assignment8

March 29, 2021

```
[2]: import cv2 # opencv 2
import numpy as np
import matplotlib.pyplot as plt
from sklearn import datasets
```

1 Loading Image

```
[3]: img = datasets.load_sample_image("china.jpg")
[4]: img
[4]: array([[[174, 201, 231],
             [174, 201, 231],
             [174, 201, 231],
             [250, 251, 255],
             [250, 251, 255],
             [250, 251, 255]],
            [[172, 199, 229],
             [173, 200, 230],
             [173, 200, 230],
             [251, 252, 255],
             [251, 252, 255],
             [251, 252, 255]],
            [[174, 201, 231],
             [174, 201, 231],
             [174, 201, 231],
             [252, 253, 255],
             [252, 253, 255],
             [252, 253, 255]],
```

```
[[ 88, 80,
             7],
[147, 138,
             69],
[122, 116,
             38],
[ 39, 42,
             33],
[ 8,
       14,
              2],
[ 6,
       12,
              0]],
[[122, 112,
             41],
[129, 120,
             53],
[118, 112,
            36],
...,
[ 9, 12,
              3],
[ 9, 15,
              3],
[ 16, 24,
              9]],
[[116, 103,
             35],
[104, 93,
            31],
[108, 102, 28],
[43, 49, 39],
[ 13,
       21,
             7]]], dtype=uint8)
[ 15,
       24,
```

2 Filters

...,

```
[5]: edgeDetectionKernel3channel = np.array([[-1, 0, 1], [0, 0, 0], [1, 0, -1]])
sharpenKernel3channel = np.array([[0, -1, 0], [-1, 5, -1], [0, -1, 0]])
blurKernel3channel = np.array([[1, 1, 1], [1, 1, 1], [1, 1, 1]])/9.0
sobelKernel3channel = np.array([[-1, -2, -1], [0, 0, 0], [1, 2, 1]])
outlineKernel3channel = np.array([[-1, -1, -1], [-1, 8, -1], [-1, -1, -1]])
deblurKernel3channel = np.array([[0, 2, 0], [2, 4, 2], [0, -2, 0]])
```

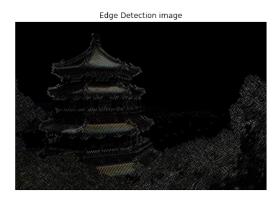
```
filtered_image = cv2.filter2D(img, -1, edgeDetectionKernel3channel)

fig = plt.figure(figsize=(16, 25))
ax1 = fig.add_subplot(2,2,1)
ax1.axis("off")
ax1.title.set_text('Original image')
ax1.imshow(img)
ax2 = fig.add_subplot(2,2,2)
ax2.axis("off")
ax2.title.set_text('Edge Detection image')
```

ax2.imshow(filtered_image)

[6]: <matplotlib.image.AxesImage at 0x7fb772d89f10>





```
filtered_image = cv2.filter2D(img, -1, sharpenKernel3channel)

fig = plt.figure(figsize=(16, 25))
    ax1 = fig.add_subplot(2,2,1)
    ax1.axis("off")
    ax1.title.set_text('Original image')
    ax1.imshow(img)
    ax2 = fig.add_subplot(2,2,2)
    ax2.axis("off")
    ax2.title.set_text('Sharpened image')
    ax2.imshow(filtered_image)
```

[7]: <matplotlib.image.AxesImage at 0x7fb772566760>





```
[8]: filtered_image = cv2.filter2D(img, -1, blurKernel3channel)
```

```
fig = plt.figure(figsize=(16, 25))
ax1 = fig.add_subplot(2,2,1)
ax1.axis("off")
ax1.title.set_text('Original image')
ax1.imshow(img)
ax2 = fig.add_subplot(2,2,2)
ax2.axis("off")
ax2.title.set_text('Blurred image')
ax2.imshow(filtered_image)
```

[8]: <matplotlib.image.AxesImage at 0x7fb772d9d3a0>



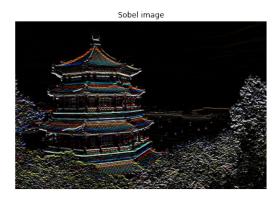


```
[9]: filtered_image = cv2.filter2D(img, -1, sobelKernel3channel)

fig = plt.figure(figsize=(16, 25))
ax1 = fig.add_subplot(2,2,1)
ax1.axis("off")
ax1.title.set_text('Original image')
ax1.imshow(img)
ax2 = fig.add_subplot(2,2,2)
ax2.axis("off")
ax2.title.set_text('Sobel image')
ax2.imshow(filtered_image)
```

[9]: <matplotlib.image.AxesImage at 0x7fb772492d90>



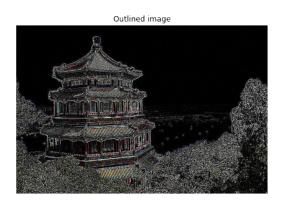


```
filtered_image = cv2.filter2D(img, -1, outlineKernel3channel)

fig = plt.figure(figsize=(16, 25))
    ax1 = fig.add_subplot(2,2,1)
    ax1.axis("off")
    ax1.title.set_text('Original image')
    ax1.imshow(img)
    ax2 = fig.add_subplot(2,2,2)
    ax2.axis("off")
    ax2.title.set_text('Outlined image')
    ax2.imshow(filtered_image)
```

[10]: <matplotlib.image.AxesImage at 0x7fb7723b3af0>





```
filtered_image = cv2.filter2D(img, -1, deblurKernel3channel)

fig = plt.figure(figsize=(16, 25))
ax1 = fig.add_subplot(2,2,1)
ax1.axis("off")
ax1.title.set_text('Original image')
```

```
ax1.imshow(img)
ax2 = fig.add_subplot(2,2,2)
ax2.axis("off")
ax2.title.set_text('Deblurred image')
ax2.imshow(filtered_image)
```

[11]: <matplotlib.image.AxesImage at 0x7fb772353880>

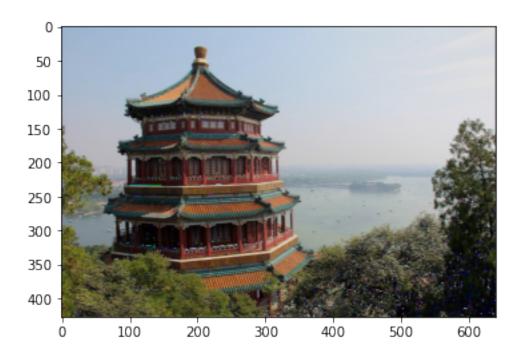




```
[12]: def convolution(image, kernel):
          img_row, img_col, img_channel = image.shape
          kernel_size = kernel.shape[0]
          padding_width = (kernel_size - 1) // 2
          output = np.zeros(image.shape, dtype = np.uint8)
          padded_img = np.zeros((img_row + 2*padding_width, img_col +_
       →2*padding_width, img_channel), dtype = np.uint8)
          padded_img[padding_width : padding_width + img_row, padding_width :__
       →padding_width + img_col] = image
          for i in range(img_row):
              for j in range(img_col):
                  output[i, j, 0] = np.sum(padded_img[i : i+kernel_size, j :__
       →j+kernel_size, 0] * kernel) // (kernel_size * kernel_size)
                  output[i, j, 1] = np.sum(padded_img[i : i+kernel_size, j :__
       →j+kernel_size, 1] * kernel) // (kernel_size * kernel_size)
                  output[i, j, 2] = np.sum(padded_img[i : i+kernel_size, j :__
       →j+kernel_size, 2] * kernel) // (kernel_size * kernel_size)
          return output
```

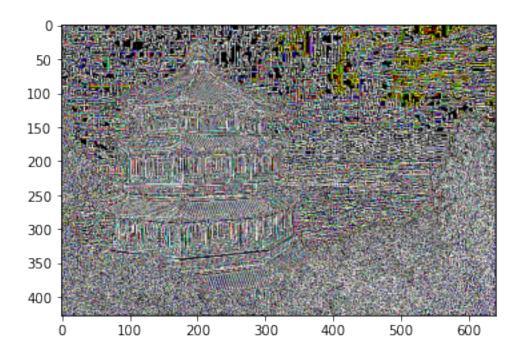
[13]: plt.imshow(convolution(img, deblurKernel3channel))

[13]: <matplotlib.image.AxesImage at 0x7fb772273790>



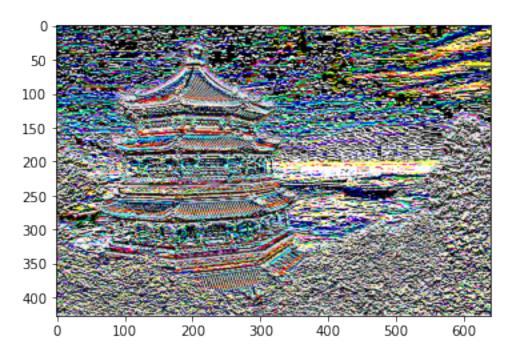
[14]: plt.imshow(convolution(img, outlineKernel3channel))

[14]: <matplotlib.image.AxesImage at 0x7fb7721d9d00>



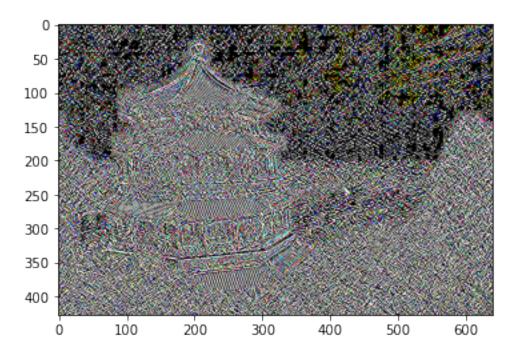
[15]: plt.imshow(convolution(img, sobelKernel3channel))

[15]: <matplotlib.image.AxesImage at 0x7fb7721bca30>



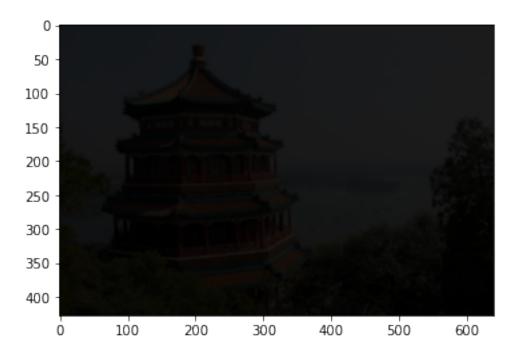
[16]: plt.imshow(convolution(img, edgeDetectionKernel3channel))

[16]: <matplotlib.image.AxesImage at 0x7fb77211c640>



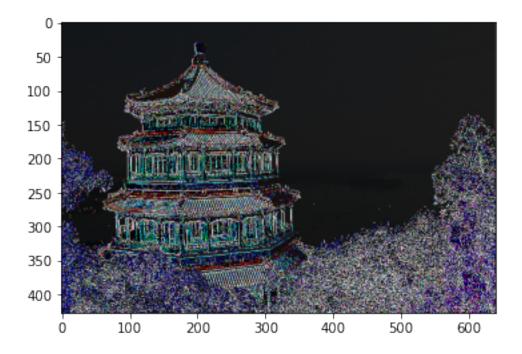
[17]: plt.imshow(convolution(img, blurKernel3channel))

[17]: <matplotlib.image.AxesImage at 0x7fb7721002b0>



[18]: plt.imshow(convolution(img, sharpenKernel3channel))

[18]: <matplotlib.image.AxesImage at 0x7fb7720d5eb0>



[]: