



The Spring Soldier

- Brooklyn Bionics -

Head of Programming: Louie Rivera
Head of Production: Tanvi Rahman
Head of Design: George Zhang

EG 1003 Section C2

Milestone 2 Presentation

March 16th, 2021





AGENDA

- » Project Objective
 - » Background Information
 - » Technical Design Description
 - » Cost Estimate
 - » Project Schedule
 - » Summary
- 

PROJECT OBJECTIVE

- » Develop prosthetic limb with at least two functioning features
 - ◇ Hand wrapping around handle, lifting weight
 - ◇ Elbow able to move vertically 90 degrees
 - ◇ Wrist capable of rotating 180 degrees

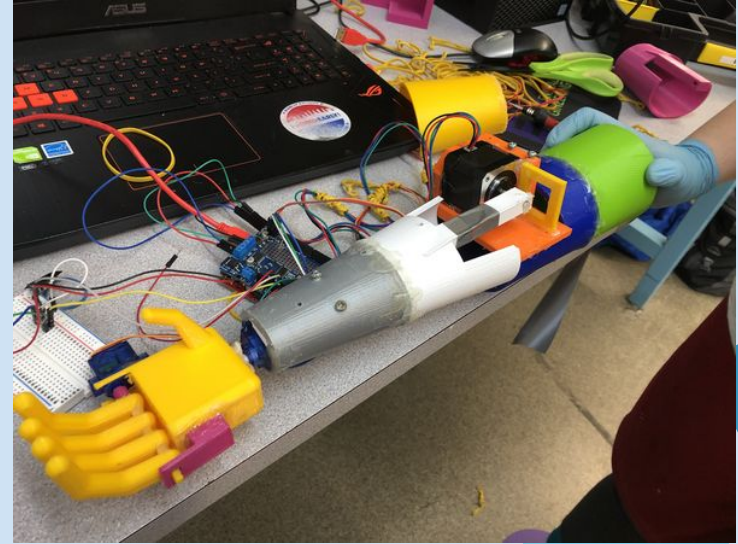


Figure 1: Example BMD Project

PROJECT OBJECTIVE

- » Initial Fusion 360 Model
- » Completed circuit on Fritzing
 - ◇ Circuit simulation on Tinkercad
- » Potential Extra Credit:
 - ◇ Functioning hand

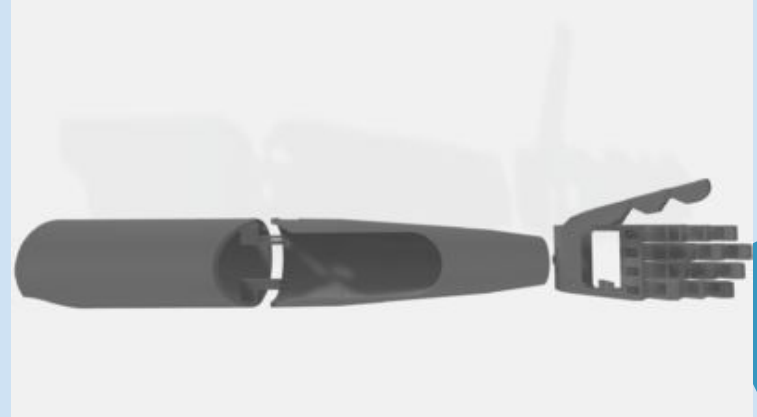


Figure 2: Sample BMD Drawing (NYU Tandon)

BACKGROUND INFORMATION

- » Improve healthcare and medical options
- » Replace lost limbs
- » Save and improve quality of lives



Figure 3: Amputee Using Prosthetic



Figure 4: The Winter Soldier

TECHNICAL DESIGN

- » Functioning elbow and wrist
- » 2 Hinges
 - ◇ 90° - 135° Elbow Rotation
 - ◇ 180° Wrist Rotation
- » Hollow forearm
- » Thumb and finger joints

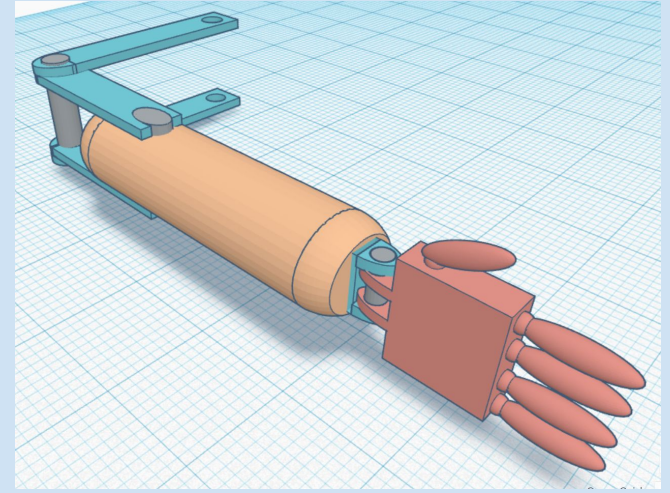


Figure 5: Preliminary CAD Drawing (Isometric)

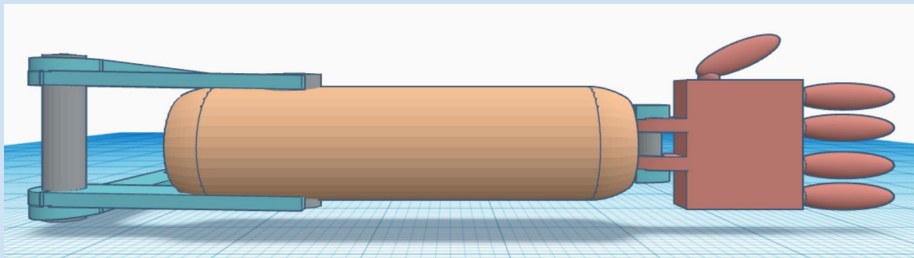


Figure 6: Preliminary CAD Drawing (Front)

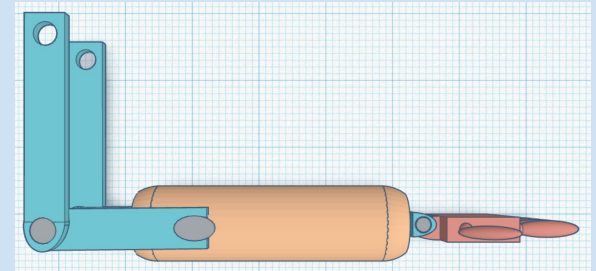


Figure 7: Preliminary CAD Drawing (Top)

TECHNICAL DESIGN

- » Functioning elbow and wrist
- » 2 Hinges
 - ◇ 90° - 135° Elbow Rotation
 - ◇ 180° Wrist Rotation
- » Hollow forearm
- » Thumb and finger joints

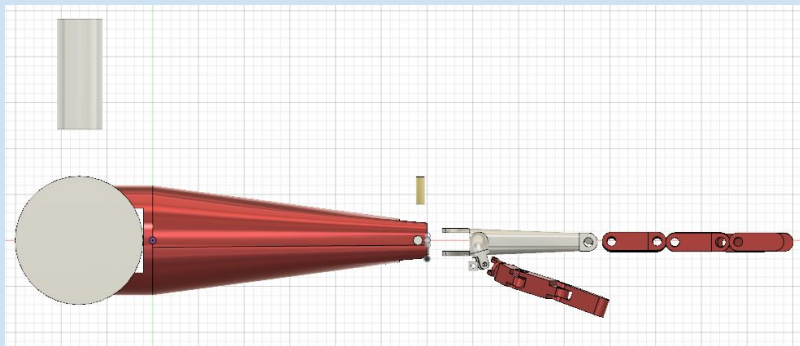


Figure 9: Initial CAD Model (Front)

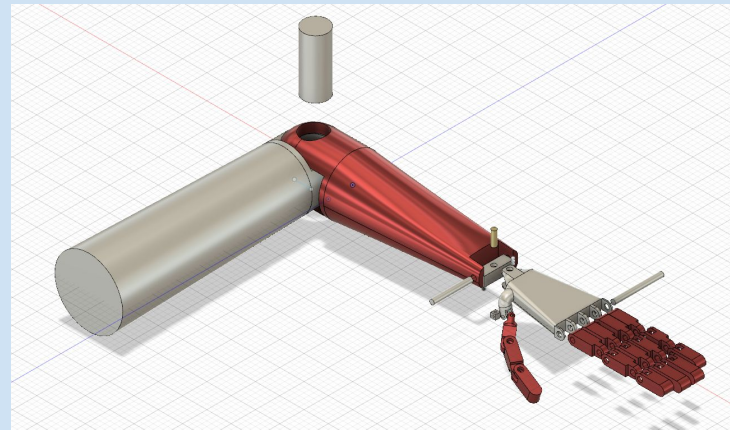


Figure 8: Initial CAD Model (Isometric)

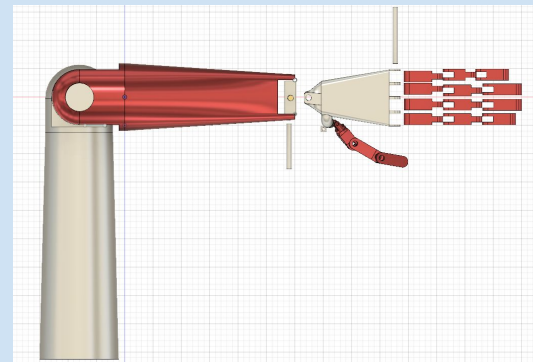


Figure 10: Initial CAD Model (Top)

TECHNICAL DESIGN

- » Myoware Muscle Sensor
- » Electromyography (EMG)
- » Servo Motor

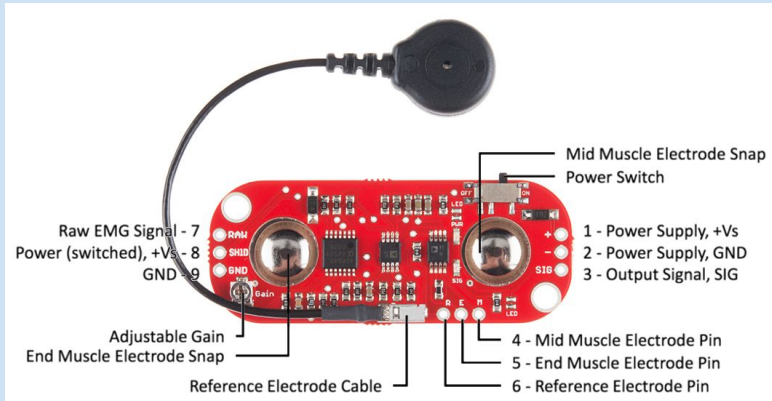


Figure 11: Muscle Sensor Layout

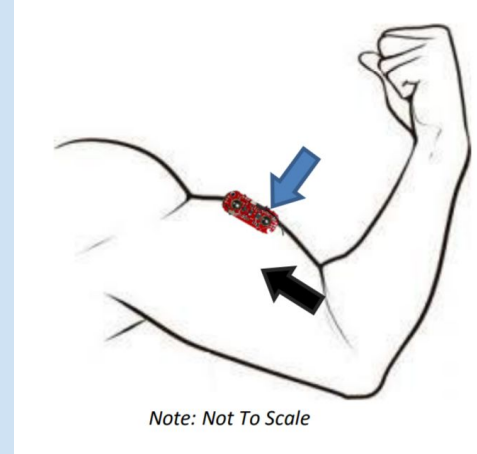


Figure 12: Example Sensor Location for Bicep (NYU Tandon)

TECHNICAL DESIGN

- » Myoware Muscle Sensor
- » Electromyography (EMG)
- » Servo Motor

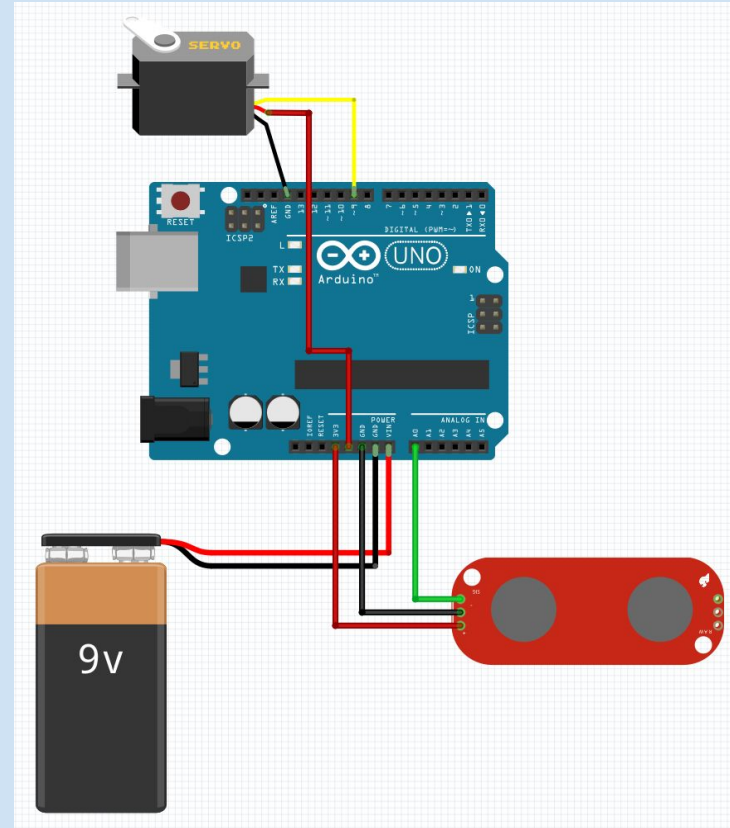


Figure 13: Circuit Diagram (Fritzing)

TECHNICAL DESIGN

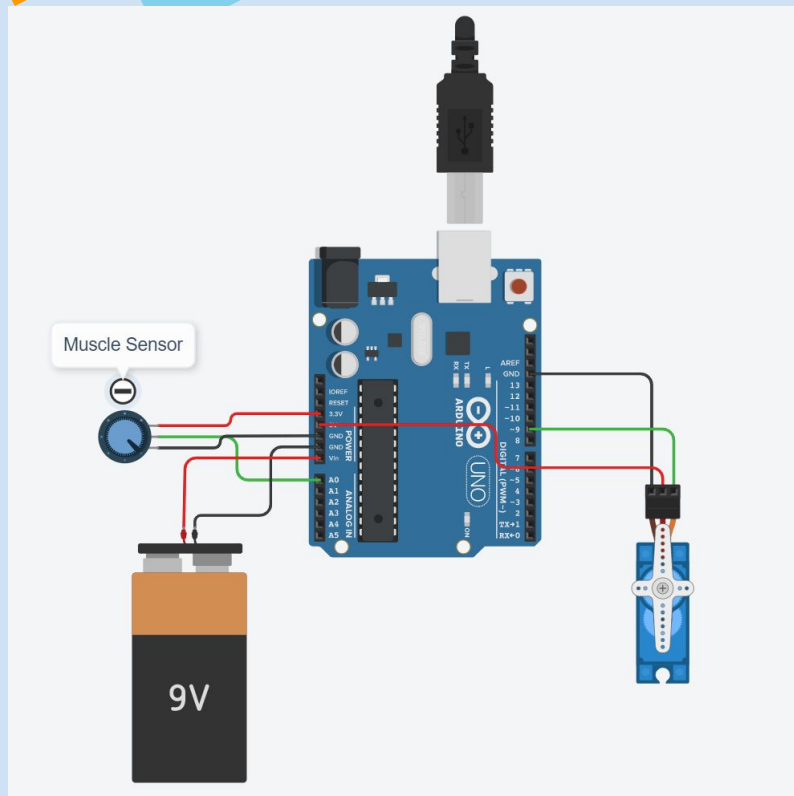


Figure 14: Circuit Diagram (Tinkercad)

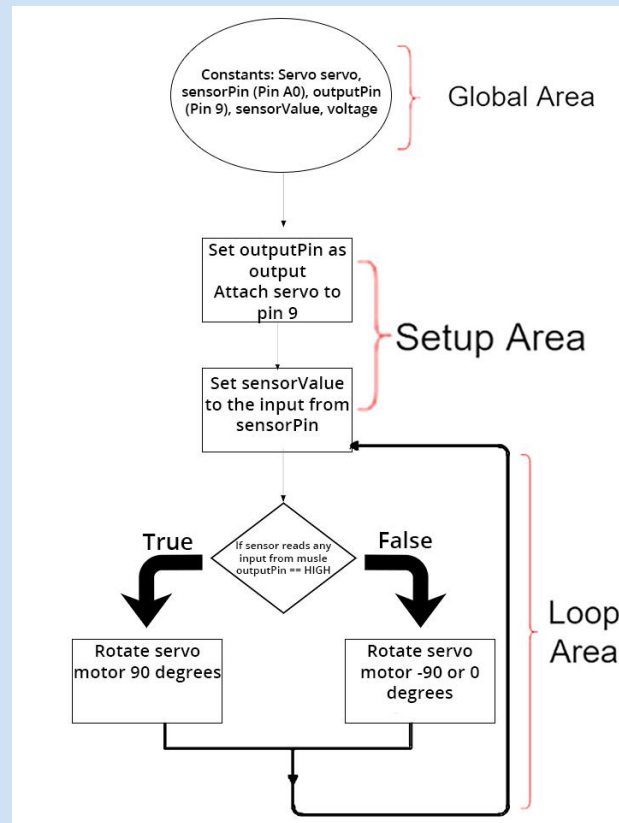


Figure 15: Arduino Code Flowchart

COST ESTIMATE

Table 1: Initial Cost Estimate

Resource	Cost Per Unit	Quantity	Cost
Plastic Printing Material	\$22.99	1	\$22.99
Arduino Cable	\$5.89	20	\$117.80
Arduino Uno Microcontroller (SparkFun Redboard)	\$18.79	1	\$18.79
Battery (9v)	\$6.99	2	\$13.98
Breadboard	\$10.99	1	\$10.99
DC motor	\$6.89	1	\$6.89
Muscle Sensor	\$37.99	2	\$75.98
Servo (Waterproof, boat/car)	\$35.99	1	\$35.99
String	\$7.99	10	\$79.90
Touch Sensor	\$11.99	1	\$11.99
Projected Labor	\$50.00	75	\$3,750
Total			\$4,145.30

COST ESTIMATE

- » Dropped:
 - ◇ Breadboard
 - ◇ Touch sensor
- » Cut price by \$30

Table 2: Updated Cost Estimate

Resource	Cost Per Unit	Quantity	Cost
Plastic Printing Material	\$22.99	1	\$22.99
Arduino Cable	\$5.89	20	\$117.80
Arduino Uno Microcontroller (SparkFun Redboard)	\$18.79	1	\$18.79
Battery (9v)	\$6.99	2	\$13.98
Muscle Sensor	\$37.99	2	\$75.98
Servo Motor	\$35.99	1	\$35.99
String	\$7.99	10	\$79.90
Projected Labor	\$50.00	75	\$3,750
Total			\$4,115.43

PROJECT SCHEDULE

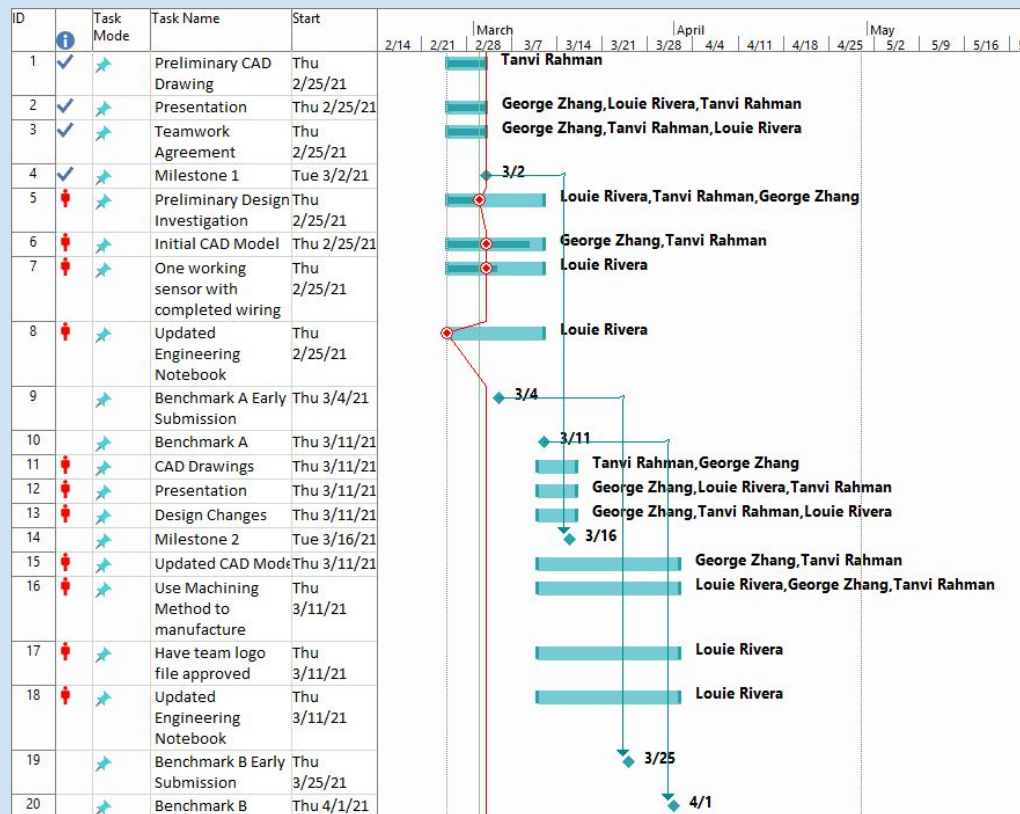


Figure 16: Initial Project Schedule

PROJECT SCHEDULE

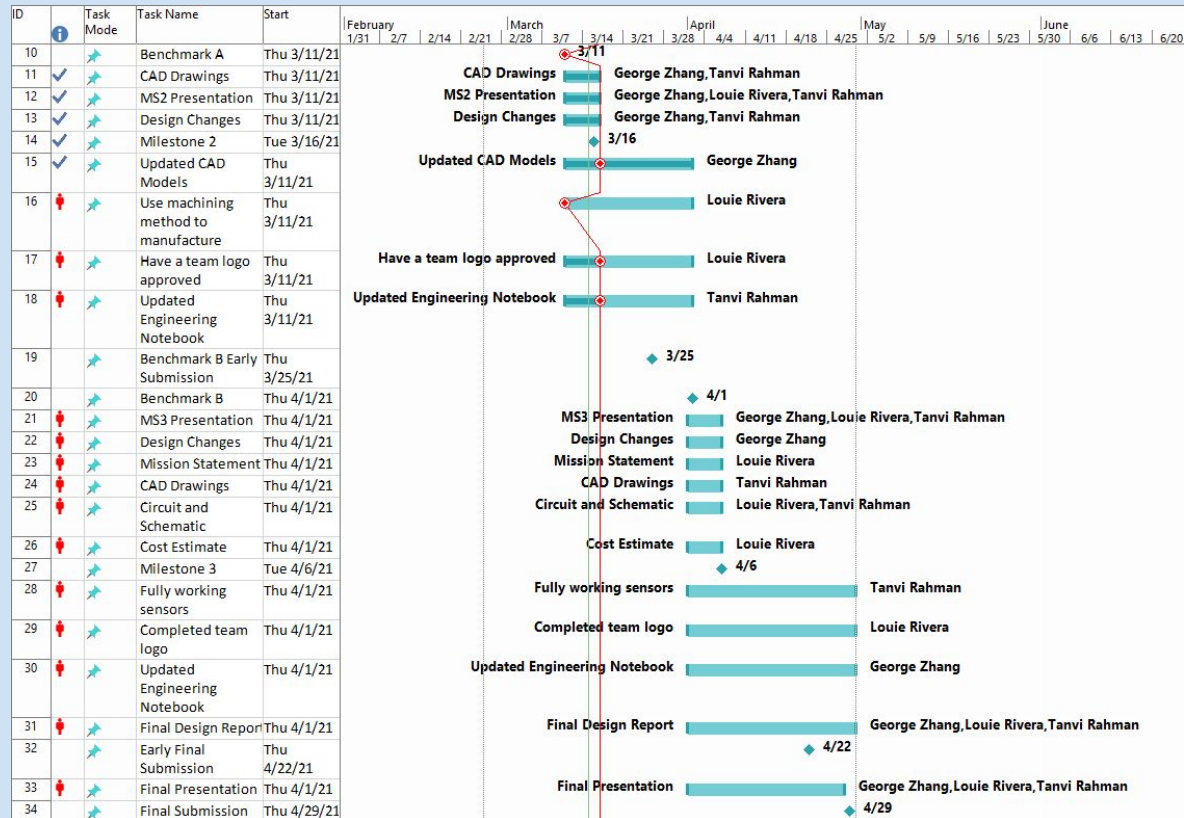


Figure 17: Updated Project Schedule

SUMMARY

» Ahead of schedule

- ◇ 90% CAD model and 75% circuit completed
- ◇ On track for early benchmark submission.

» Next Milestone:

- ◇ Complete CAD design.
- ◇ Completed sensor and motor integration
- ◇ Complete circuit





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