

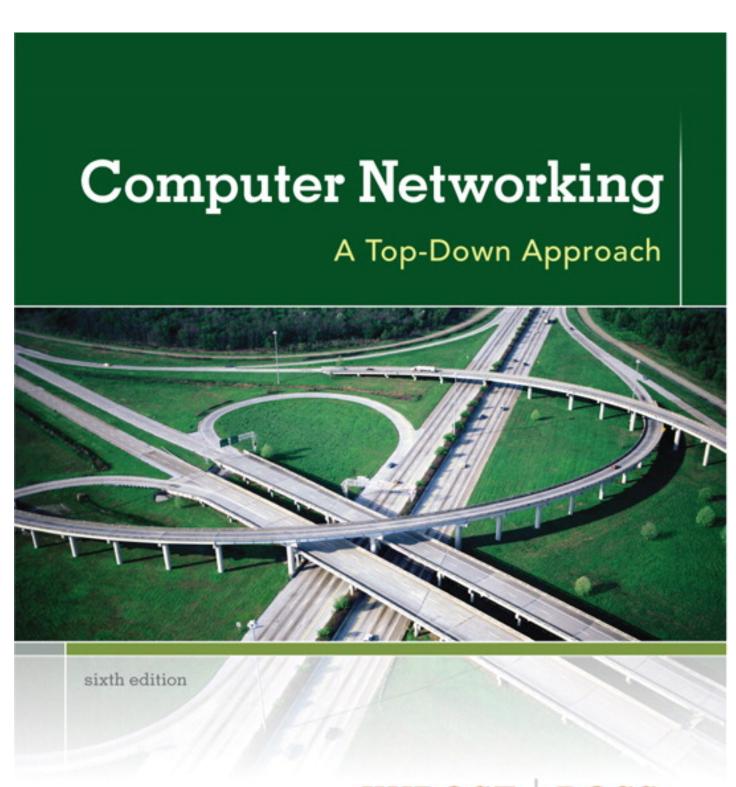
# Mobile Computing

Lecture 6: Wireless LAN (Continue)



# Slides Credits with modifications

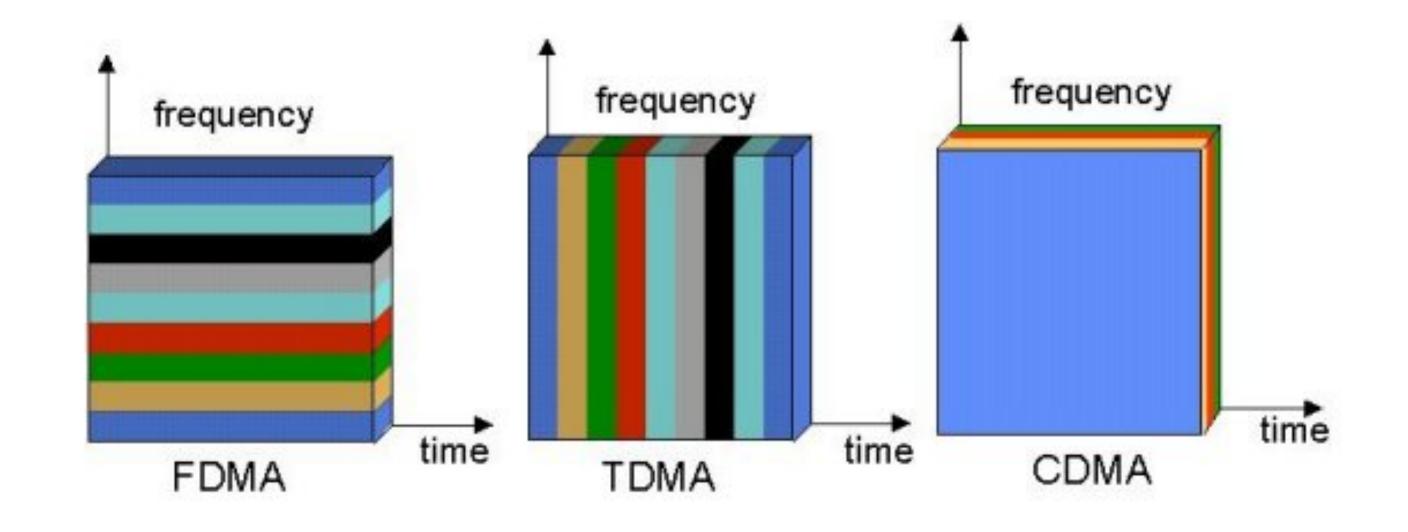
Computer Networking: A Top Down Approach
6th edition
Jim Kurose, Keith Ross
Addison-Wesley
March 2012

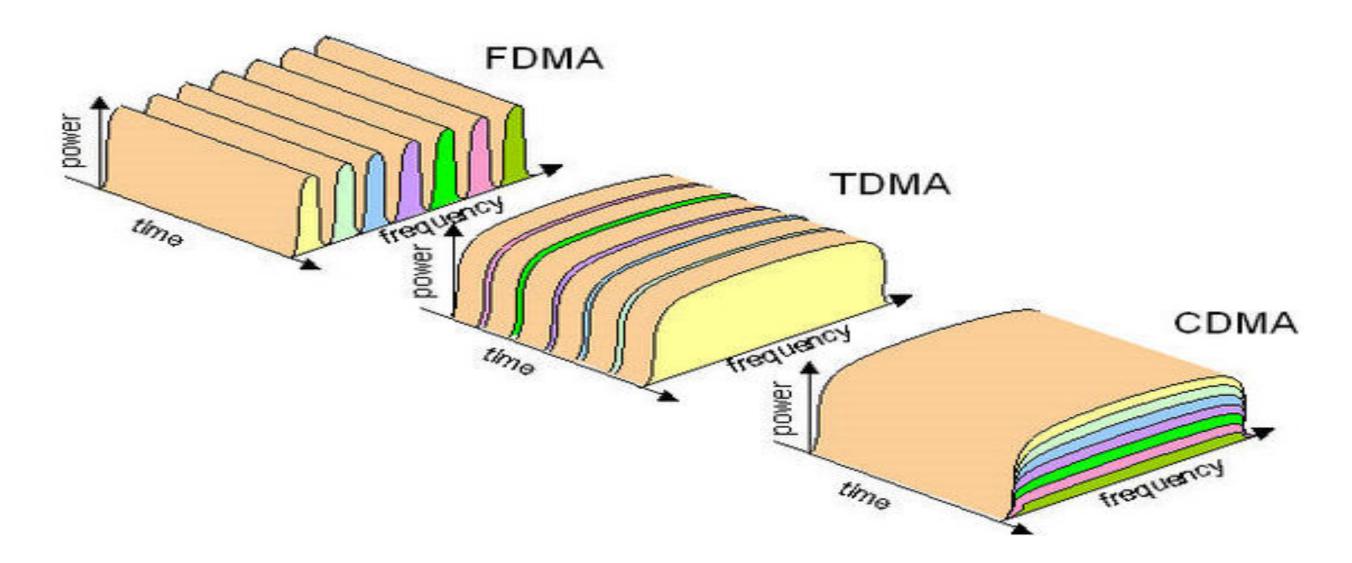


KUROSE ROSS

### TDMA vs FDMA vs CDMA

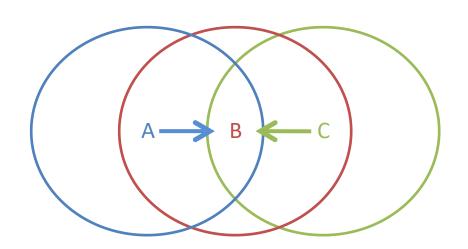
Recap





# Hidden Terminal Problem

- A and C cant see each other, both send to B
- Collision will happen at B



# IEEE 802.11 Wireless LAN

#### 802.11b

- \*2.4-2.485 GHz unlicensed spectrum
- up to 11 Mbps
- \*direct sequence spread spectrum (DSSS) modulation in physical layer.

#### 802.11a

- 5.1-5.8 GHz range
- Uses OFDM
- Pros: fast speed up to 54 Mbps
- Cons: higher cost, shorter range

#### 802.11g

- 2.4-2.485 GHz range
- up to 54 Mbps
- Pros: fast speed, good signal range, backward compatible with 802.11b devices.
- Cons: higher cost, interference with other appliances is possible

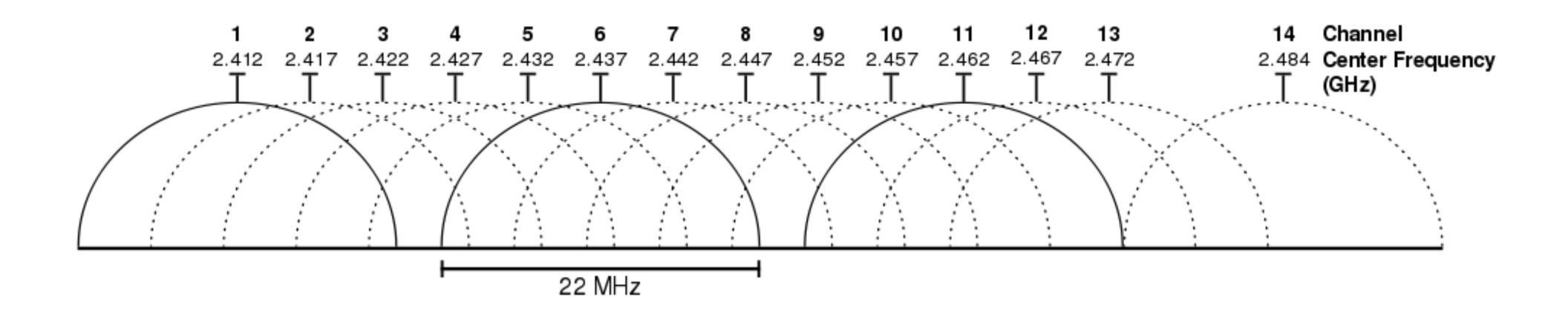
#### 802.11n: multiple antennae

- Operates in both 2.4 GHz and (optional) 5 GHz range
- up to 200 Mbps (using MIMO)
- Pros: fast speed, good signal range, more resistant to interference.
- Cons: highest cost.

- all use CSMA/CA for multiple access
- all have base-station and ad-hoc network versions

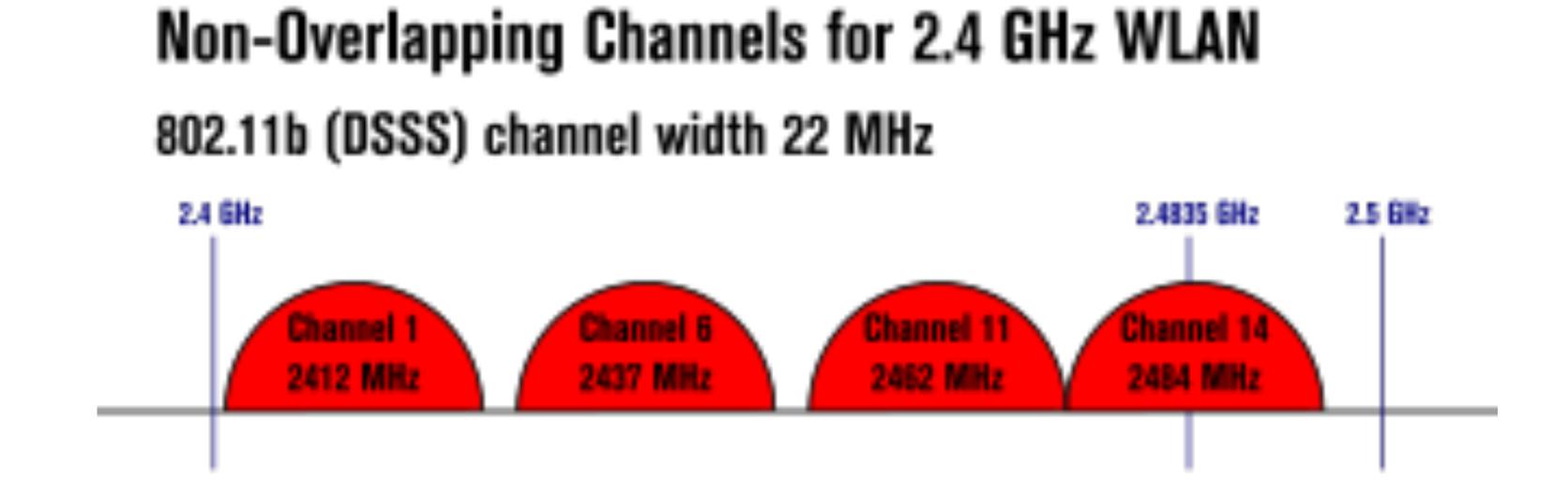
# WIFI channel planning

- •WIFI 802.11b/g/n uses the 2.4 ISM band.
- The 2.4 GHz frequency band is divided into 14 channels with 5 MHz spacing between them (except channel 14).
- •USA uses 11 channels, Europe uses 13 and Japan uses 14.



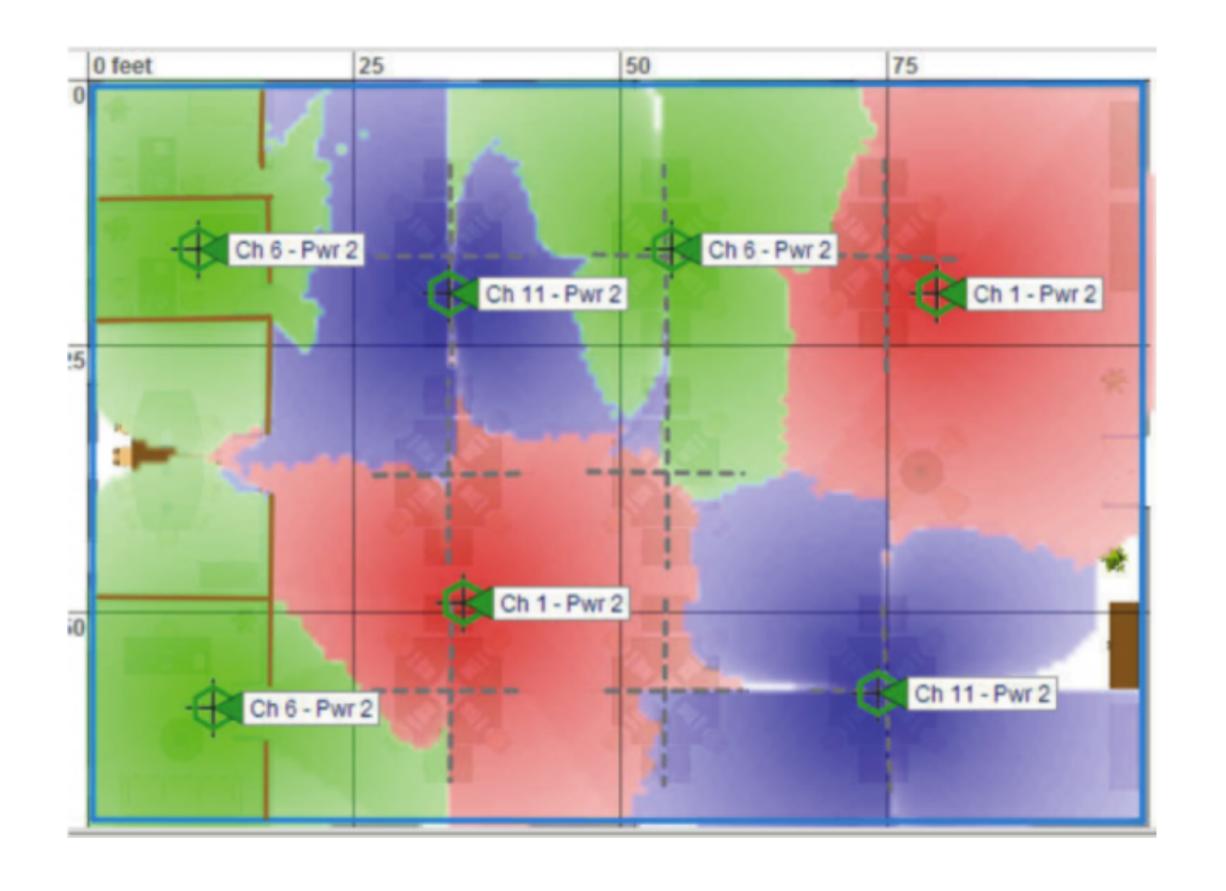
# WIFI channel planning

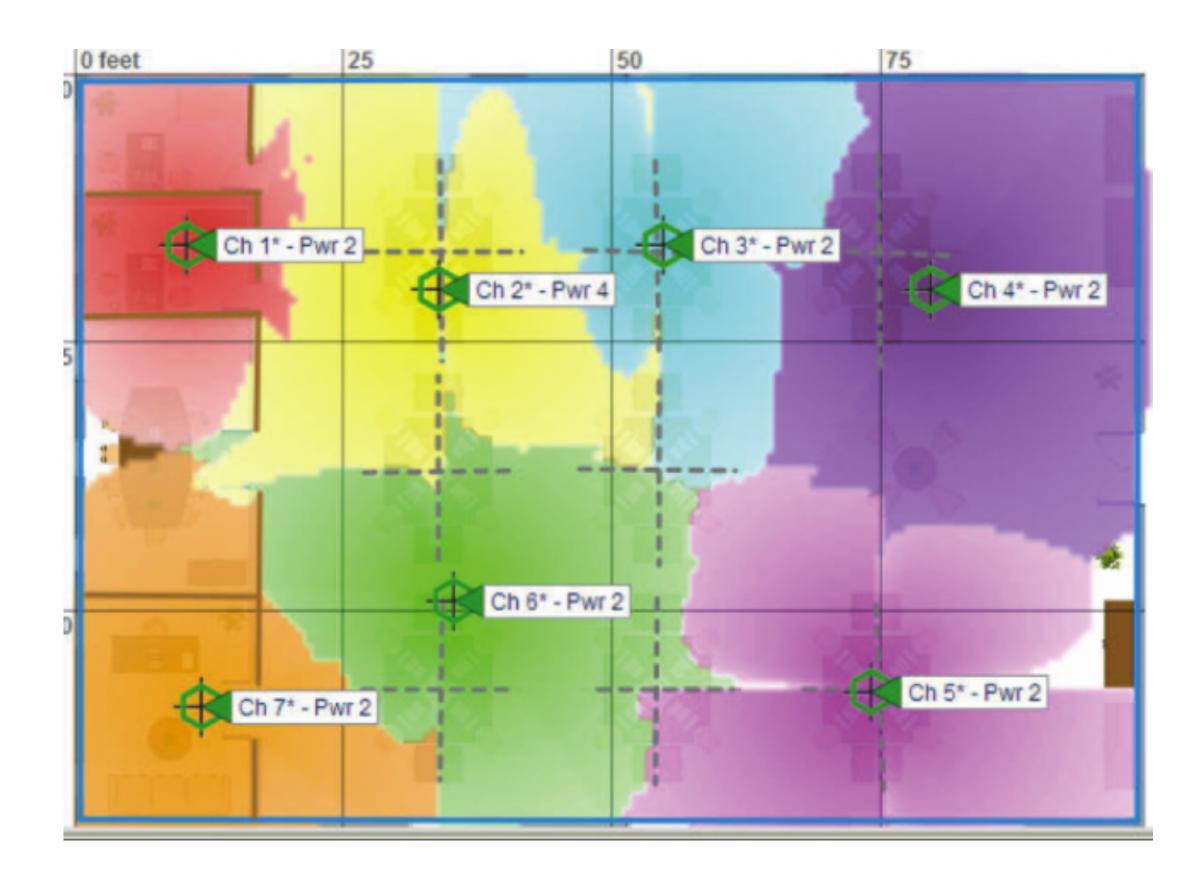
- •802.11b (DSSS) requires 22 MHz channel bandwidth for communication. This means there is a maximum of 3 channels (channel 1, 6, 11) in USA- that are not overlapping.
- Proper choice of channel can be useful to minimize co-channel interference between neighboring devices and increase the network throughput.



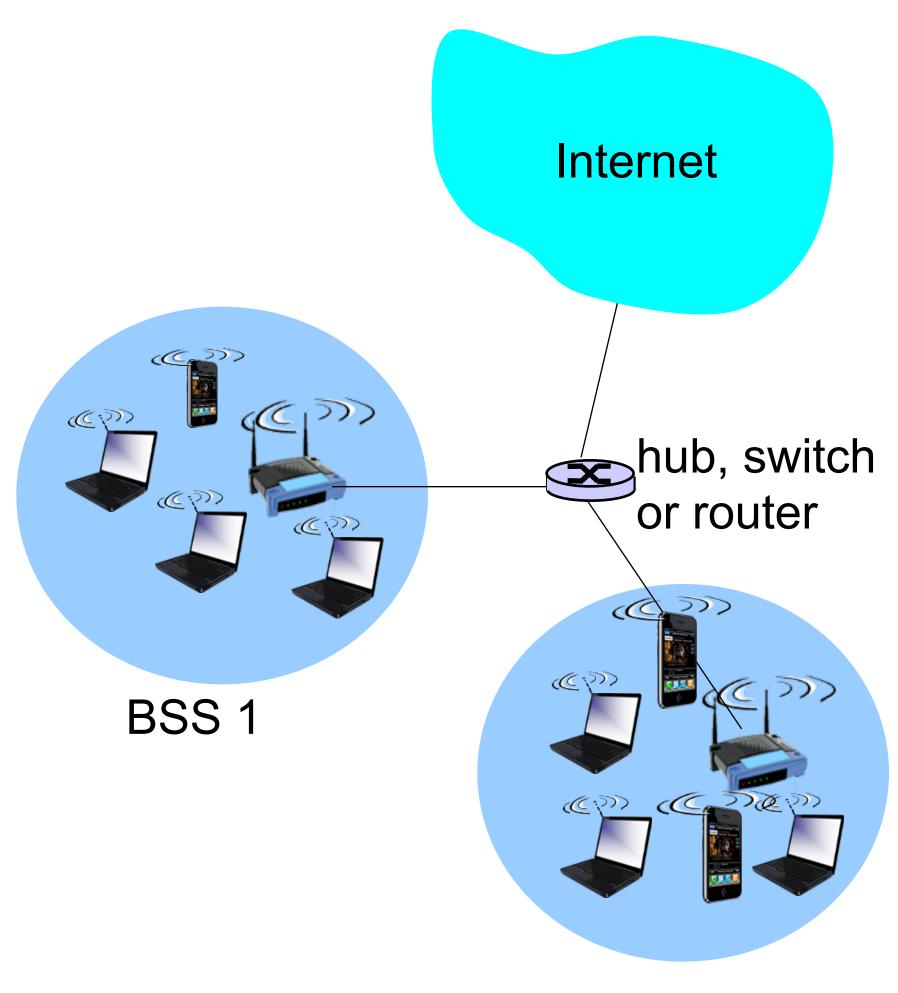
# Quiz

• The figures below show channel planning to provide coverage over a floorpan with 7 APs. Which assignment is better?





# 802.11 LAN architecture

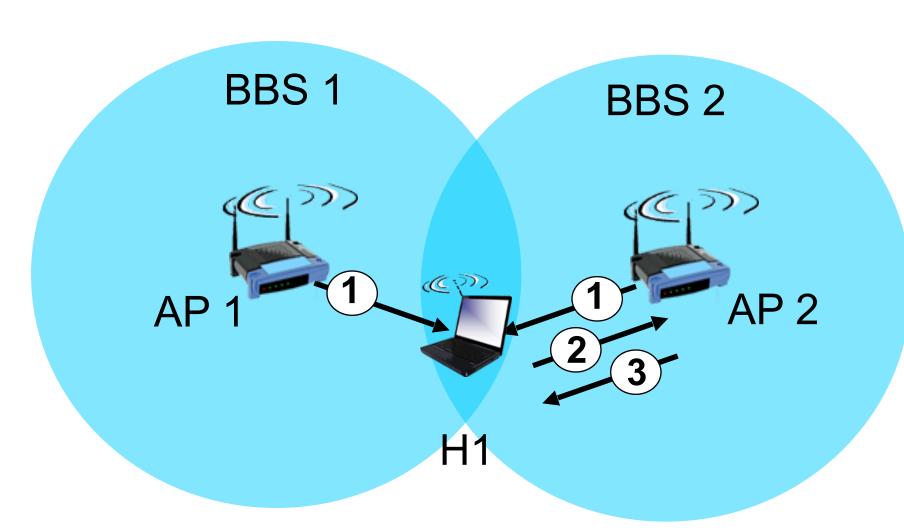


- wireless host communicates with base station
  - base station = access point(AP)
- Basic Service Set (BSS) (aka "cell") in infrastructure mode contains:
  - wireless hosts
  - access point (AP): base station
  - ad hoc mode: hosts only

# 802.11: Channels, association

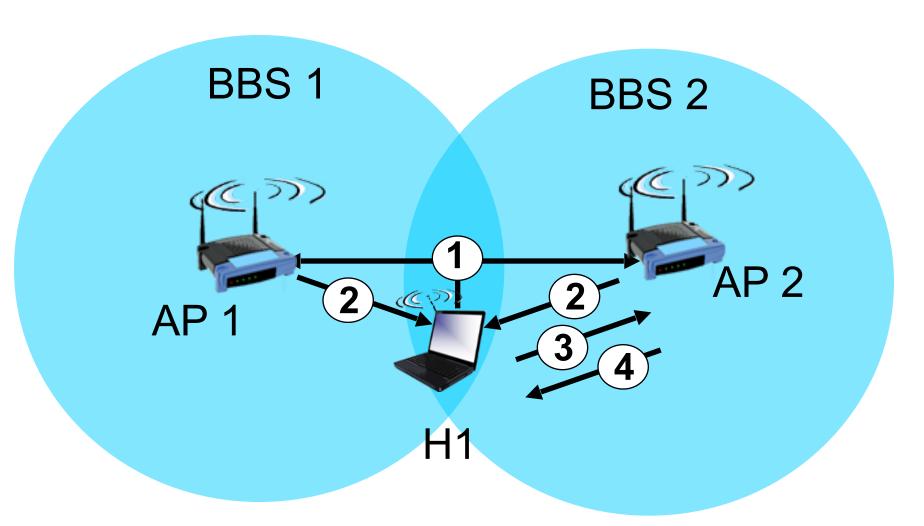
- \* 802.11b: 2.4GHz-2.485GHz spectrum divided into 11 channels at different frequencies
  - AP admin chooses frequency for AP
  - interference possible: channel can be same as that chosen by neighboring AP!
- \* host: must associate with an AP
  - scans channels, listening for beacon frames containing AP's name (SSID) and MAC address
  - selects AP to associate with
  - may perform authentication
  - will typically run DHCP to get IP address in AP's subnet

# 802.11: passive/active scanning



#### passive scanning:

- (1) beacon frames sent from APs
- (2) association Request frame sent: H1 to selected AP
- (3) association Response frame sent from selected AP to H1



#### active scanning:

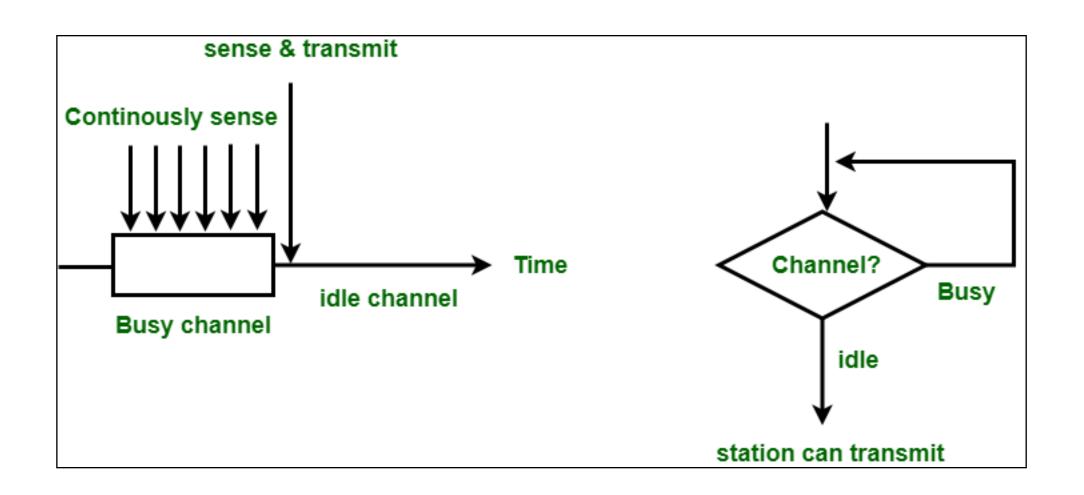
- (1) Probe Request frame broadcast from H1
- (2) Probe Response frames sent from APs
- (3) Association Request frame sent: H1 to selected AP
- (4) Association Response frame sent from selected AP to H1

### CSMA

- CSMA (Carrier Sense Multiple Access):
- Listen before transmit
  - If channel sensed idle: transmit entire frame.
  - If channel sensed busy, defer transmissions.
- Analogous to humans (don't interrupt others)

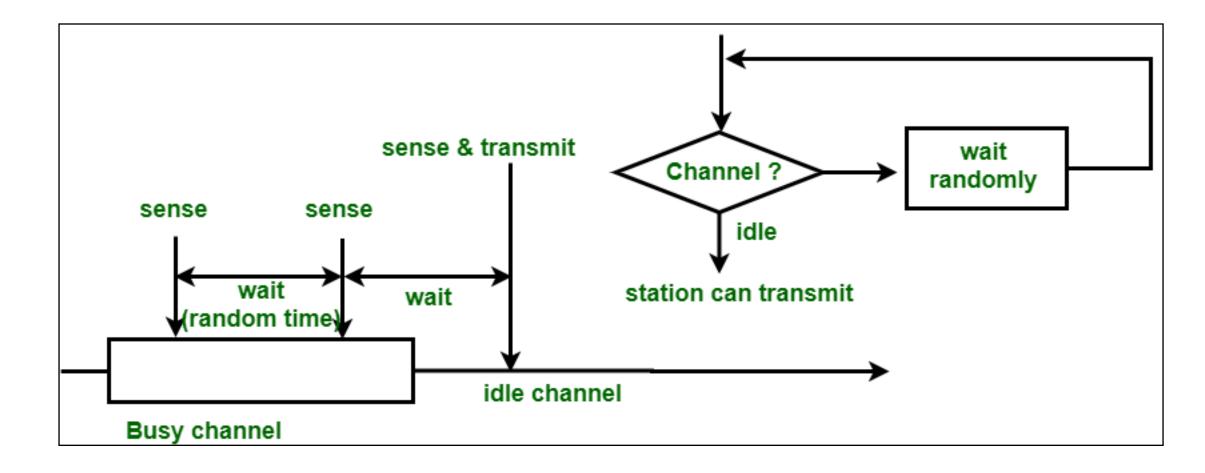
### CSMA

- Different variations including :
  - \* 1-persistent: aggressive transmission algorithm.
    - If idle, transmit immediately
    - If busy, keep sensing continuously until channel becomes idle.



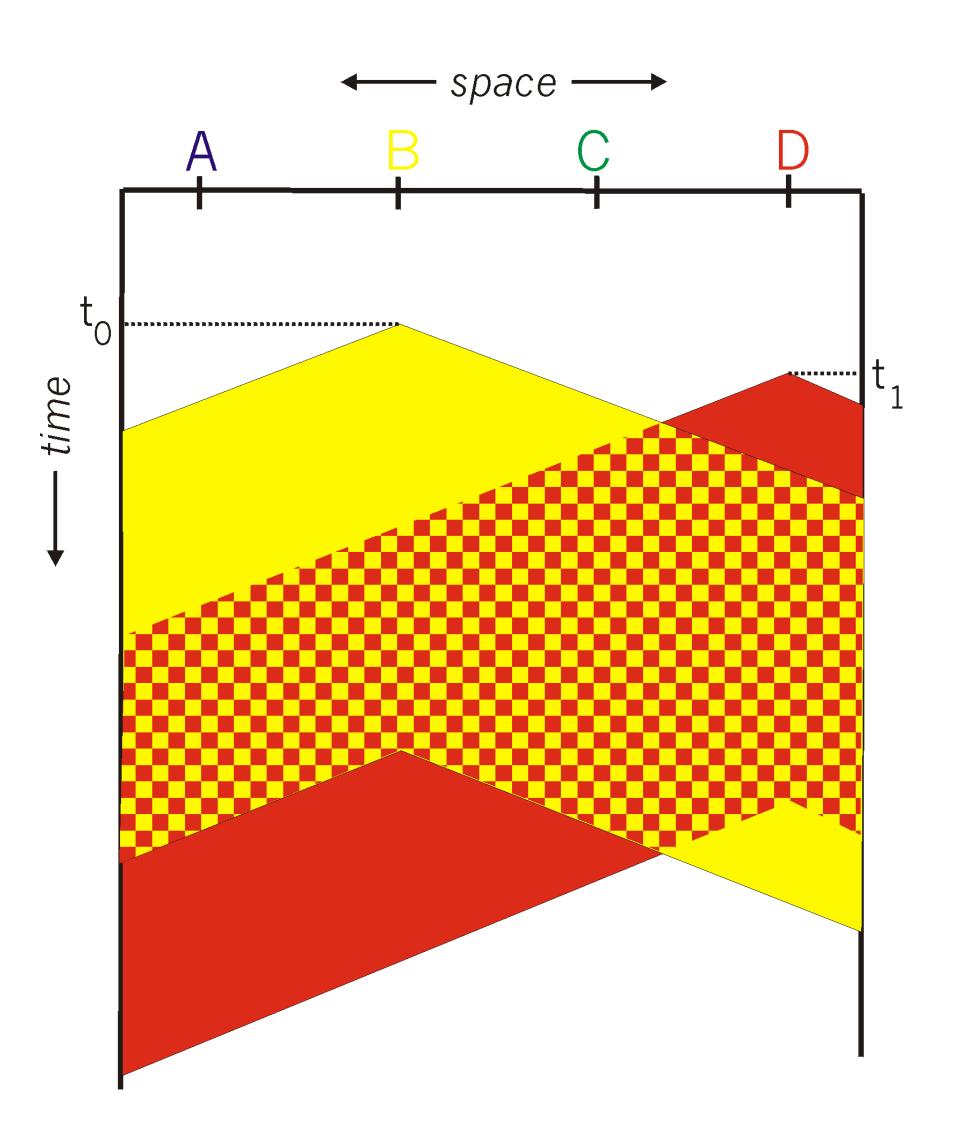
#### Non-persistent:

- If busy, wait for a random period of time, then repeat.
- If idle transmit immediately.



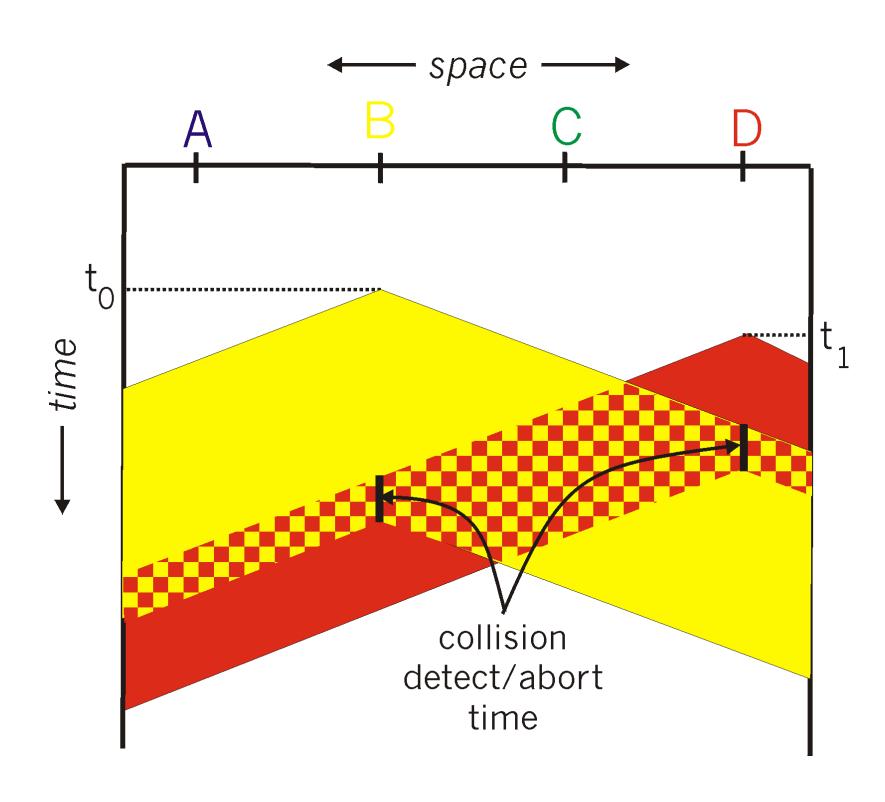
## CSMA

- Collision can still occur.
  - Propagation delays means two node may not hear each other's transmission immediately.
- Collision causes an entire packet transmission to be wasted.



#### CSMA (Carrier Sense Multiple Access / Collision Detection):

- Used in Ethernet networks.
  - If channel is sensed idle, then start transmission immediately.
  - If channel is sensed busy, the keep listening until it becomes idle then transmit.
  - While transmitting, keep listening for any collision, collision can be detected after a short time period.
  - Once collision detected at a sender, the sender will abort transmissions to reduce the channel wastage time.
  - Each sender will backoff using "binary exponential backoff" before re-attempt transmission.



#### Binary exponential backoff algorithm

- After the first collision, wait for 0 or 1 "slot time" period before retrying.
- After the second collision, wait for 0, 1, 2, or 3 "slot times" before retrying.
- After the  $n^{th}$  collision, wait for a number of slot times = k where is a random integer between 0 and  $2^n-1$
- After 10 collisions, the wait time value then remains the same for 6 further attempts
- After 16 unsuccessful attempts, station gives up and reports error

#### Binary exponential backoff algorithm

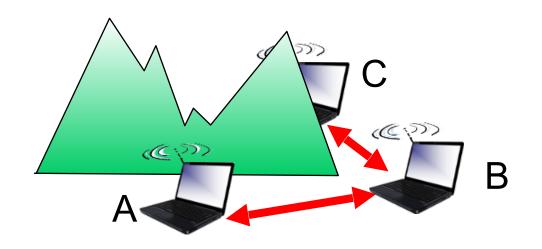
- Slot time = the times it takes to send 1 data frame on the medium.
   i.e. when frame size = 512bits and link speed is 10 Mbit/s, then slot time = 51.2 micro second.
- When congestion increases, stations will back off by larger amounts of time to reduce the probability of collision.
- After a maximum number of collisions, transmission is aborted.

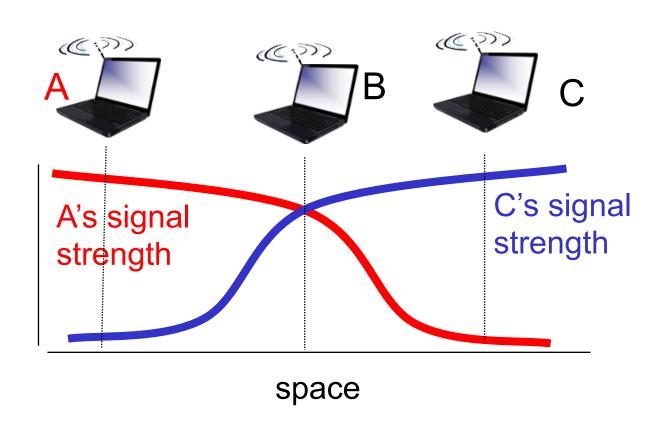
Unfortunately, collision detection can not be applied in wireless networks.



# IEEE 802.11: multiple access

- \* 802.11: *no* collision detection!
  - difficult to receive (sense collisions) when transmitting due to weak received signals (fading)
  - can't sense all collisions in any case: hidden terminal, fading





### IEEE 802.11 MAC Protocol: CSMA/CA

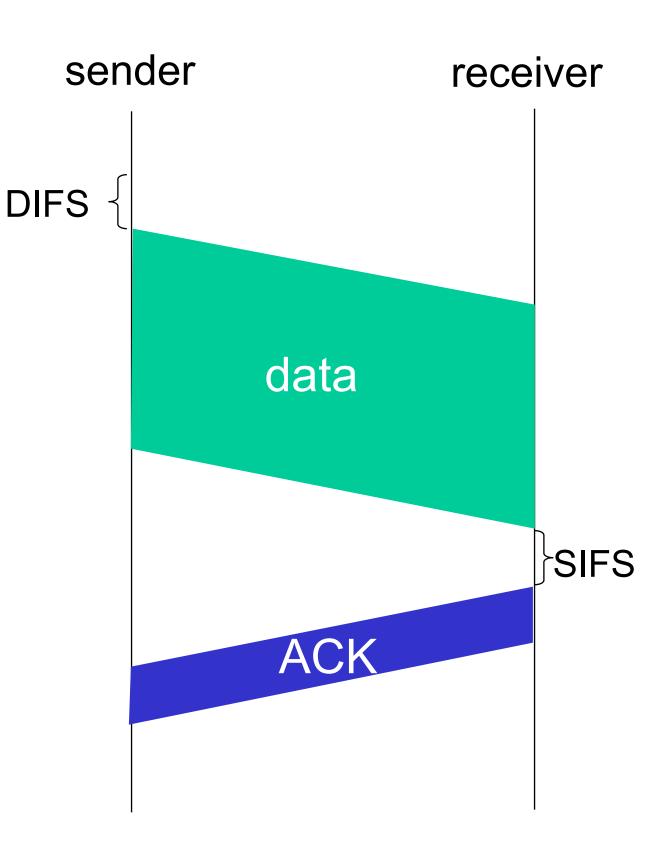
goal: avoid collisions: CSMA/C(ollision)A(voidance)

Sender transmits the entire data frame, and then start a timer to wait for ACK to be sent by receiver after SIFS interval.

What will happen if collusion occur?

- No ACK will mean that the frame was corrupted.

In wireless network, there is a non-eligible chance of delivery failure while sending a frame to destination.



### IEEE 802.11 MAC Protocol: CSMA/CA

goal: avoid collisions: CSMA/C(ollision)A(voidance)
Distributed Coordination Function (DCF)

- 1 if sense channel idle for **DIFS** then transmit entire frame (no CD)
- 2 if sense channel busy then

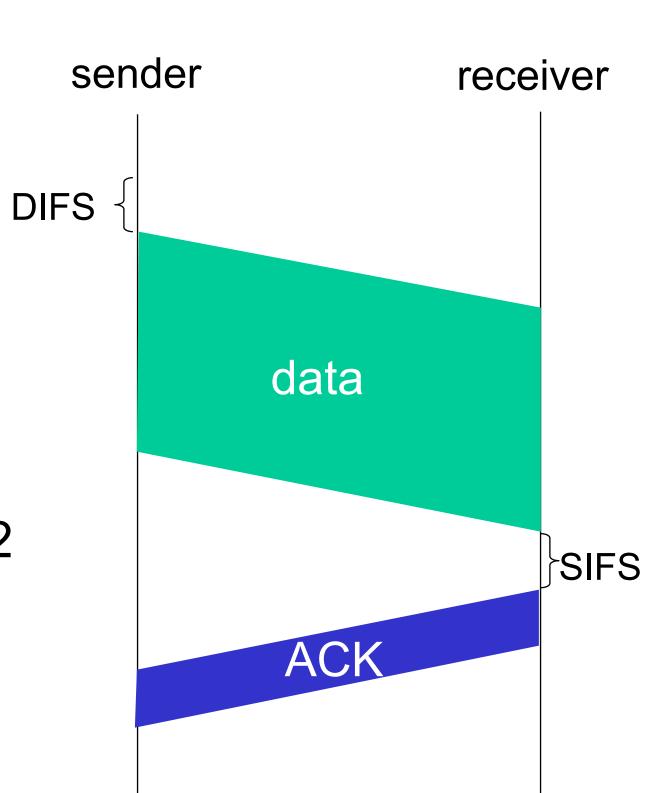
Pick a random backoff value using binary exponential timer.

- Counter counts down while channel idle for DIFS
- Counter is frozen when channel is busy
- transmit when timer expires and wait for ACK.
- •if no ACK received, increase random backoff interval, repeat 2
- If ACK received, reset the counter to 1

#### 802.11 receiver

- if frame received OK

return ACK after SIFS (ACK needed due to hidden terminal problem)



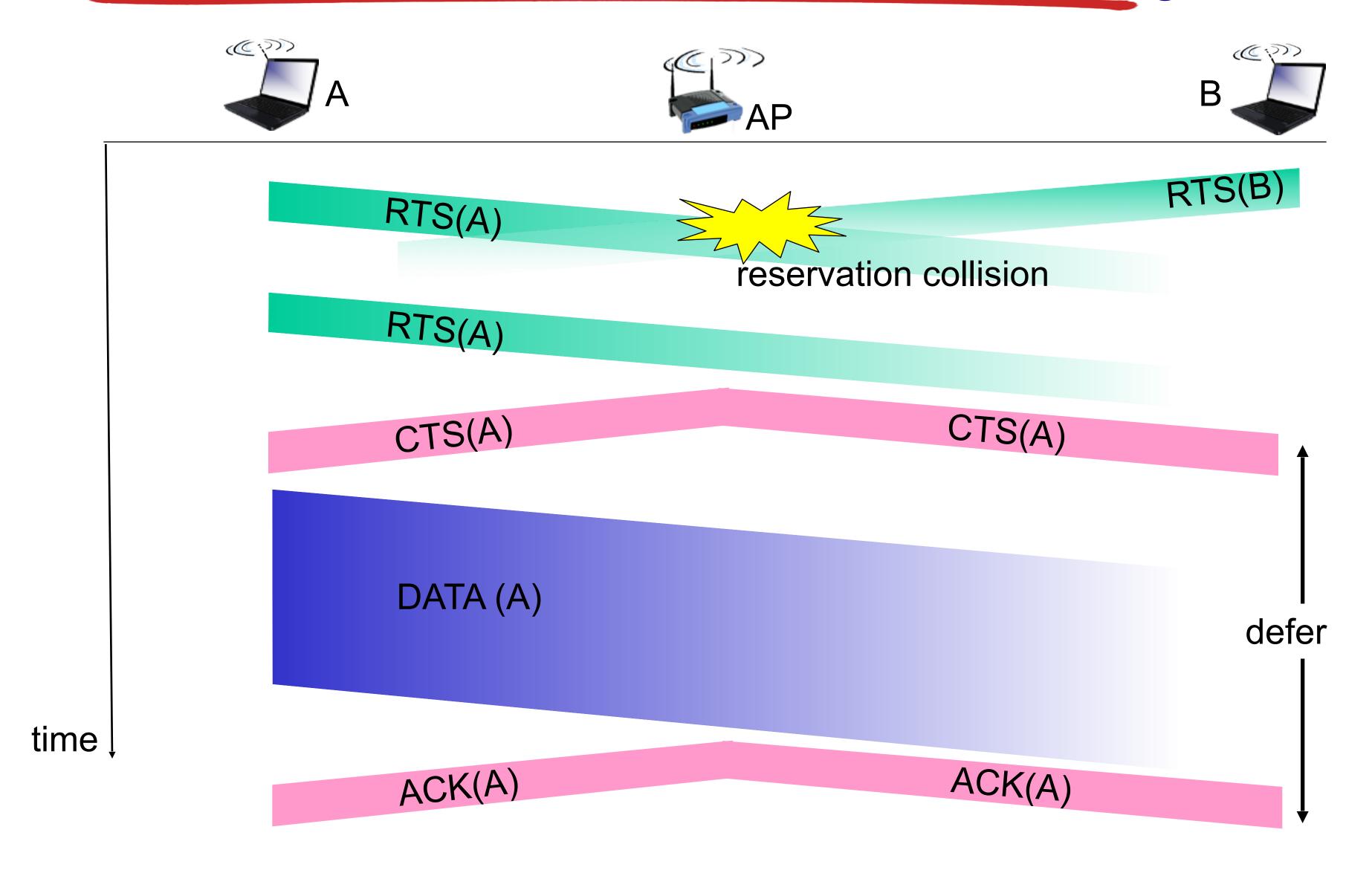
# Avoiding collisions (more)

idea: allow sender to "reserve" channel rather than random access of data frames: avoid collisions of long data frames

- sender first transmits small request-to-send (RTS) packets to BS using CSMA
  - RTSs may still collide with each other (but they're short)
- Solution Between Be
- CTS heard by all nodes
  - sender transmits data frame
  - other stations defer transmissions

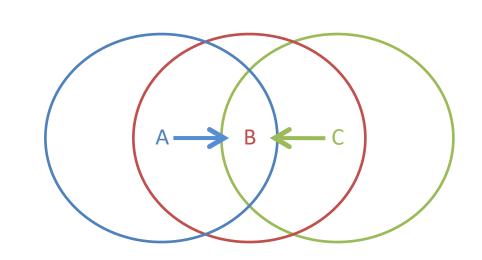
avoid data frame collisions completely using small reservation packets!

# Collision Avoidance: RTS-CTS exchange



# Solving Hidden Terminal Problem

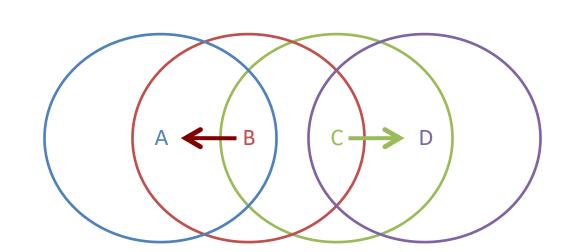
\* A and C cant see each other, both send to B



- \* RTS/CTS can help
  - Both A and C would send RTS that B would see first
  - B only responds with one CTS (say, echoing A's RTS)
  - C detects that CTS doesn't match and wont send

# **Exposed Terminal Problem**

- B sending to A, C wants to send to D
- As C receives packets, carrier sense would prevent it from sending to D, even though wouldn't interfere



- \* RTS/CTS can help
  - C hears RTS from B, but not CTS from A
  - C knows its transmission will not interfere at B's receiver
  - C is safe to transmit to D