) supervise DDEMs. Unsupervised DDEMs (fixed illumination estimation models based on certain hypotheses) are (I) GreyWorld (GW) [52], (II) maxRGB [53], (III) Shades of Grey (SoG) [54], and (IV) Edge-based method [55], etc. However, the supervised DDEMs (estimation models based on the color distribution and/or features training) are Color-by-Correlation (C-by-C) [56], Spatio-Spectral statistics-based method (Spatio-Spectral) [57], Neural Networks-based method (NN) [58], Support Vector Regression-based method (SVR) [59], Gamut Mapping [60], edge-based Gamut Mapping [61], etc.

Illumination colors of all the test images are computed using fixed DDEMs. The effectiveness of the assumed model (DDEMs) depends upon the distribution of colors of the test image.

To overcome the limitation of model fixing, image content analysis is deployed for illumination estimation in “Content Driven Estimation Methods” (CDEM). CDEMs are combinational methods [62], where several models are deployed on the same image followed by the best estimation technique or image’s content characteristics are combined with the outputs.

Optical properties of surfaces and the lighting conditions excluding reflected sources or shadows, are analyzed to measure surface intensity (Photometric flux per unit area or visible flux density is used to measure illuminance (I)).

3. Uneven illuminated imaging

Uneven illumination correction (at low magnification) is required for the images that are derived by shining light on two-dimensional objects [63]. No matter how evenly illuminated, vignetting (darkening at corners with a spotlight appearance) is introduced by the imaging devices or magnification tubes in all images. Various imaging techniques (segmentation, edge detection, etc.) and texture based feature extraction mechanism for unevenly illuminated images are discussed in these following sub-sections.

3.1. Uneven illuminated image segmentation

The performance of local threshold-based segmentation techniques for uneven illuminated images is highly sensitive to noise injection and the choice of initial window size for both fixed window method, or window merging technique. In [64] an adaptive thresholding based image segmentation technique, the window growing technique outperformed window merging techniques. The problem of background extraction and segmentation is reported in [65] using morphological transformations. In recent times, lots of work has been done in the area of unevenly illuminated image segmentation and background extraction. In [66], a non-local spatial information and intuitionistic fuzzy entropy based technique are reported. This method has the ability to decrease the influence of uneven lighting on images and injected noise. In [67], a dynamic window based on an incremental window growing approach

achieved an excellent capability to handle a higher number of segmentation levels. In [68], a modified fuzzy C-means image segmentation is used for the same. The proposed technique obtained efficient results for uneven lighting segmenting the image by pattern, where biased intensity fields present.

3.2. Edge detection for uneven illuminated images

The main reasons for false edge detection in unevenly illuminated images are depth, surface normal vector, lighting and reflection discontinuousness. Background noise generated by the presence of a large obstacle, the noise of the imaging system is also responsible for the same. However, in dark image there is a high chance of edge information loss. In [69], wavelet similarity based technique is reported for edge detection from unevenly illuminated images. For edge detection of low illuminated images [70], a short step affine transformation Sobel algorithm is implemented. Comparison with one order and two order edge algorithms are also carried out. In [71], modeling and detection of blurred illumination edges are reported.

3.3. “Illumination-insensitive” texture feature extraction

Under different lighting conditions, the same surface texture looks dissimilar. The extracted feature set from the same surface under varying illumination is significantly different. Based on illumination compensation or enhancement, a texture-feature extraction methodology from the original surface [72] is applied, resulting in an “illumination-insensitive” [73] feature.

Geometric invariant classification of multispectral texture and Zernike moments of illumination is illustrated in [74]. Extraction of “illumination-invariant” features on the basis of natural images statistics are discussed in [75]. Illumination normalization on large and small scale features are reported in [76].

4. Uneven illumination correction

The intrinsic image is described by two pixel-wise multiplication techniques, namely, (I) illumination, and (II) reflectance. Illumination and reflectance are required to correct the unevenness of illumination and visual quality enhancement of low local contrast image [77]. In literature, several techniques are already being reported to normalize uneven illumination and background correction. In this section, various normalization and correction techniques and their application area are discussed.

4.1. Uneven illumination normalization

Varying light is the major problem of uneven illumination. Uneven illumination normalization techniques without using training images and keeping the computational complexity low is always a challenging task [78,79]. Histogram equalization [80,81] is a technique to enhance the global contrast of an image and works fine only when the entire image is either dark or bright irrespective of backgrounds and foregrounds. To overcome this limitation, researchers have already reported various improved techniques [82], such as (I) block-based histogram equalization [83], (II) adaptive histogram equalization [84], (III) oriented local histogram equalization [85], and (IV) local normalization technology [86]. Logarithm Transforms [87], Gaussian mixture model [88], Power-law transformations [89], and contrast stretching transformation [90] are also widely used for the uneven illumination normalization purpose. Photometric normalization [91] based approaches, namely (I) single-scale retinex [92,93], (II) multi-scale retinex [94], (III) adaptive single scale retinex [95], (IV) homomorphic filtering [96], (V) single-scale self quotient image [97], (VI) multi-scale self quotient image [98], (VII) DCT-based normalization [99], and (VIII) wavelet-based normalization [69] are reported in the literature. Apart from illumination properties, all these techniques are based on human perception theory.

Application of histogram equalization, log transformation, and gamma correction [100] to rectify the uneven illumination problem of face recognition followed by the compression function in the retinal filter (COMP) is discussed.

Fast and easy DCT based techniques for illumination estimation and enhancement are reported for real-time systems in [101] and [102]. A discussion on linear and non-linear contrast enhancement techniques was addressed in [103]. In [104], presented a quotient image processing where different smoothing filter techniques are used to improve image quality in varying contrast condition. The proposed method is compared with morphological quotient image, self and dynamic quotient images. In [105], the same author proposed a framework based on 2D Gaussian illumination for contrast correction using the Quadtree technique (to locate low light region). A Fuzzy C-Means (FCM) reported in [106] for the reduction of low illumination. In [107], a multiplicative image formation models and Laplace interpolation and in [108] Weber’s law were used for the same purpose. Local normalization methods depend on four main factors, namely, normal distribution (NORM), histogram equalization (HE), histogram matching (HM) and Gamma Intensity Correction (GIC) [109]. Multiscale illumination normalization using dual-tree complex wavelet transform in the logarithmic domain was presented in [110]. In order to preserve the mean brightness of an image, Singular Value Decomposition (SVD) was applied for low contrast enhancement techniques [111].

4.2. Uneven background correction

Pixel vignetting is a common problem for digital images captured by the sensors. The majority of the digital sensors are flat. Pixels present in the center of the sensor receive light rays directly (at an angle of 90°), whereas the corner pixels receive the rays at a slight angle. The falloff pixel intensity from the center towards the edges of the image is commonly known as pixel vignetting.

Uneven illumination images are obtained using the following expression:

$$U_i(p, q) = I_i(p, q) + B(p, q) \quad (5)$$

where U_i is the uneven illumination image, $I_i(p, q)$ is the same source image in ideal condition, and $B(p, q)$ is the extracted background image. Initially, the background image is generated using a low pass filter followed by subtracting from the source image to balance the contrast. Subtracted image is contrast stretched to compensate for the effects produced by the earlier subtraction operation. Two types of background subtraction techniques, namely, prospective correction and retrospective correction are used for the correction of uneven illumination of an image (vignetting). It is assumed that the image composes a homogeneous background with a brighter or darker small object [112,113].

a. Prospective Correction

Prospective correction uses two different types of additional images acquired during image capturing. In the first category, images are obtained keeping the background without light (dark image) and the next category is the background with light after removal of the object (bright image). Number of images of these two categories are captured for the reduction of noise and attenuation of lighting defects [114–116]. Following transformation function is used to obtain a corrected image ($Corr_i(p, q)$):

$$Corr_i(p, q) = \frac{o(p, q) - d(p, q)}{b(p, q) - d(p, q)} * C \quad (6)$$

here $o(p, q)$ is the source image, $d(p, q)$ and $b(p, q)$ represent the dark image and bright image, respectively. C is a normalization constant used for the purpose of recovering the source image color [117], which is computed as:

$$C = \frac{\text{Mean}(o(p, q))}{\text{Mean}\left(\frac{o(p, q) - d(p, q)}{b(p, q) - d(p, q)}\right)} \quad (7)$$

The correction of a bright image (where the available image is the only bright image) depends upon the image acquisition device. The device can be linear or logarithmic with a gamma of 1. For a linear device, the corrected image is obtained using this following expressions:

$$Corr_i(p, q) = \frac{o(p, q)}{b(p, q)} * C \quad (8)$$

$$C = \frac{\text{Mean}(o(p, q))}{\text{Mean}\left(\frac{o(p, q)}{b(p, q)}\right)} \quad (9)$$

For logarithmic devices, corrected images is obtained by subtracting the source image from the bright image.

For dark image, the correct expression is given by:

$$Corr_i(p, q) = o(p, q) - d(p, q) + \text{mean}(d(p, q)) \quad (10)$$

Perspective correction techniques are reported for document imaging in several studies. In [118], a perspective distortion correction approaches for document imaging (especially for uncalibrated images of documents) is reported. In [119], fuzzy sets and morphological operations based perspective distortion removal and recovering technique of front-parallel view of text with a single image are reported. In other work [120], finding a technique of distorting information and rectification of the prespective Chinese document images (without prior knowledge of imagesilas edge and paragraphpsilas format) are reported. For correction of distorted images in documents, Chinese characterpsilas features of vertical strokes and horizontal characteristics of text line are implemented. The skew correction and perspective rectification in camera-based Farsi document images are described in [121].

b. Retrospective Correction

In the absence of additional image, an ideal illumination model is required for retrospective correction.

The technique is simple after removal of the object from the background (to generate the bright image) deployed prospective correction.

Various filtering techniques are used for retrospective correction, namely, (I) low-pass filter, (II) morphological filter, and (III) homomorphic filter. Apart from filtering techniques (IV) linear regression, and (V) surface fitting with polynomial is also used for the same.

(I) Using Low-pass Filtering

To compensate for illumination, background (low-pass filter with a very large kernel has used background estimation) is subtracted from the source image as the correct expression is given by:

$$Corr_i(p, q) = o(p, q) - LPF(o(p, q)) + \text{mean}(LPF(o(p, q))) \quad (11)$$

where $LPF(o(p, q))$ is the low pass filtered image (of the input image), and $\text{mean}(LPF(o(p, q)))$ is the mean of low pass filtered image.

• Using Morphological Filtering

In the morphological filtering method, two mathematical morphology operators are used to calculate the background, namely, (I) opening and (II) closing. The working principle of morphological filtering technique corresponds to top hat filtering process (black top hat for bright image and white top hat for dark background), where the high frequencies are removed keeping the low frequencies without change.

The following equations show the source image correction technique using a black top hat (BTH) as:

$$Corr_i(p, q) = BTH(o(p, q) + \text{mean}(\text{closing}(o(p, q)))) \quad (12)$$

$$Corr_i(p, q) = (o(p, q) - \text{closing}(o(p, q)) + \text{mean}(\text{closing}(o(p, q)))) \quad (13)$$

• Using Homomorphic Filtering

The background is calculated using homomorphic filtering with a low-pass filter in the homomorphic filtering method. The following equation shows a source image correction technique using homomorphic filtering technique:

$$Corr_i(p, q) = \exp(LPF(\log(o(p, q)))) * C \quad (14)$$

This logarithm of the source image passes through a low pass filter to remove the background and the exponent is used to restore the image. where C is a normalization coefficient, which is given by:

$$C = \frac{\text{Mean}(o(p, q))}{\text{Mean}(\frac{o(p, q)}{\exp(LPF(\log(o(p, q))))})} \quad (15)$$

• Using Linear Regression

The background is calculated utilizing the orthogonal linear regression in the linear regression method. The following eqn. shows a source image correction technique using linear regression techniques:

$$Corr_i(p, q) = o(p, q) - LR(o(p, q)) - \text{mean}(LR(o(p, q))) \quad (16)$$

where $LR(o(p, q))$ is the linear regression of the source image in p and q . Also, $\text{mean}(LR(o(p, q)))$ is the mean of the same. This correction mechanism fails to work on a complex background.

• Using Surface Fitting with Polynomial

The background is calculated utilizing a minimum square fit of a polynomial in surface fitting with polynomial method (e.g.-second-order, Legendre, etc.). The background image is deducted from the source image to compensate for illumination.

The following eqn. shows source image correction technique using a surface fitting with polynomial technique (that approximates the background):

$$Corr_i(p, q) = o(p, q) - \text{Poly}(o(p, q)) - \text{mean}(\text{Poly}(o(p, q))) \quad (17)$$

where $\text{Poly}(o(p, q))$ is a polynomial image of the source image in p and q . Also, $\text{mean}(\text{Poly}(o(p, q)))$ is the mean of the polynomial image.

Respective correction techniques are more robust and desirable because the combined information across multiple images is used for illumination correction function (ICF) [122]. Color image correction is not possible by using the above mentioned techniques. The color image is converted into hue, saturation, lightness (HSV) color space, followed by deploying corrections on the lightness channel.

Retrospective correction is widely studied in medical imaging, especially MR Imaging. Studying adiabatic magnetic resonance imaging sequence, an automatic retrospective correction mechanism of intensity variations observed in a high-resolution surface coil MR image of the rat brain is presented in [123]. In [124], a simple image-based technique for retrospective correction of physiological motion effects in fMRI is presented. The problem of retrospective correction of intensity inhomogeneity in MR images is addressed in [125]. An optimization framework is used to minimize the information of the corrected image, keeping the global intensity statistic preserved. In [126], retrospective correction of intensity inhomogeneities due to the heel effect in digital radio-graphs is reported. In a recent work [127], a Generative Adversarial Networks (GANs) based retrospective correction is proposed for rigid and non-rigid MR motion artifacts. In addition, a diffusion tensor imaging emerges from coil combination mode is reported for bias correction in [128].

4.3. Shadow removal

Presence of shadows leads to quality degradation of images and cause image interpretation problem [129]. To recover illumination field, three different types of shadow removal techniques are used in literature to preserve the texture well and keep the shadow boundary smooth, namely, (I) model-based shadow removal, (II) additive shadow removal, and (III) combined shadow removal [130].

a. Model-based shadow removal

Two types of light sources, viz., direct and ambient light, are used in model-based shadow removal technique. The term ‘direct light’ is self-explanatory, while the reflected light from surrounding surfaces is termed as the ‘ambient light’. The entire direct light or part of it is occluded for the shadow areas.

b. Additive shadow removal

The difference to the pixels in the shadow areas is added to compute the average pixel intensities in the shadow and lit areas of the image.

c. Combined shadow removal

It is a hybrid technique of the previously mentioned two techniques. The initial step involves conversion of the image to the YCbCr color-space. Then, correction on the Y channel is carried out followed by correction of Cb and Cr channels by model-based method. Preservation of chromaticity in cases when shadow covers most of the background with effective change in brightness is well documented in [131,132].

To compute normalized RGB for both foreground and corresponding background, single Gaussian is used and even for background modelling. Comparison between the two is also carried out to evaluate their similarity index.

Selection of gradient directions of each dark pixel from the foreground using a designated threshold is addressed in [133]. Computation of the corresponding background pixel is carried out and it is eliminated based on the same shadow.

Proposed technique works fine when the texture component of the background is strong. Evaluation of color similarity between foreground and background (considered a shadow, if similar), calculation of normalized cross-correlation among foreground colors and its corresponding background is done by implementing HIS color model. Mixture of Gaussians (MOG) technique with minor modifications for background modelling was reported in [134,135]. Classification of a pixel as an object or background depends on its chromaticity component. If the chromaticity component of a foreground pixel is high enough, then it is classified as an object pixel and is considered as background if the pixel is dark.

5. Applications of illumination correction methods

Illumination correction methods are used in wide application domains. In this section, correction methods implemented for remote sensing images, medical imaging modalities, underground imaging and document imaging are reported.

5.1. Remote sensing images

Presence of thin clouds, mountainous terrain, atmospheric conditions, topographic positions, etc., lead to uneven illumination of remotely sensed images. In recent times several works have been reported in this area. In the mountainous terrain, differential terrain illumination is observed in satellite imaging. Varying in reflectance of similar ground feature results misclassification of land cover classes because of its different topographic positions. Correction techniques of satellite images were reported in [136], where the distortion is caused by differential terrain illumination. The removal of effect of thin clouds to restore normal color of ground objects by applying an efficient uneven illumination correction algorithm was illustrated in [137].

Remote sensing of vegetation is severely affected by steep hill and mountain slopes. Correction techniques of satellite imagery required for operational or time-critical applications were reported in [138] and [139]. The former discusses variance of reflectance and illumination with topography, whereas the latter addressed the normalization of varying illumination and atmospheric conditions in remotely sensed images.

Radiometric processing of aerial and satellite remote-sensing imagery is addressed in [140]. Case study is reported from southwestern Yukon, Canada, where the obtained accuracy and utility of this model have been tested in the automated terrain analysis of its moderate to the high relief environment. Another case study of a moderately sloped area where comparison of illumination geometry-based methods for topographic correction of QuickBird satellite images has been carried out is discussed in [141].

5.2. Medical images

5.2.1. Retinal images

Computer-assisted diagnosis of ophthalmic disorders is studied from retinal images captured by advanced fundus camera. High-quality color digital images captured by camera delivers severely distorted resultant images as the retinal surface light reflection exhibits local luminosity and contrast variability during the acquisition process. Estimation and correction techniques for luminosity variation in retinal images are discussed in [142].

A background normalizing technique using between low pass and Gaussian filtering is reported in [143]. Dehazing for retinal vessel segmentation using Convolutional Neural Networks (CNN) is reported in [144]. Correction technique using Laplace interpolation is addressed in [145]. Retrospective illumination correction of retinal images is reported in [146]. Contrast equalization and illumination correction in for colour fundus images addressed in [147–150].

5.2.2. Microscopy images

Many digital microscopy images suffer from inhomogeneity due to uneven illumination (because of misaligned optics, dust, non-uniform light sources and vignetting [151], etc.) or camera nonlinearity commonly known as shading artifacts. The actual measurements and the right perception of the sample image can alter the intensity inhomogeneity of the stitched images. The quality

improvement is reported using flat-field correction technique (Vignetting function) in [152]. In [153], three methods for retrospective correction of vignetting on medical microscopy images is reported. The reported techniques are compared with a prospective correction method. Two new retrospective shading correction algorithms for whole slide image (WSI) is addressed in [154]. The common forms of WSI are namely, (I) multiple image tiles before mosaicking, and (II) an already-stitched image. Mosaicking artifacts in multimodal images for illumination correction is presented in [155], and a fully convolutional network for dermoscopy image illumination correction is reported in [156]. High throughput microscopic image illumination correction is presented in [157].

5.2.3. Magnetic resonance images

Magnetic Resonance images [158–161] produced by old MRI machines are corrupted by bias field signal (low-frequency) and very smooth signal [162]. The authors in [163] stated the spatial sensitivity profile of the surface coil from the original anatomical image. In addition, the normalization technique was discussed in [164]. Both [165] and [166] deal with intensity inhomogeneities in which knowledge of tissue properties is applied. While the former deals with correction of intensity inhomogeneities, whereas the latter addresses a parametric estimate of intensity inhomogeneities applied to MRI. Radiofrequency inhomogeneity correction on the reproducibility of intracranial volumes is addressed in [167]. The authors in [168] and [169] addressed the study of an automatic intensity-correction algorithm for high-resolution MR imaging of the human brain, by using phased array detectors. MR grayscale inhomogeneity correction using optimized homomorphic unsharp masking is addressed in [170].

The degree of uneven illumination distortion during medical image acquisition are suggested to be abandoned or re-acquired to ensure the reliability of computed aided diagnosis results.

5.3. Underwater images

When light travels in water, it gets absorbed and scattered. Three major difficulties exist for underwater imaging, namely, (I) color cast, (II) under-exposure, and (III) fuzz. In [171], the authors proposed using color correction and illumination adjustment to achieve a new technique of underwater image enhancement.

In [172], color correction of underwater images and in [173] a nonuniform illumination correction technique for underwater images is reported using the maximum likelihood estimation method. Dehazing technique used for the underwater image enhancement resulting in minimum loss of information and histogram distribution has been stated in [174]. However, in [175] the same technique with wavelength compensation is addressed.

In a very recent study, underwater image restoration is presented using Convolutional Neural Network [176].

5.4. Document imaging

Document image recognition by OCR is highly affected by under condition of uneven illumination. A Retinex-based illumination correction method was proposed to resolve it in [177]. In [178], of the authors used convex hulls in nonparametric illumination correction for scanned document images. An adaptive correction technique is presented in the nonuniform illumination of multi-spectral digital images.

Apart from these, there are many areas where illumination corrections are widely used (e.g. fisheye imaging [179], ground-based astronomical Image [180], endoscopic camera [181], object tracking for video processing [182–186] etc.)

6. Objective assessment

To evaluate the enhancement results, three objective metrics namely, (I) RMS contrast [187], (II) discrete entropy [188], and (III) lightness of error (LOE) [189] are used.

6.1. RMS contrast

Contrast makes an object distinguishable from others. RMS contrast is represented as:

$$\text{Contrast}_{\text{RMS}} = \sqrt{\frac{1}{MN} \sum_{i=0}^{N-1} \sum_{j=0}^{M-1} \{I(i, j) - \bar{I}\}^2}$$

where $I(i, j)$ is the normalized intensity of pixel from 0 to 1 at the position (i, j) . \bar{I} is the average intensity [190–193].

6.2. Discrete entropy

Entropy is the amount of information contained in an image. Flat images have zero entropy, whereas image containing heavy objects has high entropy value [194]. Entropy is represented as:

$$H = - \sum_i P_i \log_2 P_i$$

where P_i is the probability between two adjacent pixel differences is i .

6.3. Lightness of error (LOE)

Small Lightness of Error (LOE) represents [195] better naturalness preservation. The lightness $L(x,y)$ of an image is given as the maximum of its three color channels:

$$L_{(x,y)} = \max_{c \in [r,g,b]} I^c(x, y) \quad (18)$$

For each pixel (x,y) , the relative order difference (ROD) of the lightness between the original image I and its enhanced version I_e is defined as follows:

$$ROD_{(x,y)} = \sum_{i=1}^m \sum_{j=1}^n (U(L(x, y), L(i, j)) \oplus U(L_e(i, j))) \quad (19)$$

$$U(x, y) = \begin{cases} 1 & \text{for } x > y \\ 0 & \text{else} \end{cases} \quad (20)$$

where m and n are the height and width, $U(x,y)$ is the unit step function and \oplus is the operator. The LOE measure is demarcated as:

$$LOE = \frac{1}{m*n} \sum_{i=1}^m \sum_{j=1}^n ROD(i, j) \quad (21)$$

Natural stimuli and efficiency calculations is the use for RMS contrast [196–198]. To characterize original and enhanced images, discrete entropy (a statistical measure of randomness) is deployed in [199]. In [62,200], LOE is used to access naturalness preservation objectively.

7. Conclusion

Reduction of variations in illumination or their entire elimination (for ease of use in industrial settings) can be achieved in the implementation of appropriate image processing techniques before level-sensitive processing. In this study, many of the state-of-the-art methods for non-uniform illumination correction, background correction techniques, and shadow correction, are reported. Besides this, various illumination models, estimation, unevenly illuminated image processing are also discussed.

This review study of the reported analyses done by implementing various image processing techniques reveals that there is ample scope to study and propose hardware considerations for performing correction techniques in real-time systems.

Conflict of interest statement

No conflict of interest.

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