

CMSC740

Advanced Computer Graphics

Fall 2025
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Overview

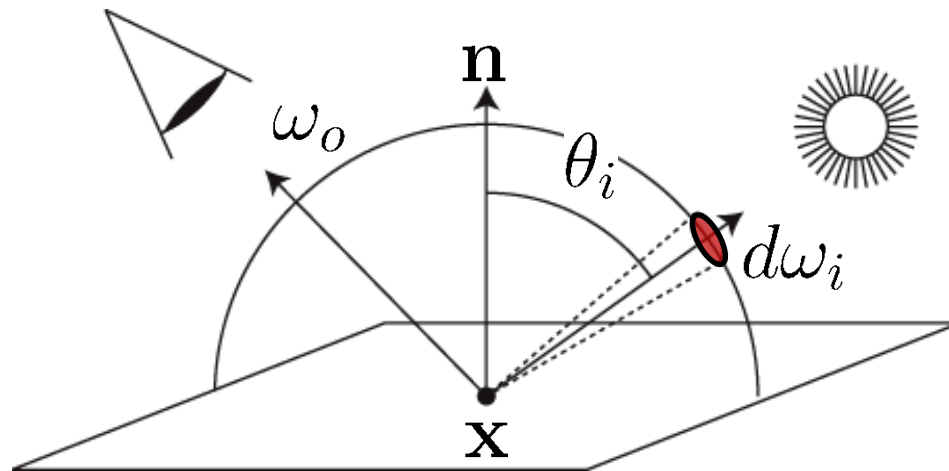
Advanced sampling techniques

- Surface form of hemispherical integrals
- Multiple importance sampling
- Beyond uniform pseudo random numbers

Reflection equation

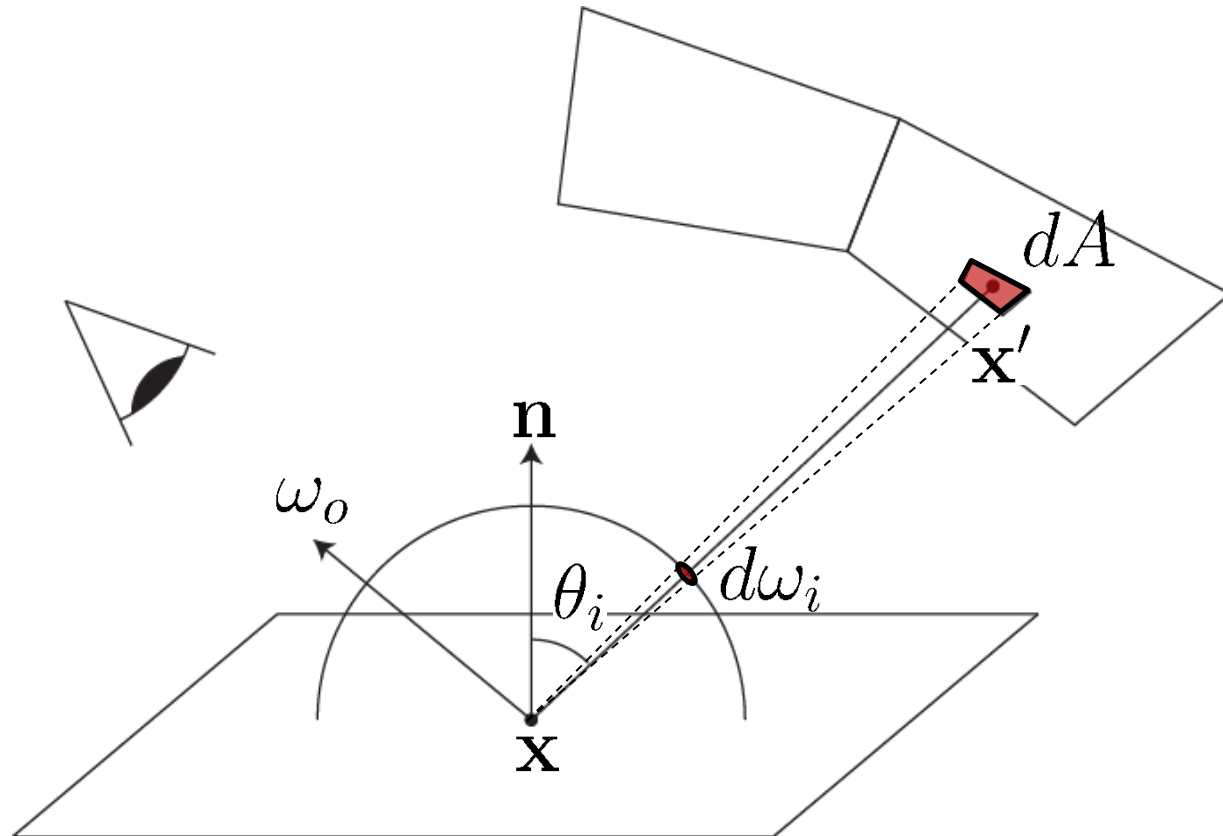
- So far: **directional form** of reflection equation
- Integration over **solid angle**

$$L_o(\mathbf{x}, \omega_o) = \int_{\mathcal{H}^2(\mathbf{n})} f(\mathbf{x}, \omega_o, \omega_i) L_i(\mathbf{x}, \omega_i) \cos \theta_i d\omega_i$$



Surface form

- Integration over surface elements dA instead of solid angle $d\omega_i$



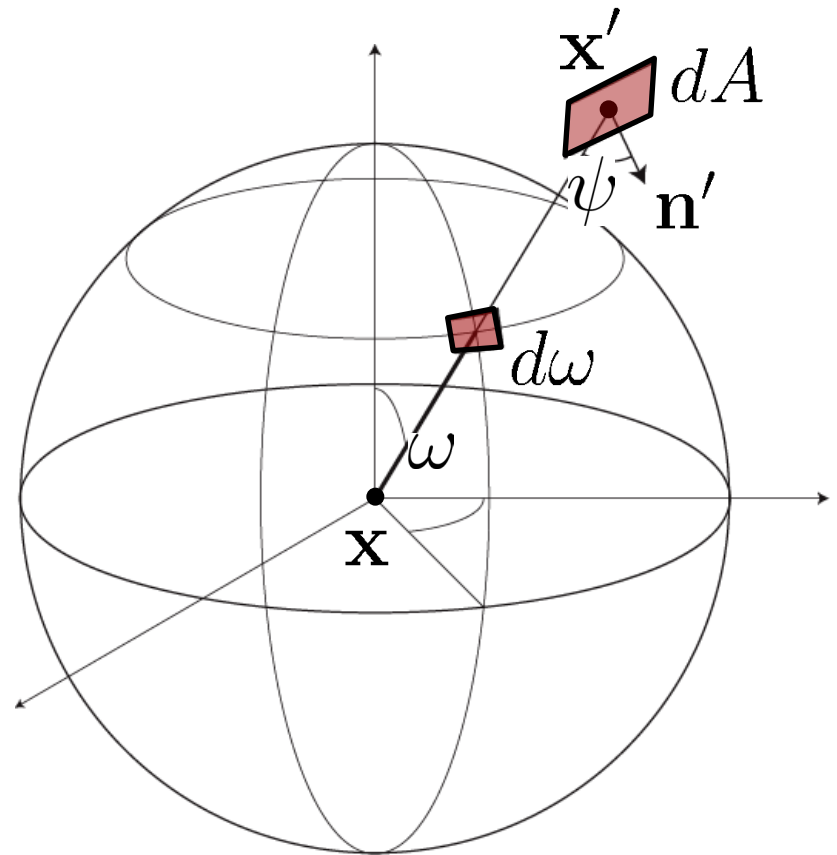
Change of integration variables

- Solid angle spanned by differential surface element dA at location \mathbf{x}' with normal \mathbf{n}'

$$d\omega = \frac{\cos \psi}{\|\mathbf{x}' - \mathbf{x}\|^2} dA$$

where

$$\cos \psi = \frac{\mathbf{n}' \cdot (\mathbf{x} - \mathbf{x}')}{\|\mathbf{x}' - \mathbf{x}\|}$$



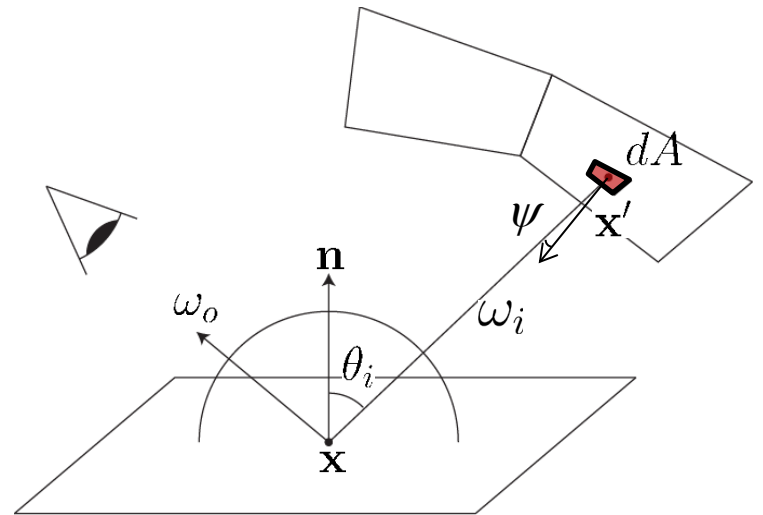
Surface form

- Reflection integral over all **visible** surface elements

$$L_o(\mathbf{x}, \omega_o) =$$

$$\int_{\text{all } \mathbf{x}' \text{ visible to } \mathbf{x}} f(\mathbf{x}, \omega_o, \omega_i) L_i(\mathbf{x}, \omega_i) \cos \theta_i \frac{\cos \psi}{\|\mathbf{x}' - \mathbf{x}\|^2} dA$$

where $\omega_i = \frac{\mathbf{x}' - \mathbf{x}}{\|\mathbf{x}' - \mathbf{x}\|}$



Surface form

- Reflection integral over **all** surfaces using **visibility function**

$$L_o(\mathbf{x}, \omega_o) = \int_{\text{all } \mathbf{x}'} f(\mathbf{x}, \omega_o, \omega_i) L_i(\mathbf{x}, \omega_i) \overbrace{\frac{v(\mathbf{x}, \mathbf{x}') \cos \theta_i \cos \psi}{\|\mathbf{x}' - \mathbf{x}\|^2}}^{\text{Geometry term}} dA$$

where the visibility function is

$$v(\mathbf{x}, \mathbf{x}') = \begin{cases} 1 & \text{if } \mathbf{x} \text{ and } \mathbf{x}' \text{ are mutually visible} \\ 0 & \text{otherwise.} \end{cases}$$

Overview

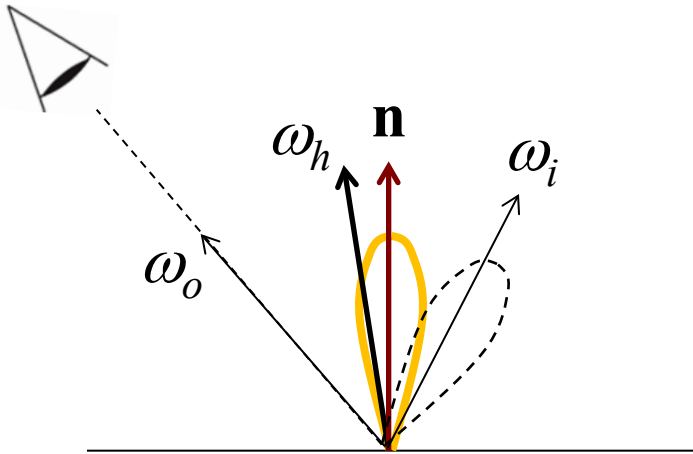
Advanced sampling techniques

- Surface form of hemispherical integrals
- Multiple importance sampling
- Beyond uniform pseudo random numbers

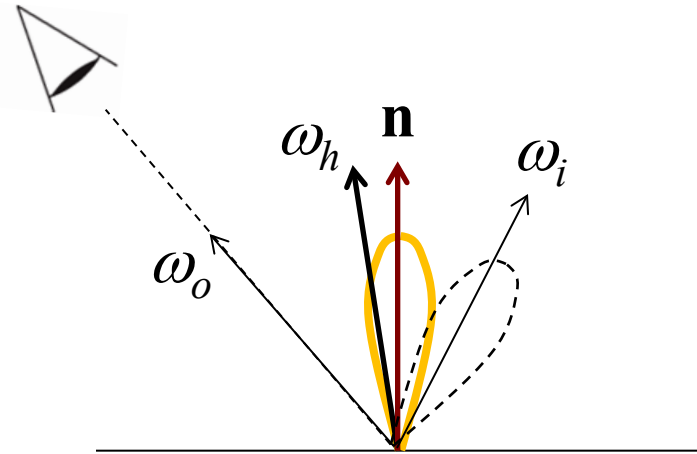
Sampling direct illumination

- How to best distribute samples?

Area light



Area light



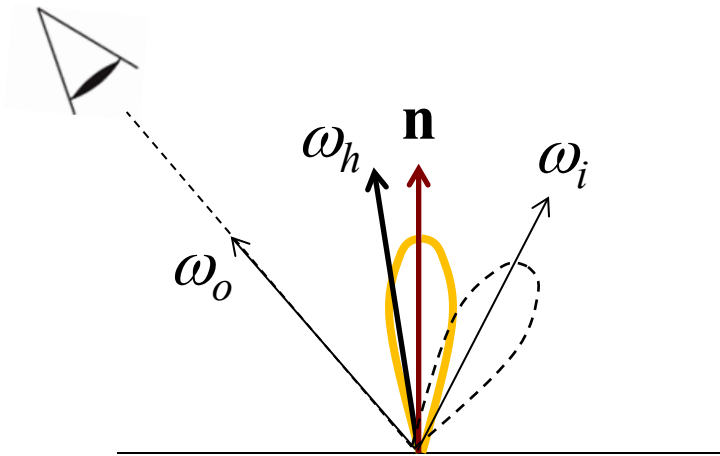
BSDF vs. are light sampling

- Importance sample the BSDF: place more samples where BSDF is large
- Importance sample the light source: place more samples where emission is large (non-zero)

BSDF vs. are light sampling

- A. It is better to importance sample using the BSDF
- B. It is better to importance sample the light source

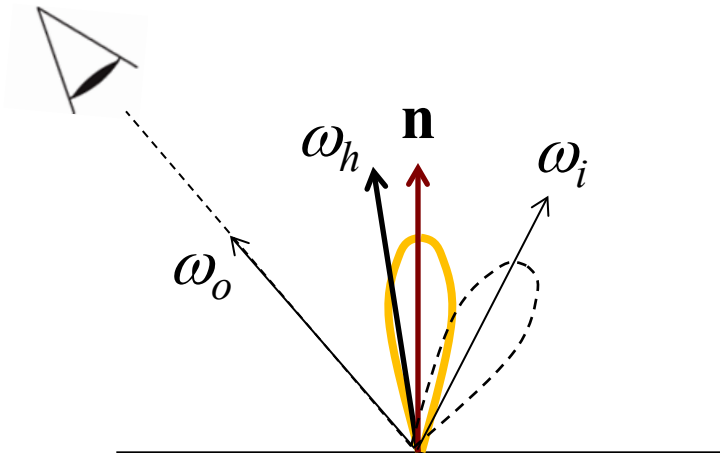
Area light



BSDF vs. are light sampling

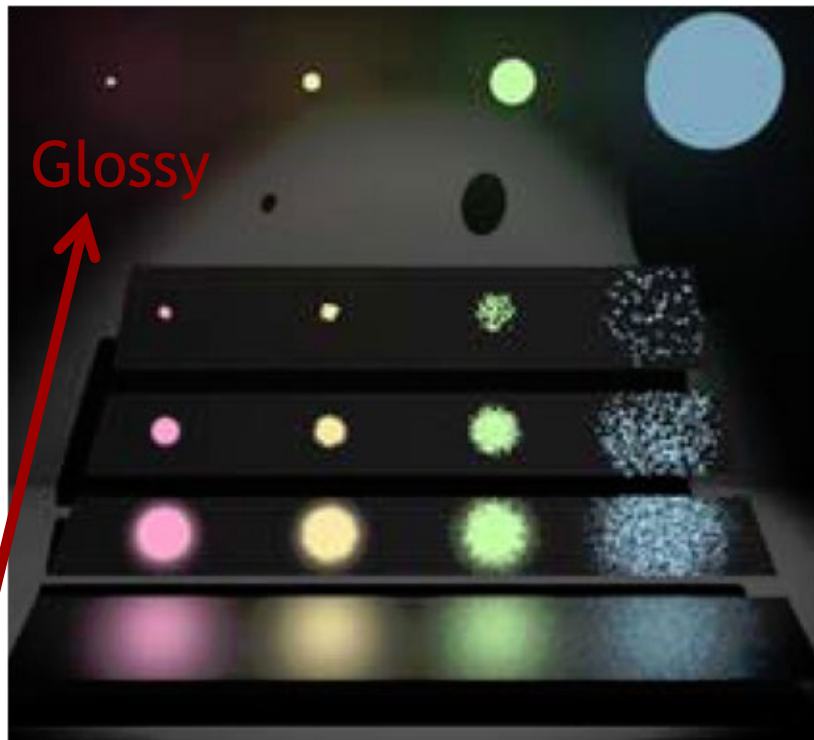
- A. It is better to importance sample using the BSDF
- B. It is better to importance sample the light source

Area light

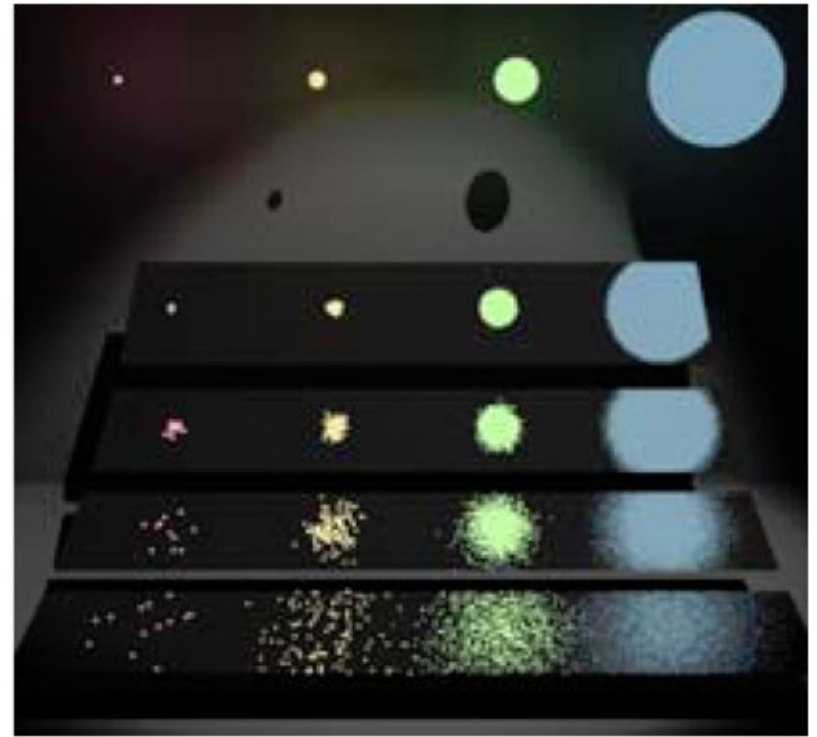


Sampling direct illumination

Sampling according to the light (importance sampling light source areas)



Sampling according to the BSDF (importance sampling the BSDF)



Diffuse

[Veach, Guibas]

Which sampling technique?

- Importance sample light source (area form)

$$F_a = \frac{1}{N} \sum_j \frac{f(\mathbf{x}, \omega_o, \omega_{i,j}) L_i(\mathbf{x}, \omega_{i,j}) v(\mathbf{x}, \mathbf{x}'_j) \cos \theta_{i,j} \cos \psi_j}{\underbrace{\|\mathbf{x}'_j - \mathbf{x}\|^2}_{\text{Geometry term}} \underbrace{p(\mathbf{x}'_j)}_{\text{PDF proportional to emission}}}$$

- Importance sample BSDF (directional form)

$$F_d = \frac{1}{N} \sum_j \frac{f(\mathbf{x}, \omega_o, \omega_{i,j}) L_i(\mathbf{x}, \omega_{i,j}) \cos \theta_i}{\underbrace{p(\omega_{i,j})}_{\text{PDF proportional to BSDF}}}$$

Multiple importance sampling (MIS)

- Naive approach: use both sampling techniques and average, that is, $(F_a + F_d)/2$
 - Variance is bounded by **larger variance** of two techniques
- MC estimator F with multiple importance sampling
 - Weighted average, with weights that reduce variance in optimal way
 - n sampling techniques p_i , weights w_i
 - N samples from each technique, j -th sample of i -th technique $X_{i,j}$

$$F = \frac{1}{N} \sum_{j=1}^N \sum_{i=1}^n w_i(X_{i,j}) \frac{f(X_{i,j})}{p_i(X_{i,j})}$$

N samples Weighted average
of n techniques

Requirement: partition of unity $\sum_{i=1}^n w_i(x) = 1$ for all x

Multiple importance sampling (MIS)

- Unbiased estimator of integral, as before!
- Weights for provable variance reduction
 - Balance heuristics

$$w_i(x) = \frac{p_i(x)}{\sum_{k=1}^n p_k(x)}$$

- Power heuristics

$$w_i(x) = \frac{p_i^2(x)}{\sum_{k=1}^n p_k^2(x)}$$

- Details, proofs http://graphics.stanford.edu/papers/veach_thesis/thesis.pdf

Multiple importance sampling

Naïve sampling



Optimal sampling



Same number of samples

[Veach, Guibas]

Implementation

- Multiple importance sampling for making connection to light source (shadow rays, also called “next event estimation”) is simple extension of standard unidirectional path tracing
- Take two samples for each next event estimation
 - One by sampling the BRDF/BSDF (next randomly sampled ray direction)
 - One by sampling the light
 - Combine using MIS weights

Implementation

- For MIS weights w_i , need to compute probability densities of taking each sample with both techniques
- Need to express both densities in same parameterization (surface area or solid angle)

$$p_{solid\ angle} = p_{area} / \cos * r^2$$

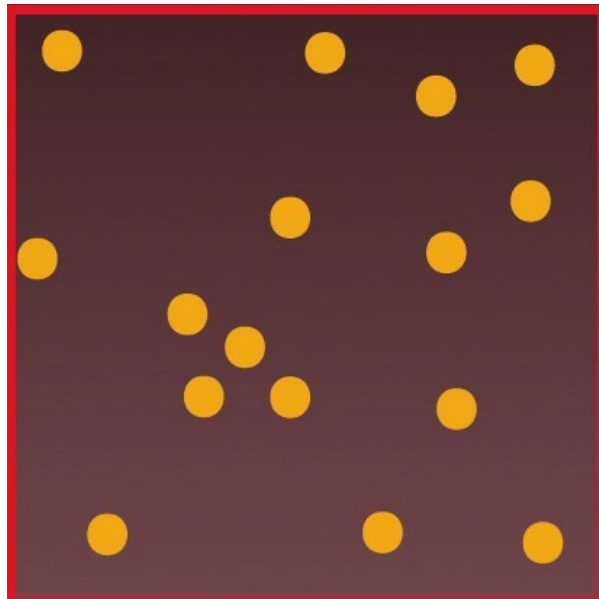
Overview

Advanced sampling techniques

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Observation

- Sample distributions from uniform random numbers can have large gaps and dense clusters
- „Sample space is covered quite non-uniformly“
 - Leads to variance in Monte Carlo estimates



2D samples from uniform random numbers

Stratified sampling

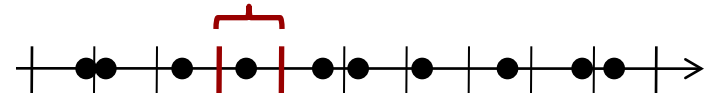
- Intuition: clumping of samples is bad
- Instead of canonic uniform random variables, generate variables in strata
 - One sample per stratum
 - **Everything else stays the same**

Clumping



Uniform

Stratum

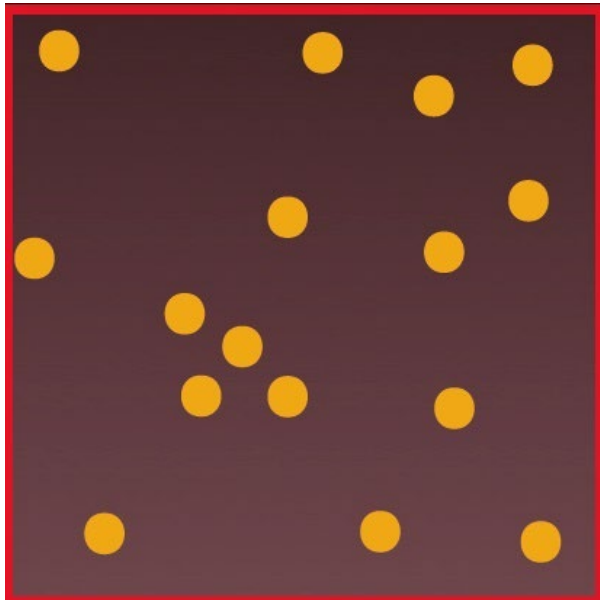


Stratified

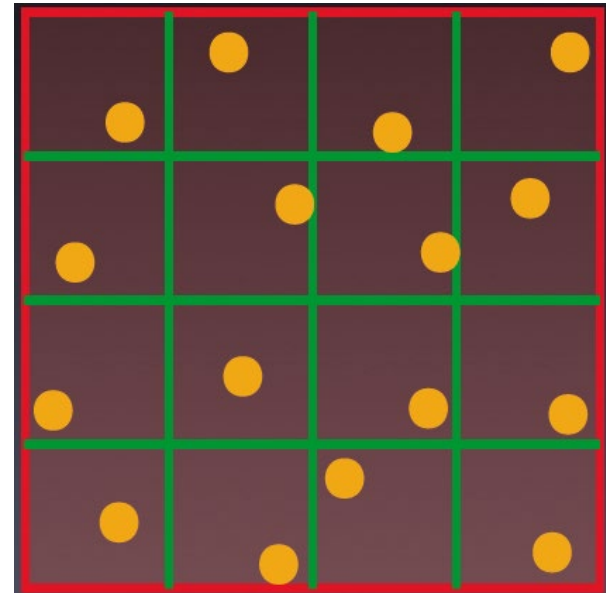
Jittered sampling

- Stratification using uniform grid
- „Jittered“ sample randomly in each cell
- Not suitable for higher dimensions (curse of dimensionality)

Uniform



Jittered



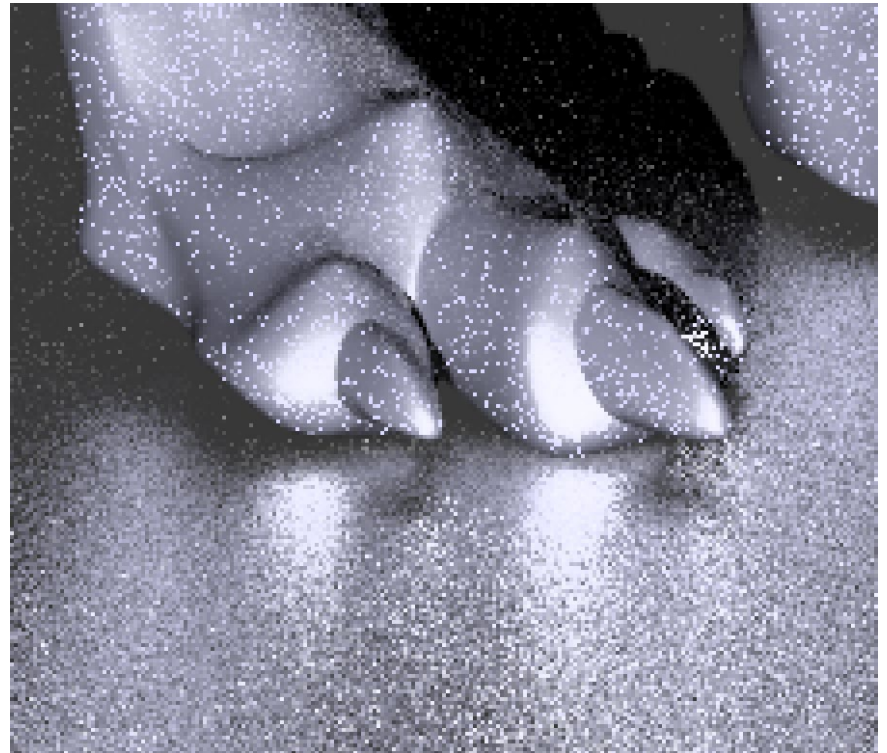
Comparison

- Sampling glossy reflection

Uniform



Stratified



[Pharr, Humphreys]

Other stratified sampling patterns

- N-rooks (Latin hypercube) sampling

http://en.wikipedia.org/wiki/Latin_hypercube_sampling

- Advantage over jittered grid: can generate any number n of samples, not restricted to $n \times m$ grid

- Quasi-Monte Carlo

http://en.wikipedia.org/wiki/Quasi-Monte_Carlo_method

- Based on **low-discrepancy** instead of pseudo-random samples

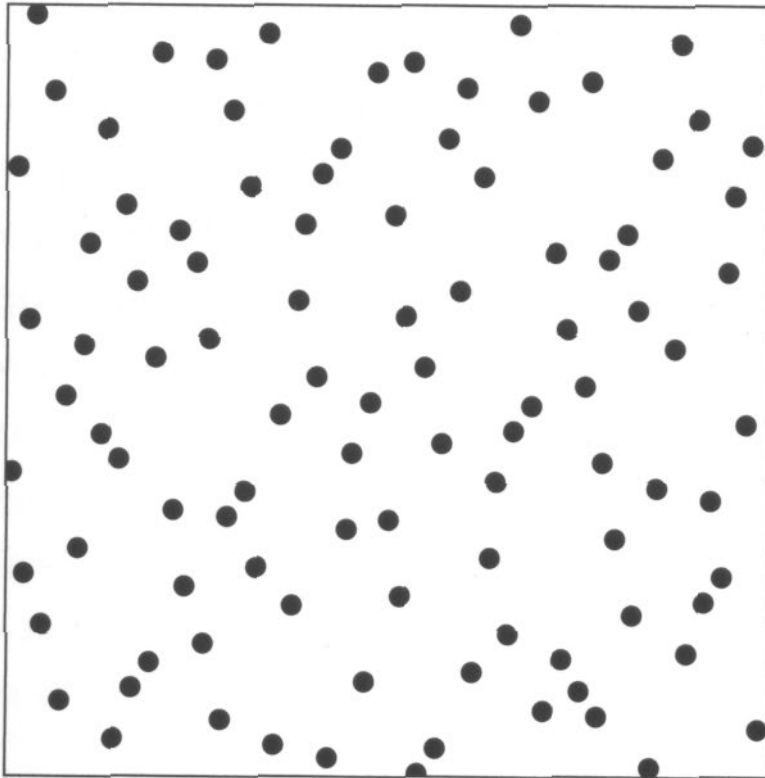
http://en.wikipedia.org/wiki/Low-discrepancy_sequence

- Low-discrepancy sequences have more uniform distribution of points, less clumping, also in higher dimensions
- Can show theoretically that convergence improves

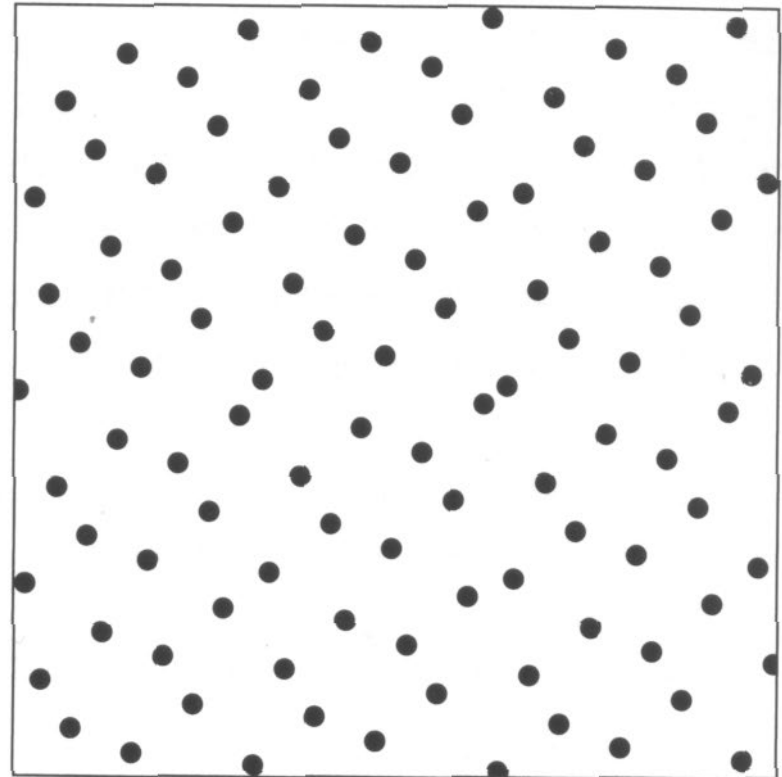
Low-discrepancy sequences

- First 100 points of 2D sequences

http://en.wikipedia.org/wiki/Constructions_of_low-discrepancy_sequences



Halton sequence



Hammerseley sequence

Note on implementation

- Any of the improved sampling sequences (jittered, Latin hypercube, low-discrepancy) yield sequences of points $(\xi_1, \xi_2, \dots, \xi_n)$ in unit hypercube $[0,1]^n$
- Can directly substitute these for pseudo-random points $(\xi_1, \xi_2, \dots, \xi_n)$
 - No need to change rest of implementation

Next time

- Generalized path sampling (three-point form or rendering equation, BDP)