

CMSC740

Advanced Computer Graphics

Fall 2025

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Overview

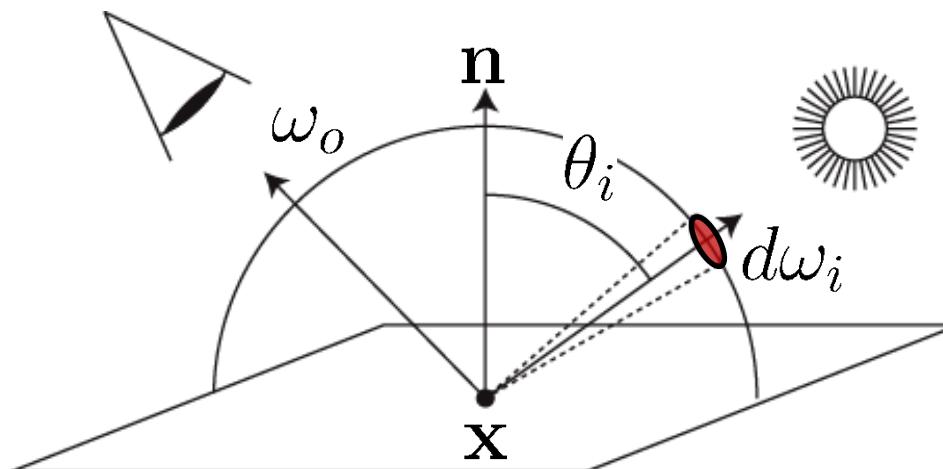
Advanced sampling techniques

- Surface form of hemispherical integrals
- Multiple importance sampling
- Beyond uniform pseudo random numbers

Reflection equation

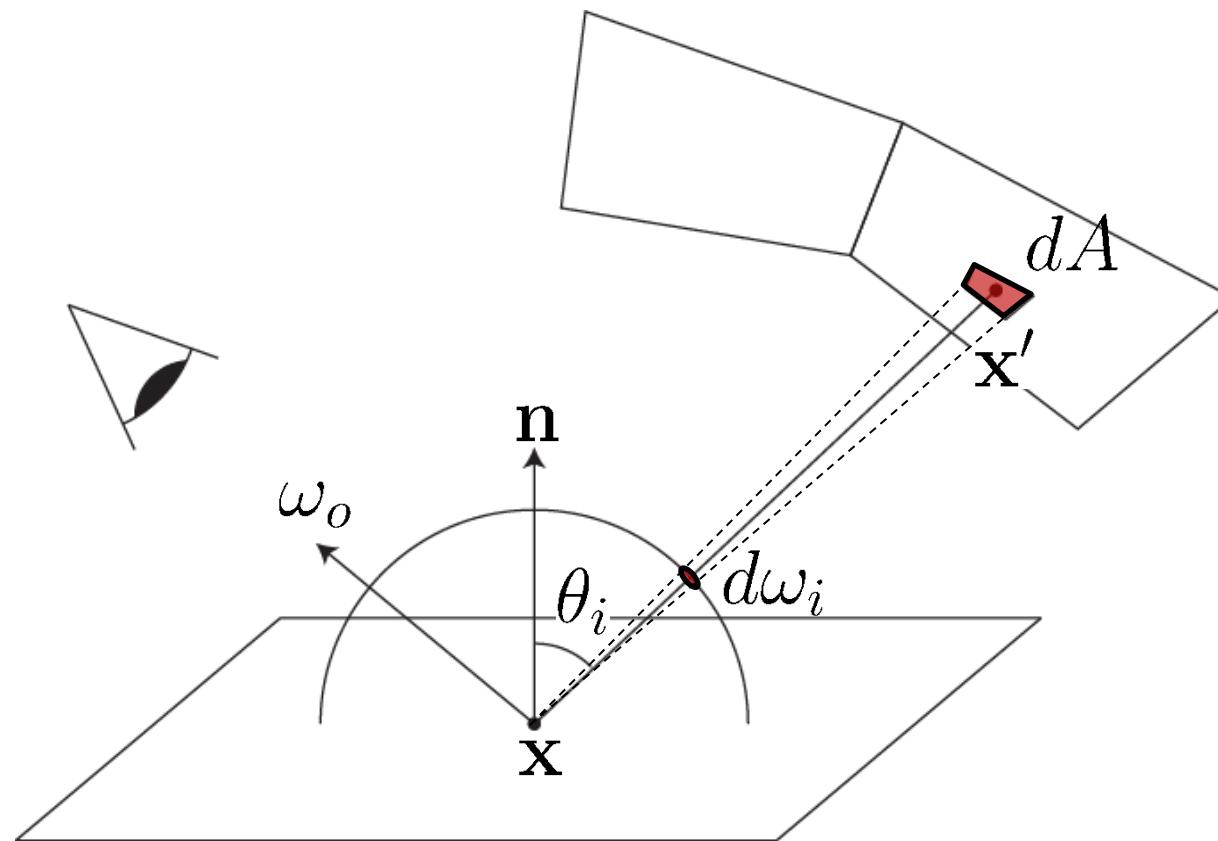
- So far: **directional form** of reflection equation
- Integration over **solid angle**

$$L_o(\mathbf{x}, \omega_o) = \int_{\mathcal{H}^2(\mathbf{n})} f(\mathbf{x}, \omega_o, \omega_i) L_i(\mathbf{x}, \omega_i) \cos \theta_i d\omega_i$$



Surface form

- Integration over surface elements dA instead of solid angle $d\omega_i$



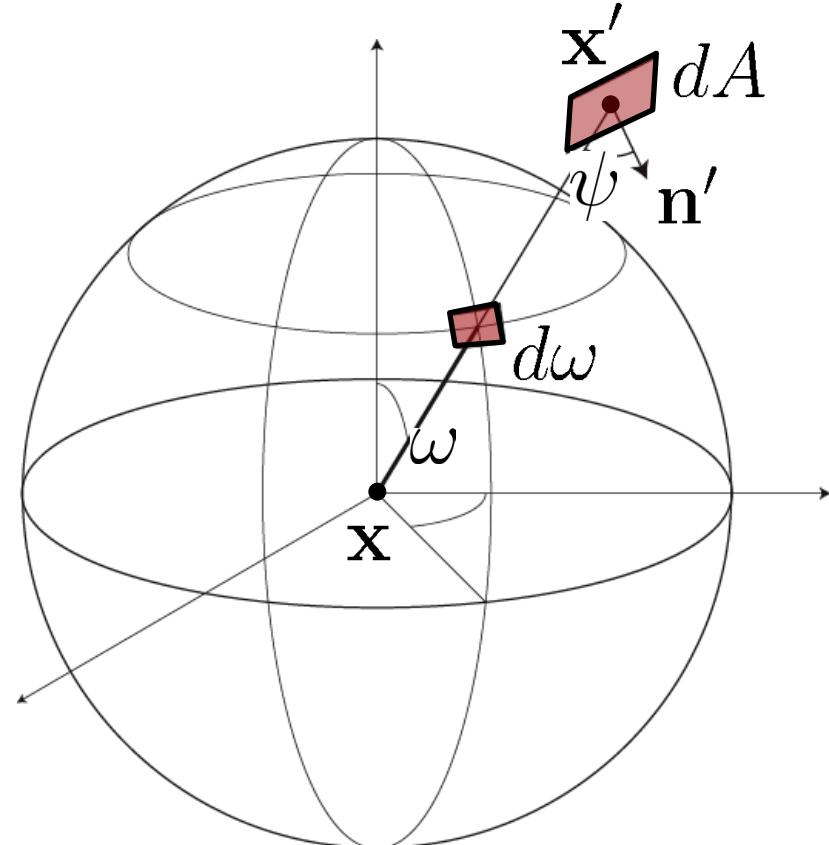
Change of integration variables

- Solid angle spanned by differential surface element dA at location \mathbf{x}' with normal \mathbf{n}'

$$d\omega = \frac{\cos \psi}{\|\mathbf{x}' - \mathbf{x}\|^2} dA$$

where

$$\cos \psi = \frac{\mathbf{n}' \cdot (\mathbf{x} - \mathbf{x}')}{\|\mathbf{x}' - \mathbf{x}\|}$$



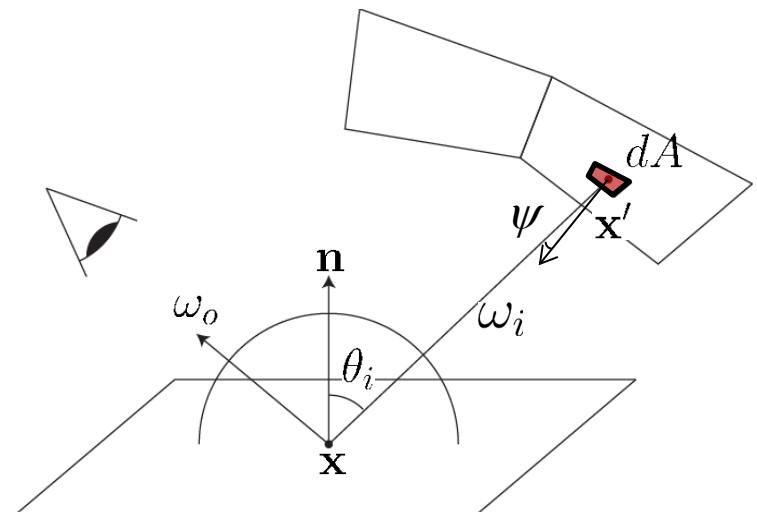
Surface form

- Reflection integral over all **visible** surface elements

$$L_o(\mathbf{x}, \omega_o) =$$

$$\int_{\text{all } \mathbf{x}' \text{ visible to } \mathbf{x}} f(\mathbf{x}, \omega_o, \omega_i) L_i(\mathbf{x}, \omega_i) \cos \theta_i \frac{\cos \psi}{\|\mathbf{x}' - \mathbf{x}\|^2} dA$$

where $\omega_i = \frac{\mathbf{x}' - \mathbf{x}}{\|\mathbf{x}' - \mathbf{x}\|}$



Surface form

- Reflection integral over all surfaces using visibility function

$$L_o(\mathbf{x}, \omega_o) = \int_{\text{all } \mathbf{x}'} f(\mathbf{x}, \omega_o, \omega_i) L_i(\mathbf{x}, \omega_i) \frac{v(\mathbf{x}, \mathbf{x}') \cos \theta_i \cos \psi}{\|\mathbf{x}' - \mathbf{x}\|^2} dA$$

Geometry term

where the visibility function is

$$v(\mathbf{x}, \mathbf{x}') = \begin{cases} 1 & \text{if } \mathbf{x} \text{ and } \mathbf{x}' \text{ are mutually visible} \\ 0 & \text{otherwise.} \end{cases}$$

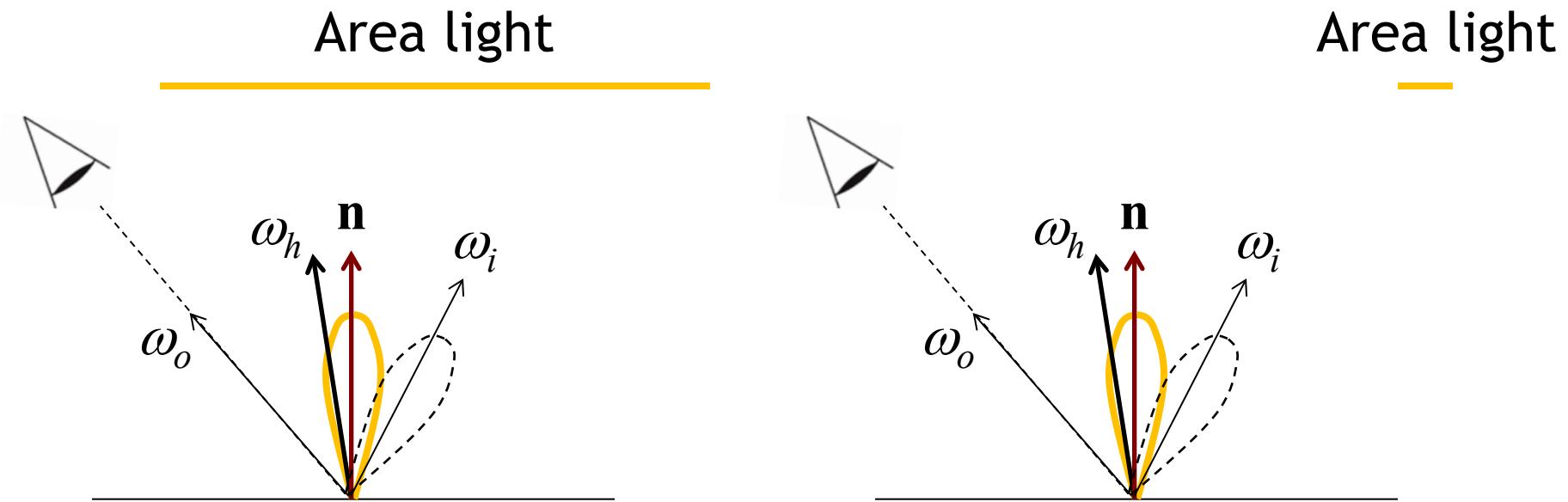
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Sampling direct illumination

- How to best distribute samples?

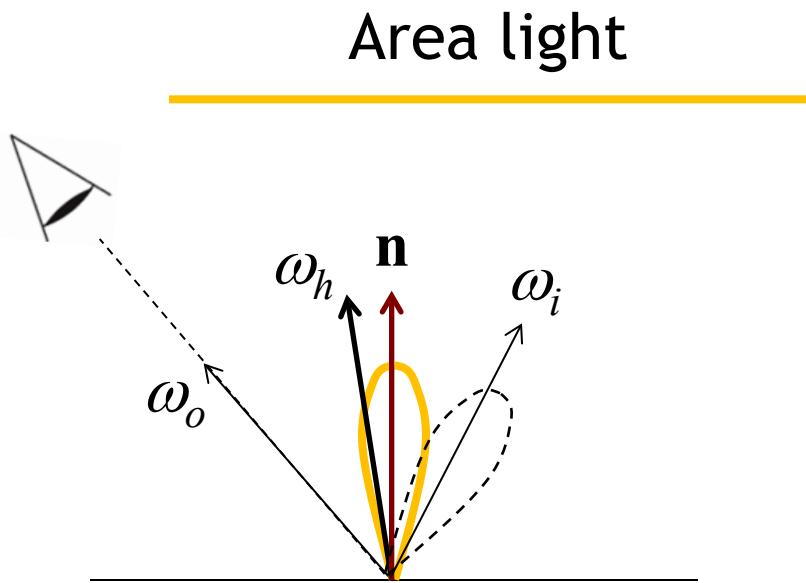


BSDF vs. area light sampling

- Importance sample the BSDF: place more samples where BSDF is large
- Importance sample the light source: place more samples where emission is large (non-zero)

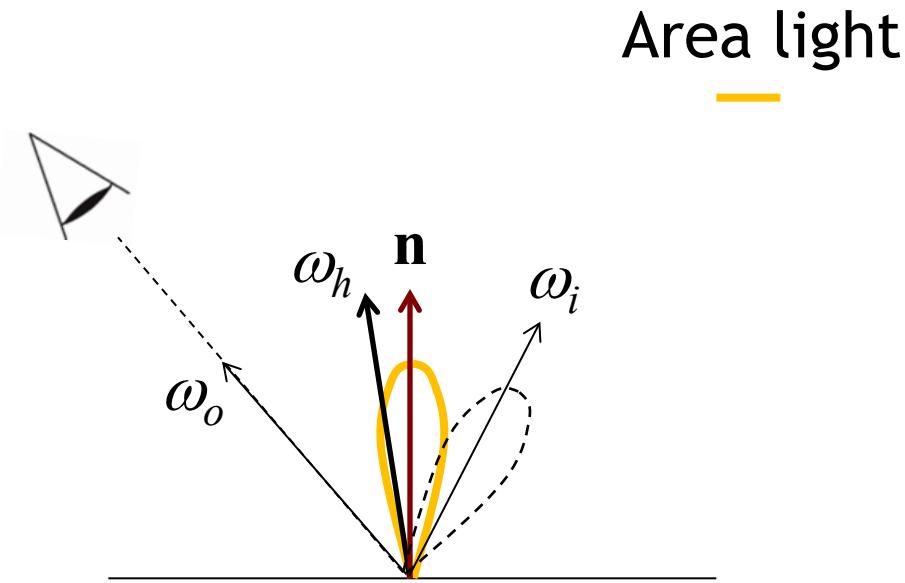
BSDF vs. area light sampling

- A. It is better to importance sample using the BSDF
- B. It is better to importance sample the light source



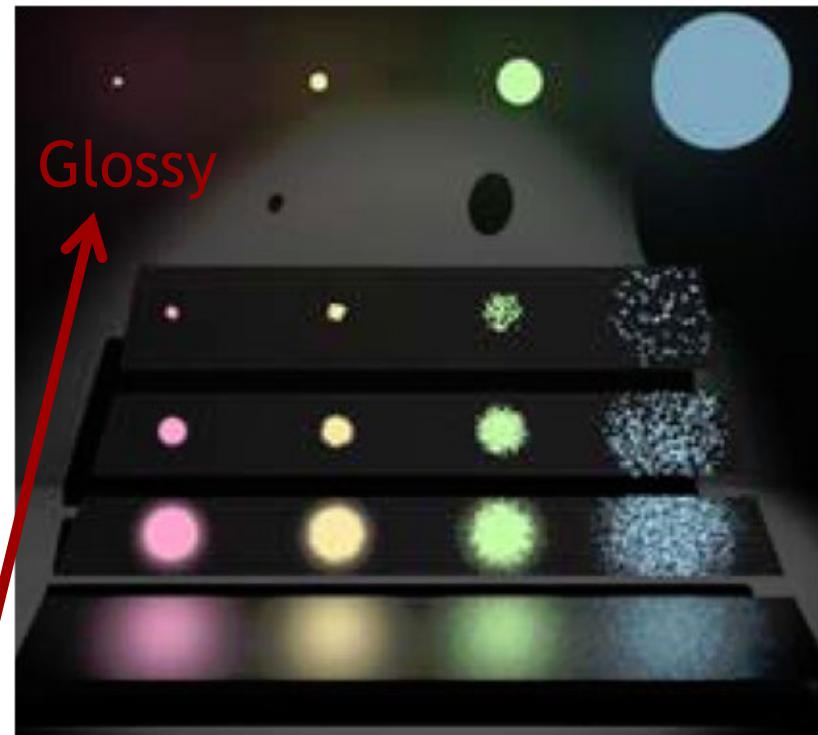
BSDF vs. area light sampling

- A. It is better to importance sample using the BSDF
- B. It is better to importance sample the light source



Sampling direct illumination

Sampling according
to the light (importance
sampling light source areas)



Glossy

Sampling according
to the BSDF (importance
sampling the BSDF)



[Veach, Guibas]

Which sampling technique?

- Importance sample light source (area form)

$$F_a = \frac{1}{N} \sum_j \frac{f(\mathbf{x}, \omega_o, \omega_{i,j}) L_i(\mathbf{x}, \omega_{i,j}) v(\mathbf{x}, \mathbf{x}'_j) \cos \theta_{i,j} \cos \psi_j}{\|\mathbf{x}'_j - \mathbf{x}\|^2 p(\mathbf{x}'_j)}$$

PDF proportional
to emission

Geometry term

- Importance sample BSDF (directional form)

$$F_d = \frac{1}{N} \sum_j \frac{f(\mathbf{x}, \omega_o, \omega_{i,j}) L_i(\mathbf{x}, \omega_{i,j}) \cos \theta_i}{p(\omega_{i,j})}$$

PDF proportional to BSDF

Multiple importance sampling (MIS)

- Naive approach: use both sampling techniques and average, that is, $(F_a + F_d)/2$
 - Variance is bounded by **larger variance** of two techniques
- MC estimator F with multiple importance sampling
 - Weighted average, with weights that reduce variance in optimal way
 - n sampling techniques p_i , weights w_i
 - N samples from each technique, j -th sample of i -th technique $X_{i,j}$

$$F = \frac{1}{N} \sum_{j=1}^N \sum_{i=1}^n w_i(X_{i,j}) \frac{f(X_{i,j})}{p_i(X_{i,j})}$$

N samples Weighted average
of n techniques

Requirement: partition of unity $\sum_{i=1}^n w_i(x) = 1$ for all x

Multiple importance sampling (MIS)

- Unbiased estimator of integral, as before!
- Weights for provable variance reduction
 - Balance heuristics

$$w_i(x) = \frac{p_i(x)}{\sum_{k=1}^n p_k(x)}$$

- Power heuristics

$$w_i(x) = \frac{p_i^2(x)}{\sum_{k=1}^n p_k^2(x)}$$

- Details, proofs http://graphics.stanford.edu/papers/veach_thesis/thesis.pdf

Multiple importance sampling

Naïve sampling



Optimal sampling



Same number of samples

[Veach, Guibas]

Implementation

- Multiple importance sampling for making connection to light source (shadow rays, also called “next event estimation”) is simple extension of standard unidirectional path tracing
- Take two samples for each next event estimation
 - One by sampling the BRDF/BSDF (next randomly sampled ray direction)
 - One by sampling the light
 - Combine using MIS weights

Implementation

- For MIS weights w_i , need to compute probability densities of taking each sample with both techniques
- Need to express both densities in same parameterization (surface area or solid angle)

$$p_{\text{solid angle}} = p_{\text{area}} / \cos * r^2$$

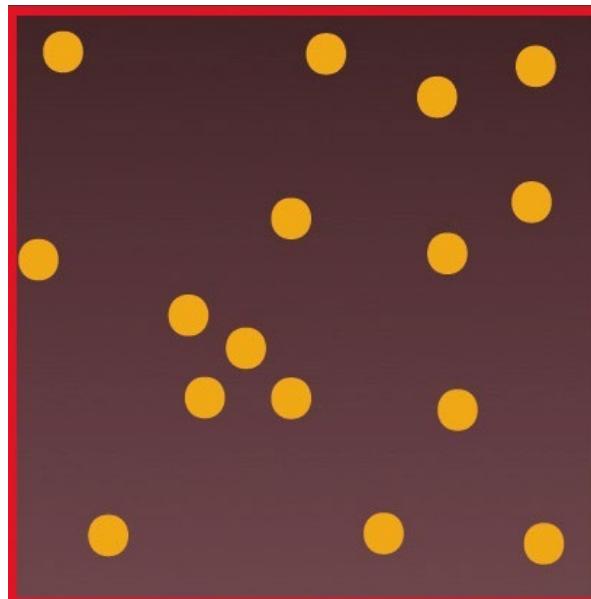
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Observation

- Sample distributions from uniform random numbers can have large gaps and dense clusters
- „Sample space is covered quite non-uniformly“
 - Leads to variance in Monte Carlo estimates

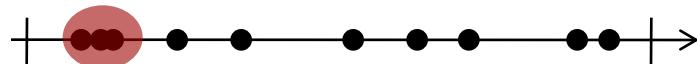


2D samples from uniform random numbers

Stratified sampling

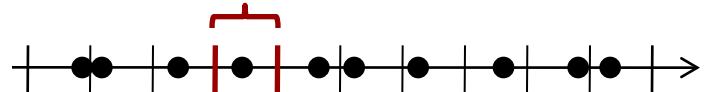
- Intuition: clumping of samples is bad
- Instead of canonic uniform random variables, generate variables in strata
 - One sample per stratum
 - **Everything else stays the same**

Clumping



Uniform

Stratum

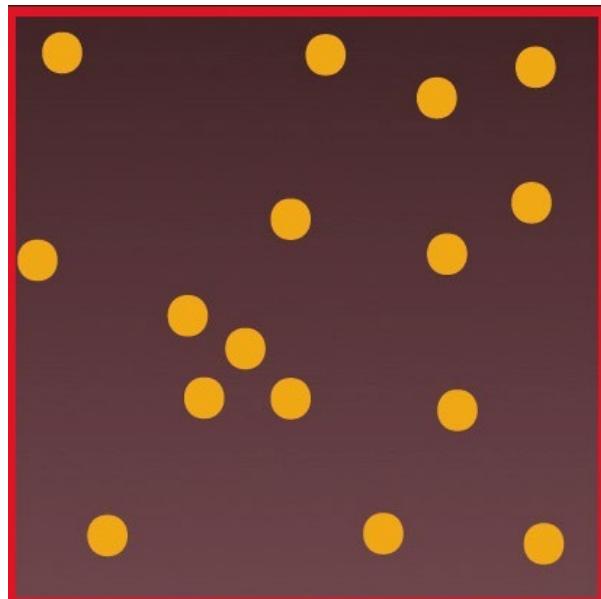


Stratified

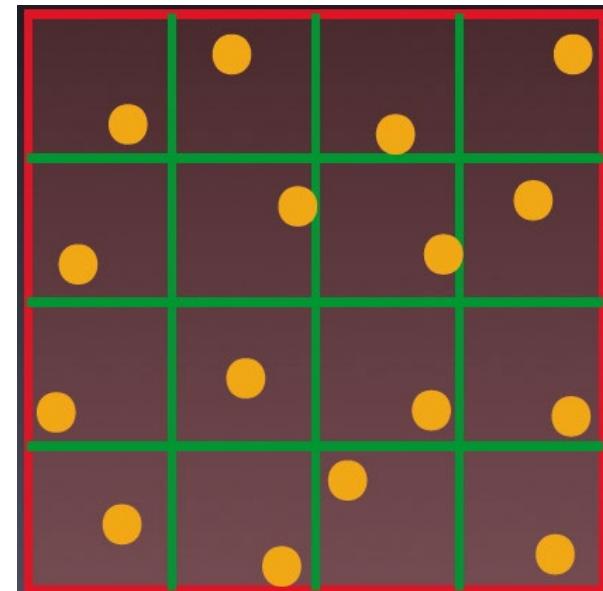
Jittered sampling

- Stratification using uniform grid
- „Jittered“ sample randomly in each cell
- Not suitable for higher dimensions (curse of dimensionality)

Uniform



Jittered



Comparison

- Sampling glossy reflection

Uniform



Stratified



[Pharr, Humphreys]

Other stratified sampling patterns

- N-rooks (Latin hypercube) sampling

http://en.wikipedia.org/wiki/Latin_hypercube_sampling

- Advantage over jittered grid: can generate any number n of samples, not restricted to $n \times m$ grid

- Quasi-Monte Carlo

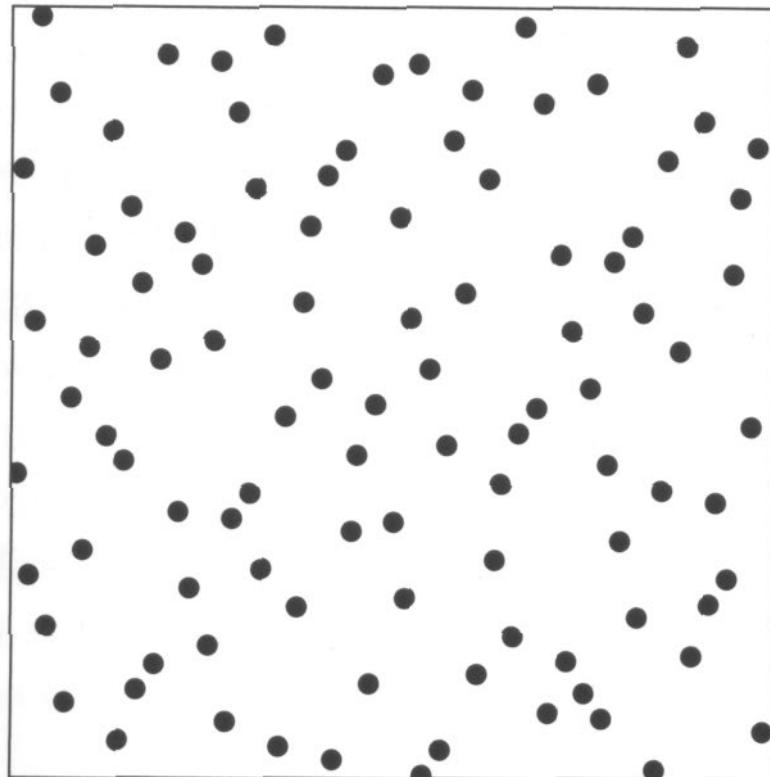
http://en.wikipedia.org/wiki/Quasi-Monte_Carlo_method

- Based on **low-discrepancy** instead of pseudo-random samples
http://en.wikipedia.org/wiki/Low-discrepancy_sequence
- Low-discrepancy sequences have more uniform distribution of points, less clumping, also in higher dimensions
- Can show theoretically that convergence improves

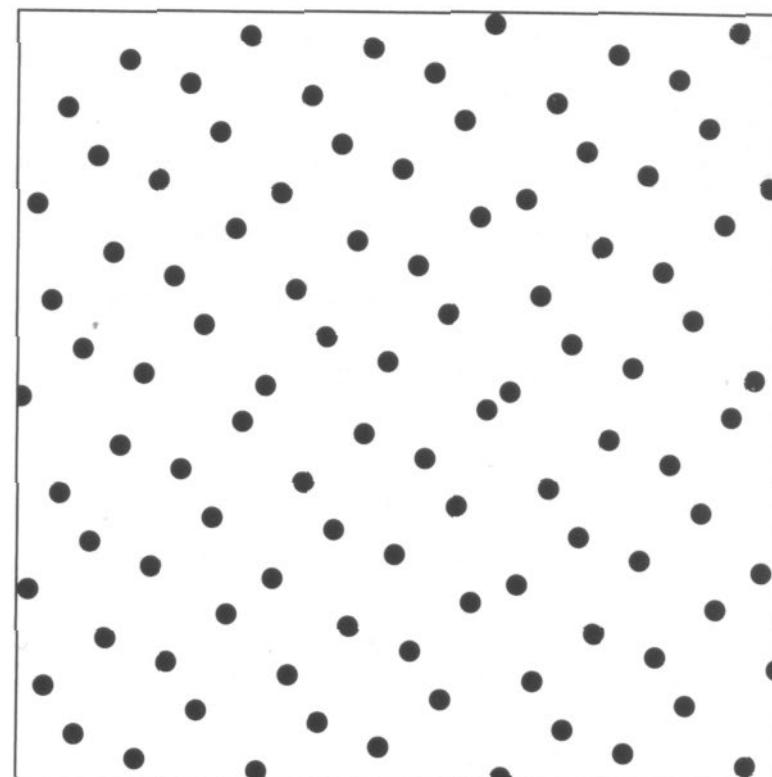
Low-discrepancy sequences

- First 100 points of 2D sequences

http://en.wikipedia.org/wiki/Constructions_of_low-discrepancy_sequences



Halton sequence



Hammersley sequence

Note on implementation

- Any of the improved sampling sequences (jittered, Latin hypercube, low-discrepancy) yield sequences of points $(\xi_1, \xi_2, \dots \xi_n)$ in unit hypercube $[0,1]^n$
- Can directly substitute these for pseudo-random points $(\xi_1, \xi_2, \dots \xi_n)$
 - No need to change rest of implementation

Next time

- Generalized path sampling (three-point form or rendering equation, BDP)