assignment13

May 13, 2021

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[]: import numpy as np
     import pandas as pd
     import gym
[]: np.random.seed(42)
     from gym import envs
     print(envs.registry.all())
    dict_values([EnvSpec(Copy-v0), EnvSpec(RepeatCopy-v0),
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    EnvSpec(HandManipulateBlockTouchSensors-v0),
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EnvSpec(NameThisGame-ram-v0), EnvSpec(NameThisGame-ram-v4),
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EnvSpec(PrivateEye-ram-v4), EnvSpec(PrivateEye-ramDeterministic-v0),
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EnvSpec(QbertDeterministic-v0), EnvSpec(QbertDeterministic-v4),
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EnvSpec(Seaquest-ram-v0), EnvSpec(Seaquest-ram-v4), EnvSpec(Seaquest-
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EnvSpec(Skiing-ramDeterministic-v0), EnvSpec(Skiing-ramDeterministic-v4),
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ram-v4), EnvSpec(Solaris-ramDeterministic-v0), EnvSpec(Solaris-
ramDeterministic-v4), EnvSpec(Solaris-ramNoFrameskip-v0), EnvSpec(Solaris-
ramNoFrameskip-v4), EnvSpec(SpaceInvaders-v0), EnvSpec(SpaceInvaders-v4),
EnvSpec(SpaceInvadersDeterministic-v0), EnvSpec(SpaceInvadersDeterministic-v4),
EnvSpec(SpaceInvadersNoFrameskip-v0), EnvSpec(SpaceInvadersNoFrameskip-v4),
EnvSpec(SpaceInvaders-ram-v0), EnvSpec(SpaceInvaders-ram-v4),
EnvSpec(SpaceInvaders-ramDeterministic-v0), EnvSpec(SpaceInvaders-
ramDeterministic-v4), EnvSpec(SpaceInvaders-ramNoFrameskip-v0),
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EnvSpec(StarGunner-v4), EnvSpec(StarGunnerDeterministic-v0),
EnvSpec(StarGunnerDeterministic-v4), EnvSpec(StarGunnerNoFrameskip-v0),
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EnvSpec(StarGunner-ram-v4), EnvSpec(StarGunner-ramDeterministic-v0),
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EnvSpec(VideoPinball-v4), EnvSpec(VideoPinballDeterministic-v0),
EnvSpec(VideoPinballDeterministic-v4), EnvSpec(VideoPinballNoFrameskip-v0),
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EnvSpec(VideoPinball-ram-v4), EnvSpec(VideoPinball-ramDeterministic-v0),
EnvSpec(VideoPinball-ramDeterministic-v4), EnvSpec(VideoPinball-
ramNoFrameskip-v0), EnvSpec(VideoPinball-ramNoFrameskip-v4),
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EnvSpec(WizardOfWorDeterministic-v0), EnvSpec(WizardOfWorDeterministic-v4),
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EnvSpec(YarsRevengeDeterministic-v0), EnvSpec(YarsRevengeDeterministic-v4),
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EnvSpec(YarsRevenge-ram-v0), EnvSpec(YarsRevenge-ram-v4), EnvSpec(YarsRevenge-
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EnvSpec(YarsRevenge-ramNoFrameskip-v0), EnvSpec(YarsRevenge-ramNoFrameskip-v4),
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EnvSpec(ZaxxonDeterministic-v4), EnvSpec(ZaxxonNoFrameskip-v0),
EnvSpec(ZaxxonNoFrameskip-v4), EnvSpec(Zaxxon-ram-v0), EnvSpec(Zaxxon-ram-v4),
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EnvSpec(Zaxxon-ramDeterministic-v0), EnvSpec(Zaxxon-ramDeterministic-v4),
    EnvSpec(Zaxxon-ramNoFrameskip-v0), EnvSpec(Zaxxon-ramNoFrameskip-v4),
    EnvSpec(CubeCrash-v0), EnvSpec(CubeCrashSparse-v0),
    EnvSpec(CubeCrashScreenBecomesBlack-v0), EnvSpec(MemorizeDigits-v0)])
[]: env = gym.make('FrozenLake-v0')
     env.seed(42)
     env.reset()
     env.render()
     print("Action Space {}".format(env.action_space))
     print("State Space {}".format(env.observation_space))
    SFFF
    FHFH
    FFFH
    HFFG
    Action Space Discrete(4)
    State Space Discrete(16)
[]: # take some random steps
     reward_total = 0
     obs = env.reset()
     env.render()
     for i in range(5):
         action = env.action_space.sample() #take step using random action from_
      → possible actions (action_space)
         obs, reward, done, info = env.step(action)
         reward_total += reward
         env.render()
     #Print the reward of these random action
     print("Total reward: %r" % reward_total)
    SFFF
    FHFH
    FFFH
    HFFG
      (Right)
    SFFF
    FHFH
    FFFH
    HFFG
      (Up)
    SFFF
    FHFH
```

```
FFFH
HFFG
  (Right)
SFFF
FHFH
FFFH
HFFG
  (Right)
SFFF
FHFH
FFFH
HFFG
  (Right)
SFFF
FHFH
FFFH
HFFG
Total reward: 0.0
```

1 Q-learning algorithm

```
[]: |qtable = np.zeros([env.observation_space.n, env.action_space.n]) #You could_
     →also make this dynamic if you don't know all games states upfront
     discount = 0.9 # discount factor
     learningrate = 0.9 # learning rate
     for episode in range(1, 10001):
         done = False
         reward_total = 0
         state = env.reset()
         while done != True:
             action = np.argmax(qtable[state]) #choosing the action with the highest_
      \hookrightarrow Q value
             state_new, reward, done, info = env.step(action) #take the action
             qtable[state,action] += learningrate * (reward + discount * np.
      →max(qtable[state_new,:]) - qtable[state,action]) #Update Q-marix using_
      \rightarrowBellman equation
                 \#Q[obs,action] = rew + gamma * np.max(Q[obs2]) # same equation but_{\sqcup}
      →with learning rate = 1 returns the basic Bellman equation
             reward_total = reward_total + reward
             state = state_new
         if episode % 50 == 0:
             print('Episode {} Total Reward: {}'.format(episode,rew_tot))
```

Episode 50 Total Reward: 0.0 Episode 100 Total Reward: 0.0 Episode 150 Total Reward: 0.0

```
Episode 200 Total Reward: 0.0
Episode 250 Total Reward: 0.0
Episode 300 Total Reward: 0.0
Episode 350 Total Reward: 0.0
Episode 400 Total Reward: 0.0
Episode 450 Total Reward: 0.0
Episode 500 Total Reward: 0.0
Episode 550 Total Reward: 0.0
Episode 600 Total Reward: 0.0
Episode 650 Total Reward: 0.0
Episode 700 Total Reward: 0.0
Episode 750 Total Reward: 0.0
Episode 800 Total Reward: 0.0
Episode 850 Total Reward: 0.0
Episode 900 Total Reward: 0.0
Episode 950 Total Reward: 0.0
Episode 1000 Total Reward: 0.0
Episode 1050 Total Reward: 0.0
Episode 1100 Total Reward: 0.0
Episode 1150 Total Reward: 0.0
Episode 1200 Total Reward: 0.0
Episode 1250 Total Reward: 0.0
Episode 1300 Total Reward: 0.0
Episode 1350 Total Reward: 0.0
Episode 1400 Total Reward: 0.0
Episode 1450 Total Reward: 0.0
Episode 1500 Total Reward: 0.0
Episode 1550 Total Reward: 0.0
Episode 1600 Total Reward: 0.0
Episode 1650 Total Reward: 0.0
Episode 1700 Total Reward: 0.0
Episode 1750 Total Reward: 0.0
Episode 1800 Total Reward: 0.0
Episode 1850 Total Reward: 0.0
Episode 1900 Total Reward: 0.0
Episode 1950 Total Reward: 0.0
Episode 2000 Total Reward: 0.0
Episode 2050 Total Reward: 0.0
Episode 2100 Total Reward: 0.0
Episode 2150 Total Reward: 0.0
Episode 2200 Total Reward: 0.0
Episode 2250 Total Reward: 0.0
Episode 2300 Total Reward: 0.0
Episode 2350 Total Reward: 0.0
Episode 2400 Total Reward: 0.0
Episode 2450 Total Reward: 0.0
Episode 2500 Total Reward: 0.0
Episode 2550 Total Reward: 0.0
```

```
Episode 2600 Total Reward: 0.0
Episode 2650 Total Reward: 0.0
Episode 2700 Total Reward: 0.0
Episode 2750 Total Reward: 0.0
Episode 2800 Total Reward: 0.0
Episode 2850 Total Reward: 0.0
Episode 2900 Total Reward: 0.0
Episode 2950 Total Reward: 0.0
Episode 3000 Total Reward: 0.0
Episode 3050 Total Reward: 0.0
Episode 3100 Total Reward: 0.0
Episode 3150 Total Reward: 0.0
Episode 3200 Total Reward: 0.0
Episode 3250 Total Reward: 0.0
Episode 3300 Total Reward: 0.0
Episode 3350 Total Reward: 0.0
Episode 3400 Total Reward: 0.0
Episode 3450 Total Reward: 0.0
Episode 3500 Total Reward: 0.0
Episode 3550 Total Reward: 0.0
Episode 3600 Total Reward: 0.0
Episode 3650 Total Reward: 0.0
Episode 3700 Total Reward: 0.0
Episode 3750 Total Reward: 0.0
Episode 3800 Total Reward: 0.0
Episode 3850 Total Reward: 0.0
Episode 3900 Total Reward: 0.0
Episode 3950 Total Reward: 0.0
Episode 4000 Total Reward: 0.0
Episode 4050 Total Reward: 0.0
Episode 4100 Total Reward: 0.0
Episode 4150 Total Reward: 0.0
Episode 4200 Total Reward: 0.0
Episode 4250 Total Reward: 0.0
Episode 4300 Total Reward: 0.0
Episode 4350 Total Reward: 0.0
Episode 4400 Total Reward: 0.0
Episode 4450 Total Reward: 0.0
Episode 4500 Total Reward: 0.0
Episode 4550 Total Reward: 0.0
Episode 4600 Total Reward: 0.0
Episode 4650 Total Reward: 0.0
Episode 4700 Total Reward: 0.0
Episode 4750 Total Reward: 0.0
Episode 4800 Total Reward: 0.0
Episode 4850 Total Reward: 0.0
Episode 4900 Total Reward: 0.0
Episode 4950 Total Reward: 0.0
```

```
Episode 5000 Total Reward: 0.0
Episode 5050 Total Reward: 0.0
Episode 5100 Total Reward: 0.0
Episode 5150 Total Reward: 0.0
Episode 5200 Total Reward: 0.0
Episode 5250 Total Reward: 0.0
Episode 5300 Total Reward: 0.0
Episode 5350 Total Reward: 0.0
Episode 5400 Total Reward: 0.0
Episode 5450 Total Reward: 0.0
Episode 5500 Total Reward: 0.0
Episode 5550 Total Reward: 0.0
Episode 5600 Total Reward: 0.0
Episode 5650 Total Reward: 0.0
Episode 5700 Total Reward: 0.0
Episode 5750 Total Reward: 0.0
Episode 5800 Total Reward: 0.0
Episode 5850 Total Reward: 0.0
Episode 5900 Total Reward: 0.0
Episode 5950 Total Reward: 0.0
Episode 6000 Total Reward: 0.0
Episode 6050 Total Reward: 0.0
Episode 6100 Total Reward: 0.0
Episode 6150 Total Reward: 0.0
Episode 6200 Total Reward: 0.0
Episode 6250 Total Reward: 0.0
Episode 6300 Total Reward: 0.0
Episode 6350 Total Reward: 0.0
Episode 6400 Total Reward: 0.0
Episode 6450 Total Reward: 0.0
Episode 6500 Total Reward: 0.0
Episode 6550 Total Reward: 0.0
Episode 6600 Total Reward: 0.0
Episode 6650 Total Reward: 0.0
Episode 6700 Total Reward: 0.0
Episode 6750 Total Reward: 0.0
Episode 6800 Total Reward: 0.0
Episode 6850 Total Reward: 0.0
Episode 6900 Total Reward: 0.0
Episode 6950 Total Reward: 0.0
Episode 7000 Total Reward: 0.0
Episode 7050 Total Reward: 0.0
Episode 7100 Total Reward: 0.0
Episode 7150 Total Reward: 0.0
Episode 7200 Total Reward: 0.0
Episode 7250 Total Reward: 0.0
Episode 7300 Total Reward: 0.0
Episode 7350 Total Reward: 0.0
```

```
Episode 7400 Total Reward: 0.0
Episode 7450 Total Reward: 0.0
Episode 7500 Total Reward: 0.0
Episode 7550 Total Reward: 0.0
Episode 7600 Total Reward: 0.0
Episode 7650 Total Reward: 0.0
Episode 7700 Total Reward: 0.0
Episode 7750 Total Reward: 0.0
Episode 7800 Total Reward: 0.0
Episode 7850 Total Reward: 0.0
Episode 7900 Total Reward: 0.0
Episode 7950 Total Reward: 0.0
Episode 8000 Total Reward: 0.0
Episode 8050 Total Reward: 0.0
Episode 8100 Total Reward: 0.0
Episode 8150 Total Reward: 0.0
Episode 8200 Total Reward: 0.0
Episode 8250 Total Reward: 0.0
Episode 8300 Total Reward: 0.0
Episode 8350 Total Reward: 0.0
Episode 8400 Total Reward: 0.0
Episode 8450 Total Reward: 0.0
Episode 8500 Total Reward: 0.0
Episode 8550 Total Reward: 0.0
Episode 8600 Total Reward: 0.0
Episode 8650 Total Reward: 0.0
Episode 8700 Total Reward: 0.0
Episode 8750 Total Reward: 0.0
Episode 8800 Total Reward: 0.0
Episode 8850 Total Reward: 0.0
Episode 8900 Total Reward: 0.0
Episode 8950 Total Reward: 0.0
Episode 9000 Total Reward: 0.0
Episode 9050 Total Reward: 0.0
Episode 9100 Total Reward: 0.0
Episode 9150 Total Reward: 0.0
Episode 9200 Total Reward: 0.0
Episode 9250 Total Reward: 0.0
Episode 9300 Total Reward: 0.0
Episode 9350 Total Reward: 0.0
Episode 9400 Total Reward: 0.0
Episode 9450 Total Reward: 0.0
Episode 9500 Total Reward: 0.0
Episode 9550 Total Reward: 0.0
Episode 9600 Total Reward: 0.0
Episode 9650 Total Reward: 0.0
Episode 9700 Total Reward: 0.0
Episode 9750 Total Reward: 0.0
```

```
Episode 9800 Total Reward: 0.0
    Episode 9850 Total Reward: 0.0
    Episode 9900 Total Reward: 0.0
    Episode 9950 Total Reward: 0.0
    Episode 10000 Total Reward: 0.0
[]: # Let's see how the algorithm solves the taxi game by following the policy to_
     → take actions delivering max value
     reward_total=0
     state= env.reset()
     env.render()
     done=False
     while done != True:
         action = np.argmax(qtable[state])
         state, reward, done, info = env.step(action) #take step using selected_{\sqcup}
         reward_total = reward_total + reward
         env.render()
     #Print the reward of these actions
     print("Total reward is %r" % reward_total)
```

```
SFFF
FHFH
FFFH
HFFG
  (Left)
SFFF
FHFH
FFFH
HFFG
Total reward is 0.0
```

```
[]: import time
     from IPython.display import clear_output
     env.s = 166
     reward total=0
     env.render()
     done=False
     while done != True:
         action = np.argmax(qtable[state])
         state, reward, done, info = env.step(action)
         reward_total = reward_total + reward
         time.sleep(1)
         clear_output(wait=True)
         env.render()
      (Left)
    SFFF
    FHFH
    FFFH
    HFFG
    #Adding stochasticity to our Q-learning algorithm
[]: qtable = np.zeros([env.observation_space.n, env.action_space.n]) #we could also_
     → make this dynamic if we
     #don't know all games states upfront
     discount = 0.9 # discount factor
     learningrate = 0.9 # learning rate
     epsilon = 0.2 # threshold of stochasticity
     for episode in range(1,10001):
         done = False
         reward total = 0
         state = env.reset()
         while done != True:
             explore_eploit = np.random.uniform(0, 1)
             if explore_eploit < epsilon:</pre>
                 action = env.action_space.sample() # explore action space
             else:
                 action = np.argmax(qtable[state]) # exploit learned values
             state_new, reward, done, info = env.step(action) #take the action
             qtable[state,action] += learningrate * (reward + discount * np.
      →max(qtable[state_new,:]) - qtable[state,action]) #Update Q-marix using
      \rightarrowBellman equation
             reward_total = reward_total + reward
             state = state_new
         if episode % 50 == 0:
```

print('Episode {} Total Reward: {}'.format(episode,reward_total))

```
Episode 50 Total Reward: 0.0
Episode 100 Total Reward: 0.0
Episode 150 Total Reward: 0.0
Episode 200 Total Reward: 0.0
Episode 250 Total Reward: 0.0
Episode 300 Total Reward: 0.0
Episode 350 Total Reward: 0.0
Episode 400 Total Reward: 0.0
Episode 450 Total Reward: 0.0
Episode 500 Total Reward: 0.0
Episode 550 Total Reward: 0.0
Episode 600 Total Reward: 0.0
Episode 650 Total Reward: 1.0
Episode 700 Total Reward: 1.0
Episode 750 Total Reward: 0.0
Episode 800 Total Reward: 0.0
Episode 850 Total Reward: 1.0
Episode 900 Total Reward: 0.0
Episode 950 Total Reward: 0.0
Episode 1000 Total Reward: 0.0
Episode 1050 Total Reward: 0.0
Episode 1100 Total Reward: 1.0
Episode 1150 Total Reward: 0.0
Episode 1200 Total Reward: 0.0
Episode 1250 Total Reward: 0.0
Episode 1300 Total Reward: 0.0
Episode 1350 Total Reward: 0.0
Episode 1400 Total Reward: 1.0
Episode 1450 Total Reward: 0.0
Episode 1500 Total Reward: 0.0
Episode 1550 Total Reward: 0.0
Episode 1600 Total Reward: 0.0
Episode 1650 Total Reward: 0.0
Episode 1700 Total Reward: 0.0
Episode 1750 Total Reward: 0.0
Episode 1800 Total Reward: 0.0
Episode 1850 Total Reward: 0.0
Episode 1900 Total Reward: 0.0
Episode 1950 Total Reward: 0.0
Episode 2000 Total Reward: 0.0
Episode 2050 Total Reward: 0.0
Episode 2100 Total Reward: 0.0
Episode 2150 Total Reward: 0.0
Episode 2200 Total Reward: 0.0
Episode 2250 Total Reward: 0.0
Episode 2300 Total Reward: 1.0
Episode 2350 Total Reward: 0.0
Episode 2400 Total Reward: 0.0
```

```
Episode 2450 Total Reward: 1.0
Episode 2500 Total Reward: 0.0
Episode 2550 Total Reward: 1.0
Episode 2600 Total Reward: 0.0
Episode 2650 Total Reward: 0.0
Episode 2700 Total Reward: 0.0
Episode 2750 Total Reward: 0.0
Episode 2800 Total Reward: 0.0
Episode 2850 Total Reward: 0.0
Episode 2900 Total Reward: 0.0
Episode 2950 Total Reward: 0.0
Episode 3000 Total Reward: 0.0
Episode 3050 Total Reward: 0.0
Episode 3100 Total Reward: 0.0
Episode 3150 Total Reward: 1.0
Episode 3200 Total Reward: 0.0
Episode 3250 Total Reward: 0.0
Episode 3300 Total Reward: 0.0
Episode 3350 Total Reward: 0.0
Episode 3400 Total Reward: 1.0
Episode 3450 Total Reward: 0.0
Episode 3500 Total Reward: 0.0
Episode 3550 Total Reward: 0.0
Episode 3600 Total Reward: 0.0
Episode 3650 Total Reward: 1.0
Episode 3700 Total Reward: 0.0
Episode 3750 Total Reward: 0.0
Episode 3800 Total Reward: 0.0
Episode 3850 Total Reward: 0.0
Episode 3900 Total Reward: 0.0
Episode 3950 Total Reward: 0.0
Episode 4000 Total Reward: 0.0
Episode 4050 Total Reward: 1.0
Episode 4100 Total Reward: 0.0
Episode 4150 Total Reward: 0.0
Episode 4200 Total Reward: 0.0
Episode 4250 Total Reward: 0.0
Episode 4300 Total Reward: 0.0
Episode 4350 Total Reward: 1.0
Episode 4400 Total Reward: 0.0
Episode 4450 Total Reward: 0.0
Episode 4500 Total Reward: 1.0
Episode 4550 Total Reward: 0.0
Episode 4600 Total Reward: 0.0
Episode 4650 Total Reward: 0.0
Episode 4700 Total Reward: 0.0
Episode 4750 Total Reward: 0.0
Episode 4800 Total Reward: 0.0
```

```
Episode 4850 Total Reward: 0.0
Episode 4900 Total Reward: 0.0
Episode 4950 Total Reward: 0.0
Episode 5000 Total Reward: 1.0
Episode 5050 Total Reward: 0.0
Episode 5100 Total Reward: 0.0
Episode 5150 Total Reward: 0.0
Episode 5200 Total Reward: 0.0
Episode 5250 Total Reward: 0.0
Episode 5300 Total Reward: 0.0
Episode 5350 Total Reward: 0.0
Episode 5400 Total Reward: 0.0
Episode 5450 Total Reward: 0.0
Episode 5500 Total Reward: 0.0
Episode 5550 Total Reward: 0.0
Episode 5600 Total Reward: 0.0
Episode 5650 Total Reward: 0.0
Episode 5700 Total Reward: 0.0
Episode 5750 Total Reward: 1.0
Episode 5800 Total Reward: 0.0
Episode 5850 Total Reward: 0.0
Episode 5900 Total Reward: 1.0
Episode 5950 Total Reward: 0.0
Episode 6000 Total Reward: 0.0
Episode 6050 Total Reward: 1.0
Episode 6100 Total Reward: 0.0
Episode 6150 Total Reward: 0.0
Episode 6200 Total Reward: 0.0
Episode 6250 Total Reward: 0.0
Episode 6300 Total Reward: 0.0
Episode 6350 Total Reward: 0.0
Episode 6400 Total Reward: 1.0
Episode 6450 Total Reward: 0.0
Episode 6500 Total Reward: 0.0
Episode 6550 Total Reward: 0.0
Episode 6600 Total Reward: 0.0
Episode 6650 Total Reward: 0.0
Episode 6700 Total Reward: 0.0
Episode 6750 Total Reward: 0.0
Episode 6800 Total Reward: 0.0
Episode 6850 Total Reward: 0.0
Episode 6900 Total Reward: 0.0
Episode 6950 Total Reward: 1.0
Episode 7000 Total Reward: 0.0
Episode 7050 Total Reward: 0.0
Episode 7100 Total Reward: 0.0
Episode 7150 Total Reward: 0.0
Episode 7200 Total Reward: 0.0
```

```
Episode 7250 Total Reward: 0.0
Episode 7300 Total Reward: 0.0
Episode 7350 Total Reward: 0.0
Episode 7400 Total Reward: 0.0
Episode 7450 Total Reward: 0.0
Episode 7500 Total Reward: 0.0
Episode 7550 Total Reward: 0.0
Episode 7600 Total Reward: 0.0
Episode 7650 Total Reward: 0.0
Episode 7700 Total Reward: 0.0
Episode 7750 Total Reward: 0.0
Episode 7800 Total Reward: 0.0
Episode 7850 Total Reward: 0.0
Episode 7900 Total Reward: 0.0
Episode 7950 Total Reward: 0.0
Episode 8000 Total Reward: 0.0
Episode 8050 Total Reward: 0.0
Episode 8100 Total Reward: 0.0
Episode 8150 Total Reward: 0.0
Episode 8200 Total Reward: 0.0
Episode 8250 Total Reward: 0.0
Episode 8300 Total Reward: 0.0
Episode 8350 Total Reward: 0.0
Episode 8400 Total Reward: 0.0
Episode 8450 Total Reward: 0.0
Episode 8500 Total Reward: 0.0
Episode 8550 Total Reward: 1.0
Episode 8600 Total Reward: 0.0
Episode 8650 Total Reward: 0.0
Episode 8700 Total Reward: 0.0
Episode 8750 Total Reward: 0.0
Episode 8800 Total Reward: 0.0
Episode 8850 Total Reward: 0.0
Episode 8900 Total Reward: 0.0
Episode 8950 Total Reward: 0.0
Episode 9000 Total Reward: 1.0
Episode 9050 Total Reward: 0.0
Episode 9100 Total Reward: 0.0
Episode 9150 Total Reward: 1.0
Episode 9200 Total Reward: 0.0
Episode 9250 Total Reward: 0.0
Episode 9300 Total Reward: 0.0
Episode 9350 Total Reward: 0.0
Episode 9400 Total Reward: 0.0
Episode 9450 Total Reward: 0.0
Episode 9500 Total Reward: 0.0
Episode 9550 Total Reward: 0.0
Episode 9600 Total Reward: 0.0
```

```
Episode 9750 Total Reward: 0.0
    Episode 9800 Total Reward: 0.0
    Episode 9850 Total Reward: 0.0
    Episode 9900 Total Reward: 0.0
    Episode 9950 Total Reward: 0.0
    Episode 10000 Total Reward: 1.0
[]: # referenced from https://www.kaggle.com/charel/
      \rightarrow learn-by-example-reinforcement-learning-with-qym
     env = gym.make('FrozenLake-v0')
     env.reset()
     Q = np.zeros([env.observation_space.n, env.action_space.n]) #we could also make_
     →this dynamic if we don't know all games states upfront
     gamma = 0.95 # discount factor
     alpha = 0.9 # learning rate
     epsilon = 0.1 #
     for episode in range(1,50001):
         done = False
         obs = env.reset()
         while done != True:
             if np.random.rand(1) < epsilon:</pre>
                 # exploration with a new option with probability epsilon, the
      →epsilon greedy approach
                 action = env.action_space.sample()
             else:
                 # exploitation
                 action = np.argmax(Q[obs])
             obs2, rew, done, info = env.step(action) #take the action
             Q[obs,action] += alpha * (rew + gamma * np.max(Q[obs2]) -
      \rightarrowQ[obs,action]) #Update Q-marix using Bellman equation
             obs = obs2
         if episode % 5000 == 0:
             #report every 5000 steps, test 100 games to get avarage point score for
      →statistics and verify if it is solved
             rew average = 0.
             for i in range(100):
                 obs= env.reset()
                 done=False
                 while done != True:
                     action = np.argmax(Q[obs])
```

Episode 9650 Total Reward: 0.0 Episode 9700 Total Reward: 0.0

```
obs, rew, done, info = env.step(action) #take step using □
      \rightarrow selected action
                     rew_average += rew
             rew_average=rew_average/100
             print('Episode {} avarage reward: {}'.format(episode, rew_average))
             if rew average > 0.8:
                 # FrozenLake-v0 defines "solving" as getting average reward of 0.78_{\sqcup}
      → over 100 consecutive trials.
                 # Test it on 0.8 so it is not a one-off lucky shot solving it
                 print("Frozen lake solved")
                 break
    Episode 5000 avarage reward: 0.0
    Episode 10000 avarage reward: 0.28
    Episode 15000 avarage reward: 0.45
    Episode 20000 avarage reward: 0.37
    Episode 25000 avarage reward: 0.54
    Episode 30000 avarage reward: 0.68
    Episode 35000 avarage reward: 0.21
    Episode 40000 avarage reward: 0.0
    Episode 45000 avarage reward: 0.17
    Episode 50000 avarage reward: 0.44
[]: # Let's see how the algorithm solves the frozen-lakes game
     rew_tot=0.
     obs= env.reset()
     done=False
     while done != True:
         action = np.argmax(Q[obs])
         obs, rew, done, info = env.step(action) #take step using selected action
         rew_tot += rew
         env.render()
     print("Reward:", rew_tot)
      (Left)
    SFFF
    FHFH
    FFFH
    HFFG
      (Left)
    SFFF
    FHFH
    FFFH
```

HFFG (Left) SFFF FHFH FFFH HFFG (Left) SFFF FHFH FFFH HFFG (Left) SFFF FHFH FFFH HFFG (Up) SFFF FHFH FFFH HFFG (Left) SFFF

FHFH FFFH HFFG (Up) SFFF FHFH FFFH HFFG (Left) SFFF FHFH FFFH HFFG (Up) SFFF FHFH FFFH HFFG (Left) SFFF FHFH FFFH HFFG (Up) SFFF FHFH FFFH HFFG (Left) SFFF FHFH FFFHHFFG (Left) SFFF FHFH FFFH HFFG (Left) SFFF FHFH FFFH HFFG (Left) SFFF FHFH FFFH

HFFG

(Left) SFFF FHFH FFFHHFFG (Left) SFFF FHFH FFFH **HFFG** (Left) SFFF FHFH FFFH HFFG (Left) SFFF FHFH FFFH HFFG (Left) SFFF FHFH FFFH HFFG (Up) SFFF FHFH FFFH HFFG (Down) SFFF FHFH FFFH HFFG (Up) SFFF FHFH FFFH HFFG (Down) SFFF FHFHFFFH HFFG (Up) SFFF

FHFH

```
FFFH
    HFFG
      (Up)
    SFFF
    FHFH
    FFFH
    HFFG
      (Down)
    SFFF
    FHFH
    FFFH
    HFFG
     (Up)
    SFFF
    FHFH
    FFFH
    HFFG (Down)
    SFFF
    FHFH
    FFFH
    HFFG
    Reward: 1.0
[]:
```