

Some Formulas

- $\cos \theta = \frac{\vec{u} \cdot \vec{v}}{|\vec{u}||\vec{v}|}$, where θ is the angle between \vec{u} and \vec{v} , with $0 \leq \theta \leq \pi$.
- $\text{proj}_{\vec{v}} \vec{u} = \frac{\vec{u} \cdot \vec{v}}{|\vec{v}|^2} \vec{v}$
- $|\vec{u} \times \vec{v}| = |\vec{u}||\vec{v}| \sin \theta$
- The area of the parallelogram spanned by the 3D vectors \vec{u} and \vec{v} is equal to $|\vec{u} \times \vec{v}|$.
- The volume of the parallelepiped spanned by the 3D vectors $\vec{u}, \vec{v}, \vec{w}$ is $|(\vec{u} \times \vec{v}) \cdot \vec{w}|$.
- Some trigonometric identities:

$$\begin{aligned}\sin(-\theta) &= -\sin \theta, & \cos(-\theta) &= \cos(\theta), \\ \cos^2 \theta + \sin^2 \theta &= 1, \\ \sin 2\theta &= 2 \sin \theta \cos \theta, & \cos 2\theta &= \cos^2 \theta - \sin^2 \theta\end{aligned}$$

- **Linear equation.** The equation takes the form of

$$\frac{dy}{dx} + p(x)y = f(x).$$

This equation can be solved by using the following formulas:

$$\frac{dz}{dx} = p(x)z \quad (\text{integrating factor}); \quad y(x) = \frac{1}{z(x)} \int z(x)f(x)dx.$$

- **Exact equation.** The equation takes the form of

$$N(x, y) + M(x, y) \frac{dy}{dx} = 0$$

such that

$$\frac{\partial}{\partial y} N(x, y) = \frac{\partial}{\partial x} M(x, y).$$

This equation can be solved by $F(x, y(x)) = C$ for an implicit solution $y = y(x)$ such that $F(x, y)$ satisfies

$$N(x, y) = \frac{\partial F}{\partial x}(x, y), \quad M(x, y) = \frac{\partial F}{\partial y}(x, y).$$

- **Bernoulli equation.** The equation takes the form of

$$\frac{dy}{dx} + p(x)y = f(x)y^n \quad (n \neq 1).$$

This equation can be solved as the linear equation

$$\frac{du}{dx} + (1 - n)p(x)u = (1 - n)f(x)$$

by the substitution $u = 1/y^{n-1}$.

- **Homogeneous equation.** The equation takes the form of

$$\frac{dy}{dx} = F(y/x).$$

This equation can be solved as the separable equation

$$x \frac{du}{dx} + u = F(u)$$

by the substitution $u = y/x$. Also, a function $f(x, y)$ can be expressed as $f(x, y) = F(y/x)$ if $f(tx, ty) = f(x, y)$ for all $t \neq 0$ and all x, y .

- **Second-order homogeneous linear equations with constant coefficients.**

For $ay'' + by' + cy = 0$ with real coefficients $a \neq 0, b, c$ and characteristic polynomial $p(z)$, the solutions are given as follows:

- If $p(z)$ has distinct real roots $r_1 \neq r_2$, then $y = C_1 e^{r_1 x} + C_2 e^{r_2 x}$.
- If $p(z)$ has complex roots $\alpha \pm \beta i$ for $\beta \neq 0$, then $y = C_1 e^{\alpha x} \cos(\beta x) + C_2 e^{\alpha x} \sin(\beta x)$.
- If $p(z)$ has a double root $r = r_1 = r_2$, then $y = C_1 e^{rx} + C_2 x e^{rx}$.

Also, recall that for the quadratic polynomial $Ax^2 + Bx + C$, the roots are given by $\frac{-B \pm \sqrt{B^2 - 4AC}}{2A}$.

- **Method of undetermined coefficients.** (1) The equation

$$p(D)y = e^{\gamma x}, \quad p(z) = az^2 + bz + c,$$

can be solved by

$$y(x) = \frac{e^{\gamma x}}{p(\gamma)} \quad \text{if } p(\gamma) \neq 0.$$

(2) The equations

$$\begin{aligned} p(D)y &= e^{\alpha x} \cos(\beta x), & p(z) &= az^2 + bz + c, \\ p(D)y &= e^{\alpha x} \sin(\beta x), & p(z) &= az^2 + bz + c, \end{aligned}$$

for real α, β , have solutions take the form of

$$y(x) = Ae^{\alpha x} \cos(\beta x) + Be^{\alpha x} \sin(\beta x).$$

(3) The equation

$$ay'' + by' + cy = Ax^2 + Bx + C$$

has a solution taking the form of $y(x) = \alpha x^2 + \beta x + \gamma$, where $a, b, c, A, B, C, \alpha, \beta, \gamma$ are constants.

- **Variation of parameters.** To find a particular solution y_p for the equation $ay'' + by' + cy = f(x)$ by using the method of variation of parameters, choose the two functions y_1, y_2 defining the complementary solutions $y_c = C_1 y_1 + C_2 y_2$, and then set $y_p = v_1 y_1 + v_2 y_2$, where $v_1(x)$ and $v_2(x)$ satisfy

$$\begin{cases} v_1' y_1 + v_2' y_2 = 0, \\ v_1' y_1' + v_2' y_2' = f/a. \end{cases}$$

- **Cauchy–Euler equation.** The equation takes the form of

$$a_2 x^2 \frac{d^2 y}{dx^2} + a_1 x \frac{dy}{dx} + a_0 y = g(x).$$

The equation can be solved by using the following substitution:

$$x = e^t, \text{ which implies } x^2 \frac{d^2 y}{dx^2} = \frac{d^2 y}{dt^2} - \frac{dy}{dt} \quad \text{and} \quad x \frac{dy}{dx} = \frac{dy}{dt}.$$

- Laplace transforms.

$\mathcal{L}\{t^n\}(s) = \frac{n!}{s^{n+1}}, s > 0; n = 0, 1, 2 \dots$
$\mathcal{L}\{\sin(\theta t)\}(s) = \frac{\theta}{s^2 + \theta^2}, s > 0$
$\mathcal{L}\{\cos(\theta t)\}(s) = \frac{s}{s^2 + \theta^2}, s > 0$
$\mathcal{L}\{e^{at}f(t)\}(s) = \mathcal{L}\{f(t)\}(s - a), s > a$
$\mathcal{L}\{t^n f(t)\}(s) = (-1)^n \frac{d^n}{ds^n} \mathcal{L}\{f(t)\}(s)$
$\mathcal{L}\{f'(t)\}(s) = -f(0) + s\mathcal{L}\{f(t)\}(s)$
$\mathcal{L}\{f''(t)\}(s) = -f'(0) - sf(0) + s^2\mathcal{L}\{f(t)\}(s)$